

# Lecture 2 Part A: VC Dimension

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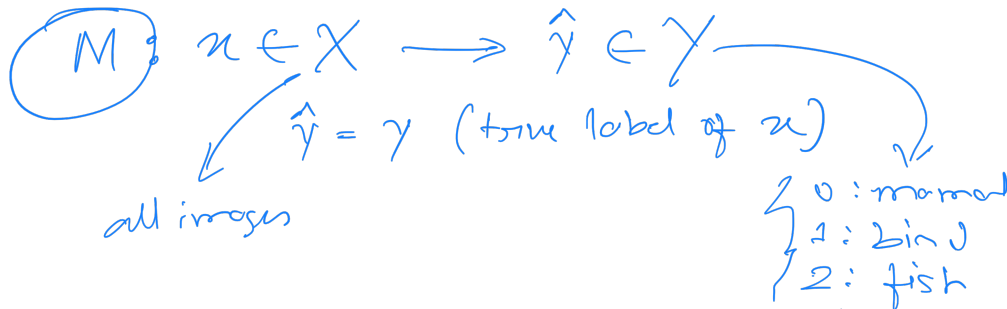
Advanced Machine Learning 2022

(based on slides by Madhavan Mukund)

# Representational capacity

## PAC learning guarantee

Let  $\mathcal{H}$  be a hypothesis class,  $\delta, \epsilon > 0$  and  $S$  a training set of size  $n \geq \frac{1}{\epsilon}(\ln |\mathcal{H}| + \ln(1/\delta))$  drawn using  $D$ . With probability  $\geq 1 - \delta$ , every  $h \in \mathcal{H}$  with true error  $\text{err}_D > \epsilon$  has training error  $\text{err}_S > 0$ .



- Training Set  $S = \{(x, y) \mid x \in X\}$

$$S \rightarrow M$$

-  $M$  "works well"

given some  $x \in X$  (st-  $x \notin S$ )

$M(x) = y$  (true label of  $x$ )  
with high probability

$S \rightarrow$  Representation of the  
real data

# Representational capacity

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## Uniform convergence

Let  $\mathcal{H}$  be a hypothesis class,  $\delta, \epsilon > 0$ . If a training set  $S$  of size  $n \geq \frac{1}{2\epsilon^2} (\ln |\mathcal{H}| + \ln(2/\delta))$  is drawn using  $D$ , then with probability  $\geq 1 - \delta$ , every  $h \in \mathcal{H}$  satisfies  $|\text{err}_S(h) - \text{err}_D(h)| \leq \epsilon$ .

$$n \in \mathbb{X}$$

Distr  $D$  on  $\mathbb{X}$

$$n \sim_D \mathbb{X}$$

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- $|\mathcal{H}|$  is **representational capacity**, when  $\mathcal{H}$  is finite

$VC\text{-Dim of } \mathcal{H}$

- How do we adapt and apply these bounds when  $\mathcal{H}$  is infinite?

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- **Example:**
  - $X = \mathbb{R} \times \mathbb{R}$
  - $\mathcal{H}$  : Axis-parallel rectangles
  - $A$  : Four points forming a diamond

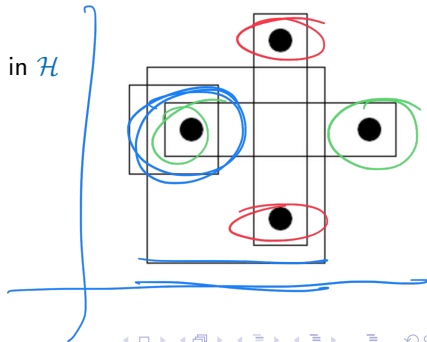
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$$X = \{ \cdot, \cdot, \cdot, \cdot \}$$

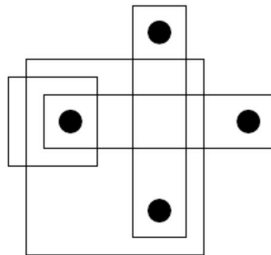
$$\mathcal{H} = \{ \text{Various rectangles} \}$$

$$2^{|X|}$$



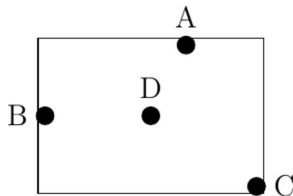
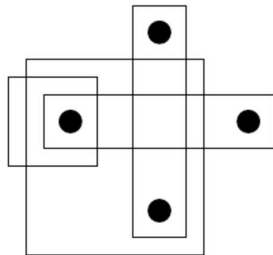
# VC-Dimension [Vapnik-Chervonenkis]

- VC-Dimension of  $\mathcal{H}$  — size of the largest subset of  $X$  shattered by  $\mathcal{H}$ 
  - For axis-parallel rectangles, VC-dimension is at least 4



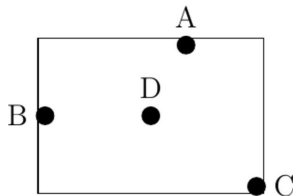
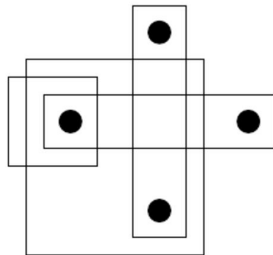
# VC-Dimension [Vapnik-Chervonenkis]

- VC-Dimension of  $\mathcal{H}$  *→ all rectangles* — size of the largest subset of  $X$  shattered by  $\mathcal{H}$ 
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  - Not a **universal** requirement — some sets of size 4 may not be shattered



# VC-Dimension [Vapnik-Chervonenkis]

- VC-Dimension of  $\mathcal{H}$  — size of the largest subset of  $X$  shattered by  $\mathcal{H}$ 
  - For axis-parallel rectangles, VC-dimension is at least 4
  - Not a **universal** requirement — some sets of size 4 may not be shattered
- No set of size 5 can be shattered by axis-parallel rectangles
  - Draw a **bounding box** rectangle — each edge touches a boundary point
  - At least one point lies inside the bounding box
  - Any set that includes the boundary points also includes the interior point



# VC-Dimension, Examples

- Intervals of reals have VC-dimension 2
  - $X = \mathbb{R}$ ,  $\mathcal{H} = \{[a, b] \mid a \leq b \in \mathbb{R}\}$
  - Cannot shatter 3 points: consider subset with first and third point

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- Pairs of intervals of reals have VC-dimension 4
  - $X = \mathbb{R}$ ,  $\mathcal{H} = \{[a, b] \cup [c, d] \mid a \leq b, c \leq d \in \mathbb{R}\}$
  - Cannot shatter 5 points: consider subset with first, third and fifth point



# VC-Dimension, Examples

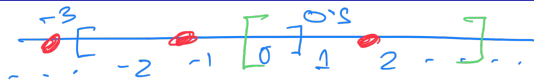
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- Finite sets of real numbers
  - $X = \mathbb{R}, \mathcal{H} = \{Z \mid Z \subseteq \mathbb{R}, |Z| < \infty\}$
  - Can shatter any finite set of reals — VC-dimension is **infinite**

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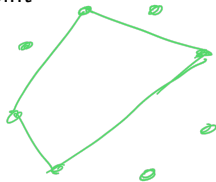
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- Convex polygons,  $X = \mathbb{R} \times \mathbb{R}$

- For any  $n$ , place  $n$  points on unit circle

- Each subset of these points is a convex polygon — VC-dimension is **infinite**

# VC-dimension and machine learning

## PAC learning guarantee

$$\sqrt{\text{VC dim}(\mathcal{H})}$$

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Size of  $\mathcal{H}$

VC-Dim  $\mathcal{H}$  as the measure of  
approx. power of  $\mathcal{H}$

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- We can rewrite this using VC-dimension.

## Sample bound using VC-dimension

For any class  $\mathcal{H}$  and distribution  $D$ , if a training sample  $S$  is drawn using  $D$  of size  $O\left(\frac{1}{\epsilon} \left[ \text{VC-dim}(\mathcal{H}) \ln \frac{1}{\epsilon} + \ln \frac{1}{\delta} \right]\right)$ , then with probability  $\geq 1 - \delta$ ,

- every  $h \in \mathcal{H}$  with true error  $\text{err}_D(h) \geq \epsilon$  has training error  $\text{err}_S(h) > 0$ ,
- i.e., every  $h \in \mathcal{H}$  with training error  $\text{err}_S(h) = 0$  has true error  $\text{err}_D(h) < \epsilon$

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- We can rewrite this using VC-dimension. Can similarly restate uniform convergence.

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# Summary

- PAC learning and uniform convergence use size of finite hypothesis set as measure of representational capacity
- VC-dimension provides a way of measuring capacity for infinite hypothesis sets
- VC-dimension may be finite or infinite
- For finite VC-dimension, we have analogues of PAC learning guarantee and uniform convergence
- Note that these theoretical bounds are hard to use in practice
- Difficult, if not impossible, to compute VC-dimension for complex models