## LECTURE 19

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Some of the proofs here are elaborations and cleaner expositions of what was given in class. Others are a quick summary.

## 1. Continuing analytic functions across boundaries

1.1. Continuing across line segments. Suppose $\Omega$ is a region and $L$ is a (non empty) line segment $\Omega$ which is a closed subset $\Omega$. It is immaterial whether $L$ is a closed line segment or an open line segment, or anything in between, e.g., $L=(0,1]$ is a closed subset of $\Omega=\{z \in \mathbf{C} \mid \operatorname{Re}(z)>0\}$. Let $\Omega^{\prime}=\Omega \backslash L$. Suppose $f: \Omega \rightarrow \mathbf{C}$ is a continuous function such that $f(z)$ is analytic on $\Omega^{\prime}$. If $L$ is a singleton set, then by the Riemann removable singularity theorem, $f$ is analytic on $\Omega$. This remains true even when $L$ has positive length as the following argument shows.

First, without loss of generality, we may assume $L$ is a horizontal line segment, by applying the transformation $z \mapsto e^{i \theta} z$ for a suitable real number $\theta$ on the region $\Omega$. Let $R$ be any (closed, bounded) rectangle in $\Omega$ with sides parallel to the real and imaginary axes. We claim that

$$
\int_{\partial R} f(z) d z=0
$$

If $L$ is part of one of edges of $R$, say the bottom edge, then for $\eta>0$ let $R_{\eta}$ be the rectangle whose bottom edge is at a distance $\eta$ from the bottom edge of $R$, and whose right and left edges follow the right and left edges of $R$, until a distance $\eta$ from the bottom edge of $R$, and whose top edge agrees with the top edge of $R$. The length of the bottom edge of $R$ equals that of the bottom edge of $R_{\eta}$. Let this be denoted $\ell$. Then, with the bottom left corner of $R$ being $z_{0}=a+i b$, we have

$$
\begin{aligned}
\left|\int_{\partial R} f(z) d z-\int_{\partial R_{\eta}} f(z) d z\right|= & \left|\int_{a}^{a+\ell} f(x+i b) d x-\int_{a}^{a+\ell} f(x+i(b+\eta)) d x\right| \\
& +\left|\int_{b}^{b+\eta} f(a+\ell+i y) d y-\int_{b}^{b+\eta} f(a+i y) d y\right| \\
= & \int_{a}^{a+\ell}|f(x+i b)-f(x+i(b+\eta))| d x \\
& +\int_{b}^{b+\eta}|f(a+\ell+i y)-f(a+i y)| d y \\
\leq & \int_{a}^{a+\ell}|f(x+i b)-f(x+i(b+\eta))| d x+2 \eta \sup _{z \in R}|f(z)|
\end{aligned}
$$

Since $f$ is uniformly continuous on the compact set $R$, given $\epsilon>0$ we can find $\eta>0$ such that

$$
\begin{equation*}
|f(z)-f(w)|<\frac{\epsilon}{2 \ell} \quad(z, w \in R,|z-w|<\eta) \tag{*}
\end{equation*}
$$

and such that

$$
\begin{equation*}
\eta<\frac{\epsilon}{4 \sup _{z \in R}|f(z)|} \tag{**}
\end{equation*}
$$

For $\eta$ satisfying ( $*$ ) and ( $* *$ ) we see that

$$
\begin{aligned}
\left|\int_{\partial R} f(z) d z-\int_{\partial R_{\eta}} f(z) d z\right| & \leq \int_{a}^{a+\ell}|f(x+i b)-f(x+i(b+\eta))| d x+2 \eta \sup _{z \in R}|f(z)| \\
& <\frac{\epsilon}{2 \ell} \ell+2 \sup _{z \in R}|f(z)| \eta \quad(\text { via }(*)) \\
& <\epsilon
\end{aligned}
$$

Thus

$$
\int_{\partial R} f(z) d z=\lim _{\eta \rightarrow 0} \int_{\partial R_{\eta}} f(z) d z
$$

But by Cauchy-Goursat $\int_{\partial R_{\eta}} f(z) d z=0$ for $\eta>0$. Hence

$$
\int_{\partial R} f(z) d z=0
$$

in this case. The same argument works when $L$ is part of the top horizontal line segment of $R$.

Next if $L$ intesects $R$, say at $\alpha+i \beta$, then we let $\sigma$ be the horizontal line segment from $a+i \beta$ to $a+\ell+i \beta$, and let $R_{1}$ and $R_{2}$ be the rectangles obtained from $R$ by dividing it along the horizontal line segment $\sigma$. In this case

$$
\int_{\partial R} f(z) d z=\int_{\partial R_{1}} f(z) d z+\int_{\partial R_{2}} f(z) d z=0
$$

Finally, if $L$ does not intersect $R$, then by the Cauchy-Goursat theorem we have $\int_{\partial R} f(z) d z=0$.

Thus in all cases we have $\int_{\partial R} f(z) d z=0$. Now if $D$ is any open disc in $\Omega$, say with centre $a \in \Omega$, then we can find a primitive $F$ for $f$ in $D$ by defining $F(z)$ to be the integral of $f$ along the path which starts at $a$ moves parallel to the real axis first and then moves parallel to the imaginary axis to end at $z$. From the fact that the integral of $f$ along the boundary of any rectangle in $\Omega$ (with edges parallel to the axes) is zero, it is clear that $F(z)$ can also worked out by integrating $f$ along a path which starts at $a$, and moves first parallel to the imaginary axis and then along an appropriate horizontal segment. Standard arguments, exactly as in the proof of Cauchy-Goursat in a disc, show that $F$ satisfies the Cauchy-Riemann equations and is $C^{1}$ (in fact $F_{x}=f, F_{y}=i f$ as is easily verified). Hence $F$ is analytic and so its derivative is $f$. This means $f$ is analytic on $\Omega$.
1.2. Continuing past circular arcs. Suppose the closed set $L$ in the previous section is not a line segment but an arc of a circle $C$, and suppose $f$ is continuous on $\Omega$ and analytic on $\Omega^{\prime}=\Omega \backslash L$. Then too $f$ is analytic on $\Omega$. That is worked as follows. Let $a \in C$. Consider $\Omega^{*}=\Omega \backslash\{a\}$ and $L^{*}=L \backslash\{ \}$. The univalent function $z \mapsto(z-a)^{-1}$ on $\Omega^{*}$ transforms $L^{*}$ into a line segment. Hence applying the previous argument, the function $f(z)$ is holomorphic on $\Omega^{*}$. If $a \notin \Omega$ we are done. If not, then the Riemann removable singularity theorem applies and again $f$ is holomorphic on $\Omega$.

The conclusions of the previous two subsections can be summarised as follows:
Proposition 1.2.1. Suppose $\Omega$ is a region and $L$ a closed subset of $\Omega$ which is either a line segment or a circular arc. If $f: \Omega \rightarrow \mathbf{C}$ is a continuous function which is holomorphic on $\Omega \backslash L$ then $f$ is holomorphic on $\Omega$.

## 2. Harmonic functions and the averaging property

We know that if $u$ is a harmonic function on a region $\Omega$ then $u$ has the averaging property, i.e.,

$$
\begin{equation*}
u(a)=\frac{1}{2 \pi} \int_{0}^{2 \pi} u\left(a+r e^{i \theta}\right) d \theta \tag{2.1}
\end{equation*}
$$

for all $a \in \Omega$ and all $r>0$ such that the closed disc $\bar{B}(a, r)$ is contained in $\Omega$.
The converse is also true for continuous real-valued functions on $\Omega$ with a local averaging property, a notion which we define now.

Definition 2.1.1. A real-valued function $u$ on $\Omega$ is said to have a local averaging property if for each $a \in \Omega$ we have a positive real number $\rho(a)$ such that (2.1) is true for all $0<r \leq \rho(a)$.

We then have the following result
Theorem 2.2. Let $\Omega$ be a region. A function $u: \Omega \rightarrow \mathbf{R}$ is harmonic if and only if it is continuous and has the local averaging property.

It is clear that if $u$ is harmonic it is continuous and has the local averaging property. We will prove the converse in a later lecture.

## 3. Symmetric Regions and Schwarz's Reflection Principle

3.1. Notations. Let $\mathfrak{h}$ denote the open upper half-plane and $\mathfrak{h}^{-}$the open lower half-plane. For a region $\Omega$ set $\Omega^{+}=\Omega \cap \mathfrak{h}, \Omega^{-}=\Omega \cap \mathfrak{h}^{-}$, and $\widehat{\Omega}=\{z \in \mathbf{C} \mid \bar{z} \in \Omega\}$. If $f: \Omega \rightarrow \mathbf{C}$ is a map, let

$$
\widehat{f}: \widehat{\Omega} \rightarrow \mathbf{C}
$$

be the map given by

$$
z \mapsto \overline{f(\bar{z})}
$$

Recall from Problem 1 of HW 1 that $f$ is holomorphic on $\Omega$ if and only if $\widehat{f}$ is holomorphic on $\widehat{\Omega}$. Note that $\widehat{\widehat{\Omega}}=\Omega$ and $\widehat{\widehat{f}}=f$.
Definition 3.1.1. A region $\Omega$ is said to be symmetric if $\widehat{\Omega}=\Omega$.
Lemma 3.1.2. Suppose $\Omega$ is a symmetric region, $L$ a line segment of positive length in $\Omega \cap \mathbf{R}$ and $f(z)$ a holomorphic function on $\Omega$ which takes real values on L. Then $f=\widehat{f}$.

Proof. The functions $f$ and $\widehat{f}$ are both holomorphic on $\Omega$ and agree on $L$. By the identity principle we are done.
3.2. Schwarz's Reflection Principle. Here is a weak version of the principle.

Theorem 3.2.1 (Weak Schwarz's Reflection Principle). Suppose $\Omega$ is a symmetric region, $\Omega_{1}$ the set of points in $\Omega$ with non-negative imaginary parts, and $L=\Omega \cap \mathbf{R}$. If $f: \Omega_{1} \rightarrow \mathbf{C}$ is a continuous function that is holomorphic on $\Omega^{+}$and takes real values on $L$, then $f$ can be extended to a unique holomorphic function $g$ on $\Omega$. The extended function $g$ satisfies the relation $g=\widehat{g}$.
Proof. Uniqueness of $g$ follows from the identity principle. The identity $g=\widehat{g}$ is a direct consequence of Lemma 3.1.2. Existence is the only thing that remains to be proved. Let $g: \Omega \rightarrow \mathbf{C}$ be defined by:

$$
g(z)= \begin{cases}f(z), & z \in \Omega_{1} \\ \widehat{f}(z), & z \in \Omega^{-}\end{cases}
$$

Note that $\Omega_{1}=\Omega^{+} \cup(\Omega \cap \mathbf{R})$ and hence the above does define a function on $\Omega$. A little thought shows that $\Omega$ is continuous on $\Omega$. Moreover it is holomorphic on $\Omega \backslash L=\Omega^{+} \cup \Omega^{-}$. Hence by Proposition 1.2.1, the map $g$ is holomorphic on all of $\Omega$.

The above version of Schwarz's Reflection Principle is enough for most purposes and is often called the Schwarz Reflection Principle. There is however a stronger form whose proof is independent of the above proof.

Theorem 3.2.2 (Schwarz's Reflection Principle). Let $\Omega$ and $\Omega_{1}, L$ be as in the hypothesis of Theorem 3.2.1. Let $f: \Omega^{+} \rightarrow \mathbf{C}$ be a holomorphic function such that if $x \in L$ and $\left\{z_{n}\right\}$ is a sequence of points in $\Omega^{+}$converging to $x$, then $\lim _{n \rightarrow \infty} \operatorname{Im}\left(z_{n}\right)=0$. Then $f$ can be extended to a unique holomorphic function $g$ on $\Omega$. The extended function $g$ satisfies the relation $g=\widehat{g}$.
Proof. Let $f=u+i v$ be the decomposition of $f$ into its real and imaginary parts. Define $v^{*}: \Omega \rightarrow \mathbf{C}$ by

$$
v^{*}(z)= \begin{cases}v(z), & z \in \Omega^{+} \\ 0, & z \in \Omega \cap \mathbf{R}=\Omega_{1} \cap \mathbf{R} \\ -v(\bar{z}), & z \in \Omega^{-}\end{cases}
$$

It is easy to see that $v^{*}$ is continuous. We claim that $v^{*}$ has the local averaging property on $\Omega$. Since $\left.v^{*}\right|_{\Omega^{+}}=v, v^{*}$ is harmonic on $\Omega^{+}$, and hence has the averaging property on $\Omega^{+}$. Further $v^{*}(z)=\operatorname{Im}(\widehat{f}(z))$ for $z \in \Omega^{-}$, and hence $v^{*}$ is harmonic on $\Omega^{-}$. In particular it has the averaging property there. Now suppose $a \in L$. We can find a positive real number $\rho(a)$ such that the closed disc $|z-a| \leq \rho(a)$ lies in $\Omega$. Let $D_{a}=B(a, \rho(a))$. It is easy to see that (2.1) is satisfied by $v^{*}$ for $0<r<\rho(a)$. Indeed a change of variables shows that $\int_{\pi}^{2 \pi} v\left(a+r e^{-i \theta}\right) d \theta=\int_{0}^{\pi} v\left(a+r e^{i \theta}\right) d \theta$, whence $(2 \pi)^{-1} \int_{0}^{2 \pi} v^{*}\left(a+r e^{i \theta}\right) d \theta=0=v^{*}(a)$ for $0<r \leq \rho(a)$. This proves the claim. By Theorem 2.2 we see that $v^{*}$ is harmonic.

Let $-u_{a}^{*}$ be a harmonic conjugate of $v^{*}$ on $D_{a}$, where $a \in L$ and $D_{a}$ is as above. Then $g_{a}=u_{a}^{*}+i v^{*}$ is holomorphic on $D_{a}$. Moreover on $D_{a}^{+}, g_{a}-f$ takes real values and hence must be a real constant for it is not an open map. We can pick our harmonic conjugate $-u_{a}^{*}$ in such a way that $c_{a}=0$. Then $\left.g_{a}\right|_{D_{a}^{+}}=\left.f\right|_{D_{a}}$, and
let us do so. Since $D_{a}$ is a symmetric region and $g$ takes real values on $D_{a} \cap \mathbf{R}$, by Lemma 3.1.2 we have $\widehat{g_{a}}=g_{a}$. It follows that $g_{a}(z)=\widehat{f}(z)$ for $z \in D_{a}^{-}$.

By the identity principle, for $a, b \in L,\left.g_{a}\right|_{D_{a} \cap D_{b}}=g_{b} \mid D_{a} \cap D_{b}$. If $U=\cup_{a \in L} D_{a}$, then from what we've seen, the $g_{a}$ patch to give a holomorphic function $g_{U}: U \rightarrow \mathbf{C}$ such that $g_{U}$ agrees with $f$ on $\Omega^{+} \cap U$ and with $\widehat{f}$ on $\Omega^{-} \cap U$. Since $f, g_{U}$, and $\widehat{f}$ agree on the intersections of their domains, one checks easily that they glue to give a holomorphic function $g$ on $\Omega$. As before uniqueness follows from the identity principle. The property $\widehat{g}=g$ is true because $g$ is real-valued on $L$ (see Lemma 3.1.2).

