

# Erasure-Resilient Property Testing

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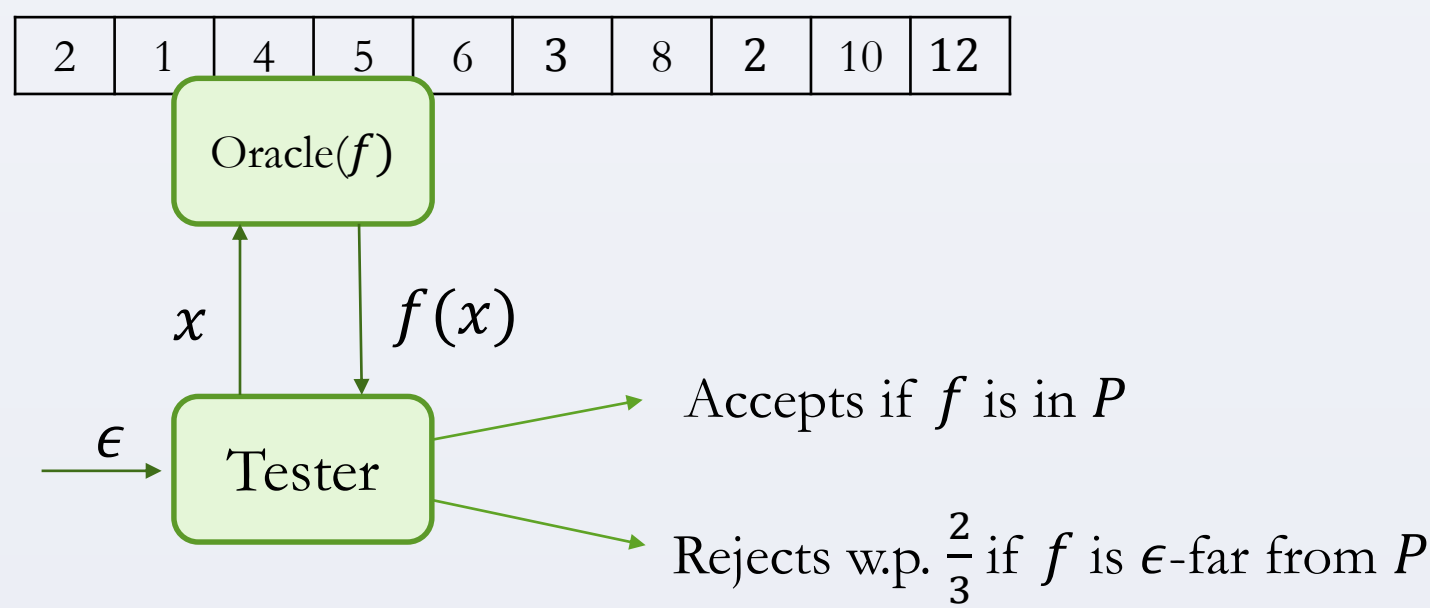
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## Background and motivation

Property testing [GGR98, RS96]

**Problem :** Test whether  $f: D \mapsto \mathbb{R}$  satisfies a property  $P$  or is  $\epsilon$ -far from satisfying  $P$ .



**Assumption:** Oracle returns values at all queried points.

What if the oracle cannot answer all the queries?

### Reasons

Some function values may be inaccessible due to:

- Adversaries erasing/corrupting them.
- Privacy requirements to hide them.

### Consequences

- Queries to erased points are wasteful as the tester learns nothing about the function.
- Tester could make several queries to erased points as it does not know the locations of erasures before querying.

**Need testers resilient to adversarial erasures.**

## Erasure-resilient property testing model

### Erased functions and distances

**$\alpha$ -erased function:** A function over domain  $D$  is  $\alpha$ -erased if it is erased on at most an  $\alpha$  fraction of  $D$ .

#### Distances



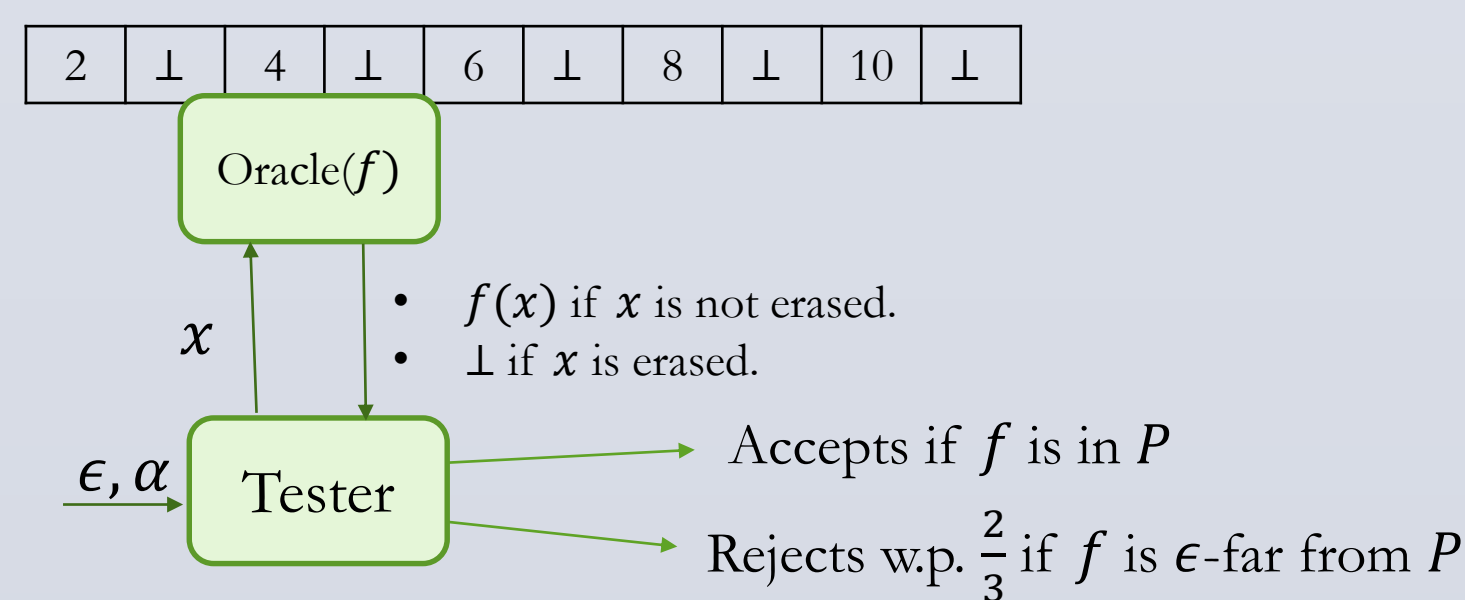
$\frac{1}{2}$ -erased sorted array : Can restore the erased points to make it sorted.



$\frac{1}{2}$ -erased  $\frac{1}{2}$ -far from sorted : At least half of the nonerased points need to be changed to make it sorted.

### Erasure-resilient tester (against adversarial erasures)

**Problem :** Given an  $\alpha$ -erased function  $f$ , test whether  $f$  satisfies a property  $P$  or is  $\epsilon$ -far from satisfying  $P$ .



#### Main Challenges

- Erasures are **adversarial** and are made before testing begins.
- Tester does not know the erased points in advance.
- The adversary knows the tester.

## Erasure-resilient testers

### Generic Transformation

**Theorem:** Testers for **extendable properties** that query points sampled uniformly and independently at random can be made  **$\alpha$ -erasure-resilient** with a **query complexity overhead of  $O(\frac{1}{1-\alpha})$** .

#### Applications

- Monotonicity over poset domains [FLNRRS02].
- Convexity of black and white images [BMR16].
- Boolean functions with  $\leq k$  runs of alternating values.

## Testers for more challenging properties

- For many important properties, most known testers are more likely to query some specific points over others.
- An adversary can use this weakness to increase the query complexity of such testers.
- At least three such testers for the monotonicity of functions over the line  $[n]$  fail if we erase just one point.

An optimal monotonicity tester for functions  $f: [n] \mapsto \mathbb{R}$  [EKRRV00]

Input :  $\epsilon \in (0,1)$

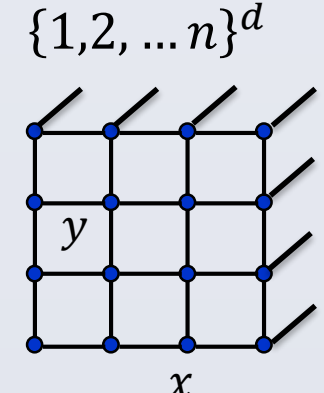
- Repeat  $O(\frac{1}{\epsilon})$  times:
  - Sample a search point  $p$  u.a.r. from  $[n]$ .
  - Do a **binary search for  $p$**  using midpoints of intervals as the pivots in each step.
  - Reject if a violation to monotonicity of  $f$  was found on the search path.
- Accept

**Erasing just the midpoint is enough to make the tester useless.**

## Properties that we focus on

- **Monotonicity** [GGLRS00, DGLRRS99, EKRRV00, F04, CS13a, CS13b, CST14, BRY14, BRY14, CDST15, KMS15, BB16], **Lipschitz property** [JR13, CS13a, BRY14, BRY14, CDJS15], other bounded derivative properties [CDJS15] and **convexity** [PRR03, BRY14].

Hypergrid  $\{1,2,\dots,n\}^d$



A function  $f: [n]^d \mapsto \mathbb{R}$  is

- **monotone** if  $x < y \Rightarrow f(x) \leq f(y)$ .
- **c-Lipschitz** if  $|f(y) - f(x)| \leq c \cdot \|y - x\|_1$ .
- **convex** for  $d = 1$  if  $\frac{f(y) - f(x)}{y - x} \leq \frac{f(z) - f(y)}{z - y}$  for all  $x < y < z$ .

## Results

### Nearly optimal erasure-resilient testers

#### Properties over the line domain $[n]$

**Theorem:**  $\alpha$ -erasure-resilient  $\epsilon$ -testing of **monotonicity**, **Lipschitz property**, and **convexity** over the line with  $O(\frac{1}{1-\alpha})$  factor query complexity overhead with respect to standard  $\epsilon$ -testing for all  $\alpha \in [0,1)$ .

#### Properties over hypergrid domains $[n]^d$

**Theorem:**  $\alpha$ -erasure-resilient  $\epsilon$ -testing of **monotonicity** and **Lipschitz property** over hypergrids with  $O(\frac{1}{1-\alpha})$  factor query complexity overhead with respect to standard  $\epsilon$ -testing for  $\alpha = O(\frac{\epsilon}{d})$ .

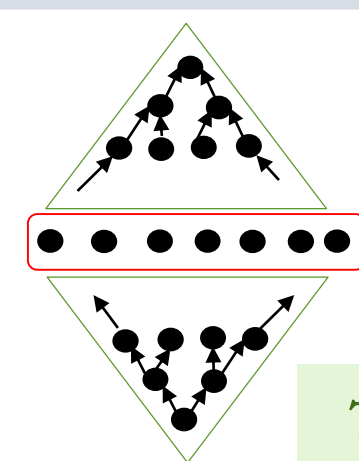
### Limitations of line testers for hypergrids

- Our erasure-resilient testers for monotonicity and Lipschitz property over hypergrids are line testers.
- For hypercubes  $\{0,1\}^d$ , such testers sample edges of the hypercube uniformly and independently at random and check for violations to the property on them.

$f(x) = 0$

$f(x) = 1$

$f(x) = 1$



•  $f$  is  $\frac{1}{2}$ -far from monotone and  $\alpha \sim \frac{1}{\sqrt{d}}$ .

• No edge in the hypercube is violated.

**Take home:** Line-testers will not work if  $\alpha = \Omega(\frac{\epsilon}{\sqrt{d}})$ .

### Separation from standard model

**Theorem:** There exists a property  $P$  and a constant  $c$  such that:

- $P$  can be  $\epsilon$ -tested with  $O(\frac{1}{\epsilon})$  queries.
- $\alpha$ -erasure-resilient testing of  $P$  requires  $\Omega(n^c)$  queries for a large range of  $\alpha$ .

## Open questions

- Is tolerant testing [PRR06] harder than erasure-resilient testing ?
- Are there testers for monotonicity and Lipschitz property over hypergrid domains that withstand more erasures ?

## Erasure-resilient monotonicity tester for $[n]$

Algorithm (modifying the tester of [EKRRV00])

**Input :** parameters  $\epsilon, \alpha \in (0,1)$ ; oracle access to function  $f: [n] \mapsto \mathbb{R} \cup \{\perp\}$ .

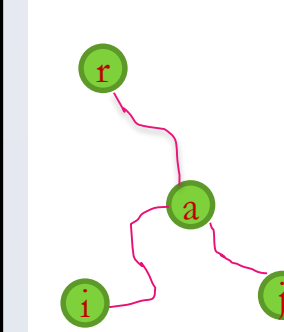
- **Accept** if the number of queries exceed  $c \cdot \frac{\log n}{\epsilon(1-\alpha)}$ .
- **Repeat**  $O(\frac{1}{\epsilon})$  times:
  - **Sample** points from  $[n]$  u.a.r. until we get a **non-erased search point  $p$** .
  - Do a **binary search for  $p$**  using **uniformly random (nonerased) pivots** in each step.
  - **Reject** if a violation to monotonicity of  $f$  was found on the search path.
- **Accept**

### Analysis overview

Tester accepts if  $f$  is a monotone function. Assume that  $f$  is  $\epsilon$ -far from monotone. Let  $\mathcal{N} \subseteq [n]$  denote the set of non-erased points.

### Proof of correctness

- Each search path is a uniformly random rooted path in a uniformly random binary search tree over  $\mathcal{N}$ .
- Tester detects a violation with probability  $\geq \epsilon$  in every iteration.



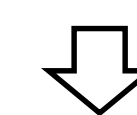
- If there are no violations in the paths to  $i$  and  $j$ , then  $f(i) < f(a) < f(j)$ .
- At least  $\epsilon$ -fraction of the paths in every binary search tree contains violations to monotonicity.

### Bounding the query complexity

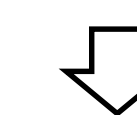
- **Combinatorial lemma:** Expected # queries to traverse a random search path in a binary search tree  $T$  of depth  $d$  over an  $\alpha$ -erased array is at most  $\frac{d}{1-\alpha}$ .

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- Expected depth of a random  $n$ -node binary search is  $O(\log n)$ .



Expected # queries to traverse a random search path in a random binary search tree over an  $\alpha$ -erased array is  $O(\frac{\log n}{1-\alpha})$ .

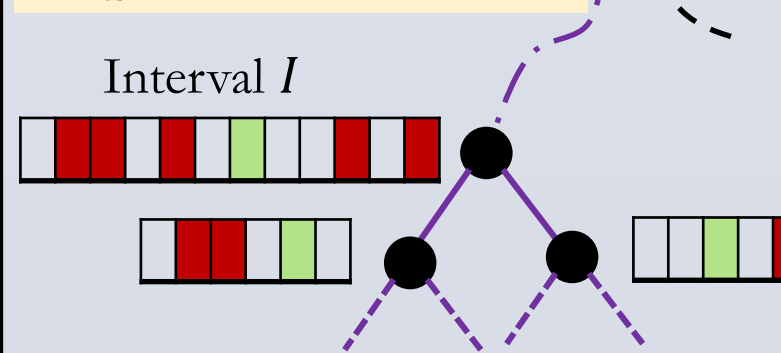


**The expected query complexity of the tester is  $O(\frac{\log n}{\epsilon(1-\alpha)})$ .**

### Proof of combinatorial lemma

Binary search tree  $T$

Depth  $d$



$\delta_I$  : fraction of erased points in interval  $I$ .

**Query weight of interval  $I$ :**

$$E[\# \text{ queries to get a nonerased point}] = \frac{1}{1-\delta_I}$$

**Query weight of a search path:**

Sum of query weights of intervals on path.

$S$  = Sum of query weights of all search paths in  $T$ .

$$E[\# \text{ of queries to traverse a random search path in } T] = \frac{S}{|N|} \leq \frac{S}{n(1-\alpha)}$$

#### Bounding $S$

# search paths through  $I$  = # nonerased points in  $I$  =  $|I| \cdot (1 - \delta_I)$

$$\Rightarrow \text{Contribution to } S \text{ from } I = |I| \cdot (1 - \delta_I) \cdot \frac{1}{1-\delta_I} = |I|$$

$$\Rightarrow \text{Contribution to } S \text{ from each level of the tree } \leq n \Rightarrow S \leq n \cdot d$$

#### Final Step

$$E[\# \text{ queries to traverse a random search path in } T] \leq \frac{S}{n(1-\alpha)} \leq \frac{d}{1-\alpha}$$

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