

# Playing optimally using memory

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Based on joint work with:

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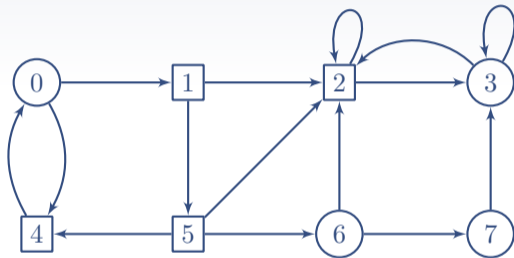
<sup>3</sup> F.R.S.-FNRS & UMONS – Université de Mons, Mons, Belgium



## Two-player games

### Example

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### Setting

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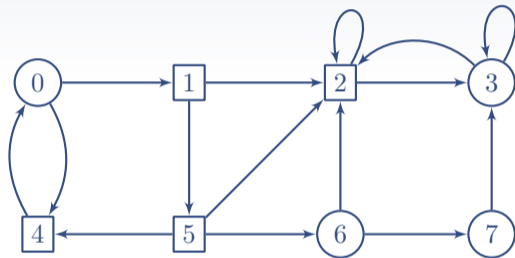
We consider:

- Finite graphs, a set of colors  $C$ , and a mapping from edges to colors.
- Two players, Max (circle) and Min (square).
- A preference relation  $\sqsubseteq$  (total preorder) over  $C^\omega$  for Max.
- Inverse relation  $\sqsubseteq^{-1}$  for Min.

## Controller synthesis

### Example

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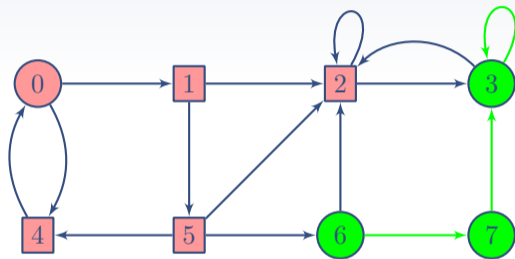


$\square$ : visit 3 at least once

# Controller synthesis

## Example

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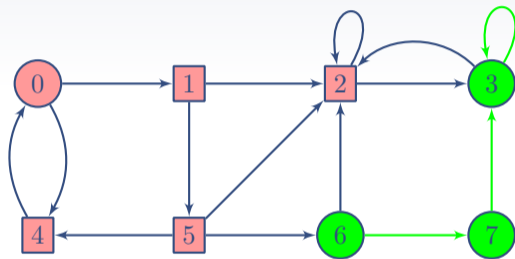


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Controller synthesis

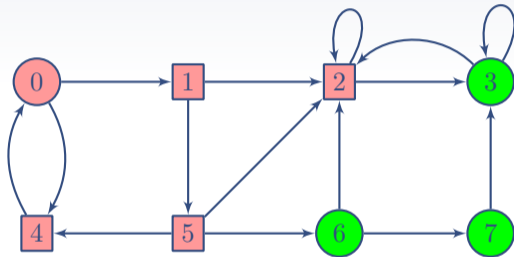
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Design *an optimal* strategy for Max w.r.t. the preference relation  $\sqsubseteq$ .

## Simple controller

### Example

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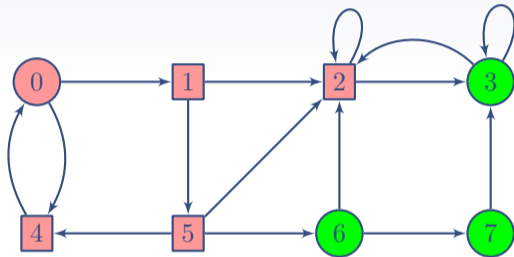


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## Simple controller

### Example

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$\sqsubseteq$ : visit 3 at least once

### Strategy for Max

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$3 \mapsto 3; 7 \mapsto 3; 6 \mapsto 7.$

# Complex controller

## Example

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$\sqsubseteq$ : infinitely often 2 and infinitely often 0



# Complex controller

## Example

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$\sqsubseteq$ : infinitely often 2 and infinitely often 0

## Strategy for Max

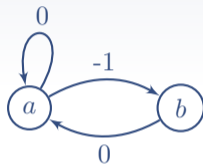
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$0 \ 1 \mapsto 2; 2 \ 1 \mapsto 0.$

## Very complex controller

### Example

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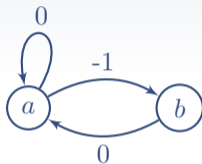


$\square$ : infinitely often  $b$  *and*  $\liminf$  of the average is  $\geq 0$

## Very complex controller

### Example

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$\square$ : infinitely often  $b$  *and*  $\liminf$  of the average is  $\geq 0$

### Strategy for Max

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$0 \mapsto 0;$	$00 \mapsto 1;$	$001 \mapsto 0;$	$0010 \mapsto 0;$
$00100 \mapsto 0;$	$001000 \mapsto 0;$	$0010000 \mapsto 1;$	$00100001 \mapsto 0;$
...	...	...	...

## Recap

### Controller synthesis

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Design *an optimal* strategy for Max w.r.t. the preference relation  $\sqsubseteq$ .

### Simple Controller

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Decision making depends on the current state; *memoryless* strategies.

### Complex Controller

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Decision making depends on a bounded history; *finite memory* strategies.

### Very complex Controller

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Decision making depends on the full history; *infinite memory* strategies.

## Memoryless determinacy

### Definition

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Both players can play *optimally* using *memoryless* strategies w.r.t  $\sqsubseteq$  and  $\sqsubseteq^{-1}$ .

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In 2005, Gimbert & Zielonka characterize the preference relations for which memoryless *optimal strategies* exist for both players.

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## Monotony

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## Selectivity

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## Furthermore

Lifting corollary (Gimbert, Zielonka'05)

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Let  $\sqsubseteq$  be a preference relation, assume that:

- i.* In *all Max-arenas* memoryless optimal strategies exist.
- ii.* In *all Min-arenas* memoryless optimal strategies exist (w.r.t.  $\sqsubseteq^{-1}$ ).

Then, **both** players have **memoryless optimal** strategies in *all two-player arenas*.

Remark

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Establishing *i.* and *ii.* is usually “easy”.

**Our hope**

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Extends all of the above to *finite memory determinacy*.

## Finite memory determinacy

Definition

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$\square$  is *finite memory determined* if finite memory optimal strategies suffice for both players.

## Finite memory determinacy

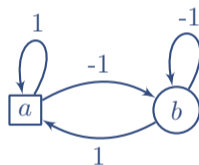
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### Example

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- i.* The running sum of weights grows up to infinity or,
- ii.* the running sum of weights takes value zero infinitely often.

## Finite memory determinacy

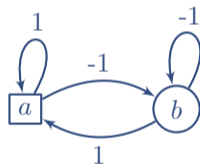
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- Max needs *infinite memory* to play optimally.

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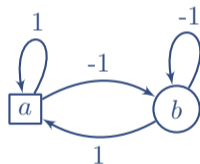
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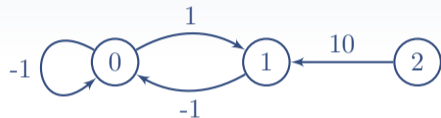


- i.* The running sum of weights grows up to infinity or,
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- Max needs *infinite memory* to play optimally.
  - In both the one-player versions *finite memory* optimal strategies exist.

## Arena dependent V.S Arena independent finite memory

ADFM

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The running sum of weights grows up to infinity or, the running sum of weights takes value zero infinitely often.

AIFM

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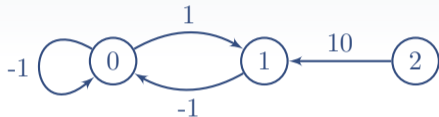


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Our contribution

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A characterization of the *arena independent* finite memory determined preference relations.

## Arena independent finite memory

### Memory structure

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An automaton-like formalism that given a color and a memory state, updates to the new memory state.



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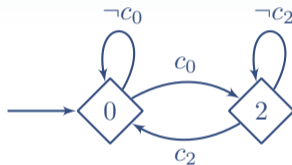
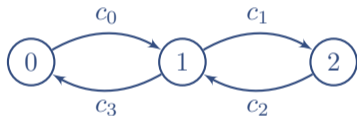
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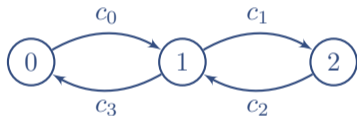


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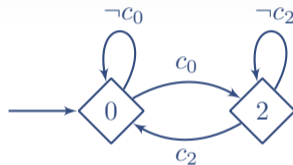
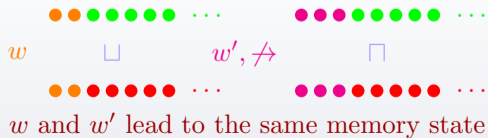
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## Example



### $\mathcal{M}$ -Monotony



### $\mathcal{M}$ -Selectivity



## Results

*Theorem (Bouyer, Le Roux, O., Randour, Vandenhove'20)*

---

Let  $\sqsubseteq$  be a preference relation and let  $\mathcal{M}$  be a memory structure, then *both players have optimal arena independant finite memory strategies based on a memory structure  $\mathcal{M}$  in all games if and only if  $\sqsubseteq$  and  $\sqsubseteq^{-1}$  are  $\mathcal{M}$ -monotone and  $\mathcal{M}$ -selective.*

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Remark

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The memory structure in the two-player case is the product of the memory structure in the one-player case.

## Comments

From finite memory to  $\mathcal{M}$ -monotone and  $\mathcal{M}$ -selective

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Follows the steps of Gimbert & Zielonka's proof.

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From  $\mathcal{M}$ -monotone and  $\mathcal{M}$ -selective to finite memory

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Requires the notion of *covered arenas*.

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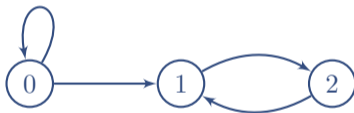
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$\sqsubseteq$ : 1 and 2 infinitely often.



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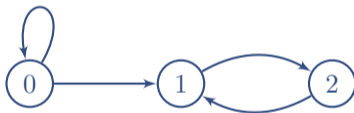
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## Crucial steps

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- i.* If  $\sqsubseteq$  is  $\mathcal{M}$ -monotone and  $\mathcal{M}$ -selective, then for any arena  $\mathcal{A}$ ,  $\mathcal{A} \times \mathcal{M}$  is a *covered* arena.
- ii.* In *covered* arenas it is possible to play optimally with memoryless strategies.

# Conclusion

## Results

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- Characterization of *AIFM*-determinacy.
- A lifting corollary in the context of *AIFM*-optimal strategies.

## Future directions

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- Characterization of *ADFM*-determinacy.
- More general arenas e.g., *stochastic games*.