

Programming in Haskell

Aug-Nov 2015

LECTURE 18

OCTOBER 20, 2015

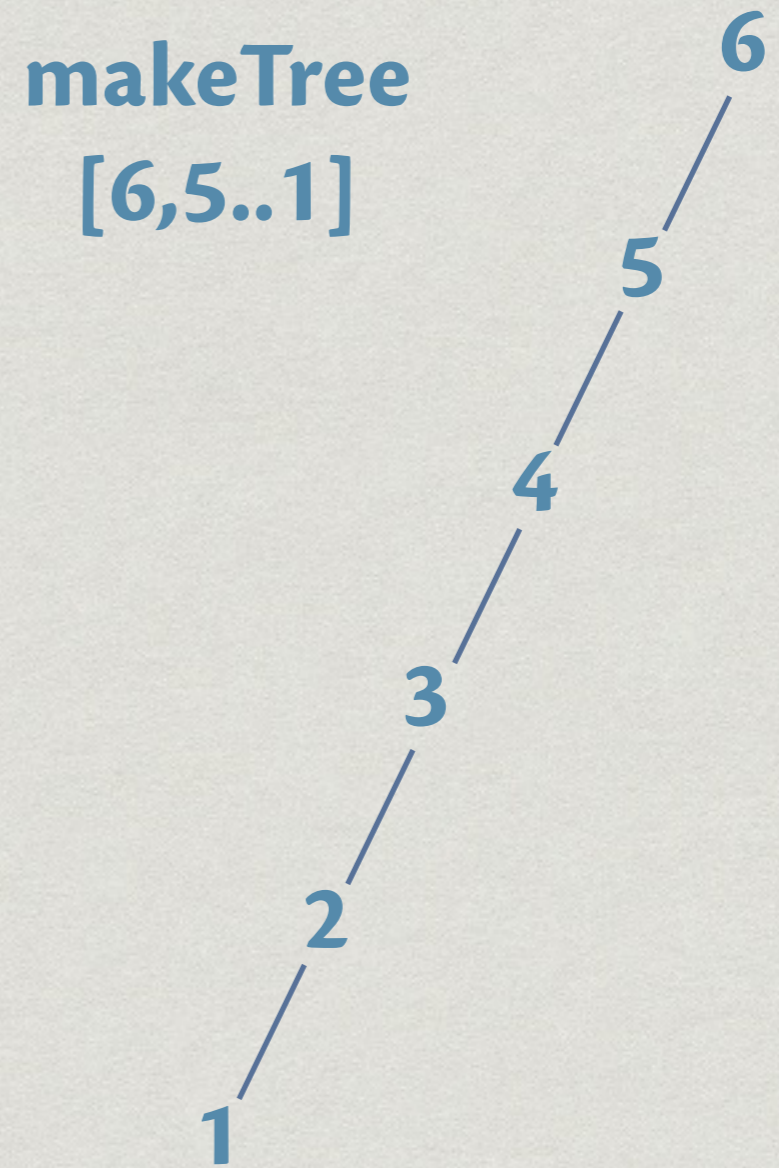
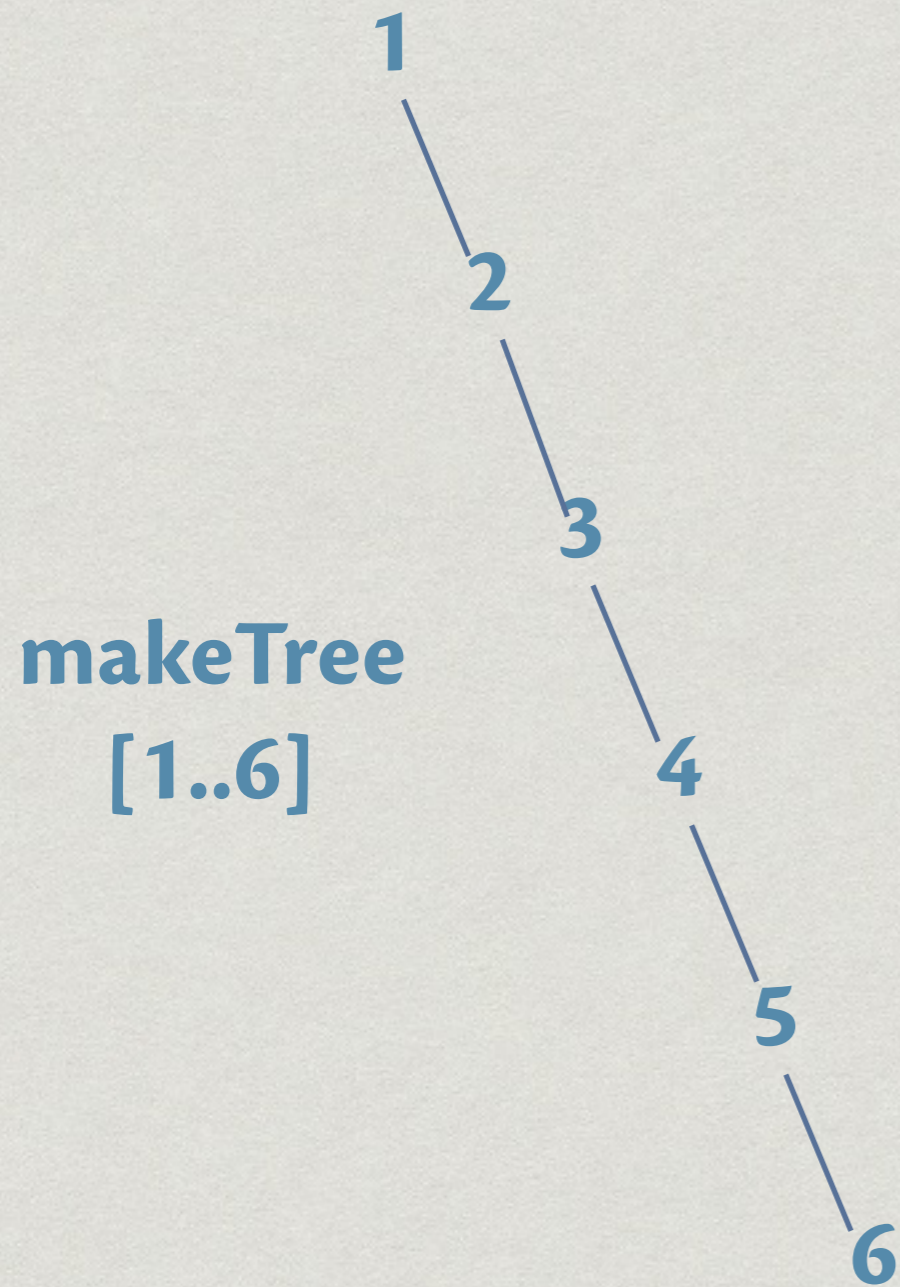
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Balance

- * The complexity of the key operations on trees depends on the **height** of the tree
- * In general, a tree might not be balanced
- * Inserting in ascending or descending order results in highly skewed trees

Balance



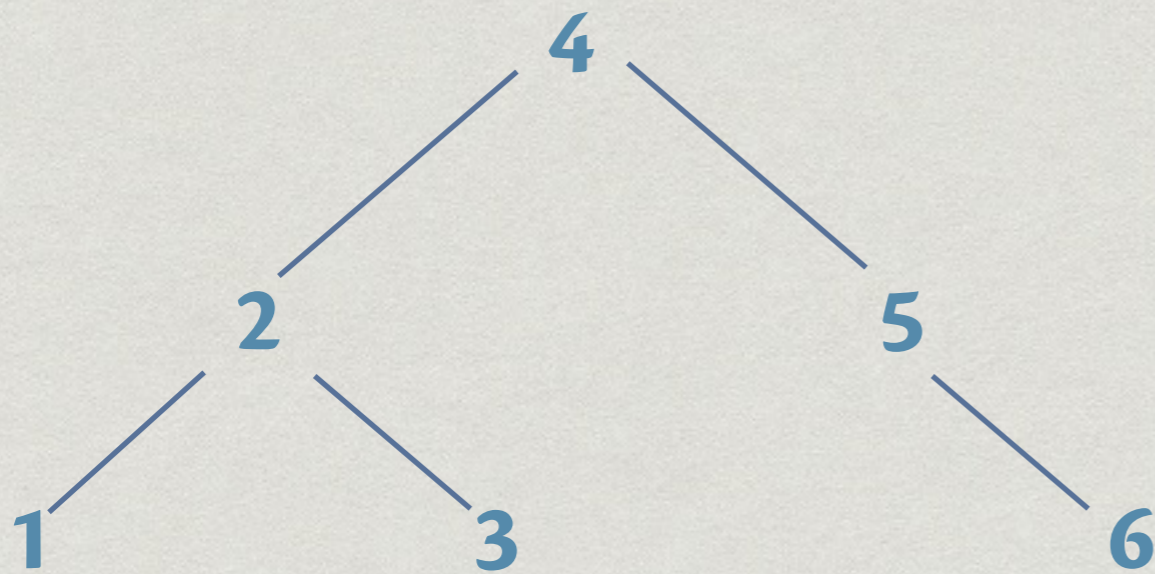
Balanced search trees

- * Ideally, for each node, the left and right subtrees differ in size by at most **1**
- * Height is guaranteed to be at most **$\log N + 1$** , where **N** is the size of the tree
- * When size is **1**, height is also **$1 = \log 1 + 1$**
- * When size is **$N > 1$** , subtrees are of size at most **$N/2$**
- * Height is **$1 + (\log N/2 + 1) = 1 + (\log N - 1 + 1)$**
 $= \log N + 1$

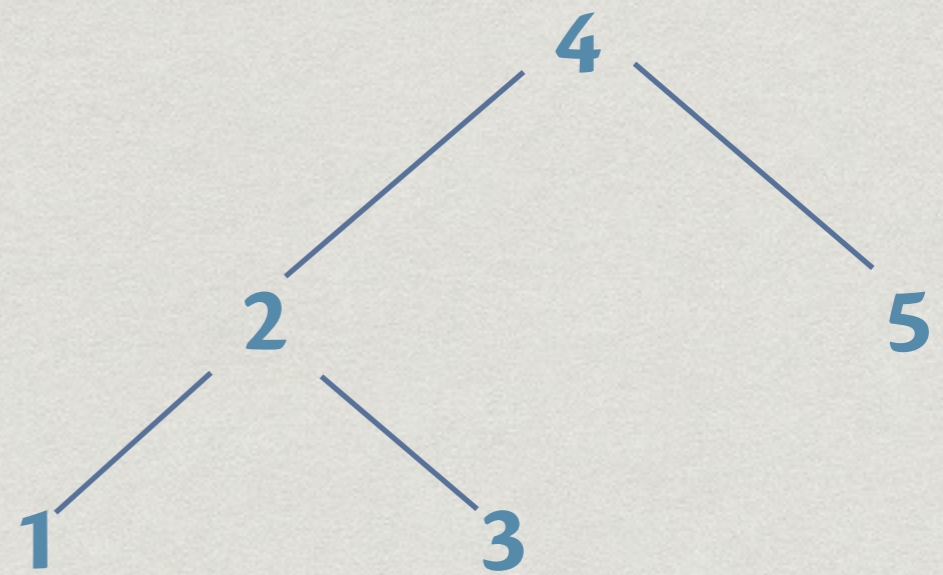
Balanced search trees

- * Not easy to maintain size balance
- * Maintain height balance instead
- * At any node
 - * The left and right subtrees differ in **height** by at most 1
 - * Somewhat easier to maintain: use tree rotations
 - * **AVL trees** (Adelson-Velskii, Landis)
 - * Height is still $O(\log N)$

Balanced search trees



**Height-balanced
and size-balanced**



**Height-balanced
not size-balanced**

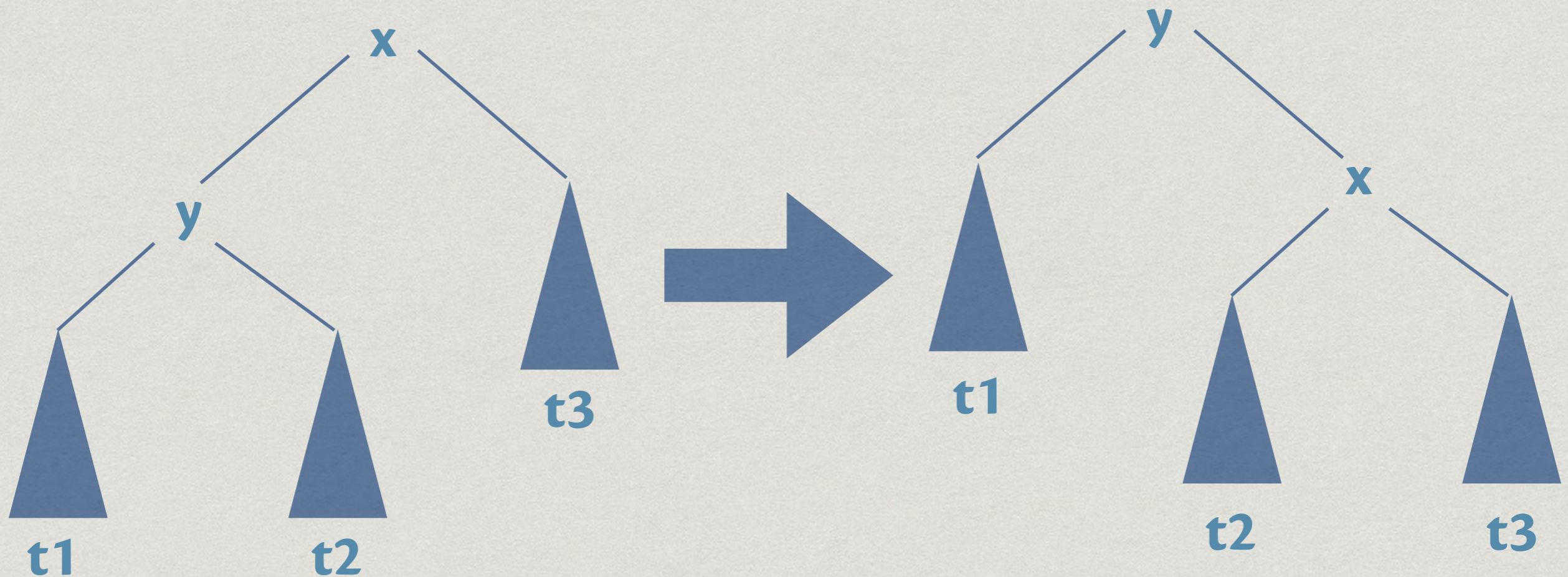
Height balanced trees

- * For a height-balanced tree of size N , the height is at most $2 \log N$
- * Let $S(h)$ be the size of the smallest height-balanced tree of height h
- * **Claim:** For $h \geq 1$, $S(h) \geq 2^{h/2}$
- * $S(1) = 1 = 2^{1/2}$
- * $S(2) = 2 = 2^{2/2}$

Height balanced trees

- * **Claim:** For $h \geq 1$, $S(h) \geq 2^{h/2}$
- * If a tree has height h , then one of the subtrees is of height $h-1$ and the other has height at least $h-2$
- *
$$\begin{aligned} S(h) &= 1 + S(h-1) + S(h-2) \geq S(h-2) + S(h-2) \\ &= 2^{(h-2)/2} + 2^{(h-2)/2} \\ &= 2^{(h-2)/2+1} = 2^{h/2} \end{aligned}$$
- * A height-balanced tree with N nodes has height at most $2 \log N$

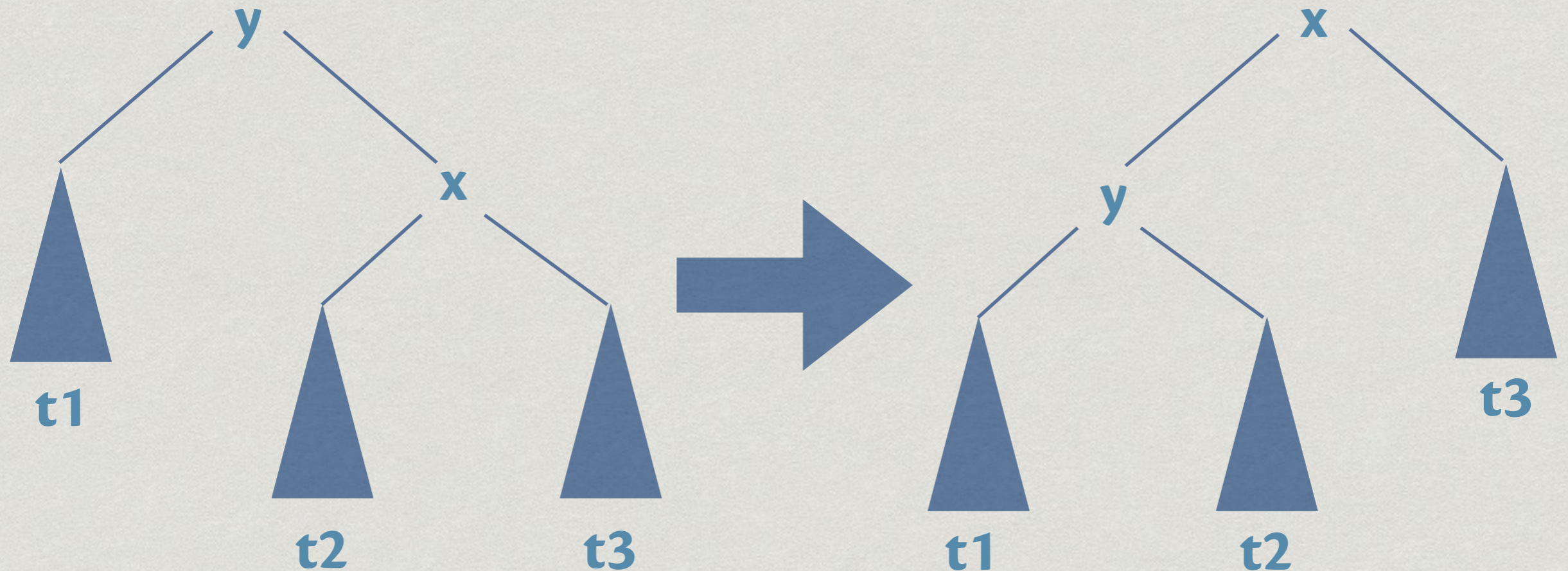
Tree rotations: rotate right



Useful when t1 has large height

`rotateright (Node (Node t1 y t2) x t3) = Node t1 y (Node t2 x t3)`

Tree rotations: rotate left



Useful when t3 has large height

`rotateleft (Node t1 y (Node t2 x t3)) = Node (Node t1 y t2) x t3`

Height balanced trees

- * Assume tree is currently balanced
- * Each insert or delete creates an imbalance
- * Fix imbalance using a **rebalance** function
- * We need to compute height of a tree (and subtrees) to check for imbalance

Height balanced trees

- * We need to compute height of a tree (and subtrees) to check for imbalance
- * $\text{height Nil} = 0$
 $\text{height (Node tl x tr)} = 1 + \max(\text{height tl}, \text{height tr})$
- * This takes $O(N)$ time
- * Save effort by storing height at each node

AVL trees

- * `data AVLTree a = Nil`
 | `Node (AVLTree a) a Int (AVLTree a)`
- * `height :: AVLTree a -> Int`
 `height Nil = 0`
 `height (Node t1 x h tr) = h`
- * We also need a measure of how skewed a tree is: its **slope**
- * `slope :: AVLTree a -> Int`
 `slope Nil = 0`
 `slope (Node t1 x h tr) = height t1 - height tr`

AVL trees: rotates

- * Since we store the height at each node, we need to adjust it after each operation
- * `rotateright :: AVLTree a -> AVLTree a`
`rotateright (Node (Node tll y hl tlr) x h tr) =`
`Node tll y nh (Node tlr x nhr tr)`
where
`nhr = 1 + max (height tlr) (height tr)`
`nh = 1 + max (height tll) nhr`
- * Constant time operation

AVL trees: rotates

- * Since we store the height at each node, we need to adjust it after each operation
- * $\text{rotateleft} :: \text{AVLTree } a \rightarrow \text{AVLTree } a$
 $\text{rotateleft } (\text{Node } t_l \ y \ h \ (\text{Node } t_r_l \ x \ h_r \ t_{r_r})) =$
 $\text{Node } (\text{Node } t_l \ y \ n_h_l \ t_r_l) \ x \ n_h \ t_{r_r}$
where
 $n_h_l = 1 + \max (\text{height } t_l) (\text{height } t_r_l)$
 $n_h = 1 + \max n_h_l (\text{height } t_{r_r})$
- * Constant time operation

Rebalancing trees

- * Recall:

$\text{slope}(\text{Node } tl \text{ x h } tr) = \text{height } tl - \text{height } tr$

- * In a height balanced tree, slope is **-1, 0, or 1**

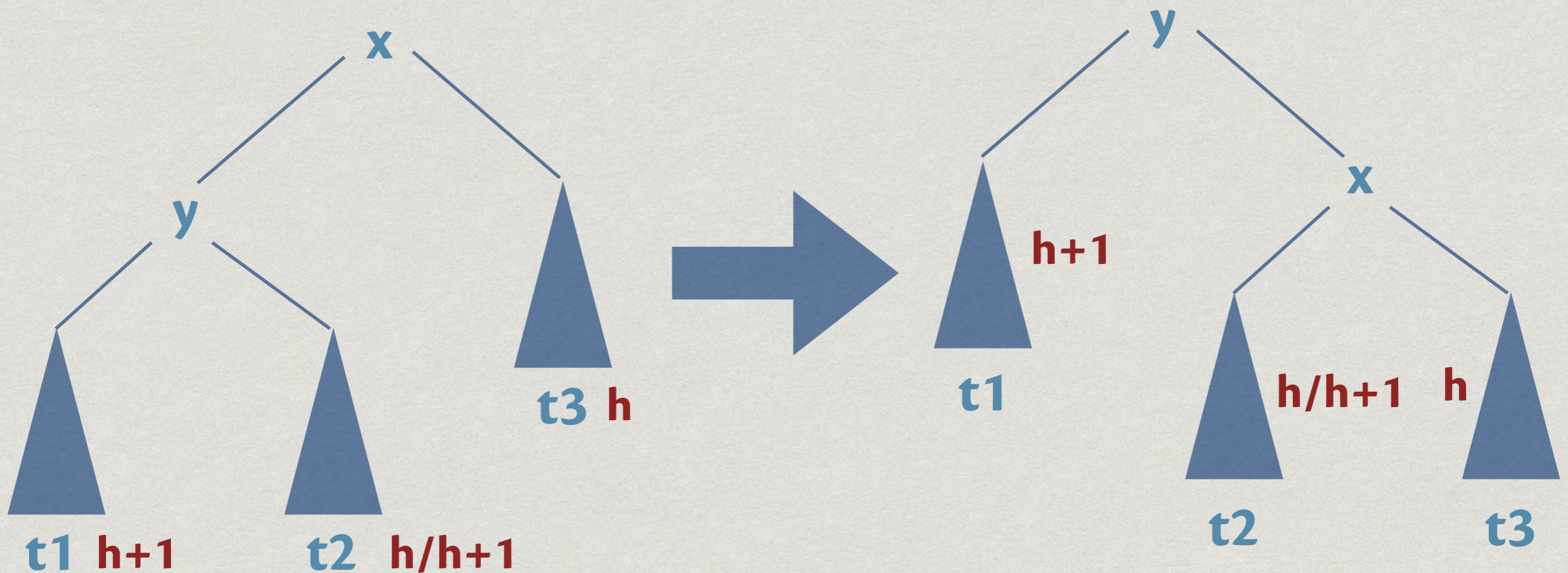
- * After an insert or delete, slope can be **-2, -1, 0, 1, or 2**

- * Violations happen only at nodes visited by operation

- * We rebalance each node on the path visited by operation

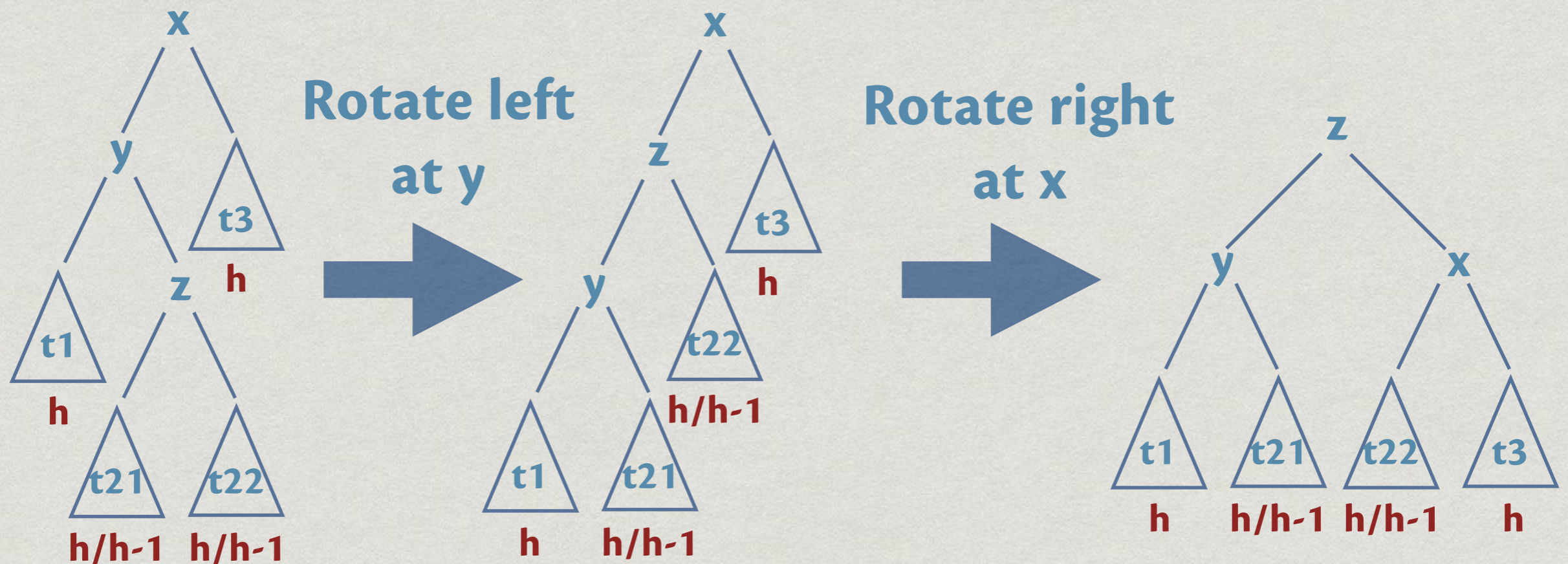
Rebalancing: slope = 2

- * Assume slope of a tree is 2 and both subtrees are balanced
- * **Case 1:** slope of left subtree is 0 or 1. **Rotate right**



Rebalancing: slope = 2

- * Assume slope of a tree is **2** and both subtrees are balanced
- * **Case 2:** slope of left subtree is **-1**. **Rotate left and rotate right**



Rebalancing: slope = -2

- * Symmetric to the slope = 2 case
- * Two subcases:
 - * slope of right subtree is 0 or -1
 - * slope of right subtree is 1
- * Handled symmetrically

The rebalance function

```
* rebalance :: AVLTree a -> AVLTree a
rebalance (Node tl x h tr)
  | abs (st) < 2           = Node tl x h tr
  | st == 2 && stl /= -1   = rotateright (Node tl x h tr)
  | st == 2 && stl == -1  = rotateright (Node
                                (rotateleft tl) x h tr)
  | st == -2 && str /= 1   = rotateleft (Node tl x h tr)
  | st == -2 && str == 1  = rotateleft (Node tl x h
                                (rotateright tr))
```

where

```
    st      = slope (Node tl x h tr)
    stl     = slope tl
    str     = slope tr
```

* Constant time operation

Searching in a tree

- * `search :: Ord a => AVLTree a -> a -> Bool`
`search Nil v = False`
`search (Node tl x h tr) v`
 - | `x == v` = True
 - | `v < x` = `search tl v`
 - | otherwise = `search tr v`
- * Time taken: proportional to **height** (= $2 \log N$)

Inserting in a tree

- * `insert :: Ord a => AVLTree a -> a -> AVLTree a`
`insert Nil v = Node Nil v 1 Nil`
`insert (Node tl x h tr) v`
 - | `x == v` = `Node tl x h tr`
 - | `v < x` = `rebalance (Node ntl x nhl tr)`
 - | otherwise = `rebalance (Node tl x nhr ntr)`where
 - `ntl` = `insert tl v`
 - `ntr` = `insert tr v`
 - `nhl` = `1 + max (height ntl) (height tr)`
 - `nhr` = `1 + max (height tl) (height ntr)`
- * Time taken: proportional to **height** (= $2 \log N$)

Deleting from a tree

```
* delete :: Ord a => AVLTree a -> a -> AVLTree a
delete Nil v           = Nil
delete (Node tl x h tr) v
  | v < x              = rebalance (Node ntl x nh1 tr)
  | v > x              = rebalance (Node tl x nhr ntr)
  | otherwise          = if (tl == Nil) then tr else
                        rebalance (Node ty y hyr tr)
```

where

```
(y, ty) = deletemax tl
ntl     = delete tl v
ntr     = delete tr v
nh1     = 1 + max (height ntl) (height tr)
nhr     = 1 + max (height tl) (height ntr)
hyr     = 1 + max (height ty) (height tr)
```

- * Time taken: proportional to **height** (= $2 \log N$), assuming `deletemax` behaves well

deletemax

```
* deletemax :: AVLTree a -> (a, AVLTree a)
deletemax (Node tl x h Nil) = (x, tl)
                                -- At the rightmost node
deletemax (Node tl x h tr) =
    (y, rebalance (Node tl x nh ty))
                                -- Always descend right
```

where

```
(y, ty) = deletemax tr
nh      = 1 + max (height tl) (height ty)
```

* Time taken: proportional to **height** (= $2 \log N$)

Summary

- * Each operation (`insert`, `delete`, `search`) on an AVL tree takes $O(\log N)$ time
- * A sequence of N operations takes $O(N \log N)$ time
- * Fundamental, but non-trivial data structure
- * Excellent example of the power of Haskell
- * Mathematical definitions transcribed almost directly to code