

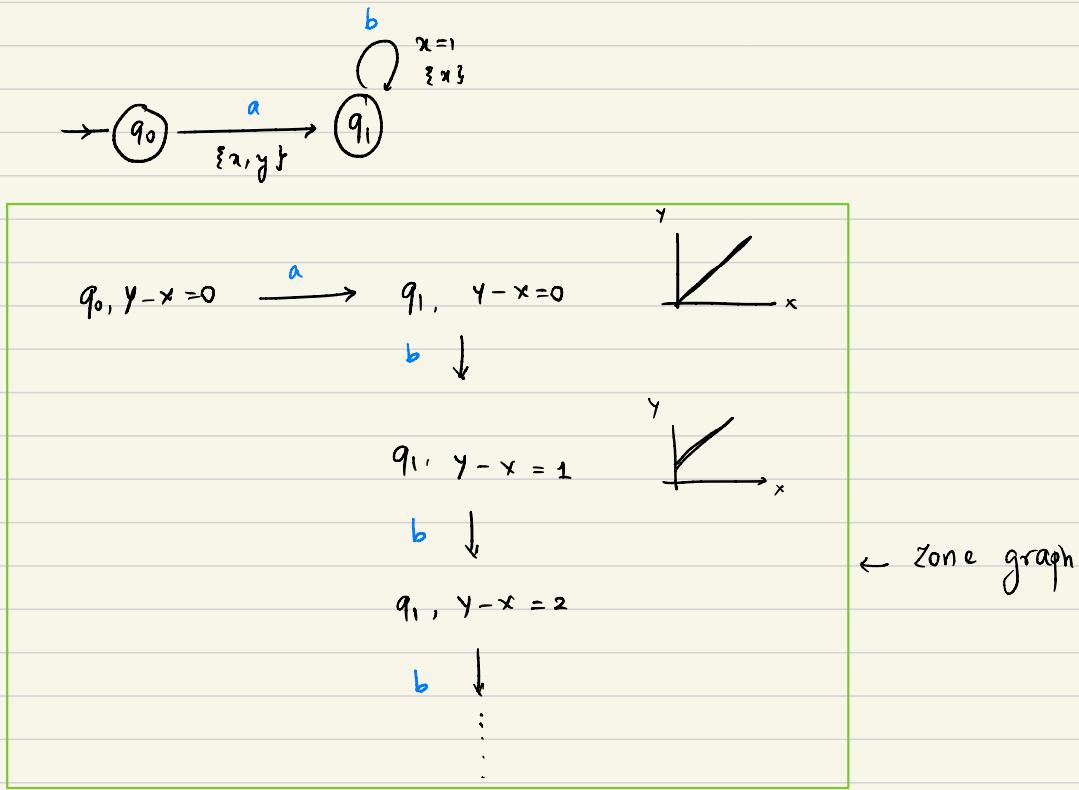
# TIMED AUTOMATA

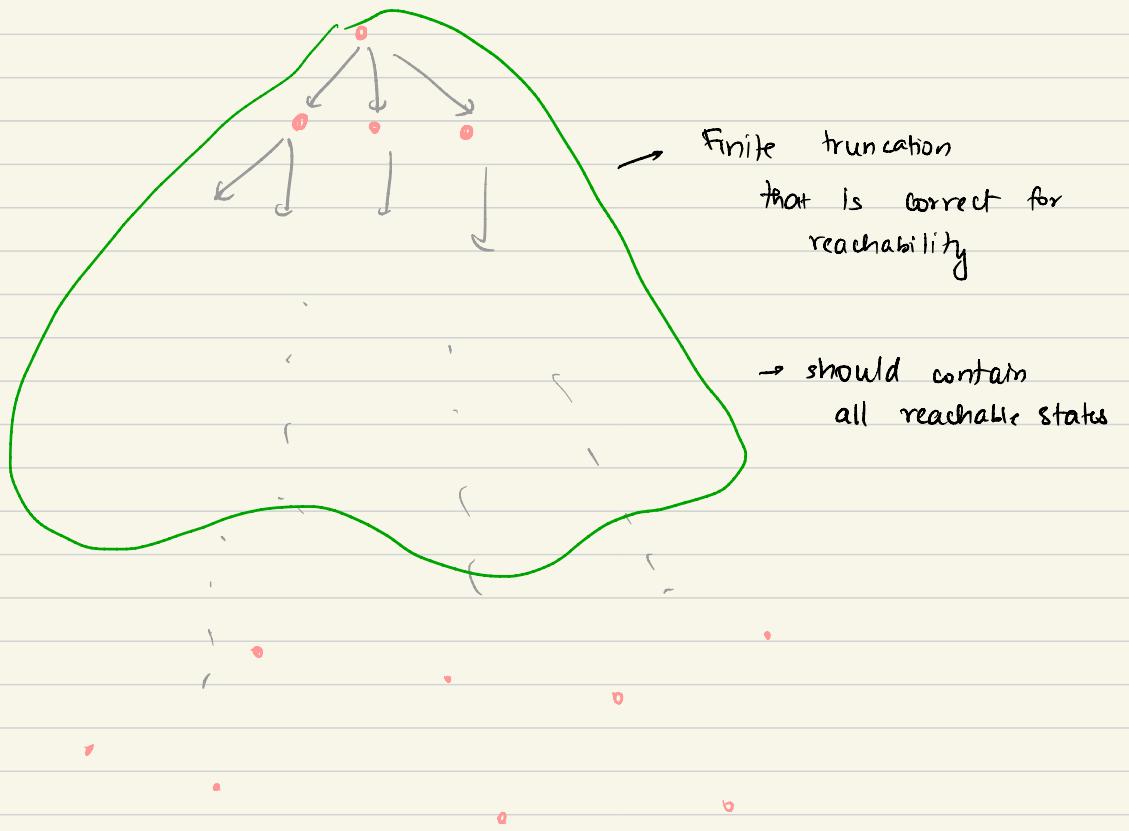
## LECTURE 13

Plan for today:

- Getting a finite truncation of the zone graph that is sound and complete for reachability

Recall:



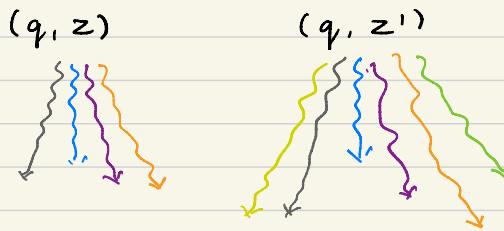


Goal:

1. Get finiteness
2. Get a small finite truncation

Main idea: Use simulations between zones

## Simulations between zones:



Core idea:  $(q, z)$  is simulated by  $(q', z')$  if

Every path from  $(q, z)$  has a "corresponding" path from  $(q', z')$

## Formalizing this idea:

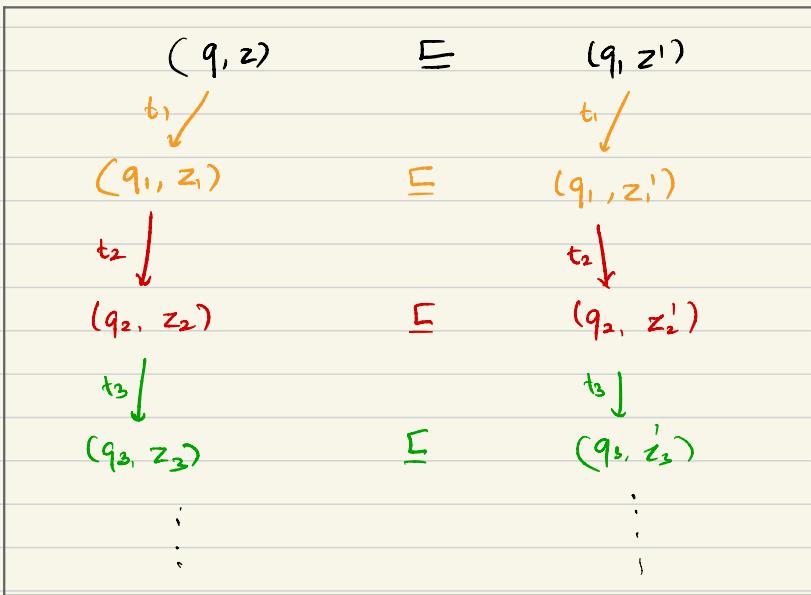
We will define a relation over nodes in the zone graph:

$$(q, z) \sqsubseteq (q', z')$$

The relation  $\sqsubseteq$  satisfies the following properties:

-1.  $\sqsubseteq$  is reflexive and transitive.

$$\begin{array}{ccc} -2. & (q, z) & \sqsubseteq (q', z') \\ \textcircled{1} \quad \forall & t \swarrow & \exists \quad \textcircled{2} \quad \downarrow \\ (q_1, z_1) & \sqsubseteq & (q_1, z'_1) \\ & \textcircled{3} & \end{array}$$



$$\begin{array}{ccc}
 (q, z) & \sqsubseteq & (q_1, z') \\
 \textcircled{1} \nexists \quad t \downarrow & \sqsupseteq & \quad \textcircled{2} \quad t \downarrow \\
 (q_1, z_1) & \sqsubseteq & (q_1, z'_1) \\
 \textcircled{3} & & 
 \end{array}$$

For every transition  $(q, z) \xrightarrow{t} (q_1, z_1)$

there exists transition  $(q, z') \xrightarrow{t} (q_1, z'_1)$

such that  $(q_1, z_1) \sqsubseteq (q_1, z'_1)$

Find a simulation relation:

$$(q, z) \sqsubseteq (q, z')$$



relating nodes which have  
same control state

So we will consider relation  $\sqsubseteq$  on zones.

$$(q, z) \sqsubseteq (q, z') \quad \text{if} \quad z \sqsubseteq z'$$

- Task is to find a relation  $\sqsubseteq$  on zones which will induce a simulation relation on nodes.

## A first attempt at a simulation:

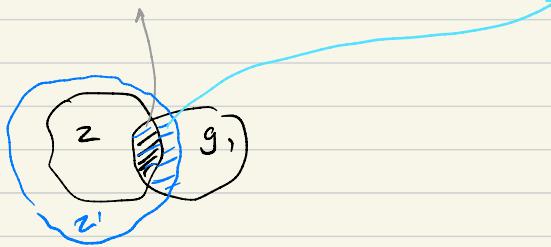
$$z \sqsubseteq z' \quad \text{if} \quad \underbrace{z \subseteq z'}$$

set inclusion

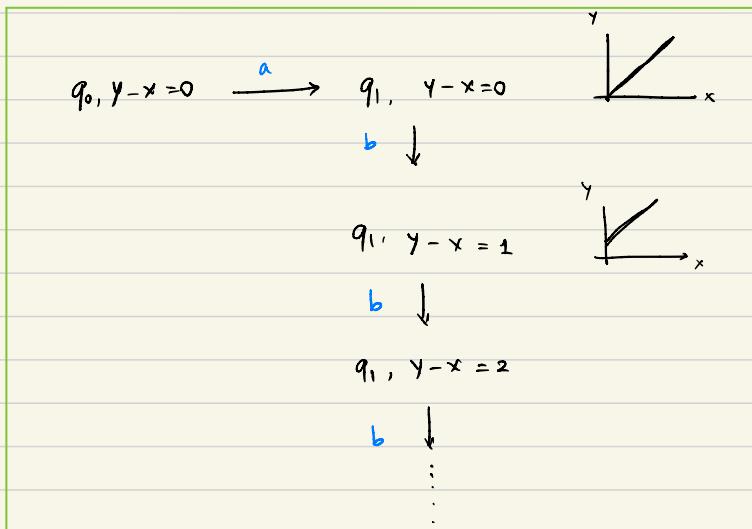
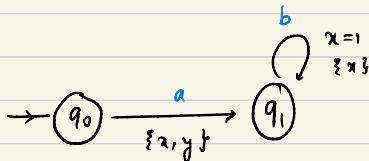
Is this a simulation?

*symbolic  
transition  
from last  
lecture*

$$\begin{array}{ccc} (q, z) & \sqsubseteq & (q, z') \\ \xrightarrow{t_1} \begin{matrix} g_1 \\ R_1 \end{matrix} & & \downarrow \begin{matrix} g_1 \\ R_1 \end{matrix} \\ (q_1, z_1) & \sqsubseteq & (q_1, z'_1) \end{array} \quad \text{when } z \subseteq z'$$
$$z_1 = \overbrace{[R_1](z \cap g_1)}^{\longrightarrow}$$
$$z'_1 = \overbrace{[R_1](z'_1 \cap g_1)}^{\longrightarrow}$$



- Set inclusion is a simulation.
- So, are we done?



← zone graph

No pair  $(q_1, y - x = i)$   $(q_1, y - x = j)$   $i \neq j$

is included in the other

- this gives no simulation in the above graph  
if we use set inclusion.

- Task is to get a "finite" simulation.

finite simulation:

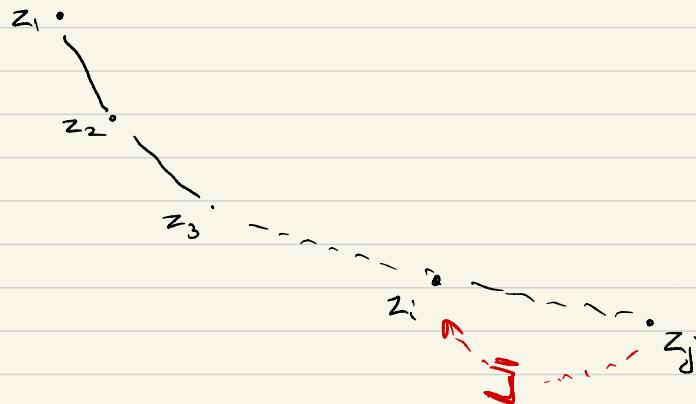
A relation  $Z \subseteq Z'$  is finite if:

for every sequence:

$z_1, z_2, \dots$

$\exists j > i \text{ s.t.}$

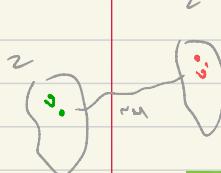
$$\boxed{z_j \sqsubseteq z_i}$$



## Simulation using regions: M-simulation

Let  $M$  be a max. bounds function attaching to each clock  $\alpha$  the maximum constant appearing in a guard involving  $\alpha$ .

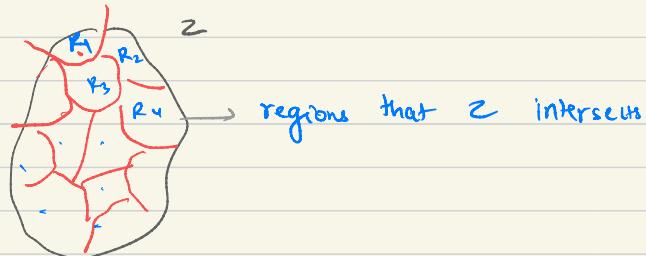
$$Z \leq_M Z' \quad \text{if}$$



$$\forall v \in Z, \exists v' \in Z' \text{ s.t. } v \sim_M v'$$

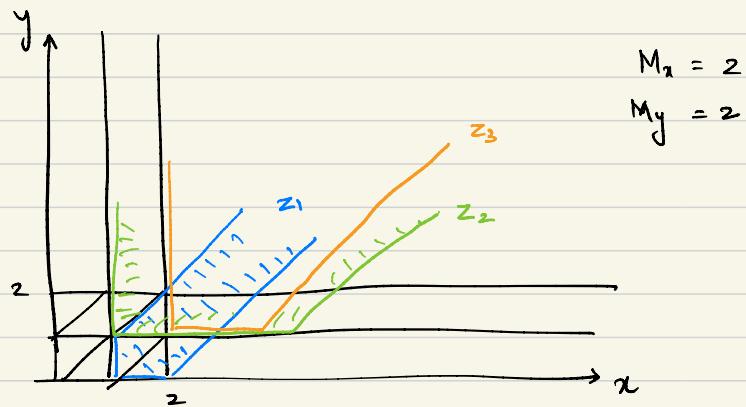
$\sim_M$  denotes region equivalence

$$\text{Regions}_M(Z) \subseteq \text{regions}_M^{(2)}$$



$$\text{Regions}_M(Z) = \{ [v]_M \mid v \in Z \}$$

Recall:  $z \leq_M z'$  if  $\text{Region}_M(z) \subseteq \text{Region}_M(z')$



1.  $z_1 \leq_M z_2$ ? No,  $(1 < x < 2, 0 < y < 1, x < y) \in z_1 \notin z_2$ .

2.  $z_2 \leq_M z_1$ ? No,  $(1 < x < 2, y > 2) \in z_2, \notin z_1$ .

3.  $z_1 \leq_M z_3$ ? No, same as (1)

4.  $z_3 \leq_M z_1$ ?

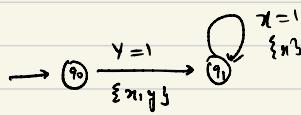
$z_3: x \geq 2$  (orange line coincides with black line)

-  $z_3 \not\leq_M z_1$   $y > 2, x = 2$

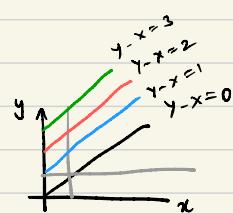
$z_3: x \geq 2$

-  $z_3 \leq_M z_1$

Example 1:



$$(q_0, y-x=0) \longrightarrow q_1, y-x=0$$



$$q_1, y-x=1$$



$$q_1, y-x=2$$

$$x=0, y>1$$



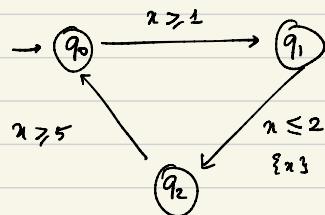
$$y-x=3 \leq_M y-x=2$$



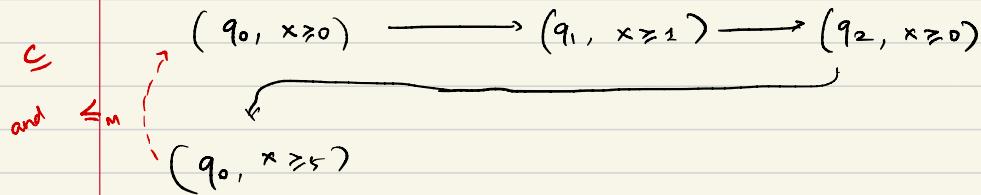
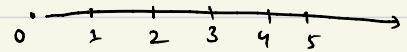
$$q_1, y-x=3$$

Using  $\leq_M$  gives a finite truncation.

Example 2:



$M=5$ , single clock.



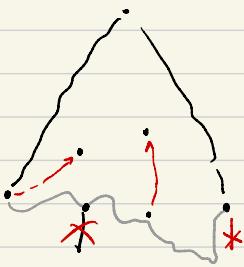
## Simulation graph:

It is a finite truncation of the zone graph computed using the following algorithm.

- The algorithm maintains two lists: Passed & Waiting.

- 1) Add initial node  $(q_0, z_0)$  to Waiting.
- 2) While  $\text{Waiting} \neq \emptyset$  do.
  - 3) - Pick  $(q, z)$  from Waiting
  - 4) - Add it to Passed.
  - 5) - For every successor  $(q_1, z_1) \xrightarrow{t} (q_1, z_1')$ :
    - 6) if  $\exists (q_1, z_1') \text{ in } \begin{cases} \text{Passed} \\ \cup \\ \text{Waiting} \end{cases}$  s.t.  $z_1 \leq_M z_1'$  skip
    - 7) else add  $(q_1, z_1)$  to Waiting

→ This algorithm computes a finite truncation of the zone graph.



Every leaf in the finite truncation is  
 either a deadlock (no enabled actions from this node)  
 or a covered node (there is a non-leaf node that simulates  
 this)

Theorem:  $(q, z) \leq_m (q, z')$  is a simulation  
on the nodes of the zone graph.

(Exercise)

Theorem:  $\leq_m$  is finite.

(Exercise)

Theorem:  $z \leq_m z'$  can be done in  $O(|x|^2)$

$x$  is the no. of clocks.

↳ Ref.: Better abstractions for timed automata  
Herbreteau, Srivathsan, Walukiewicz '16.

This is as efficient as checking inclusions between zones.

### Summary:

- We have given an algorithm to compute a finite truncation of the zone graph.
- This is based on: simulation:  $Z \leq_M Z'$  when

$$\text{Regions}_n(Z) \subseteq \text{Regions}_m(Z')$$

Remark: Current tools use more sophisticated simulation.  
(out of scope for our course).