

Unit-10: Algorithms for CTL

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NPTEL-course

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Module 3: Final algorithm

CTL model-checking problem

Given transition system M and a CTL formula ϕ , find all states of M that satisfy ϕ

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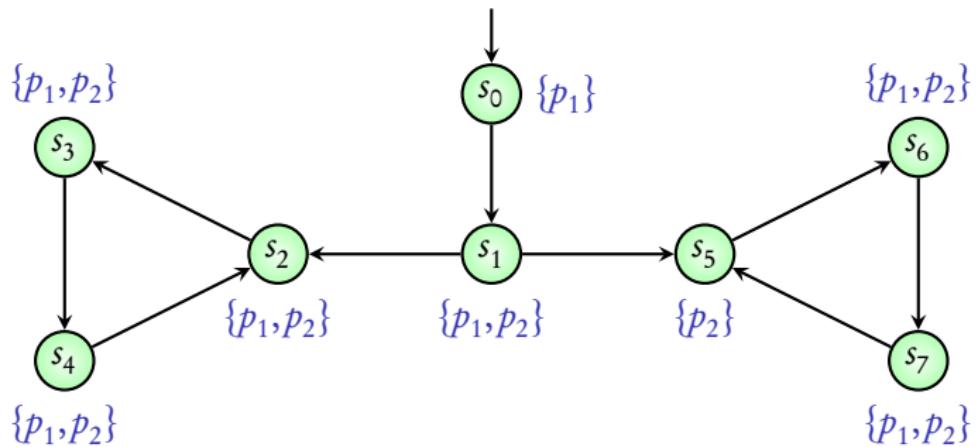
- ▶ **Module 1:** Every CTL formula can be written using EX, EU, EG
- ▶ **Module 2:** Labelling algorithms for EX, EU, EG

Coming next: Generic algorithm for a CTL formula

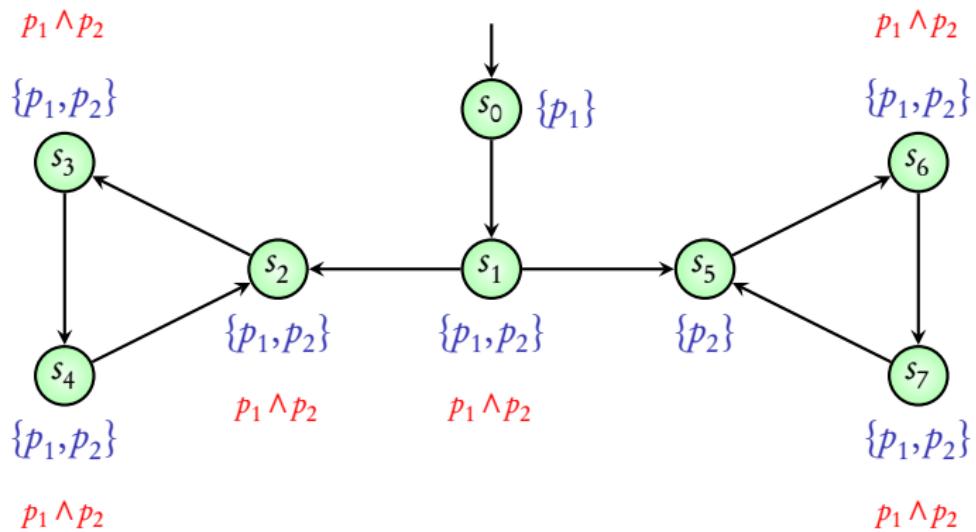
State formulae

$$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid EX \phi \mid E(\phi_1 U \phi_2) \mid EG \phi$$
 $p_i \in AP$ $\phi, \phi_1, \phi_2 : \text{State formulae}$

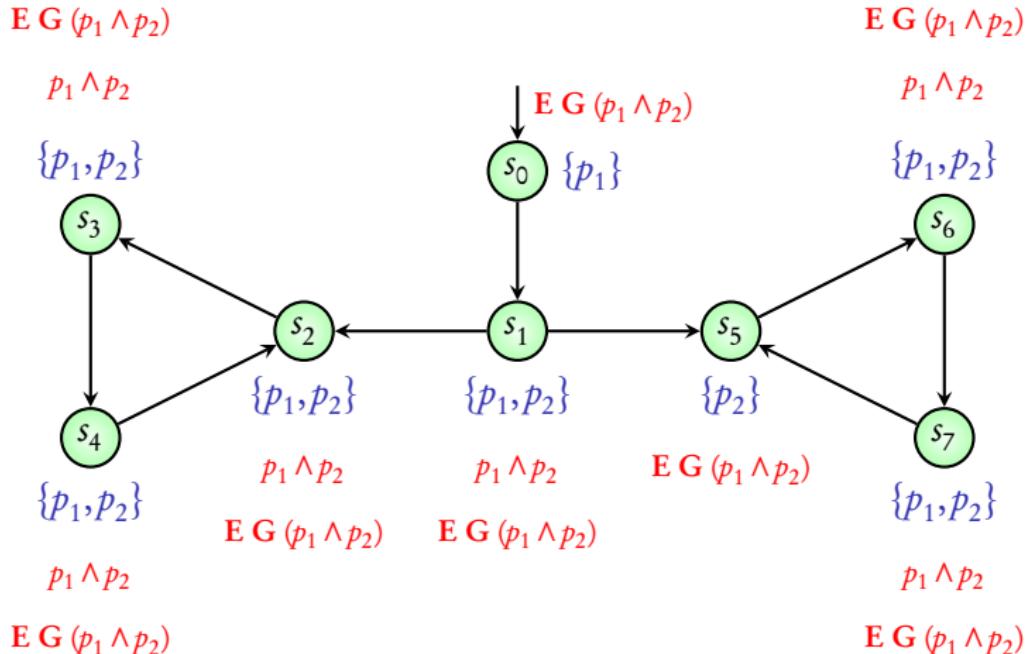
E X E G ($p_1 \wedge p_2$)



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$$\mathbf{E} \times \mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$



$$\mathbf{E} \times \mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$p_1 \wedge p_2$$

$$\{p_1, p_2\}$$

s_3

$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

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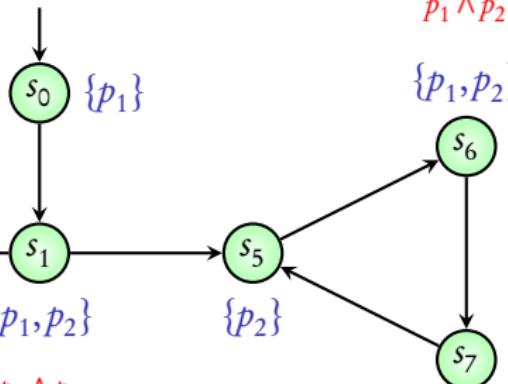
$$p_1 \wedge p_2$$

$$\{p_1, p_2\}$$

$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$



$$\mathbf{E} \times \mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$p_1 \wedge p_2$$

$$\{p_1, p_2\}$$

$$s_3$$

$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

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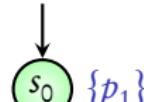
$$p_1 \wedge p_2$$

$$\{p_1, p_2\}$$

$$s_6$$

$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$



$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$p_1 \wedge p_2$$

$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$\{p_1\}$$

$$s_5$$

$$\{p_2\}$$

$$p_1 \wedge p_2$$

$$\{p_1, p_2\}$$

$$p_1 \wedge p_2$$

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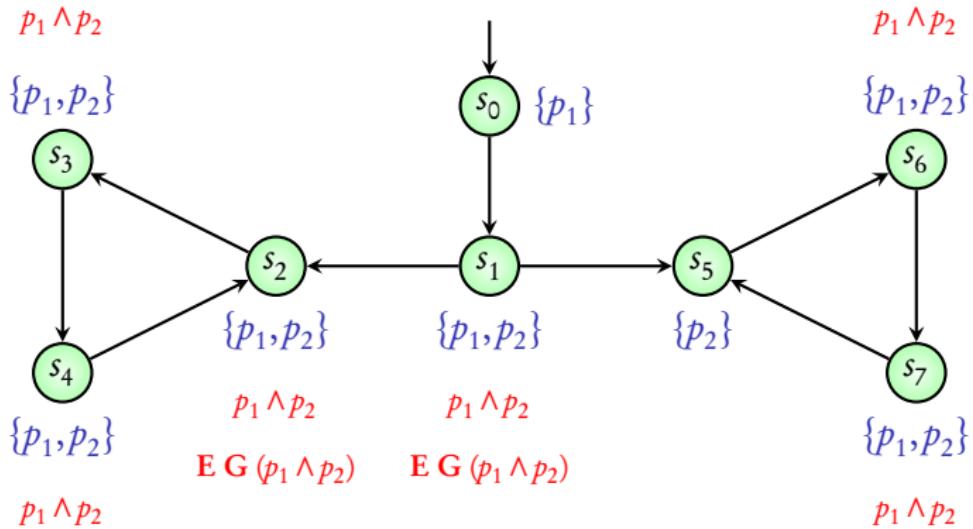
$$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$$

$$p_1 \wedge p_2$$

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$\mathbf{E} \mathbf{X} \mathbf{E} \mathbf{G} (p_1 \wedge p_2)$

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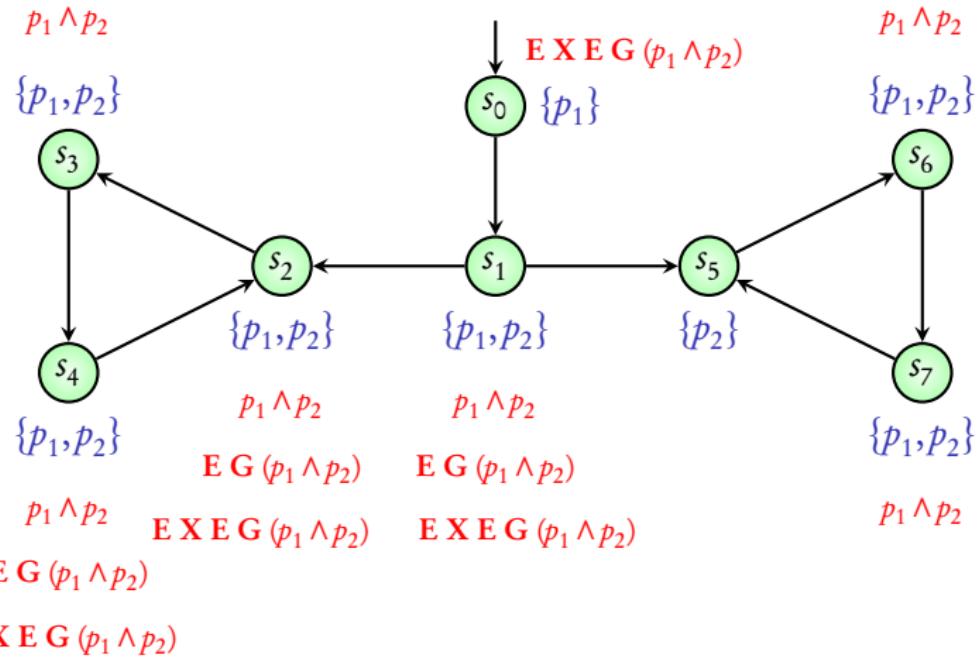


$\mathbf{E} \mathbf{G} (p_1 \wedge p_2)$

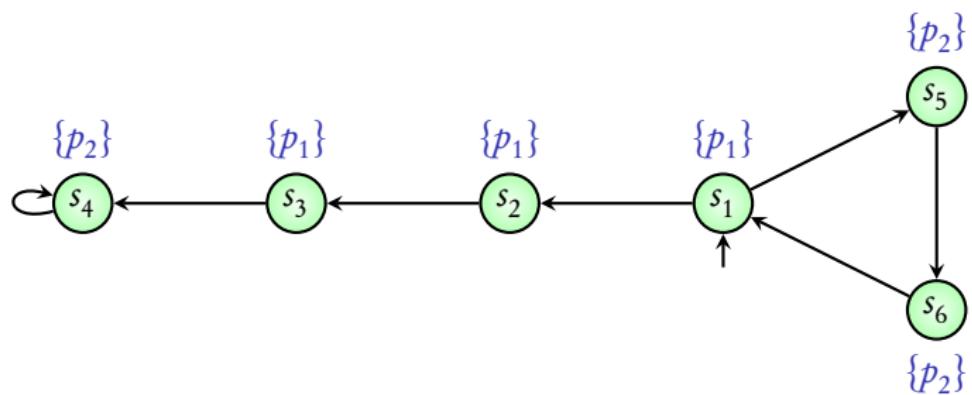
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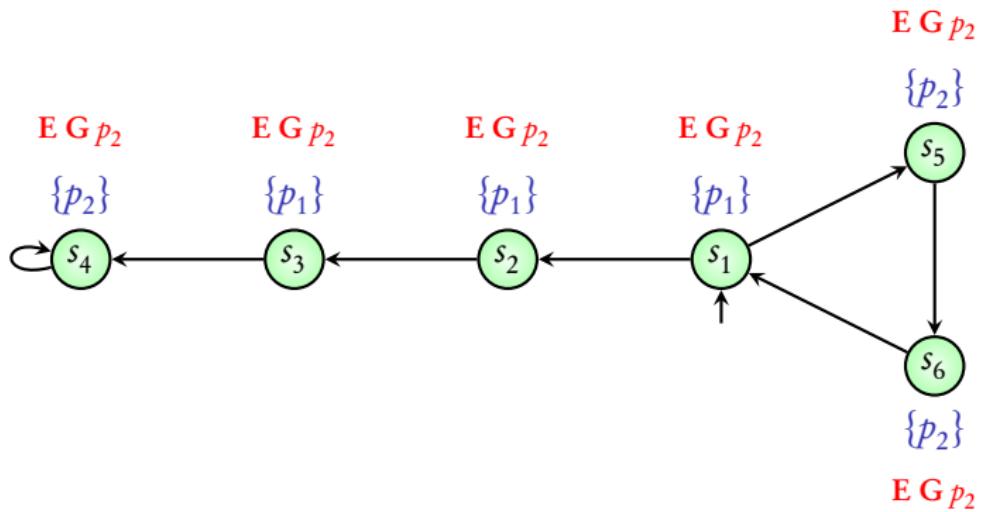
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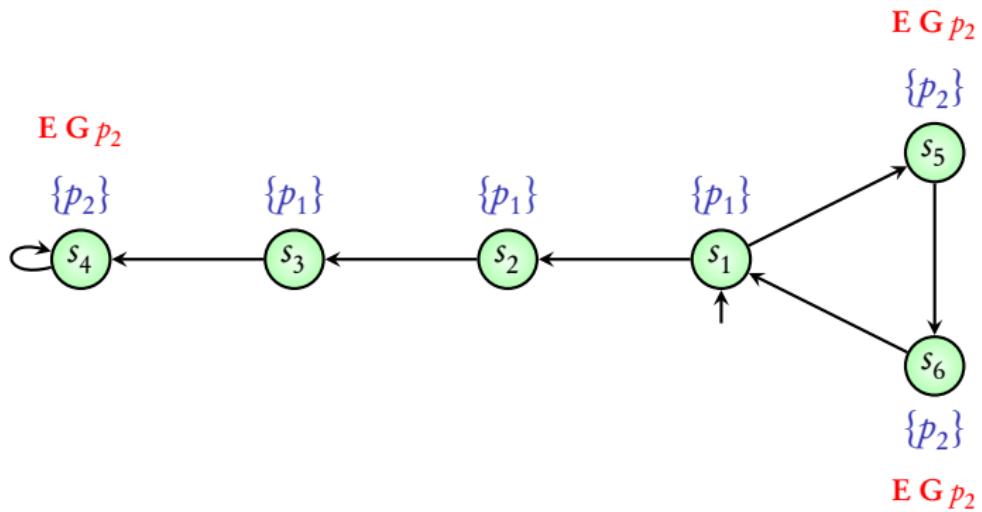


$$\mathbf{E} p_1 \mathbf{U} (\mathbf{E} \mathbf{G} p_2)$$

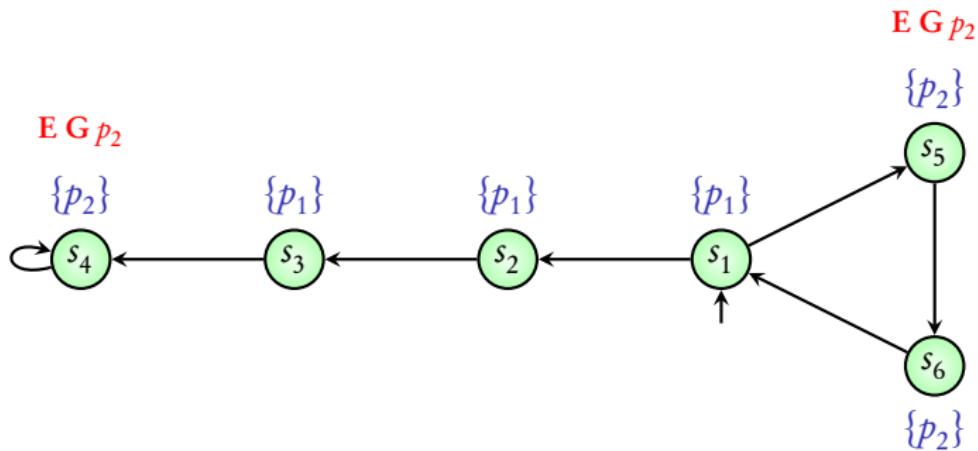


$\mathbf{E} p_1 \mathbf{U} (\mathbf{E} \mathbf{G} p_2)$ 

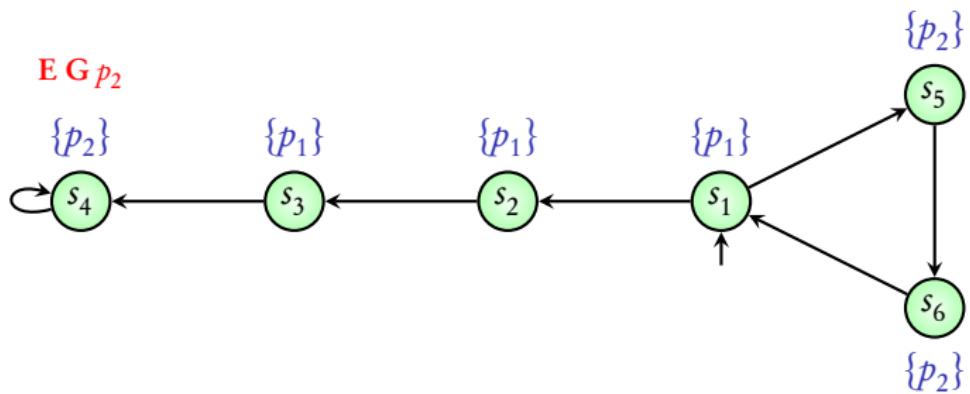
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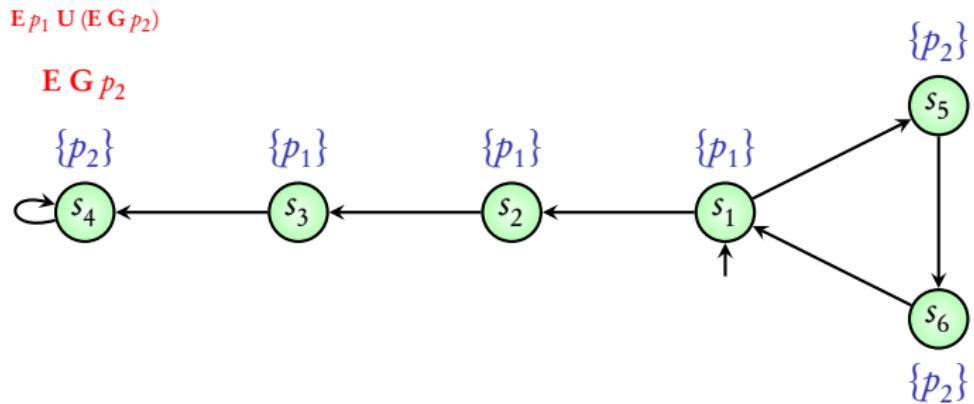
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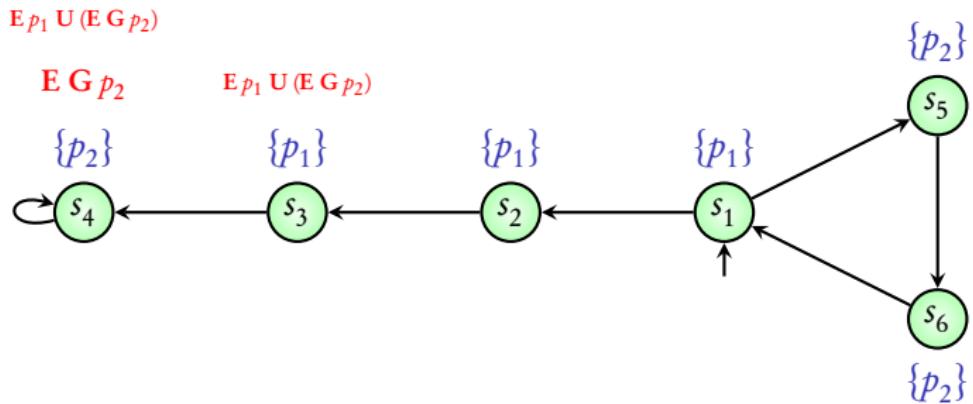
$$\mathbf{E} \ p_1 \ \mathbf{U} \ (\mathbf{E} \ \mathbf{G} \ p_2)$$



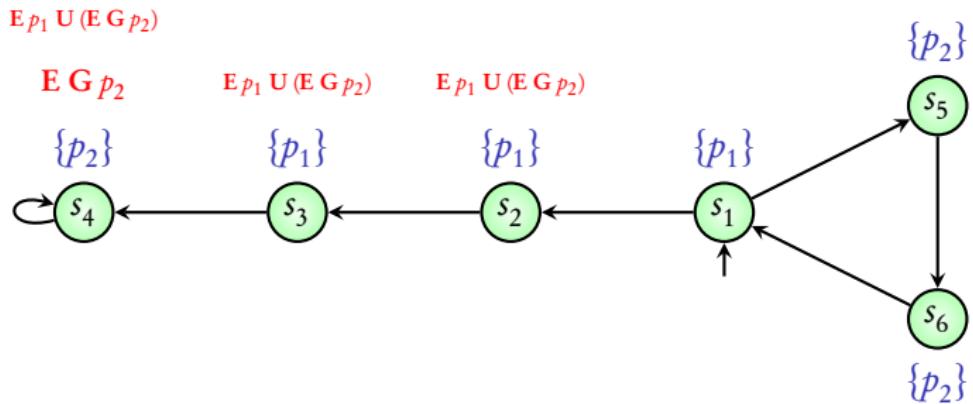
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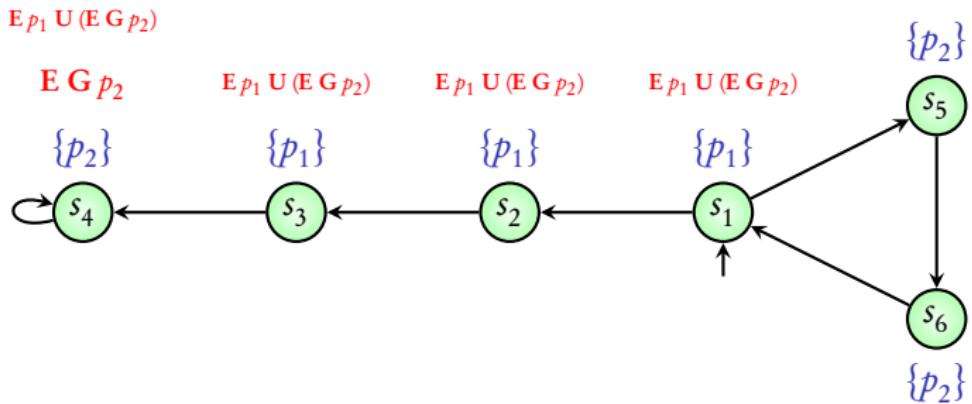
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function SAT(ϕ)

/* **Input:** Transition system M with state set S , CTL formula ϕ in ENF */

/* **Output:** Set of states satisfying ϕ */

end function

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end case

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function SAT( $\phi$ )
  /* Input: Transition system  $M$  with state set  $S$ , CTL formula  $\phi$  in ENF */
  /* Output: Set of states satisfying  $\phi$  */
```

```
case
   $\phi$  is true : return  $S$ 
```

```
end case
end function
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   $\phi$  is  $\phi_1 \wedge \phi_2$  : return SAT( $\phi_1$ )  $\cap$  SAT( $\phi_2$ )
```

```
end case
```

```
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```

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```

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```

```
     $\phi$  is E X  $\phi_1$  : return SATEX( $\phi_1$ ) /* procedure seen in Module 2 */
```

```
end case
```

```
end function
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     $\phi$  is E X  $\phi_1$  : return SATEX( $\phi_1$ ) /* procedure seen in Module 2 */
     $\phi$  is E ( $\phi_1 \cup \phi_2$ ) : return SATEU( $\phi_1, \phi_2$ ) /* procedure seen in Module 2 */

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     $\phi$  is E G  $\phi_1$  : return SATEG( $\phi_1$ ) /* procedure seen in Module 2 */

  end case
end function

```

CTL model-checking algorithm

Reference: Logic in Computer Science, by Huth and Ryan - Section 3.6.1