

Classes and objects

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Programming and Data Structures with Python

Lecture 10

Classes and objects

- Abstract datatype

- Stores some information
- Designated functions to manipulate the information
- For instance, list: `append()`, `insert()`, `delete()`, ...

How? Not specified

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- Class
 - Template for a data type
 - How data is stored
 - How public functions manipulate data

Classes and objects

- Abstract datatype
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 - Designated functions to manipulate the information
 - For instance, list: `append()`, `insert()`, `delete()`, ...
- Separate the (private) implementation from the (public) specification
- Class
 - Template for a data type
 - How data is stored
 - How public functions manipulate data
- Object
 - Concrete instance of template

Example: 2D points

- A point has coordinates (x, y)
 - `__init__()` initializes internal values x, y
 - First parameter is always `self`

l = createlist()

```
class Point:  
    def __init__(self, a, b):  
        self.x = a  
        self.y = b
```

constructor

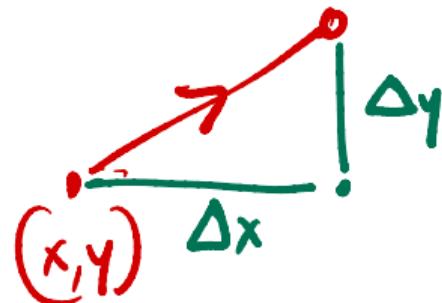
p = Point(6,4)

*Create a new
instance of Point
and assign to p*

Example: 2D points

- A point has coordinates (x, y)
 - `__init__()` initializes internal values x, y
 - First parameter is always `self`
- Translation: shift a point by $(\Delta x, \Delta y)$
 - $(x, y) \mapsto (x + \Delta x, y + \Delta y)$

`l.append(v)`
`append(l,v)`



```
class Point:
```

```
    def __init__(self,a,b):
```

```
        self.x = a
```

```
        self.y = b
```

"My" $x = a$
"My" $y = b$

```
def translate(self,deltax,deltay):
```

```
    self.x = self.x + deltax
```

```
    self.y += deltay
```

translate ($p, \Delta x, \Delta y$)

$p.\text{translate}(\Delta x, \Delta y)$

Example: 2D points

- A point has coordinates (x, y)
 - `__init__()` initializes internal values x, y
 - First parameter is always `self`
- Translation: shift a point by $(\Delta x, \Delta y)$
 - $(x, y) \mapsto (x + \Delta x, y + \Delta y)$
- Distance from the origin

$$d = \sqrt{x^2 + y^2}$$
$$\sqrt{(x-0)^2 + (y-0)^2}$$
$$(0,0) — (x,y)$$

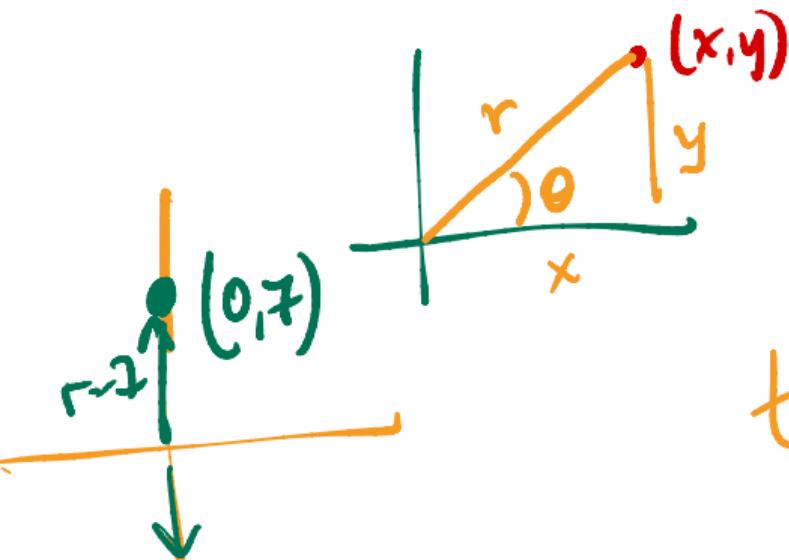


```
class Point:  
    def __init__(self,a,b):  
        self.x = a  
        self.y = b  
  
    def translate(self,deltax,deltay):  
        self.x += deltax  
        self.y += deltay  
  
    def odistance(self):  
        import math  
        d = math.sqrt(self.x*self.x +  
                      self.y*self.y)  
        return(d)
```

Polar coordinates

- (r, θ) instead of (x, y)

- $r = \sqrt{x^2 + y^2}$ ✓
- $\theta = \tan^{-1}(y/x)$



```
import math
class Point:
    def __init__(self, a, b):
        self.r = math.sqrt(a*a + b*b)
        if a == 0:
            self.theta = math.pi/2
        else:
            self.theta = math.atan(b/a)
```

Handwritten annotations: A green circle surrounds the entire class definition. A red exclamation mark is placed above the word "Point". A red checkmark is placed next to the formula $r = \sqrt{a^2 + b^2}$.

$$\tan \theta = \frac{y}{x}$$

Polar coordinates

- (r, θ) instead of (x, y)
 - $r = \sqrt{x^2 + y^2}$
 - $\theta = \tan^{-1}(y/x)$
- Distance from origin is just r

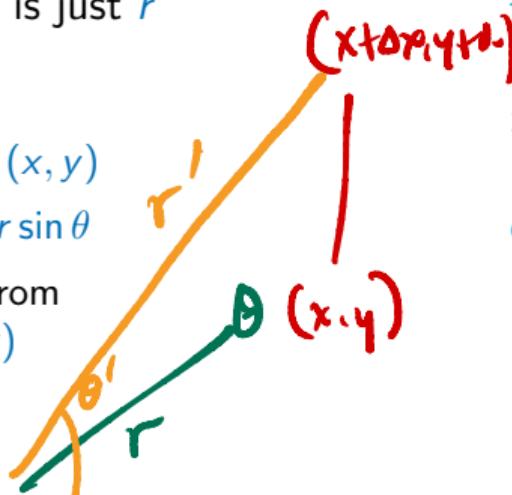
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```

```
def odistance(self):
    return(self.r)
```



Polar coordinates

- (r, θ) instead of (x, y)
 - $r = \sqrt{x^2 + y^2}$
 - $\theta = \tan^{-1}(y/x)$
- Distance from origin is just r
- Translation
 - Convert (r, θ) to (x, y)
 - $x = r \cos \theta, y = r \sin \theta$
 - Recompute r, θ from $(x + \Delta x, y + \Delta y)$



```
def translate(self,deltax,deltay):  
    x = self.r*math.cos(self.theta)  
    y = self.r*math.sin(self.theta)  
    x += deltax  
    y += deltay  
    self.r = math.sqrt(x*x + y*y)  
    if x == 0:  
        self.theta = math.pi/2  
    else:  
        self.theta = math.atan(y/x)]
```

Polar coordinates

- (r, θ) instead of (x, y)
 - $r = \sqrt{x^2 + y^2}$
 - $\theta = \tan^{-1}(y/x)$
- Distance from origin is just r
- Translation
 - Convert (r, θ) to (x, y)
 - $x = r \cos \theta, y = r \sin \theta$
 - Recompute r, θ from $(x + \Delta x, y + \Delta y)$
- Interface has not changed
 - User need not be aware whether representation is (x, y) or (r, θ)

```
def translate(self,deltax,deltay):  
    x = self.r*math.cos(self.theta)  
    y = self.r*math.sin(self.theta)  
    x += deltax  
    y += deltay  
    self.r = math.sqrt(x*x + y*y)  
    if x == 0:  
        self.theta = math.pi/2  
    else:  
        self.theta = math.atan(y/x)
```

Special functions

- `__init__()` — constructor

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- `__str__()` — convert object to string
 - `str(o) == o.__str__()`
 - Implicitly invoked by `print()`

```
class Point:
```

```
...
```

```
def __str__(self):
```

```
    return(
```

```
        '()' + str(self.x) + ',  
        + str(self.y) + '()'
```

```
)
```

str(self.x)
,
)
str(self.y)

Special functions

- `__init__()` — constructor
- `__str__()` — convert object to string
 - `str(o) == o.__str__()`
 - Implicitly invoked by `print()`
- `__add__()`
 - Implicitly invoked by `+`

```
class Point:
```

...

$p.add(q)$
 $q.add(p)$

```
def __str__(self):  
    return(  
        '('+str(self.x)+', '  
            +str(self.y)+')'  
)
```

```
def __add__(self,p):  
    return Point(self.x + p.x,  
                self.y + p.y))
```

$$\begin{aligned} P &= (x_p, y_p) \\ q &= (x_q, y_q) \\ r = P+q &\leadsto (x_p+x_q, y_p+y_q) \end{aligned}$$

```
def __add__(self, p):  
    return Point(self.x + p.x,  
                self.y + p.y))
```

→ newx = self.x + p.x
newy = self.y + p.y
newpt = Point(newx,
 newy)

return (newpt)

Special functions

- `__init__()` — constructor
- `__str__()` — convert object to string
 - `str(o) == o.__str__()`
 - Implicitly invoked by `print()`
- `__add__()`
 - Implicitly invoked by `+`
- Similarly
 - `__mult__()` invoked by `*`
 - `__lt__()` invoked by `<`
 - `__ge__()` invoked by `>=`
 - ...

```
class Point:  
    ...  
  
    def __str__(self):  
        return(  
            '('+str(self.x)+', '  
            +str(self.y)+')'  
)
```

```
def __add__(self,p):  
    return(Point(self.x + p.x,  
                self.y + p.y))
```