

Learning Linear Temporal Properties

Daniel Neider

joint work with Ivan Gavran

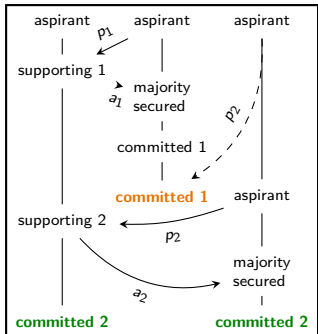
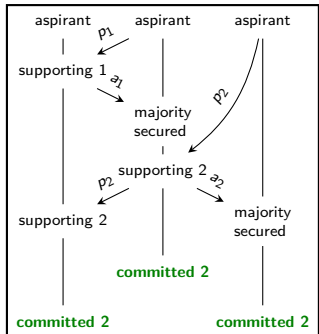


MAX PLANCK INSTITUTE
FOR SOFTWARE SYSTEMS

Complexity, Algorithms, Automata and Logic Meet
Chennai Mathematical Institute, India
January 24, 2019

Making Sense of a System's Behavior

Apache Zookeeper Leader Election



Goal

Development of learning algorithms for formulas in Linear Temporal Logic (LTL) from data

Outline

1. Learning setup
2. A base algorithm for learning LTL formulas based on SAT solving
3. A performance improvement for the base algorithm based on learning decision trees
4. Future work

1. Learning Setup

Let \mathcal{P} be a set of atomic propositions. Then,

- ▶ each $p \in \mathcal{P}$ is an LTL formula, and
- ▶ if φ and ψ are LTL formulas, so are $\neg\varphi$, $\varphi \vee \psi$, $X\varphi$, $\varphi U \psi$
(as well as $\varphi \wedge \psi$, $\varphi \rightarrow \psi$, $F\varphi$, $G\varphi$, and so on)

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- ▶ For instance, $u = \{p\}\{q\}\emptyset\{p, q\}\emptyset\{p, q\}$

Example

Let $\mathcal{P} = \{p, q, r\}$

- ▶ $\neg p \vee q$
- ▶ $X(p \wedge q)$
- ▶ $\neg p U (q \wedge X r)$

The semantics is defined by a satisfaction relation \models as follows:

$$u, i \models p \iff u: \begin{array}{c} 0 \qquad \qquad i \\ | \text{-----} | \\ p \in u(i) \end{array}$$

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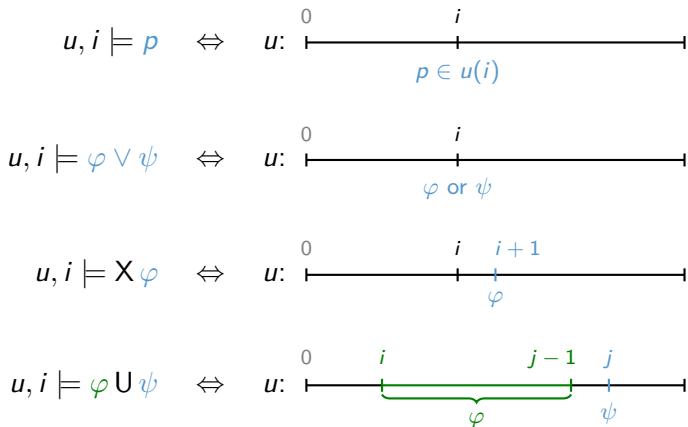
$$u, i \models p \Leftrightarrow u: \begin{array}{c} 0 \qquad \qquad i \\ | \text{-----} | \\ \qquad \qquad \qquad p \in u(i) \end{array}$$

$$u, i \models \varphi \vee \psi \Leftrightarrow u: \begin{array}{c} 0 \qquad \qquad i \\ | \text{-----} | \\ \qquad \qquad \qquad \varphi \text{ or } \psi \end{array}$$

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 \\
 u, i \models \varphi U \psi \Leftrightarrow u: \begin{array}{c} 0 \qquad i \qquad \qquad j-1 \quad j \\ \text{-----} \\ \qquad \underbrace{\qquad \qquad \qquad \varphi \qquad \qquad \qquad} \qquad \psi \end{array}
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Abbreviation: we write $u \models \psi$ for $u, 0 \models \psi$

Consider the LTL formula $\psi := X(p \wedge q)$

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	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	p						
2	q						
3	$p \wedge q$						
4	$X(p \wedge q)$						

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Sample

A *sample* is a pair $\mathcal{S} = (P, N)$ consisting of

- ▶ a finite set $P \subset (2^{\mathcal{P}})^*$ of *positive examples* (✓) and
- ▶ a finite set $N \subset (2^{\mathcal{P}})^*$ of *negative examples* (✗)

such that $P \cap N = \emptyset$

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The *size* of formula ψ is the number of its unique subformulas

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Size of an LTL Formula

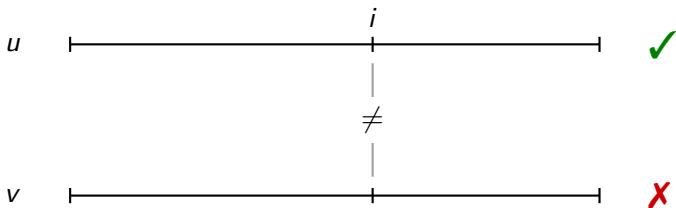
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Learning of LTL Formulas

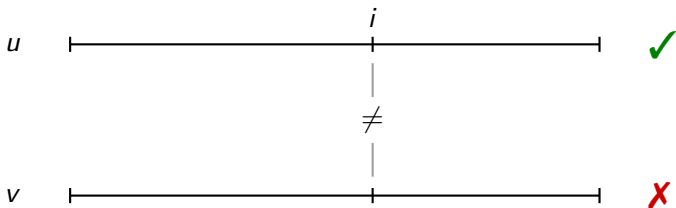
Given a sample \mathcal{S} , construct a *minimal* LTL formula ψ that is *consistent* with \mathcal{S} :

- ▶ $u \models \psi$ for each $u \in P$
- ▶ $u \not\models \psi$ for each $u \in N$

A Consistent Formula Always Exists

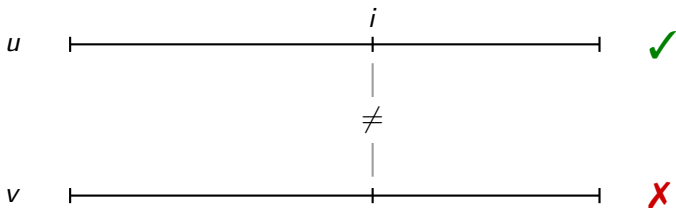


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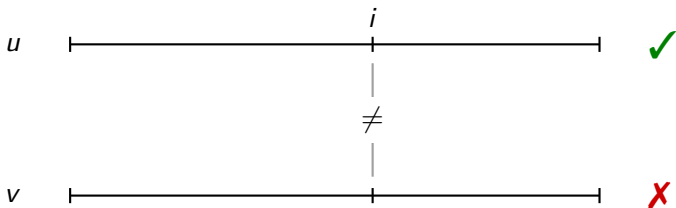
$$\left[\left(\bigwedge_{p \in u(i)} p \right) \wedge \left(\bigwedge_{q \notin u(i)} \neg q \right) \right]$$

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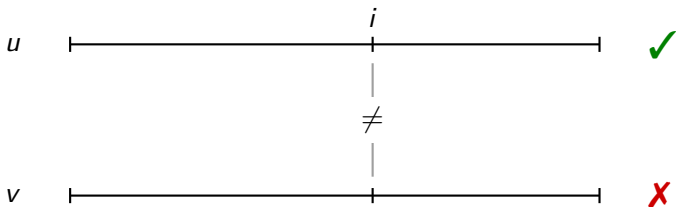
$$\overbrace{X \dots X}^{i \text{ times}} \left[\left(\bigwedge_{p \in u(i)} p \right) \wedge \left(\bigwedge_{q \notin u(i)} \neg q \right) \right]$$

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But, this formula overfits the sample!

Given: a sample \mathcal{S} and $n \in \mathbb{N}$

Question: does a consistent LTL formula of size n exist?

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Membership in NP

- ▶ Nondeterministically guess an LTL formula of size n
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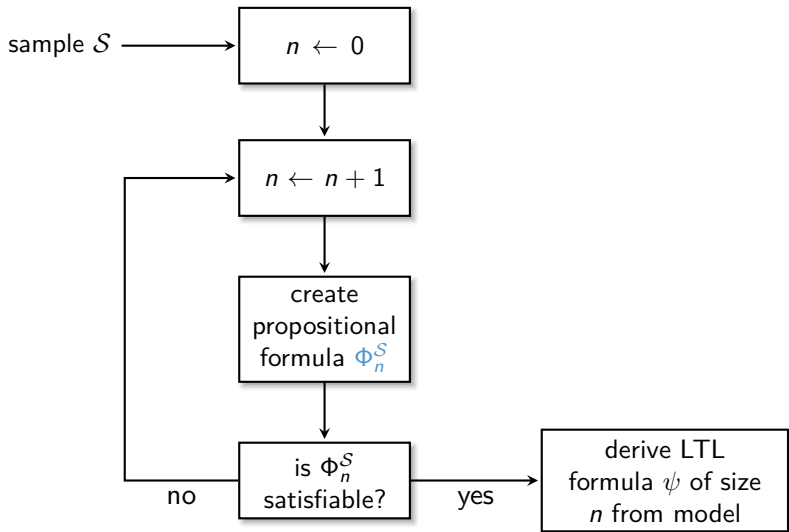
NP-Hardness?

We do not know whether the problem is NP-hard

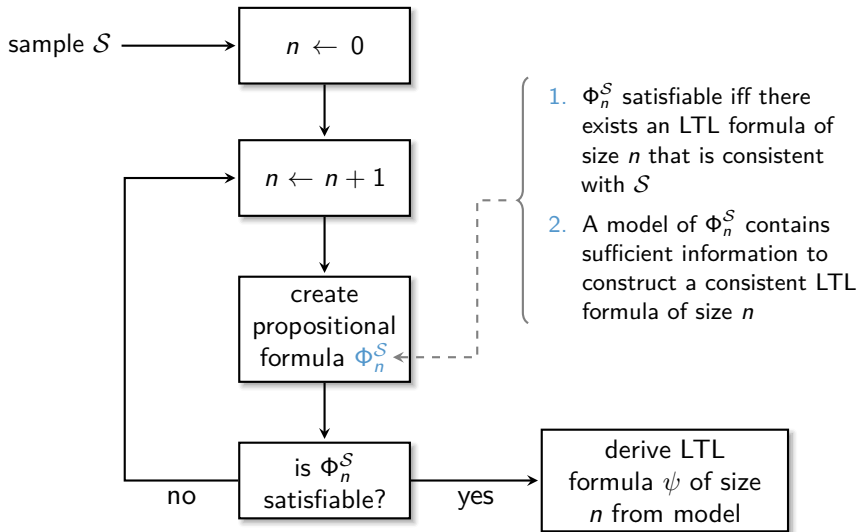
- ▶ But we strongly suspect that it is
- ▶ What are samples requiring “large” consistent formulas?
(proposal: $P = \{\{p\}^n\}$ and $N = \{\{p\}^{n+1}\}$)

2. A SAT-based Learning Algorithm

A SAT-based Learning Algorithm

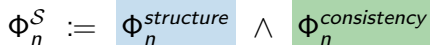


A SAT-based Learning Algorithm



$$\Phi_n^{\mathcal{S}} := \Phi_n^{\text{structure}} \wedge \Phi_n^{\text{consistency}}$$

Encodes the structure of the LTL formula

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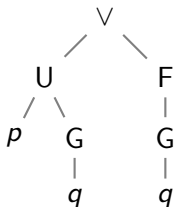
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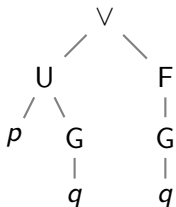
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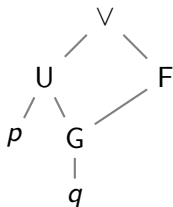


Syntax Tree

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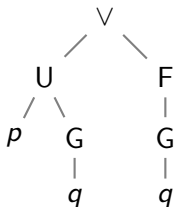


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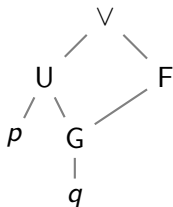


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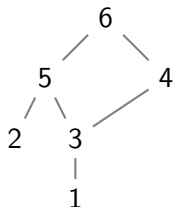
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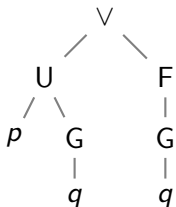


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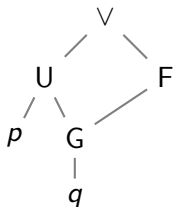


Identifiers

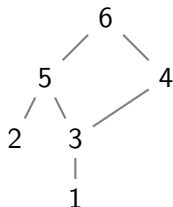
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Syntax Tree



Syntax DAG



Identifiers

Variables

- ▶ $x_{i,\lambda}$ where $i \in \{1, \dots, n\}$ and $\lambda \in \Lambda$
- ▶ $l_{i,j}$ where $i \in \{2, \dots, n\}$ and $j \in \{1, \dots, i-1\}$
- ▶ $r_{i,j}$ where $i \in \{2, \dots, n\}$ and $j \in \{1, \dots, i-1\}$

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Formula $\Phi_n^{structure}$

- ▶ For $i \in \{1, \dots, n\}$, exactly one $x_{i,\lambda}$ can be set to true:

$$\left[\bigwedge_{1 \leq i \leq n} \bigvee_{\lambda \in \Lambda} x_{i,\lambda} \right] \wedge \left[\bigwedge_{1 \leq i \leq n} \bigwedge_{\lambda \neq \lambda' \in \Lambda} \neg x_{i,\lambda} \vee \neg x_{i,\lambda'} \right]$$

- ▶ For $i \in \{2, \dots, n\}$, exactly one $l_{i,j}$ and exactly one $r_{i,j}$ can be set to true
- ▶ One of the variables $x_{1,p}$ for $p \in \mathcal{P}$ is set to true

Encodes the structure of the LTL formula

$$\Phi_n^{\mathcal{S}} := \Phi_n^{\text{structure}} \wedge \Phi_n^{\text{consistency}}$$

Ensures that the LTL formula is consistent with the sample

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	p	1	0	0	1	0	1
2	q	0	1	0	1	0	1
3	$p \wedge q$	0	0	0	1	0	1
4	$\neg(p \wedge q)$	0	0	1	0	1	0

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / \ell_{1,j} / r_{1,j}$						
2	$x_{2,\lambda} / \ell_{2,j} / r_{2,j}$						
3	$x_{3,\lambda} / \ell_{3,j} / r_{3,j}$						
4	$x_{4,\lambda} / \ell_{4,j} / r_{4,j}$						

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / \ell_{1,j} / r_{1,j}$	$y_{1,0}^u$	$y_{1,1}^u$	$y_{1,2}^u$	$y_{1,3}^u$	$y_{1,4}^u$	$y_{1,5}^u$
2	$x_{2,\lambda} / \ell_{2,j} / r_{2,j}$	$y_{2,0}^u$	$y_{2,1}^u$	$y_{2,2}^u$	$y_{2,3}^u$	$y_{2,4}^u$	$y_{2,5}^u$
3	$x_{3,\lambda} / \ell_{3,j} / r_{3,j}$	$y_{3,0}^u$	$y_{3,1}^u$	$y_{3,2}^u$	$y_{3,3}^u$	$y_{3,4}^u$	$y_{3,5}^u$
4	$x_{4,\lambda} / \ell_{4,j} / r_{4,j}$	$y_{4,0}^u$	$y_{4,1}^u$	$y_{4,2}^u$	$y_{4,3}^u$	$y_{4,4}^u$	$y_{4,5}^u$

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$$\wedge\text{-operator: } \left[x_{3,\lambda} \wedge \ell_{3,1} \wedge r_{3,2} \right] \rightarrow \left[y_{3,1}^u \leftrightarrow (y_{1,1}^u \wedge y_{2,1}^u) \right]$$

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / l_{1,j} / r_{1,j}$	$y_{1,0}^u$	$y_{1,1}^u$	$y_{1,2}^u$	$y_{1,3}^u$	$y_{1,4}^u$	$y_{1,5}^u$
2	$x_{2,\lambda} / l_{2,j} / r_{2,j}$	$y_{2,0}^u$	$y_{2,1}^u$	$y_{2,2}^u$	$y_{2,3}^u$	$y_{2,4}^u$	$y_{2,5}^u$
3	$x_{3,\lambda} / l_{3,j} / r_{3,j}$	$y_{3,0}^u$	$y_{3,1}^u$	$y_{3,2}^u$	$y_{3,3}^u$	$y_{3,4}^u$	$y_{3,5}^u$
4	$x_{4,\lambda} / l_{4,j} / r_{4,j}$	$y_{4,0}^u$	$y_{4,1}^u$	$y_{4,2}^u$	$y_{4,3}^u$	$y_{4,4}^u$	$y_{4,5}^u$

$$\text{X-operator: } \left[x_{3,\lambda} \wedge l_{3,2} \right] \rightarrow \left[y_{3,1}^u \leftrightarrow y_{2,2}^u \right]$$

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / \ell_{1,j} / r_{1,j}$	$y_{1,0}^u$	$y_{1,1}^u$	$y_{1,2}^u$	$y_{1,3}^u$	$y_{1,4}^u$	$y_{1,5}^u$
2	$x_{2,\lambda} / \ell_{2,j} / r_{2,j}$	$y_{2,0}^u$	$y_{2,1}^u$	$y_{2,2}^u$	$y_{2,3}^u$	$y_{2,4}^u$	$y_{2,5}^u$
3	$x_{3,\lambda} / \ell_{3,j} / r_{3,j}$	$y_{3,0}^u$	$y_{3,1}^u$	$y_{3,2}^u$	$y_{3,3}^u$	$y_{3,4}^u$	$y_{3,5}^u$
4	$x_{4,\lambda} / \ell_{4,j} / r_{4,j}$	$y_{4,0}^u$	$y_{4,1}^u$	$y_{4,2}^u$	$y_{4,3}^u$	$y_{4,4}^u$	$y_{4,5}^u$

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / \ell_{1,j} / r_{1,j}$	$y_{1,0}^u$	$y_{1,1}^u$	$y_{1,2}^u$	$y_{1,3}^u$	$y_{1,4}^u$	$y_{1,5}^u$
2	$x_{2,\lambda} / \ell_{2,j} / r_{2,j}$	$y_{2,0}^u$	$y_{2,1}^u$	$y_{2,2}^u$	$y_{2,3}^u$	$y_{2,4}^u$	$y_{2,5}^u$
3	$x_{3,\lambda} / \ell_{3,j} / r_{3,j}$	$y_{3,0}^u$	$y_{3,1}^u$	$y_{3,2}^u$	$y_{3,3}^u$	$y_{3,4}^u$	$y_{3,5}^u$
4	$x_{4,\lambda} / \ell_{4,j} / r_{4,j}$	$y_{4,0}^u$	$y_{4,1}^u$	$y_{4,2}^u$	$y_{4,3}^u$	$y_{4,4}^u$	$y_{4,5}^u$

$$\Phi_n^{\text{consistency}} := \left[\bigwedge_{u \in P} \Phi_n^u \wedge y_{n,0}^u \right]$$

	u	$\{p\}$	$\{q\}$	\emptyset	$\{p, q\}$	\emptyset	$\{p, q\}$
1	$x_{1,\lambda} / \ell_{1,j} / r_{1,j}$	$y_{1,0}^u$	$y_{1,1}^u$	$y_{1,2}^u$	$y_{1,3}^u$	$y_{1,4}^u$	$y_{1,5}^u$
2	$x_{2,\lambda} / \ell_{2,j} / r_{2,j}$	$y_{2,0}^u$	$y_{2,1}^u$	$y_{2,2}^u$	$y_{2,3}^u$	$y_{2,4}^u$	$y_{2,5}^u$
3	$x_{3,\lambda} / \ell_{3,j} / r_{3,j}$	$y_{3,0}^u$	$y_{3,1}^u$	$y_{3,2}^u$	$y_{3,3}^u$	$y_{3,4}^u$	$y_{3,5}^u$
4	$x_{4,\lambda} / \ell_{4,j} / r_{4,j}$	$y_{4,0}^u$	$y_{4,1}^u$	$y_{4,2}^u$	$y_{4,3}^u$	$y_{4,4}^u$	$y_{4,5}^u$

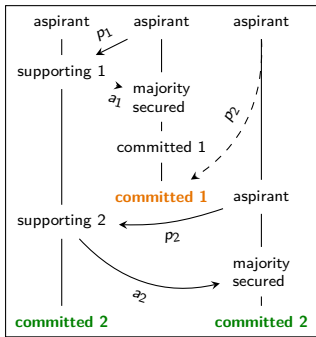
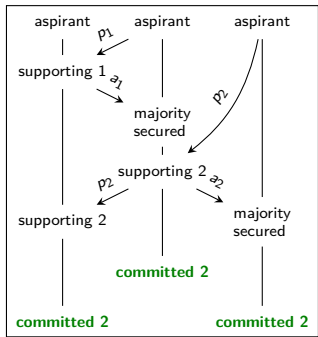
$$\Phi_n^{\text{consistency}} := \left[\bigwedge_{u \in P} \Phi_n^u \wedge y_{n,0}^u \right] \wedge \left[\bigwedge_{u \in N} \Phi_n^u \wedge \neg y_{n,0}^u \right]$$

Remark

For a sample \mathcal{S} and fixed n , the constructed propositional formula $\Phi_n^{\mathcal{S}}$ has the desired properties and ranges over $\mathcal{O}(n^2 + n \cdot |\mathcal{P}| + n \cdot |\mathcal{S}|)$ variables

Theorem

A minimal LTL formula consistent with a given sample \mathcal{S} can be found by solving a sequence of SAT queries for $\Phi_n^{\mathcal{S}}$

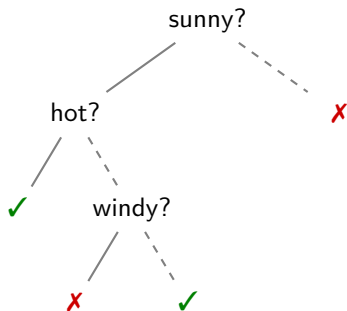


$$\psi := \neg rec(2, 1) \cup comm(1)$$

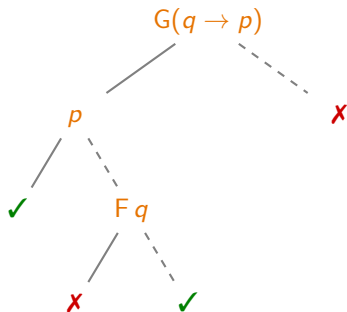
3. An Enhanced Algorithm Based on Decision Trees

Sunny?	Hot?	Windy?	Play golf or not
false	true	true	X
true	false	true	X
false	false	false	X
true	false	false	✓
true	true	true	✓

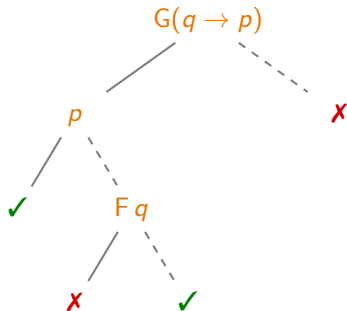
Sunny?	Hot?	Windy?	Play golf or not
false	true	true	X
true	false	true	X
false	false	false	X
true	false	false	✓
true	true	true	✓



$G(q \rightarrow p)$	p	Fq	Classification
false	true	true	\times
true	false	true	\times
false	false	false	\times
true	false	false	\checkmark
true	true	true	\checkmark

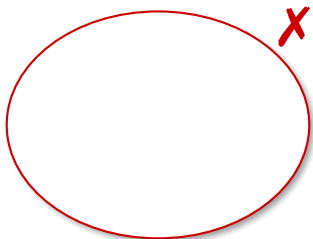
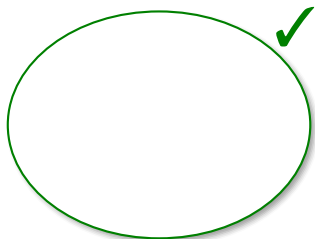


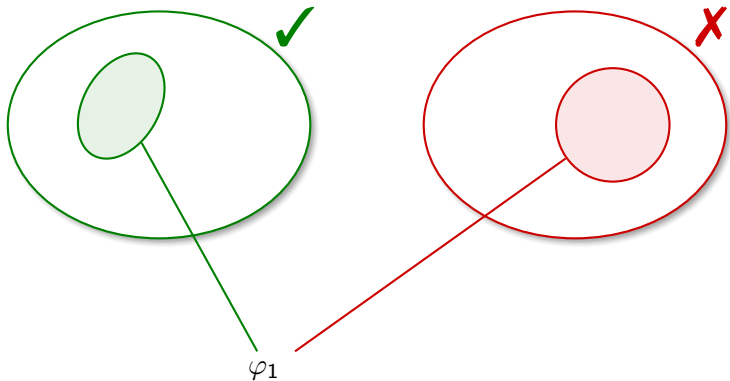
$G(q \rightarrow p)$	p	Fq	Classification
false	true	true	\times
true	false	true	\times
false	false	false	\times
true	false	false	\checkmark
true	true	true	\checkmark

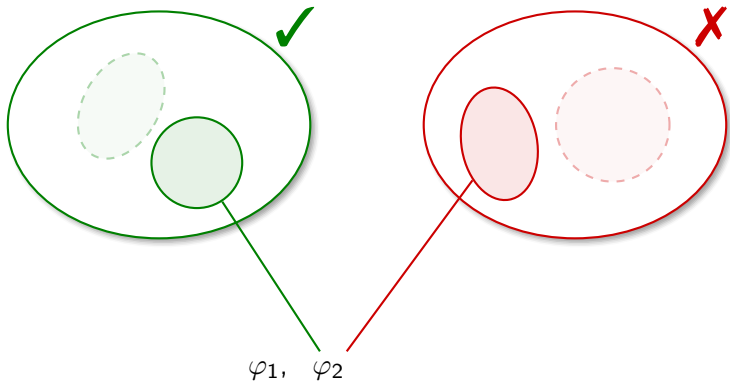


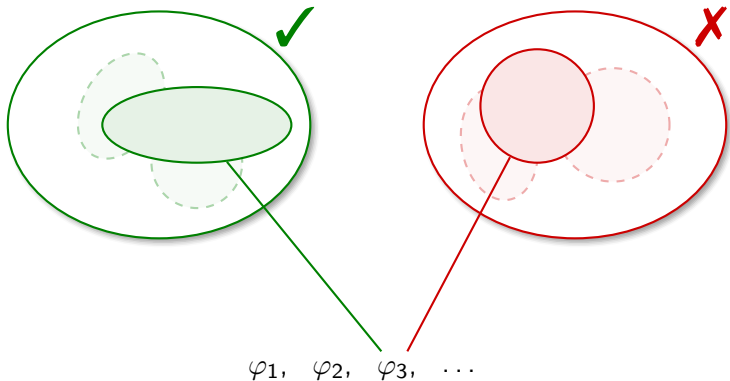
$$(G(q \rightarrow p) \wedge p) \vee$$

$$(G(q \rightarrow p) \wedge \neg p \wedge \neg Fq)$$







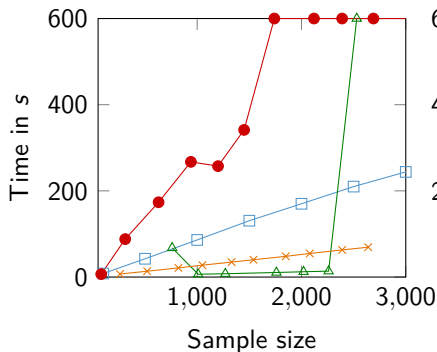


Strategy

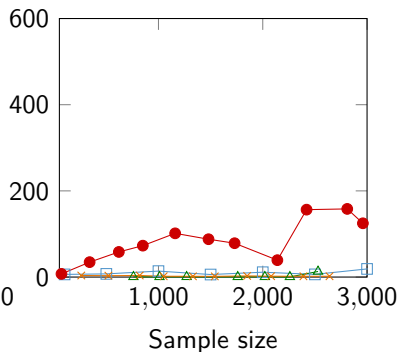
Which sampling strategy to use?

Evaluation on Synthetic Benchmarks

SAT-based algorithm



DT-enhanced algorithm



$$F p_1 \rightarrow (\neg p_0 \cup p_1)$$



$$G(p_0 \wedge (\neg p_1 \rightarrow ((\neg p_1 \cup (p_2 \wedge \neg p_1))))$$

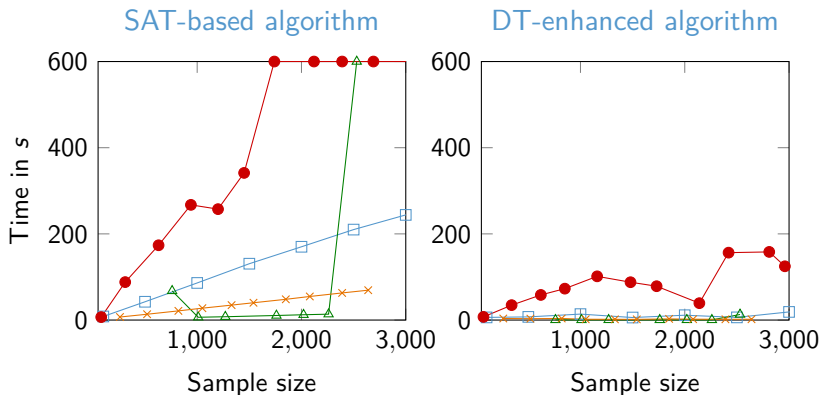


$$G(p_1 \rightarrow G p_0)$$



$$G \neg p_0$$

Evaluation on Synthetic Benchmarks



Average increase in size: 1.41

4. Future Work

Try It!

You can download our tool from gitHub

`https://github.com/gergia/samples2LTL`

Ideas for Future Work

- ▶ Gain better understanding of the complexity
- ▶ Relax learning model, allow misclassification errors (MAX-SAT)
- ▶ Learning from positive data only
- ▶ Other declarative formalisms, such as (ω -)regular expressions, PSL, STL, CTL, UML Message Sequence Charts, etc.