

Interprocedural analysis: Sharir-Pnueli's functional approach

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Outline

- 1 Motivation
- 2 Functional Approach
- 3 Example
- 4 Exercise 1
- 5 Iterative Approach

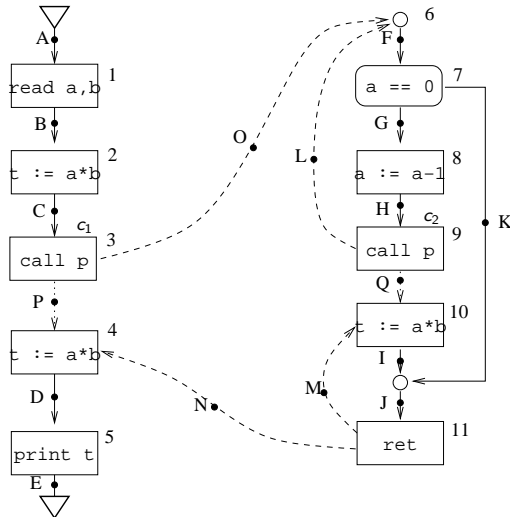
Example program with procedure calls

- We want join over all “**valid**” paths at each program point.
- Simply taking “JOP” on extended CFG would lose precision.
- Can we compute “**JVP**” (Join over Valid Paths) values instead?

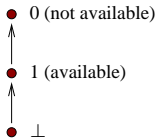
• JOP



• JVP (interprocedurally valid)

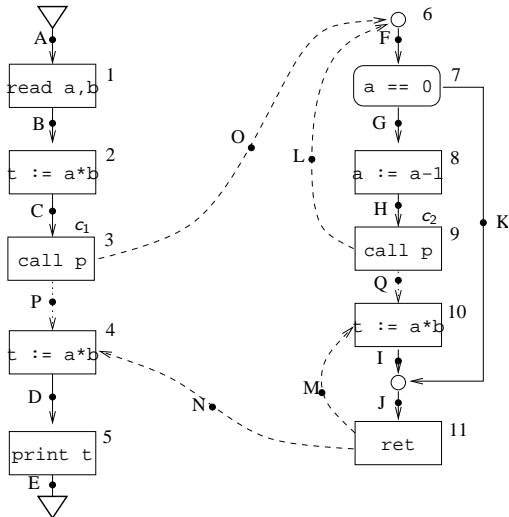


Example program: Available expressions analysis

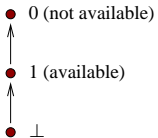


Lattice for Av-Exp analysis.

- Is $a*b$ available at program point N ?

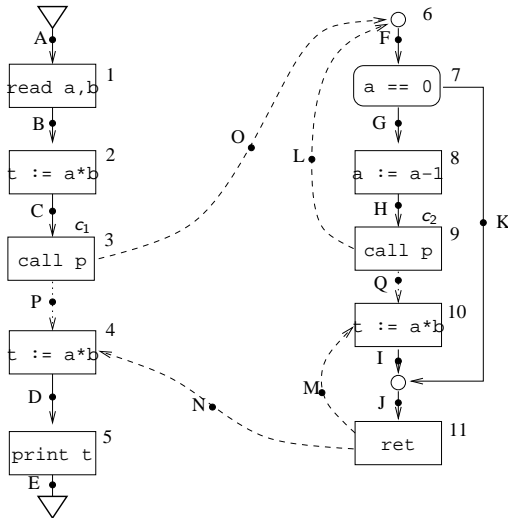


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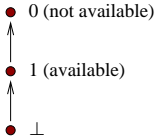


Lattice for Av-Exp analysis.

- Is $a*b$ available at program point N ?
- No if we consider all paths.

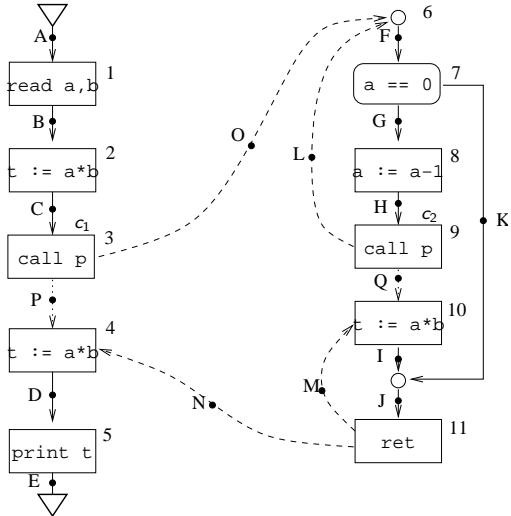


Example program: Available expressions analysis



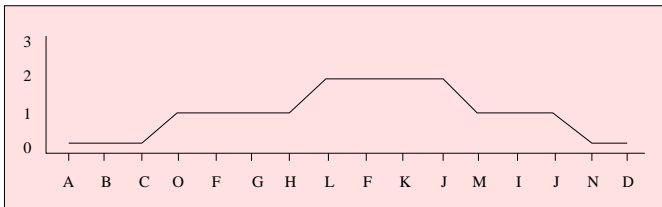
Lattice for Av-Exp analysis.

- Is $a*b$ available at program point N ?
- No if we consider all paths.
- **Yes** if we consider interprocedurally valid paths only.



Interprocedurally valid and complete paths: $IVP_0(M, N)$

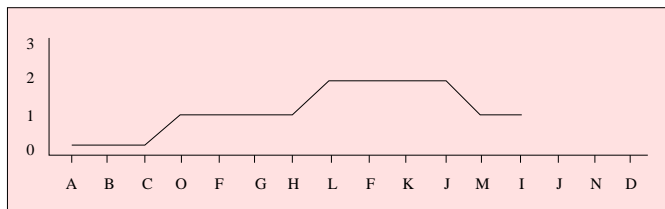
- Convention: r_p and e_p are respectively the root and return nodes of procedure p . Root of the main procedure is r_1 .
- A path ρ is **interprocedurally valid and complete** if the sequence of call nodes and return nodes form a balanced parenthesis string.
- A path in $IVP_0(r_1, D)$ for example program:



- C ("call p ") · O ··· H ("call p ") · L ··· J ("ret") · M ··· J ("ret") · N · D.
- Note that "call p " must be matched by "ret $_p$."

Interprocedurally valid paths: $IVP(M, N)$

- A path ρ is **interprocedurally valid** if it is a prefix of a valid and complete path.
- A path in $IVP(r_1, l)$ for example program:



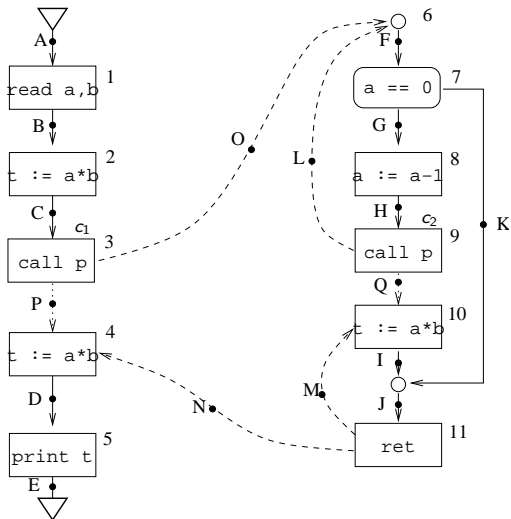
Defining JVP

For a given program P and analysis $((D, \leq), f_{MN}, d_0)$, the *join over all interprocedurally valid paths* (JVP) at point N is defined to be:

$$\bigsqcup_{\rho \in IVP(r_1, N)} f_{\rho}(d_0).$$

Equation solving: Problems with naive approach

- In non-procedural case, we setup equations to capture JOP assuming distributivity. Least solution to these equations gave us exact/over-approx JOP depending on distributive/monotonic framework.
- Try to set up similar equations for x_N (JVP at program point N).

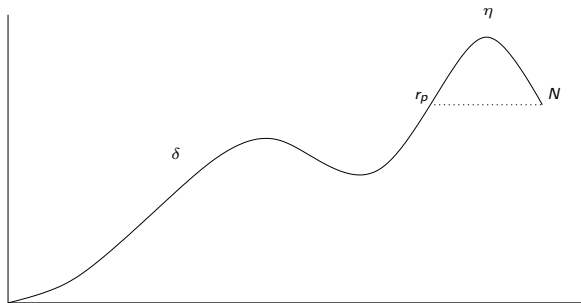


Instead try to capture join over **complete** paths first

- Set up equations to capture join over complete paths.
- Now set up equations to capture JVP using join over complete path values.

Basic idea: Why join over complete paths help

An IVP path ρ from r_1 to N in procedure p can be written as $\delta \cdot \eta$ where δ is in $\text{IVP}(r_1, r_p)$, and η is in $\text{IVP}_0(r_p, N)$.



Consider point where procedure p was last entered.

Valid and complete paths from r_p to N

For a procedure p and node N in p , define:

$$\phi_{r_p, N} : D \rightarrow D$$

given by

$$\phi_{r_p, n}(d) = \bigsqcup_{\text{paths } \rho \in \text{IVP}_0(r_p, N)} f_\rho(d).$$

$\phi_{r_p, N}$ is thus the join of all functions f_ρ where ρ is an **interprocedurally valid and complete** path from r_p to N .

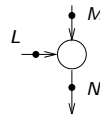
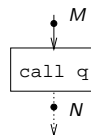
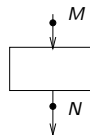
Equations (1) to capture $\phi_{r_p, N}$

$$\psi_{r_p, r_p} = id_D$$

$$\psi_{r_p, N} = f_{MN} \circ \psi_{r_p, M}$$

$$\psi_{r_p, N} = \psi_{r_q, e_q} \circ \psi_{r_p, M}$$

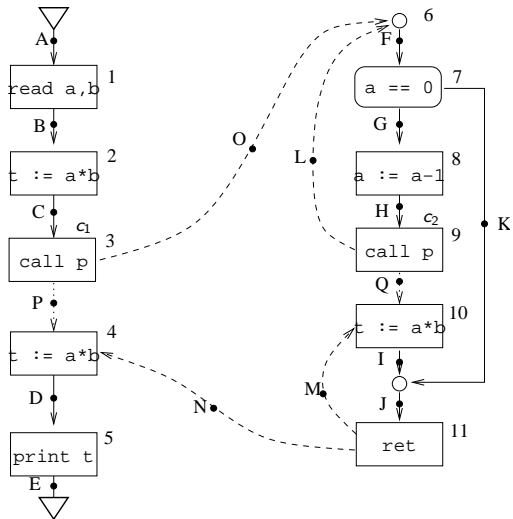
$$\psi_{r_p, N} = \psi_{r_p, L} \sqcup \psi_{r_p, M}$$



Example: Equations for ϕ 's

$$\begin{aligned} \psi_{A,A} &= id \\ \psi_{A,B} &= \mathbf{0} \circ \psi_{A,A} \\ \psi_{A,C} &= \mathbf{1} \circ \psi_{A,B} \\ \psi_{A,P} &= \phi_{F,J} \circ \psi_{A,C} \\ \psi_{A,D} &= \mathbf{1} \circ \psi_{A,P} \\ \psi_{A,E} &= id \circ \psi_{A,D} \end{aligned}$$

$$\begin{aligned} \phi_{F,F} &= id \\ \phi_{F,G} &= id \circ \psi_{F,F} \\ \phi_{F,K} &= id \circ \psi_{F,F} \\ \phi_{F,H} &= \mathbf{0} \circ \psi_{F,G} \\ \phi_{F,Q} &= \psi_{F,J} \circ \psi_{F,H} \\ \phi_{F,I} &= \mathbf{1} \circ \psi_{F,Q} \\ \phi_{F,J} &= \psi_{F,I} \sqcup \psi_{F,K} \end{aligned}$$



Equations (2) to capture JVP

$$\begin{aligned}x_1 &\geq d_0 \\x_{r_p} &= \bigsqcup_{\text{calls } c \text{ to } p \text{ in } q} \phi_{r_q, c}(x_{r_q}) \\x_n &= \phi_{r_p, n}(x_{r_p}) \quad \text{for } n \in N_p - \{r_p\}.\end{aligned}$$

Example: Equations for x_N 's (JVP)

$$x_A \geq 0$$

$$x_B = \mathbf{0}(x_A)$$

$$x_C = \mathbf{1}(x_A)$$

$$x_P = \mathbf{1}(x_A)$$

$$x_D = \mathbf{1}(x_A)$$

$$x_E = \mathbf{1}(x_A)$$

$$x_F = \mathbf{1}(x_A) \sqcup \mathbf{0}(x_F)$$

$$x_G = id(x_F)$$

$$x_K = id(x_F)$$

$$x_H = \mathbf{0}(x_F)$$

$$x_Q = \mathbf{0}(x_F)$$

$$x_I = \mathbf{1}(x_F)$$

$$x_J = id(x_F).$$

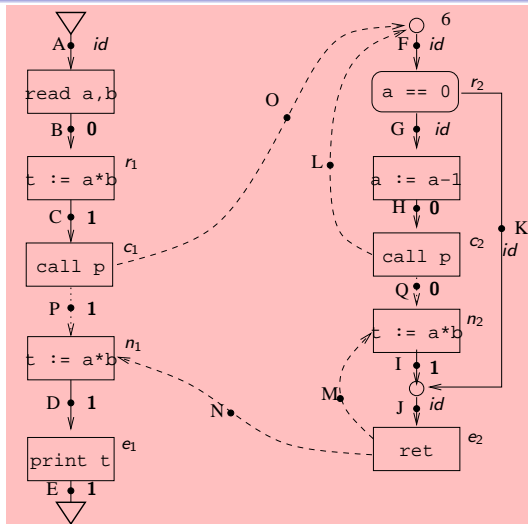


Fig. shows values of $\phi_{r_p, N}$'s in bold.

Correctness and algo

- Consider lattice (F, \leq) of **functions** from D to D , obtained by closing the transfer functions, identity, and $f_{\perp} : d \mapsto \perp$ (denoted f_{Ω} by Sharir-Pnueli) under composition and join.
- Ordering is $f \leq g$ iff $f(d) \leq g(d)$ for each $d \in D$.
- (F, \leq) is also a complete lattice.
- \bar{f} induced by Eq (1) is a monotone function on the complete lattice $(\bar{F}, \bar{\leq})$.
- LFP / least solution exists.

Claim

$\phi_{r_p, N}$'s are the least solution to Eq (1) when f_{MN} 's are distributive. Otherwise $\phi_{r_p, N}$'s are dominated by the least solution to Eq (1).

Kleene/Kildall's algo will compute LFP (assuming D finite).

Correctness and algo - II

- \bar{f} induced by Eq (2) is a monotone function on the complete lattice (\bar{D}, \leq) .
- LFP / least solution exists.

Claim

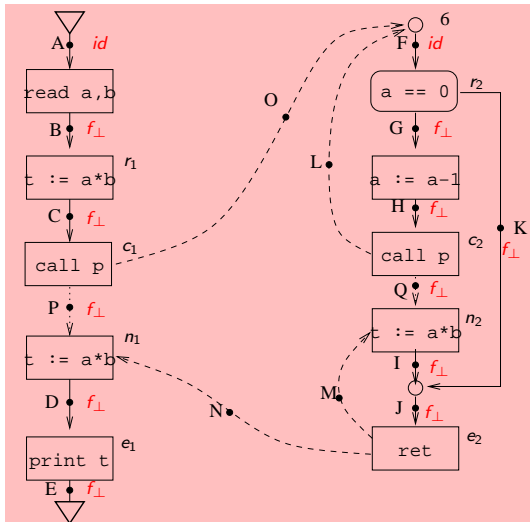
JVP_N's are the least solution to Eq (2) when f_{MN} 's are distributive. Otherwise JVP_N's are dominated by the least solution to Eq (2).

Kleene/Kildall's algo will compute LFP (assuming D finite).

Example: Equations for ϕ 's

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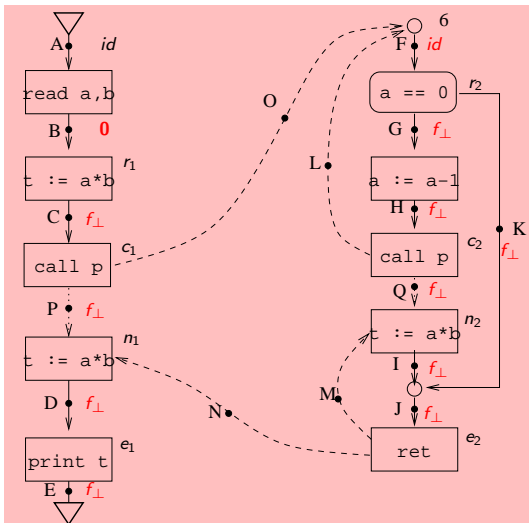
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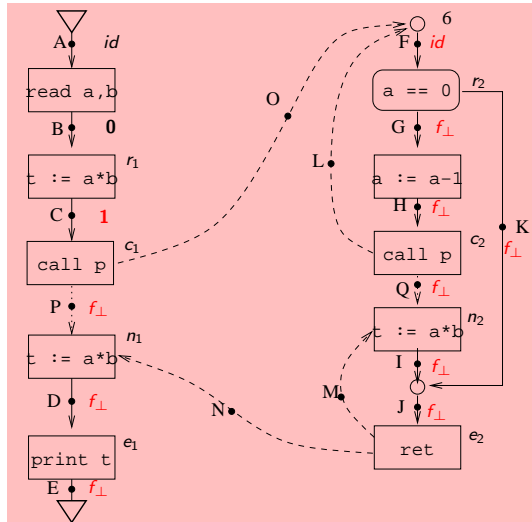
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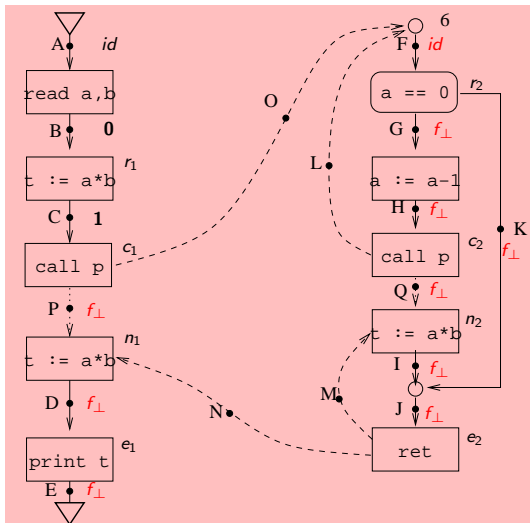
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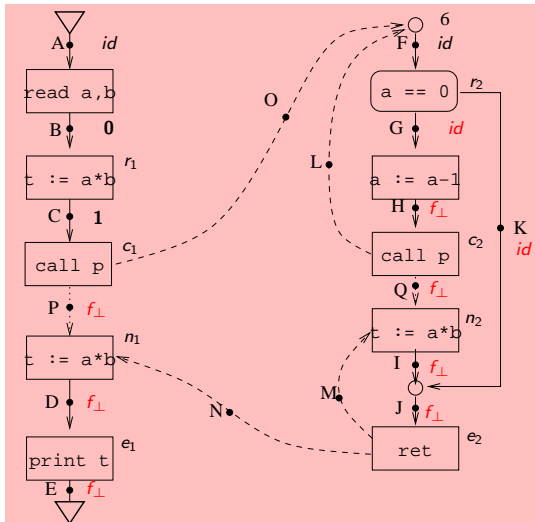
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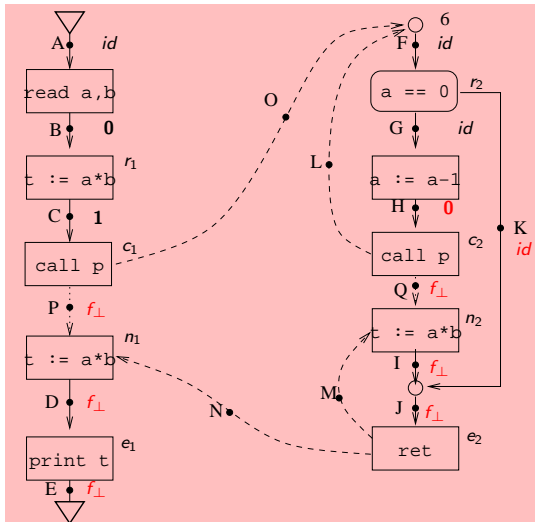
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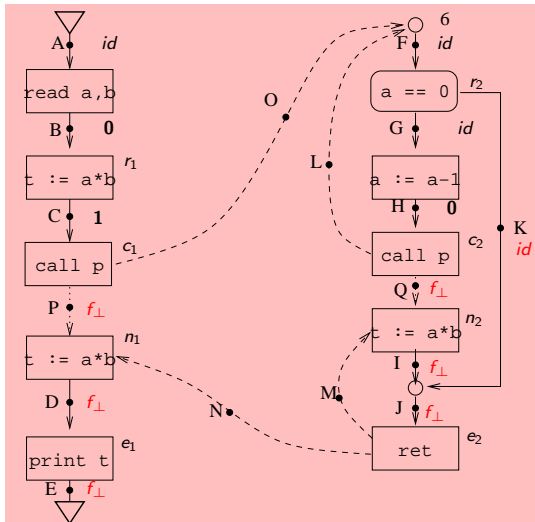
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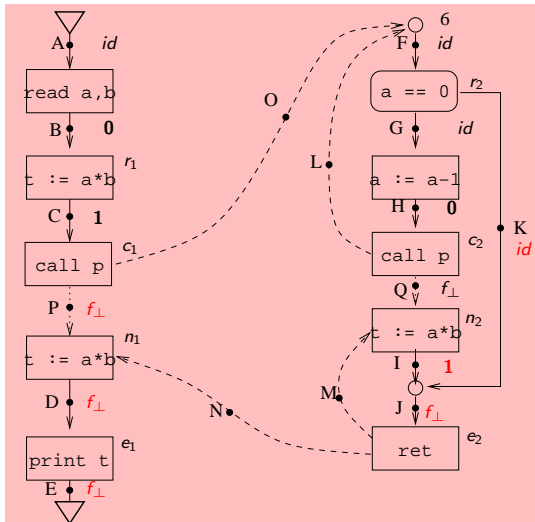
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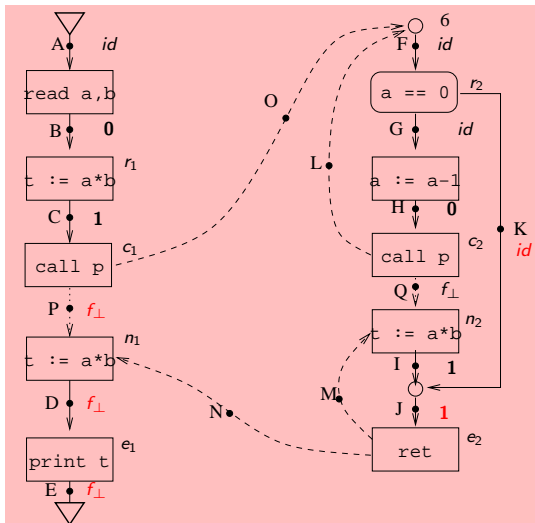
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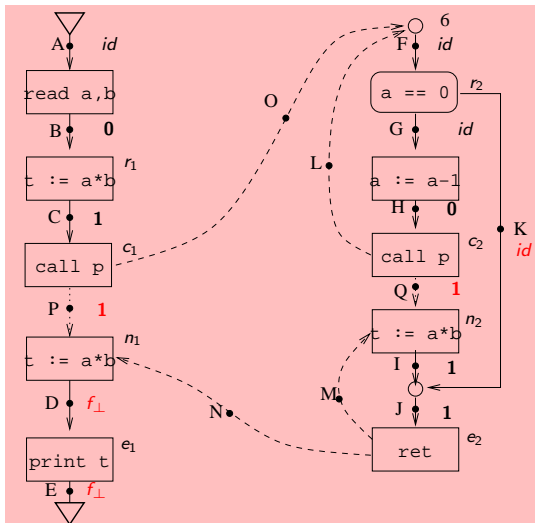
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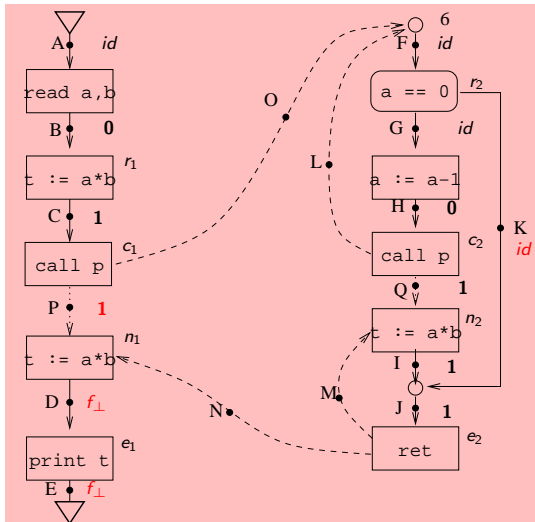
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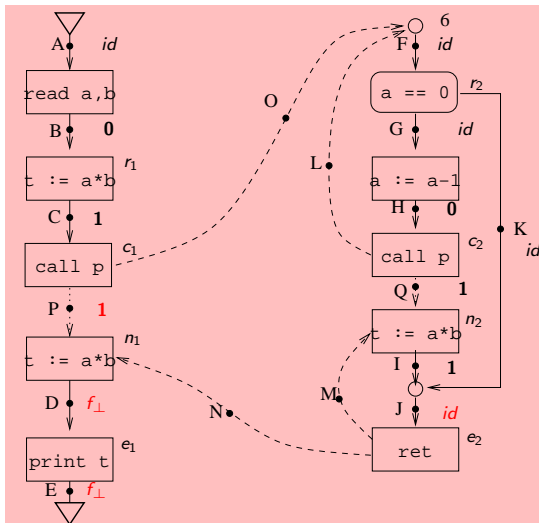
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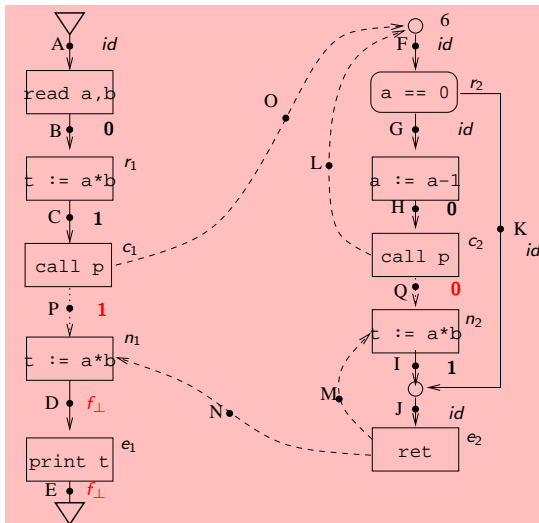
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Example: Equations for ϕ 's

$$\begin{aligned} \psi_{A,A} &= id \\ \psi_{A,B} &= \mathbf{0} \circ \psi_{A,A} \\ \psi_{A,C} &= \mathbf{1} \circ \psi_{A,B} \\ \psi_{A,P} &= \phi_{F,J} \circ \psi_{A,C} \\ \psi_{A,D} &= \mathbf{1} \circ \psi_{A,P} \\ \psi_{A,E} &= id \circ \psi_{A,D} \end{aligned}$$

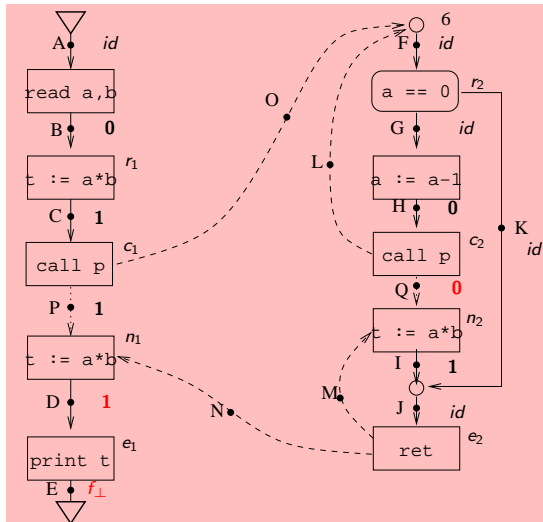
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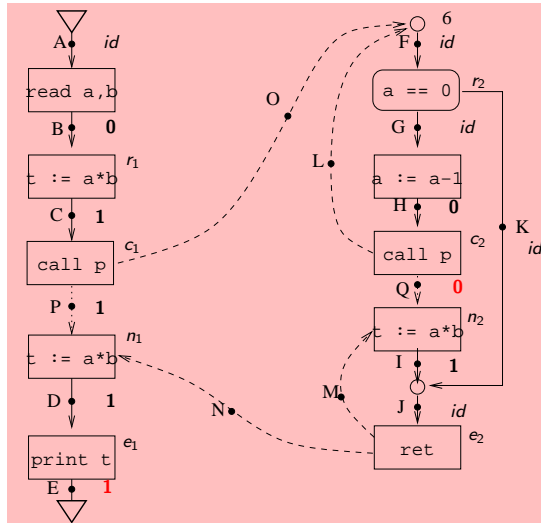
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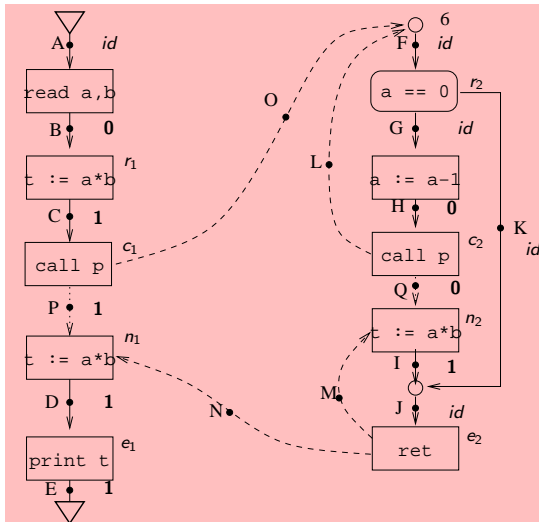
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Example: Equations for x_N 's (JVP)

$$x_A \geq 0$$

$$x_B = \mathbf{0}(x_A)$$

$$x_C = \mathbf{1}(x_A)$$

$$x_P = \mathbf{1}(x_A)$$

$$x_D = \mathbf{1}(x_A)$$

$$x_E = \mathbf{1}(x_A)$$

$$x_F = \mathbf{1}(x_A) \sqcup \mathbf{0}(x_F)$$

$$x_G = id(x_F)$$

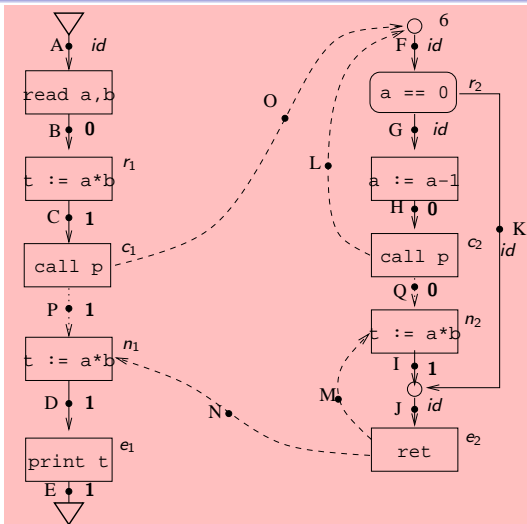
$$x_K = id(x_F)$$

$$x_H = \mathbf{0}(x_F)$$

$$x_Q = \mathbf{0}(x_F)$$

$$x_I = \mathbf{1}(x_F)$$

$$x_J = id(x_F).$$



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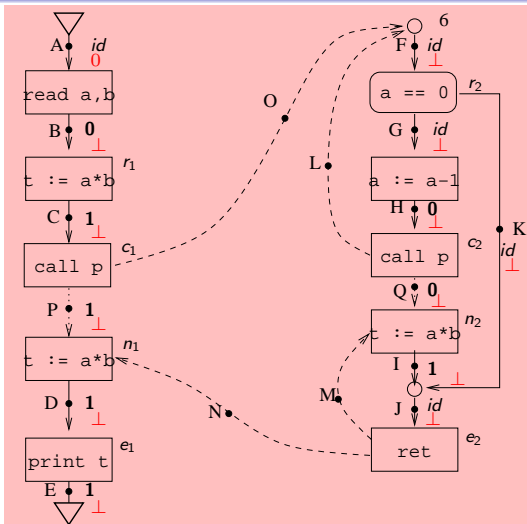


Fig shows initial (red) and final (blue) values.

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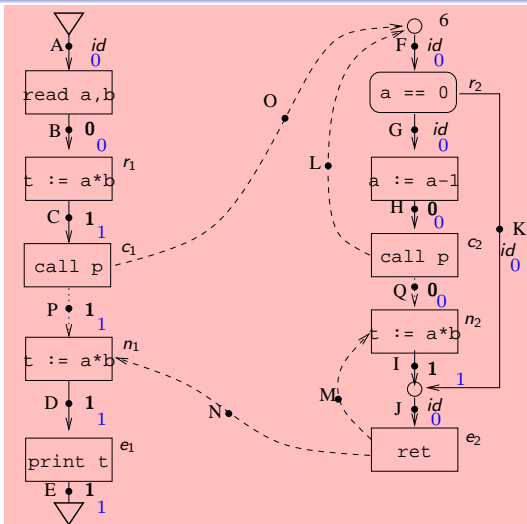
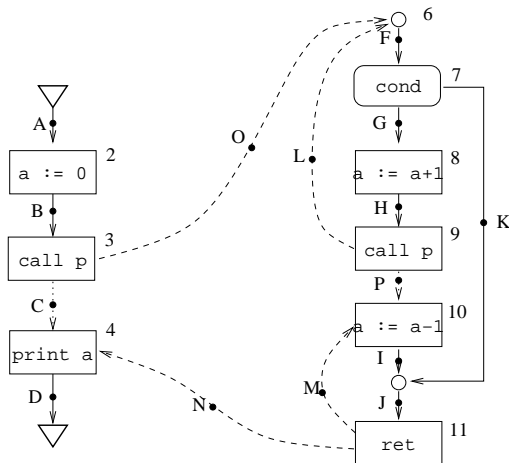


Fig shows initial (red) and final (blue) values.

Exercise

Exercise: Use the functional method to do interprocedural constant propagation analysis for the program below, with initial value \emptyset .



Summary of functional approach

- Uses a two step approach
 - ① Compute $\phi_{r_p, N}$'s.
 - ② Compute x_n 's (JVP's) at each point.

Summary of conditions: For each property (column heading), the conjunction of the ticked conditions (row headings) are sufficient to ensure the property.

	Termination	Least Sol of Eq(2) \geq JVP	Least Sol of Eq(2)= JVP
f_{MN} 's monotonic	✓	✓	
Finite underlying lattice	✓		
Distributive			✓

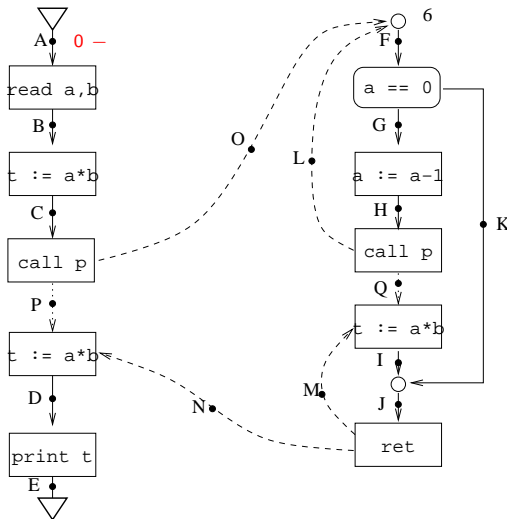
Iterative/Tabulation Approach

- Maintain a **table** of values representing the current value of $\phi_{r_p, N}$ for each program point N in procedure p .
- Informally, at N in procedure p , the table has an entry $d \mapsto d'$ if we have seen valid paths ρ from r_1 to r_p with $\bigsqcup_{\rho} f_{\rho}(d_0) = d$, and valid and complete paths δ from r_p to N with $\bigsqcup_{\delta} f_{\delta}(d) = d'$.
- Apply Kildall's algo with initial value of $d_0 \mapsto d_0$ at r_1 .

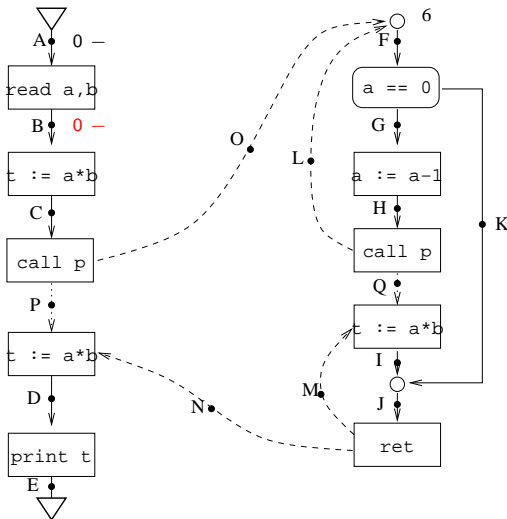
Propogation rules

- If $d \mapsto d'$ at point M , and statement corresponding to MN is not a call or ret, then propogate $d \mapsto f_{MN}(d')$ to point N .
- If $d \mapsto d'$ at point M , and statement after M is call q , then
 - propogate $d \mapsto d'$ to point r_q ,
 - propogate $d \mapsto d''$ to return site of N of M , provided we have $d' \mapsto d''$ at point e_q .
- If $d \mapsto d'$ at point e_q (i.e before ret in procedure q), then
 - If LN corresponds to a call q and $(d'' \mapsto d)$ at L , then propogate $d'' \mapsto d'$ to point N . (Do this for **all** such N).

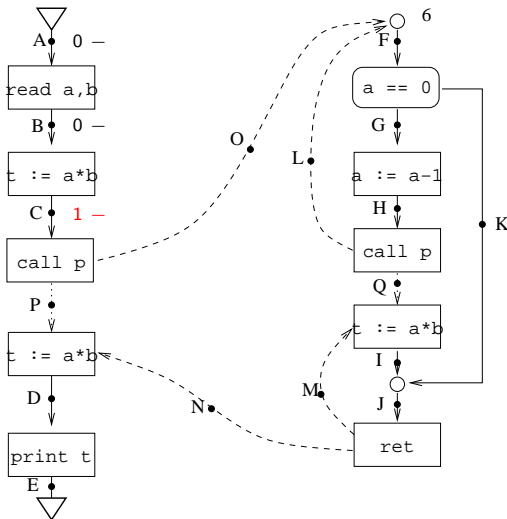
Example: Computing ϕ 's iteratively: 1



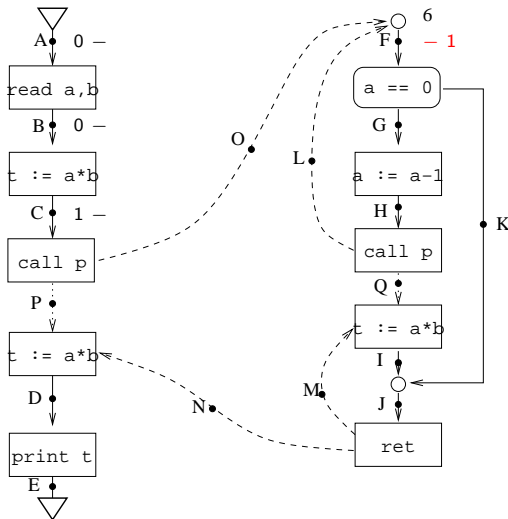
Example: Computing ϕ 's iteratively: 2

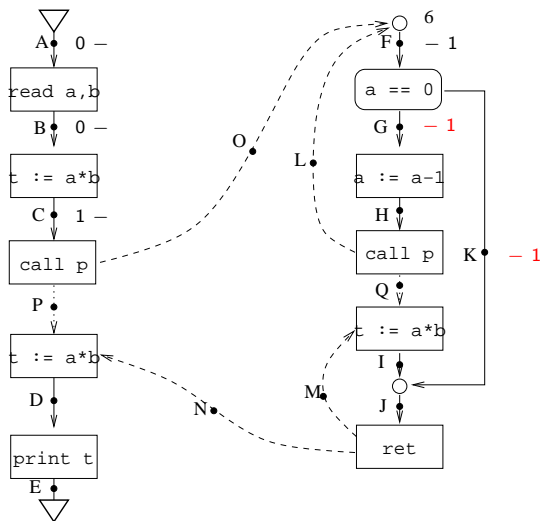


Example: Computing ϕ 's iteratively: 3

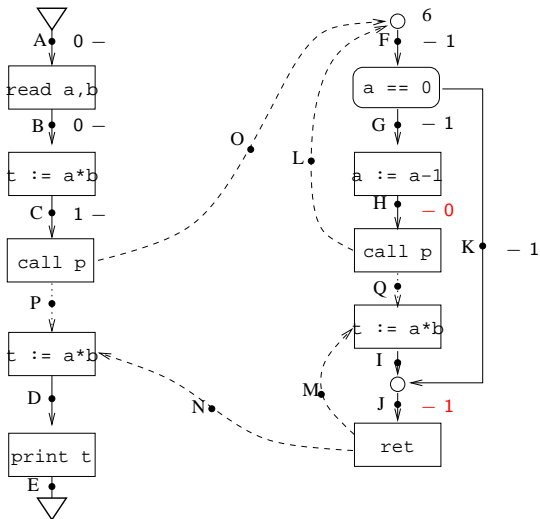


Example: Computing ϕ 's iteratively: 4

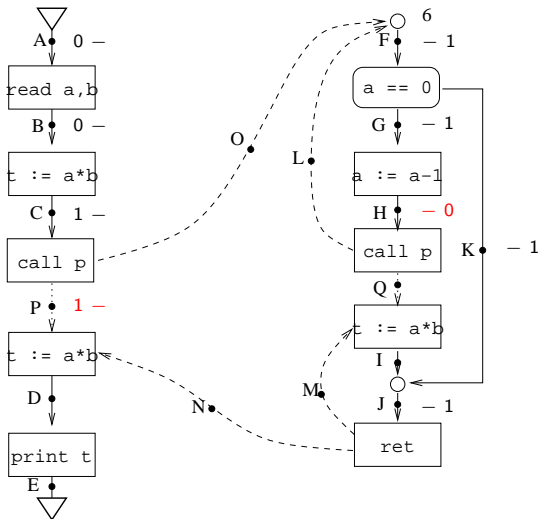


Example: Computing ϕ 's iteratively: 5

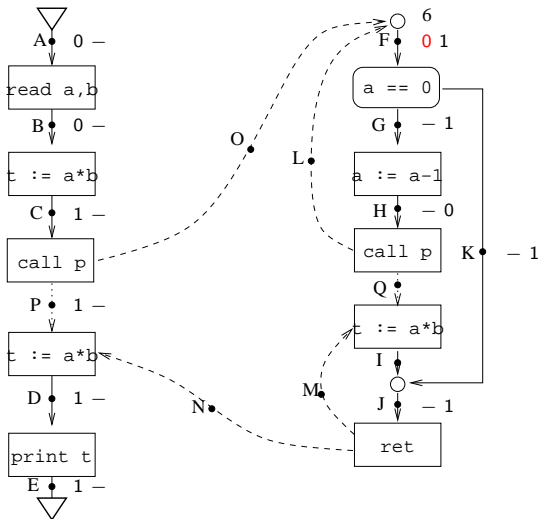
Example: Computing ϕ 's iteratively: 6



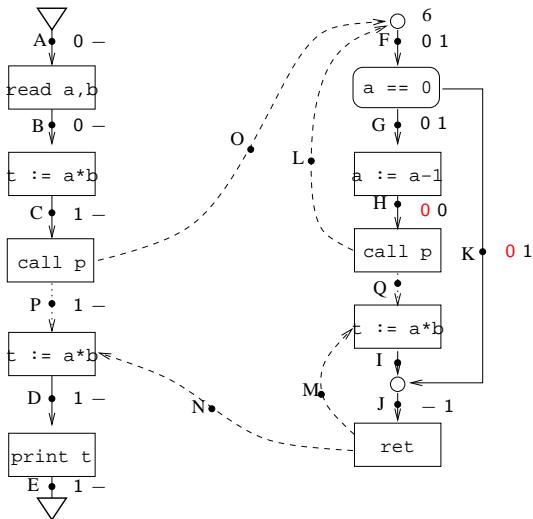
Example: Computing ϕ 's iteratively: 7



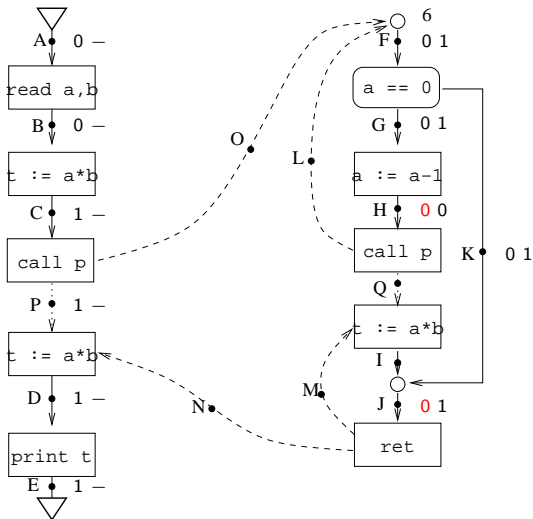
Example: Computing ϕ 's iteratively: 8



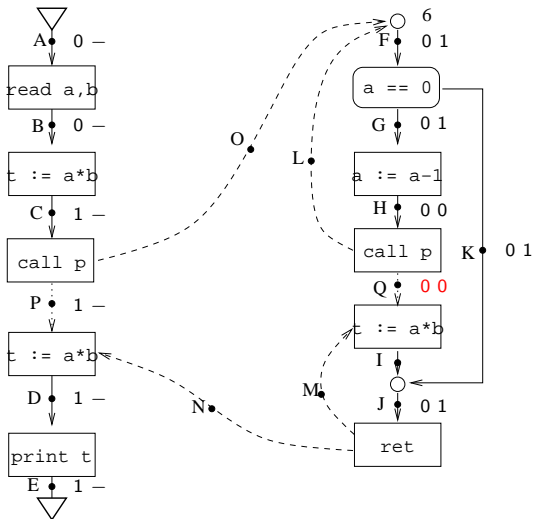
Example: Computing ϕ 's iteratively: 9



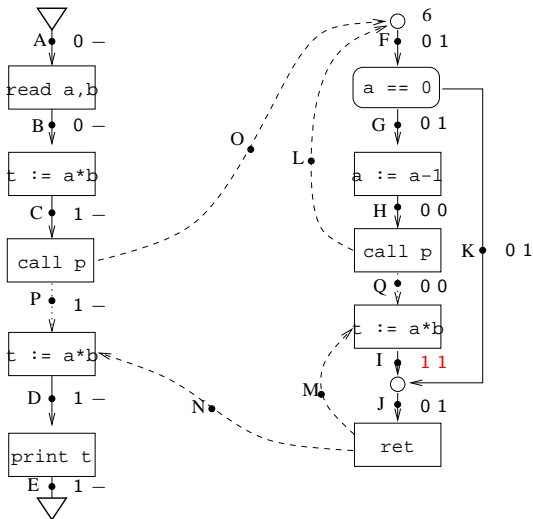
Example: Computing ϕ 's iteratively: 10



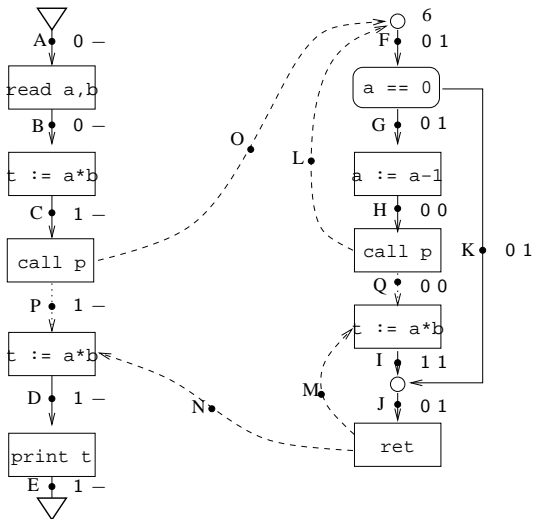
Example: Computing ϕ 's iteratively: 11



Example: Computing ϕ 's iteratively: 12

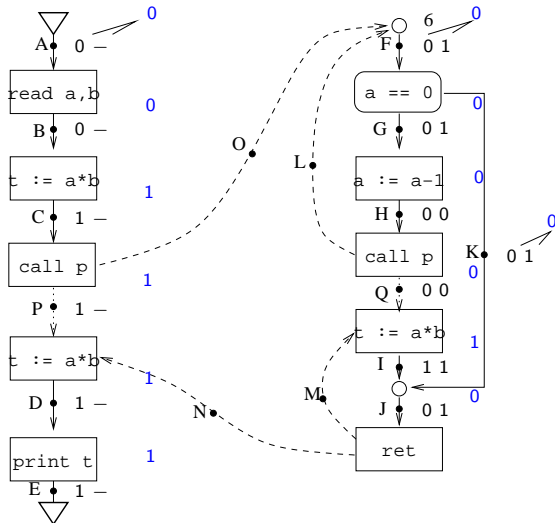


Example: Computing ϕ 's iteratively: 13



Example: Finally compute x_N 's from ϕ values

At each point N take join of reachable $\phi_{r_p, N}$ values.



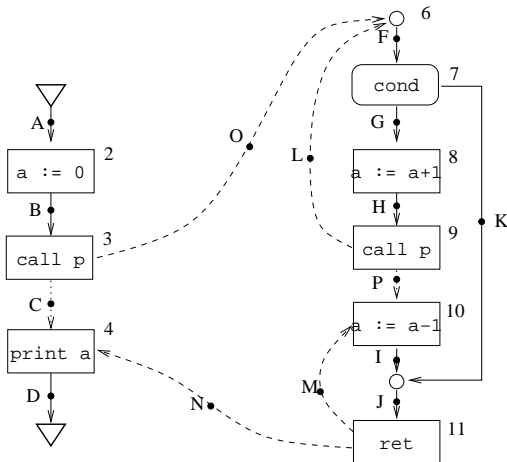
Correctness of iterative algo

$$\begin{aligned}x_1 &\geq d_0 \\x_{r_p} &= \bigsqcup_{\text{calls } c \text{ to } p \text{ in } q} \psi_{r_q, c}^*(x_{r_q}) \\x_n &= \psi_{r_p, n}^*(x_{r_p}) \quad \text{for } n \in N_p - \{r_p\}.\end{aligned}$$

- Iterative algo terminates provided underlying lattice is finite.
- It computes the least solution to the equations above, where $\psi^*(rp_N)$'s are the least solution to Eq (1).
- It thus computes an overapproximation of JVP for monotonic transfer functions, and exact JVP when transfer functions are distributive.

Exercise 2: Iterative algo

Exercise: Use the iterative algo to do constant propagation analysis for the program below with initial value \emptyset :



Comparing functional vs iterative approach

- Functional algo can terminate even when underlying lattice is infinite, provided we can represent and compose/join functions “symbolically”.
- Iterative is typically more efficient than functional since it only computes $\phi_{r_p, N}$'s for values **reachable** at start of procedure.