

Interprocedural Optimisation

Seminar Static Program Analysis

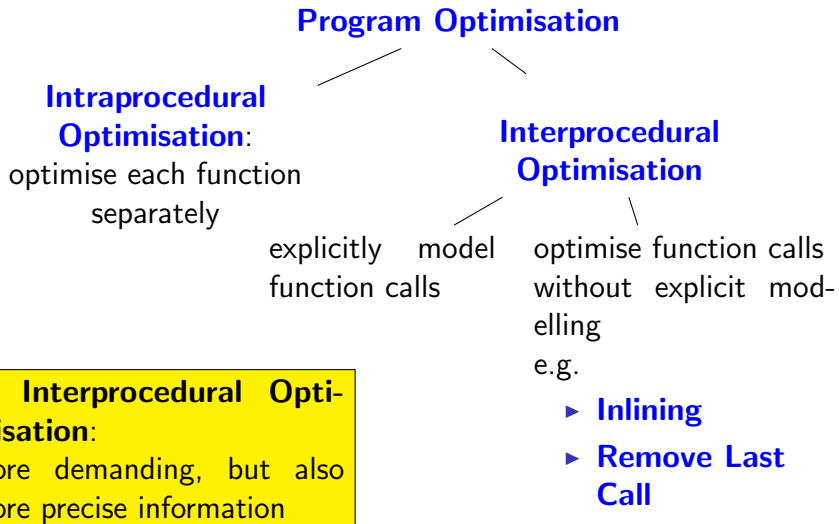
Barbara Dörr

Sources:

Übersetzerbau - Analyse und Transformation (H. Seidl, R. Wilhelm, S. Hack)
Principles of Program Analysis (F. Nielson, H.R. Nielson, C. Hankin)

12. März 2010

Forms of Program Optimisation



Interprocedural vs. Intraprocedural

disadvantage of intraprocedural optimisation:

context-insensitive optimisation:

cannot distinguish between different calls
(information is combined from all call sites)

→ imprecise information

interprocedural optimisation:

context-sensitive optimisation:

different calls reached with different contexts δ_1 and δ_2

→ information obtained clearly related to δ_1 and δ_2

⇒ more precise, but more costly

Introduction

Simple Interprocedural Optimisations

Operational Semantic

Functional Approach

Related Approaches

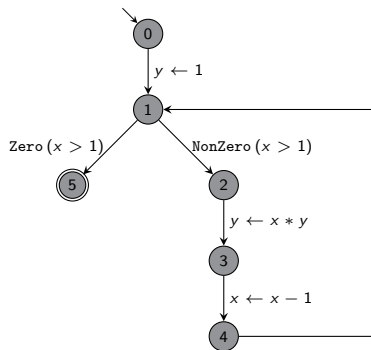
Summary

Program Representation

intraprocedural

→ program represented by a **control flow graph**:

```
y ← 1;
while (x > 1){
  y ← x*y;
  x ← x-1;
}
```



Program Representation

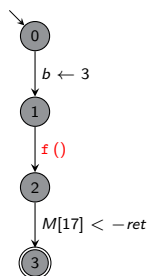
interprocedural

→ program represented by a set of control flow graphs;

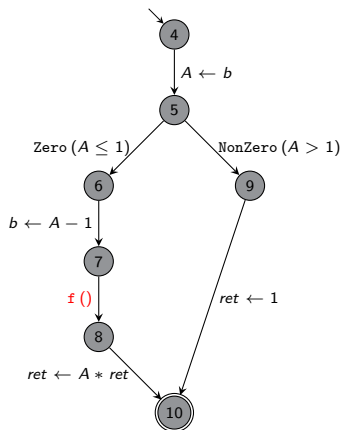
```
main() {
    b ← 3;
    f();
    M[17] ← ret;
}
```

```
f(){
    A ← b;
    if (A ≤ 1) ret ← -1;
    else {
        b ← A-1;
        f();
        ret ← A*ret;
    }
}
```

main



f ()



Edge Annotations

(x ... variable, e ... arithmetic expression)

edge effects - intraprocedural:

Test: $\text{NonZero}(e)$

$\text{Zero}(e)$

Assignment: $x \leftarrow e$

Load: $x \leftarrow M[e]$

Store: $M[e_1] \leftarrow e_2$

Empty Statement: $;$

additional edge effect - interprocedural:

Function Call: $f()$

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Inlining

inlining:

copy function body to calling point

problems:

- ▶ function has to be statically known
- ▶ local variables of calling function must not be modified
→ rename local variables
- ▶ recursive functions
→ identified from **call graph**

→

- ▶ inlining only for **leaf functions** (without calls)
- ▶ inlining only for non-recursive functions

Inlining

Call Graph

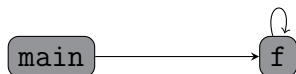
Call Graph:

nodes \sim functions

edges \sim between function f_1 and function f_2 , if f_1 calls f_2

```
main() {  
    b <- 3;  
    f();  
    M[17] <- ret;  
}
```

```
f(){  
    A <- b;  
    if (A <=1) ret <- 1;  
    else {  
        b <- A-1;  
        f();  
        ret <- A*ret;  
    }  
}
```

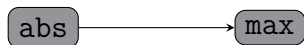


Inlining

Call Graph

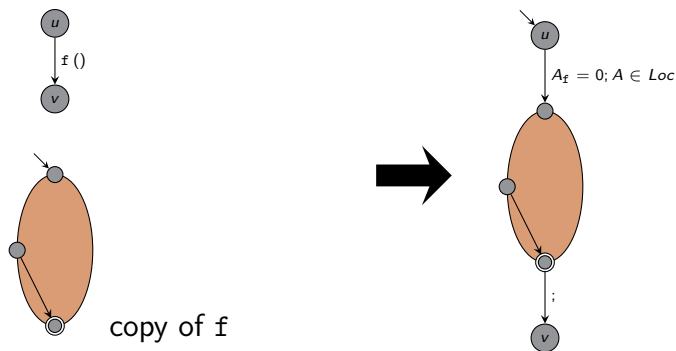
```
abs(){  
  b_1 <- b;  
  b_2 <- -b;  
  max();  
}
```

```
max(){  
  if (b_1 < b_2) ret <- b_2;  
  else ret <- b_1;  
}
```



Inlining

transformation Π :



Inlining

example

```
abs(){  
  b_1 <- b;  
  b_2 <- -b;  
  max();  
}
```

```
max(){  
  if (b_1 < b_2) ret <- b_2;  
  else ret <- b_1;  
}
```



```
abs(){  
  b_1 <- b;  
  b_2 <- -b;  
  if (b_1 < b_2) ret <- b_2;  
  else ret <- b_1;  
}
```

Remove Last Calls

→ no own stack frame needed; only replace local variables
(unconditional jump to function body)

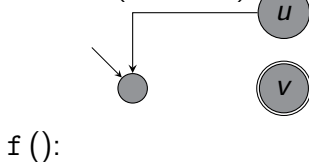
! only possible if local variables of calling function are not accessible any more

transformation LC:

$f()$:



$A = 0; (A \in Loc)$



Remove Last Calls

example

```
f(){  
  if (b_2 <= 1) ret <- b_1;  
  else {  
    b_1 <- b_1*b_2;  
    b_2 <- b_2 - 1;  
    f();  
  }  
}
```



```
f(){  
  _f: if (b_2 <= 1) ret <- b_1;  
  else {  
    b_1 <- b_1*b_2;  
    b_2 <- b_2 - 1;  
    goto _f;  
  }  
}
```

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Operational Semantic

intraprocedural

- ▶ computations are described by **paths** through the control flow graph
- ▶ computations transform the current program state
- ▶ **program state**: $s = (\rho, \mu)$ with
 - $\rho : \text{Vars} \rightarrow \text{int}$... value of variables
 - $\mu : \mathbb{N} \rightarrow \text{int}$... content of memory
- ▶ edge $k = (u, \text{lab}, v)$
 - ... entry node u , exit node v , edge annotation label
- ▶ **edge effect**: transformation $\llbracket k \rrbracket$ on program states defined by the edge k
 - $\llbracket k \rrbracket = \llbracket \text{lab} \rrbracket$

Operational Semantic

Edge Effects - intraprocedural

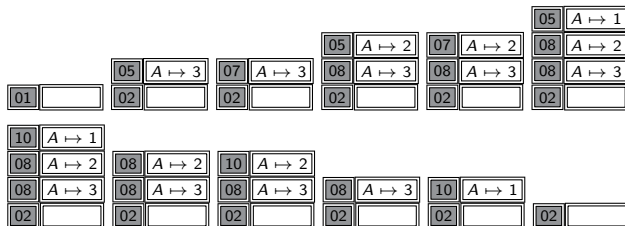
$$\begin{aligned}
 \llbracket ; \rrbracket (\rho, \mu) &= (\rho, \mu) \\
 \llbracket \text{NonZero } (e) \rrbracket (\rho, \mu) &= (\rho, \mu), \\
 &\quad \text{if } \llbracket e \rrbracket \rho \neq 0 \\
 \llbracket \text{Zero } (e) \rrbracket (\rho, \mu) &= (\rho, \mu), \\
 &\quad \text{if } \llbracket e \rrbracket \rho = 0 \\
 \llbracket x \leftarrow e \rrbracket (\rho, \mu) &= \left(\boxed{\rho \oplus \{x \mapsto \llbracket e \rrbracket \rho\}}, \mu \right) \\
 \llbracket x \leftarrow M[e] \rrbracket (\rho, \mu) &= \left(\boxed{\rho \oplus \{x \mapsto \mu(\llbracket e \rrbracket \rho)\}}, \mu \right) \\
 \llbracket M[e_1] \leftarrow e_2 \rrbracket (\rho, \mu) &= \left(\rho, \boxed{\mu \oplus \{\llbracket e_1 \rrbracket \rho \mapsto \llbracket e_2 \rrbracket \rho\}} \right)
 \end{aligned}$$

Stack Representation

Call Stack:

```
main() {
  b <- 3;
  f();
  M[17] <- ret;
}
```

```
f(){
  A <- b;
  if (A <=1) ret <- 1;
  else {
    b <- A-1;
    f();
    ret <- A*ret;
  }
}
```



Stack Representation

call stack:

- ▶ describes called and not yet finished functions
- ▶ basis of operational semantic

$$\text{config} = \text{stack} \times \text{globals} \times \text{store}$$

$$\text{globals} = \text{Glob} \rightarrow \mathbb{Z}$$

$$\text{store} = \mathbb{N} \rightarrow \mathbb{Z}$$

$$\text{stack} = \text{frame} \cdot \text{frame}^*$$

$$\text{frame} = \text{point} \times \text{locals}$$

$$\text{locals} = \text{Loc} \rightarrow \mathbb{Z}$$

! function body is a scope with own local variables

Modeling of Function Call

- ▶ call $k = (u, f(), v)$: $! \rho_f = \{x \mapsto 0 \mid x \in Loc\}$

$$\underbrace{\left(\sigma \cdot \boxed{(u, \rho_{Loc})}, \rho_{Glob}, \mu \right)}_{config} \vdash \left(\sigma \cdot \boxed{(v, \rho_{Loc}) \cdot (u_f, \rho_f)}, \rho_{Glob}, \mu \right)$$

- ▶ effect of function itself
- ▶ return from call:

$$\left(\sigma \cdot \boxed{(v, \rho_{Loc}) \cdot (r_f, -)}, \rho_{Glob}, \mu \right) \vdash \left(\sigma \cdot \boxed{(v, \rho_{Loc})}, \rho_{Glob}, \mu \right)$$

σ	...	stack
ρ_{Glob}	...	global variables
μ	...	store
(u, ρ_{Loc})	...	frame (<i>point</i> \times <i>locals</i>)

Path Effects

$$\pi : ((u, \rho_{Loc}), \rho_{Glob}, \mu) \rightsquigarrow ((v, \rho'_{Loc}), \rho'_{Glob}, \mu')$$

path π defines a partial function $\llbracket \pi \rrbracket$, that transforms $((u, \rho_{Loc}), \rho_{Glob}, \mu)$ into $((v, \rho'_{Loc}), \rho'_{Glob}, \mu')$

\Rightarrow compute transformation inductive over the structure of the path:

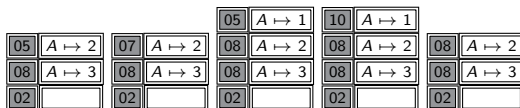
$$\llbracket \pi k \rrbracket = \llbracket k \rrbracket \circ \llbracket \pi \rrbracket$$

for a normal edge k (**composition of edge effects**)

Paths Effects

- ▶ **same-level**: all entered functions are also left again

$$\pi = \pi_1 \langle \mathbf{f} \rangle \pi_2 \langle \backslash \mathbf{f} \rangle$$



→ height of the stack stays the same

$$\llbracket \pi_1 \langle \mathbf{f} \rangle \pi_2 \langle \backslash \mathbf{f} \rangle \rrbracket = H(\llbracket \pi_2 \rrbracket) \circ \llbracket \pi_1 \rrbracket$$

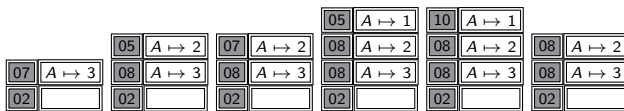
with

$$H(g)(\rho_{Loc}, \rho_{Glob}, \mu) = \mathbf{let} (\rho'_{Loc}, \rho'_{Glob}, \mu') = g(\underline{0}, \rho_{Glob}, \mu) \\ \mathbf{in} (\rho_{Loc}, \rho'_{Glob}, \mu')$$

Path Effects

- ▶ **computation that reaches a program point:**

$\pi \langle \mathbf{f} \rangle \pi'$ with π, π' is same-level



$$\llbracket \pi \langle \mathbf{f} \rangle \pi' \rrbracket (\rho_{Loc}, \rho_{Glob}, \mu) = \mathbf{let} (_, \rho'_{Glob}, \mu') = \llbracket \pi \rrbracket (\rho_{Loc}, \rho_{Glob}, \mu) \\ \mathbf{in} \llbracket \pi' \rrbracket (\underline{0}, \rho'_{Glob}, \mu')$$

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Program Analysis

\mathbb{D} ... **lattice**

→ all possible sets of analysis information that may hold at a program point

idea: collect information along all paths leading to a program point to yield analysis information that holds there

→ transformation of analysis information along edge k according to **abstract edge effect** $\llbracket k \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$

Program Analysis

interprocedural

$\text{enter}^\# : \mathbb{D} \rightarrow \mathbb{D}$

→ initialise information for the starting point of a function

$\text{combine}^\# : \mathbb{D}^2 \rightarrow \mathbb{D}$

→ combines information at the end of function body and information before entering the function

$\Rightarrow \llbracket k \rrbracket^\# D = \text{combine}^\# (D, \llbracket f \rrbracket^\# (\text{enter}^\# D))$

Example: Copy Propagation

intraprocedural

Copy Propagation:

computes for variable x at each program point the set of variables that contain the same value

→ usage may be replaced by usage of x

abstract edge effects: ($\llbracket k \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$)

$$\llbracket x \leftarrow e \rrbracket^\# V = \{x\}$$

$$\llbracket x \leftarrow M[e] \rrbracket^\# V = \{x\}$$

$$\llbracket z \leftarrow y \rrbracket^\# V = (y \in V)?V \cup \{z\} : V \setminus \{z\},$$

$$x \neq z, y \in \text{Vars}$$

$$\llbracket z \leftarrow r \rrbracket^\# V = V \setminus \{z\},$$

$$x \neq z, r \notin \text{Vars}$$

Example: Copy Propagation

interprocedural

- ▶ all variables global:

$$\begin{aligned} \text{enter}^\# V &= V \\ \text{combine}^\# (V_1, V_2) &= V_2 \end{aligned}$$

- ▶ with local variables:

- : auxiliary local variable to store value of x before the function call

$$\begin{aligned} \text{enter}^\# V &= V \cap \text{Glob} \cup \{\bullet\} \\ \text{combine}^\# (V_1, V_2) &= (V_2 \cap \text{Glob}) \cup ((\bullet \in V_2) ? V_1 \cap \text{Loc}_\bullet : \emptyset) \end{aligned}$$

with $\text{Loc}_\bullet = \text{Loc} \cup \{\bullet\}$

Abstract Effect of Function f

→ $\llbracket f \rrbracket^\#$: upper bound for abstract effect $\llbracket \pi \rrbracket^\#$ of every same-level computation π for f

→ approximated via

$$\llbracket start_f \rrbracket^\# \supseteq \text{Id}$$

$$\llbracket v \rrbracket^\# \supseteq H^\# (\llbracket f \rrbracket^\#) \circ \llbracket u \rrbracket^\#,$$

$k = (u, f(), v)$ function call

$$\llbracket v \rrbracket^\# \supseteq \llbracket k \rrbracket^\# \circ \llbracket u \rrbracket^\#,$$

$k = (u, lab, v)$ normal edge

$$\llbracket f \rrbracket^\# \supseteq \llbracket stop_f \rrbracket^\#$$

with $\llbracket v \rrbracket^\# : \mathbb{D} \rightarrow \mathbb{D}$ describes effects of all same-level computations from the beginning of f to program point v

Abstract Effects of Function f

right side of inequalities is monotone

→ system of inequalities has smallest solution

$\llbracket \cdot \rrbracket^\#$ be the smallest solution of the system of inequalities

1. $\llbracket v \rrbracket^\# \sqsupseteq \llbracket \pi \rrbracket^\#$

\forall same-level computations π from $start_f$ to v

2. $\llbracket f \rrbracket^\# \sqsupseteq \llbracket \pi \rrbracket^\#$

\forall same-level computations π of f

⇒ every solution of the system of inequalities can be used to approximate the abstract effect of a function call

Problems

- ▶ not always closed representation of monotone functions in the system of inequalities
- ▶ infinite ascending chains

⇒ in the case of copy propagation:

- ▶ complete lattice $\mathbb{V} = \{V \subseteq \text{Vars.} \mid x \in V\}$ is **atomic**
- ▶ edge effects are **distributive** (\rightarrow monotone)
- ▶ no infinite ascending chains: only finitely many variables

\rightarrow compact representation of monotone functions exists:

$$g(V) = b \sqcup \bigsqcup \{h(a) \mid a \in A \wedge a \sqsubseteq V\}$$

with $h : A \rightarrow \mathbb{V}, b \in \mathbb{V}, A \subseteq \mathbb{V}$

Abstract Effects of Function f

ex. Copy Propagation

```
main() {  
  A <- M[0];  
  if (A) print();  
  b <- A;  
  work();  
  ret <- 1-ret;  
}
```

```
work() {  
  A <- b;  
  if (A) work();  
  ret <- A;  
}
```

Abstract Effects of Function f

ex. Copy Propagation

$Vars_{\bullet} = \{A, b, ret, \bullet\}$, investigate b

\Rightarrow

$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\}$$

$$:= g_1(C)$$

$$\llbracket ret \leftarrow A \rrbracket^{\#} C = (A \in C) ? (C \cup \{ret\}) : (C \setminus \{ret\})$$

$$:= g_2(C)$$

Abstract Effects of Function f

ex. Copy Propagation

represent edge effects g_1, g_2 by $(h_1, \text{Vars}_\bullet)$, $(h_2, \text{Vars}_\bullet)$:
(enumerable for finite lattice)

	h_1	h_2
$\{b, \text{ret}, \bullet\}$	Vars_\bullet	$\{b, \bullet\}$
$\{b, A, \bullet\}$	$\{b, A, \bullet\}$	Vars_\bullet
$\{b, A, \text{ret}\}$	$\{b, A, \text{ret}\}$	$\{b, A, \text{ret}\}$

$$g_1(C) = C \cup \{A\}$$

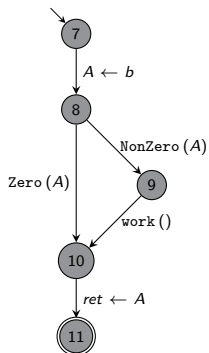
$$g_2(C) = (A \in C) ? (C \cup \{\text{ret}\}) : (C \setminus \{\text{ret}\})$$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

work():



$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

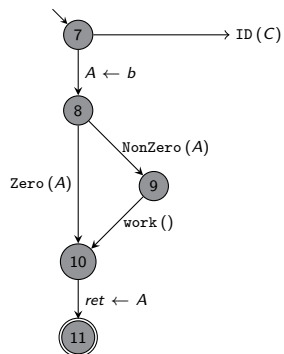
$$\llbracket ret \leftarrow A \rrbracket^{\#} C = (A \in C) ? (C \cup \{ret\}) : (C \setminus \{ret\}) := g_2(C)$$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

$work()$:



$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

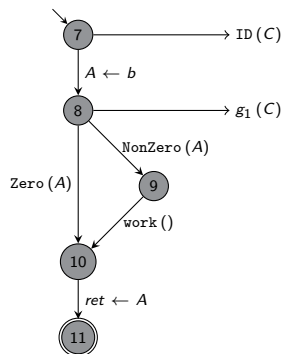
$$\llbracket ret \leftarrow A \rrbracket^{\#} C = (A \in C) ? (C \cup \{ret\}) : (C \setminus \{ret\}) := g_2(C)$$

Abstract Effects of Function f

ex. Copy Propagation

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$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

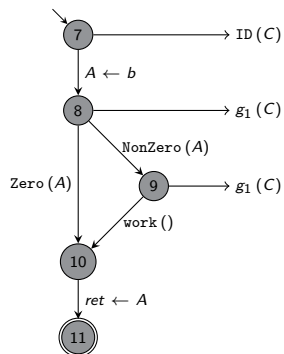
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Abstract Effects of Function f

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$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

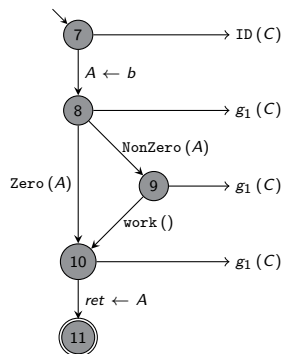
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$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

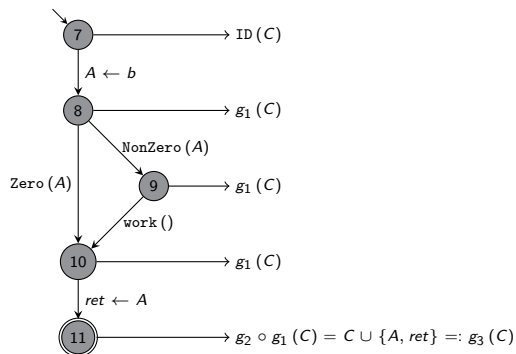
$$\llbracket \text{ret} \leftarrow A \rrbracket^{\#} C = (A \in C) ? (C \cup \{\text{ret}\}) : (C \setminus \{\text{ret}\}) := g_2(C)$$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

`work ()`:



$$\llbracket A \leftarrow b \rrbracket^{\#} C = C \cup \{A\} := g_1(C)$$

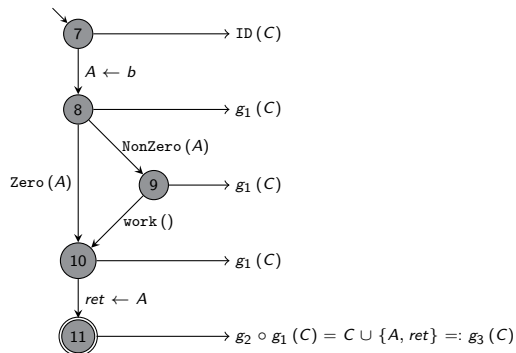
$$\llbracket ret \leftarrow A \rrbracket^{\#} C = (A \in C) ? (C \cup \{ret\}) : (C \setminus \{ret\}) := g_2(C)$$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

`work ()`:



first approximation for call of `work`:

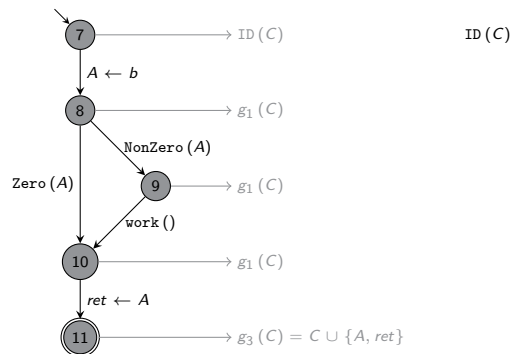
$$\text{combine}^\# (C, g_3 (\text{enter}^\# (C))) = C \cup \{ret\} := g_4 (C)$$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

`work ()`:



first approximation for call of `work`:

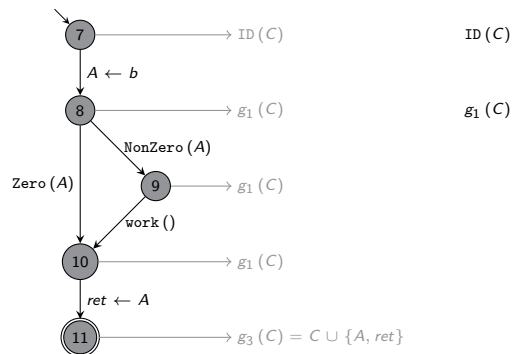
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`work ()`:



first approximation for call of `work`:

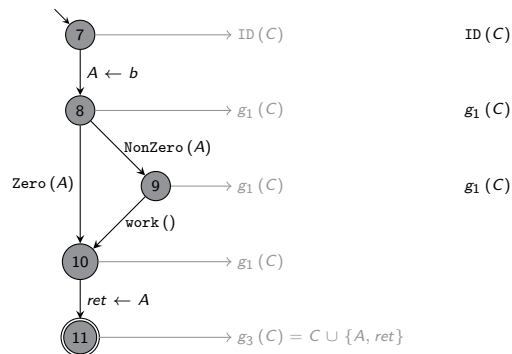
$$\text{combine}^\# (C, g_3 (\text{enter}^\# (C))) = C \cup \{ret\} := g_4 (C)$$

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`work ()`:



first approximation for call of `work`:

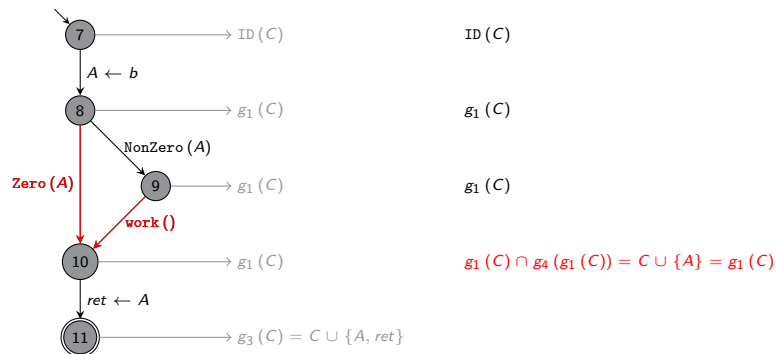
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`work ()`:



first approximation for call of `work`:

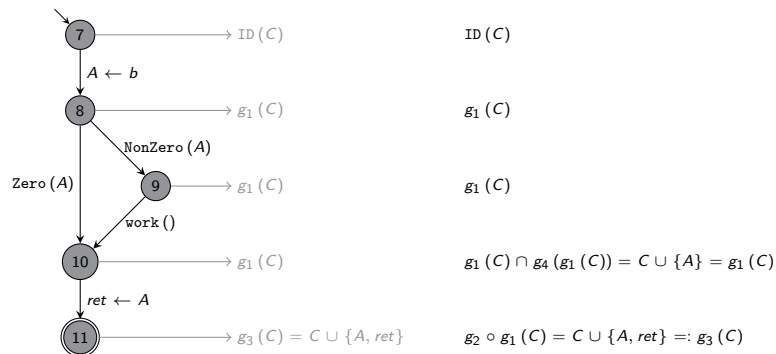
$combine^\#(C, g_3(enter^\#(C))) = C \cup \{ret\} := g_4(C)$

Abstract Effects of Function f

ex. Copy Propagation

C : set of variables that initially have the same value as b

`work ()`:



fixpoint reached after first iteration:

`work` approximated by $g_4(C) = C \cup \{ret\}$

Coincidence Theoreme

- ▶ \exists same-level computation from $start_f$ to $v \forall v \in f$,
edge effects and transformation $H^\#$ are distributive

$$\Rightarrow \llbracket v \rrbracket^\# = \bigsqcup \{ \llbracket \pi \rrbracket^\# \mid \pi \in \mathcal{T}_v \} \forall v \in f$$

(\mathcal{T}_v ...set of all same-level computations from $start_f$ to v)

- ▶ $enter^\#$ distributive, $combine^\#(x_1, x_2) = h_1(x_1) \sqcup h_2(x_2)$
 $\Rightarrow H^\#$ distributive: $H^\#(\bigsqcup \mathcal{F}) = \bigsqcup \{ H^\#(g) \mid g \in \mathcal{F} \}$

Coincidence Theoreme

ex. Copy Propagation

$$\text{enter}^\# V = V \cap \text{Glob} \cup \{\bullet\}$$

→ distributive

$$\begin{aligned} \text{combine}^\# (V_1, V_2) &= (V_2 \cap \text{Glob}) \cup (\bullet \in V_2)?V_1 \cap \text{Loc} : \emptyset \\ &= ((V_1 \cap \text{Loc}_\bullet) \cup \text{Glob}) \cap \\ &\quad ((V_2 \cap \text{Glob}) \cup \text{Loc}_\bullet) \cap \\ &\quad (\text{Glob} \cup (\bullet \in V_2)?\text{Vars}_\bullet : \text{Glob}) \end{aligned}$$

→ intersection of distributive functions of first and second argument

⇒ coincidence theoreme holds for copy propagation

Interprocedural Reachability

effects $\llbracket f \rrbracket^\#$ are approximated

→ compute for program point u a safe approximation of property $\mathcal{D}[u]$ that holds when u is reached

$$\mathcal{D}[start_{main}] \sqsupseteq \text{enter}^\#(d_0)$$

$$\mathcal{D}[start_f] \sqsupseteq \text{enter}^\#(\mathcal{D}[u]),$$

$(u, f(), v)$ calling edge

$$\mathcal{D}[v] \sqsupseteq \text{combine}^\#(\mathcal{D}[u], \llbracket f \rrbracket^\#(\text{enter}^\#(\mathcal{D}[u]))),$$

$(u, f(), v)$ calling edge

$$\mathcal{D}[v] \sqsupseteq \llbracket k \rrbracket^\#(\mathcal{D}[u]),$$

$k = (u, lab, v)$ normal edge

Interprocedural Reachability

smallest solution for system of inequalities exists because of monotonicity and it holds:

$$\mathcal{D}[v] \supseteq \llbracket \pi \rrbracket^\# d_0$$

for all paths that reach v

($d_0 \in \mathbb{D}$: information at the beginning of program execution)

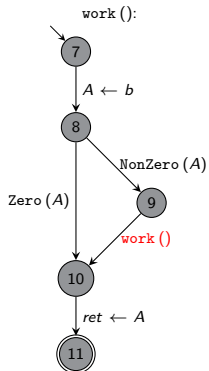
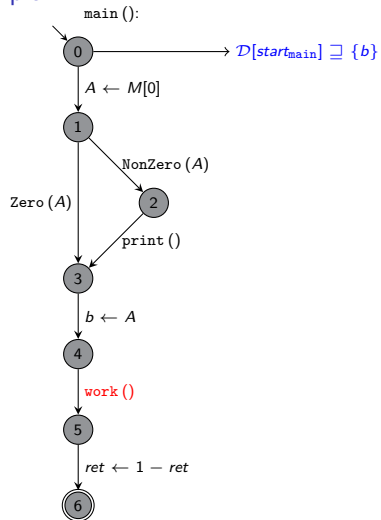
for distributive abstract edge effects and distributive transformation $H^\#$:

$$\mathcal{D}[v] = \bigsqcup \{ \llbracket \pi \rrbracket^\# d_0 \mid \pi \in \mathcal{P}_v \}$$

with \mathcal{P}_v ... set of all paths that reach v

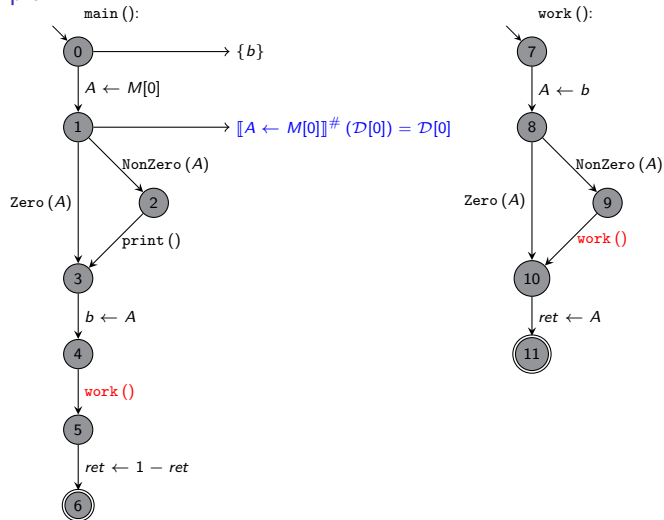
Interprocedural Reachability

example



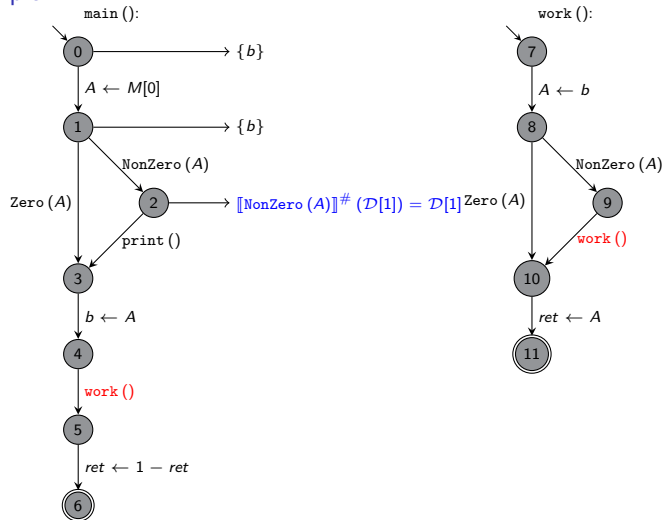
Interprocedural Reachability

example



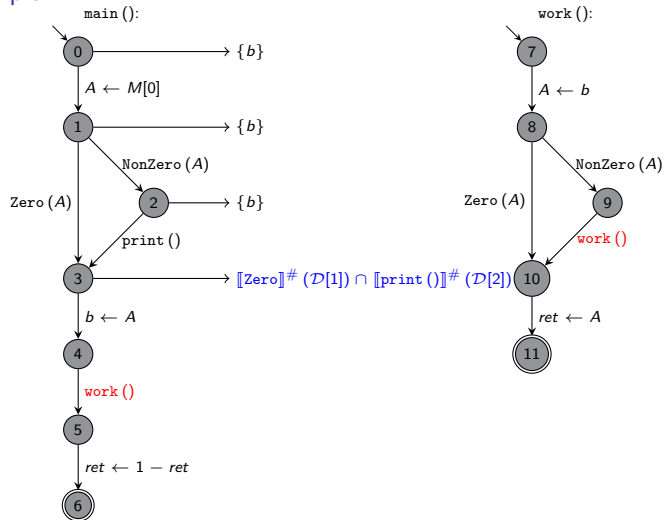
Interprocedural Reachability

example



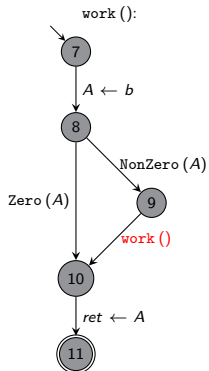
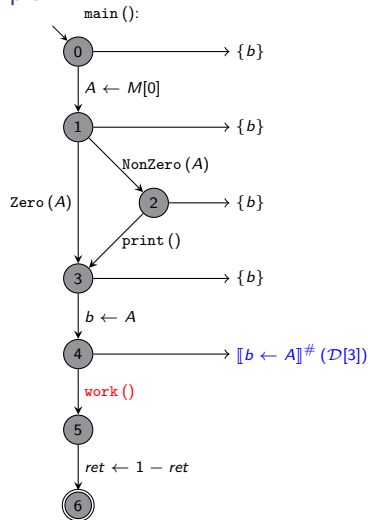
Interprocedural Reachability

example



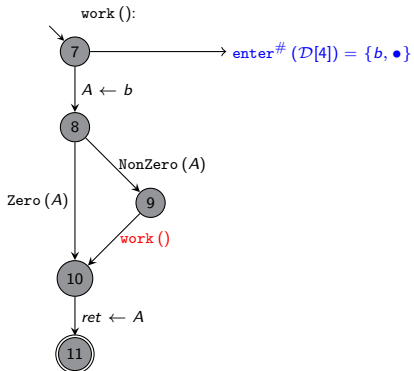
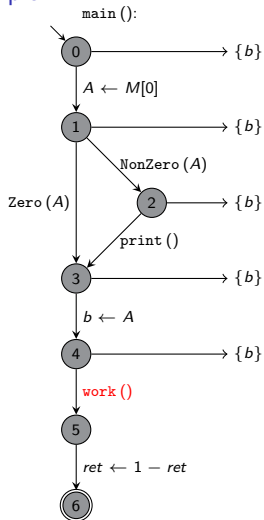
Interprocedural Reachability

example



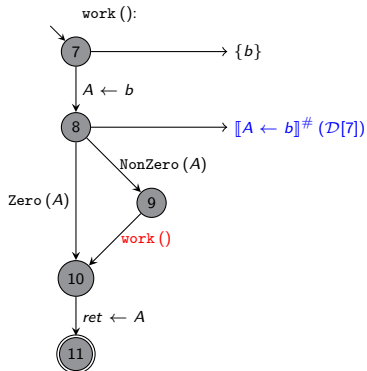
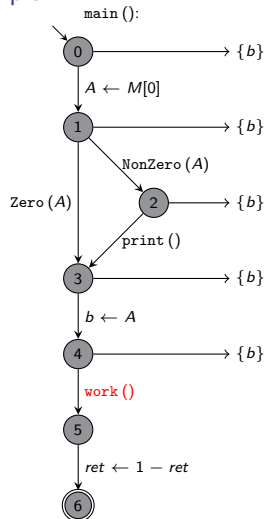
Interprocedural Reachability

example



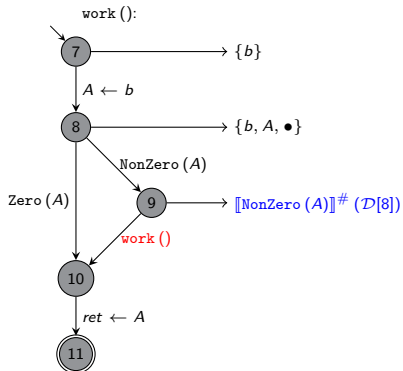
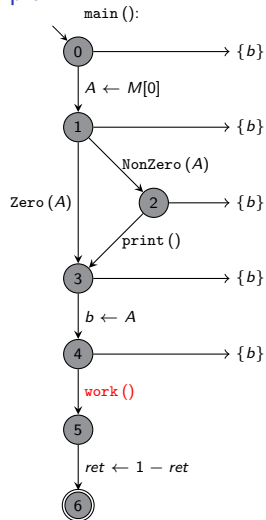
Interprocedural Reachability

example



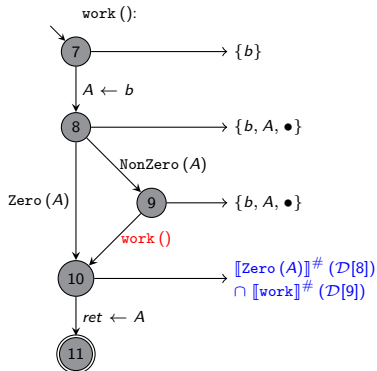
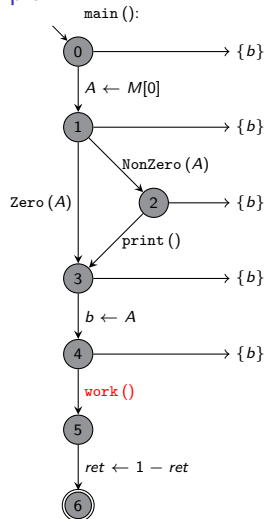
Interprocedural Reachability

example



Interprocedural Reachability

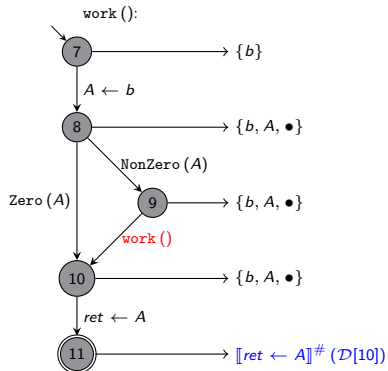
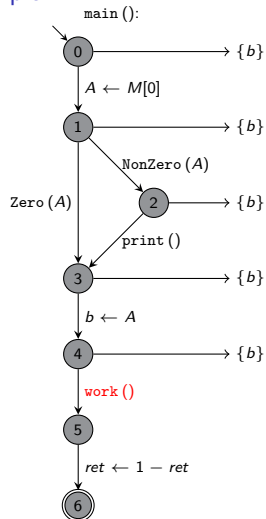
example



work approximated by
 $g_4(C) = C \cup \{ret\}$

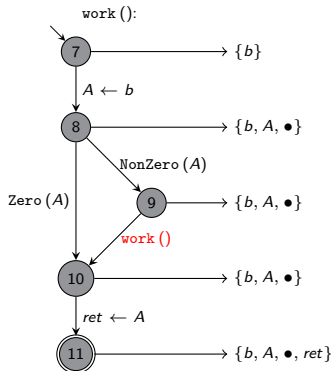
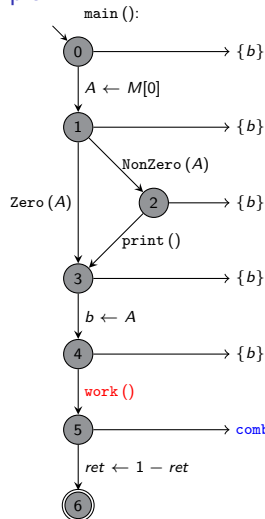
Interprocedural Reachability

example



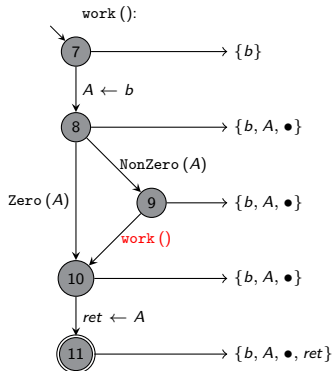
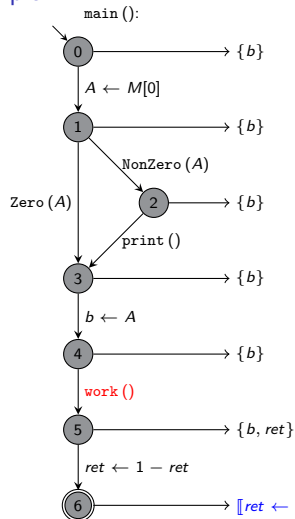
Interprocedural Reachability

example



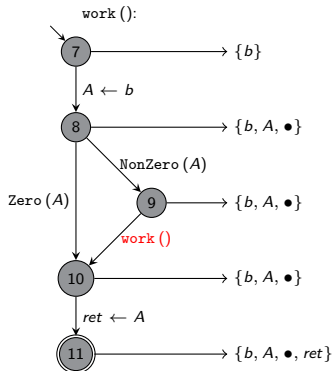
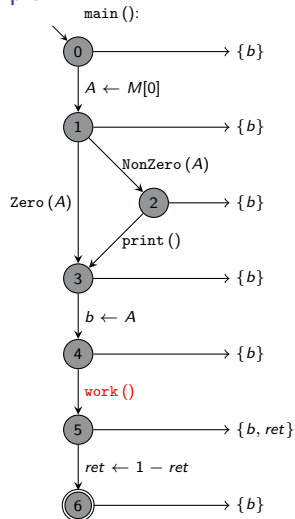
Interprocedural Reachability

example



Interprocedural Reachability

example



⇒ within the call of `work`:
 global var. `b` may be
 used instead of local var. `A`

Introduction

Simple Interprocedural Optimisations

Operational Semantic

Functional Approach

Related Approaches

Summary

Demand-Driven Interprocedural Analysis

sometimes: lattice not finite, functions cannot be represented in a compact form

→ only analyse calls in situations that really occur

! this is the case e.g. for **constant propagation**

→ use **local fixpoint algorithm**:

only compute solutions for certain inequalities;

only solve part of the system that is needed therefor

Demand-Driven Interprocedural Analysis

system of inequalities

$$\mathcal{D}[v, a] \sqsupseteq a,$$

v entry point

$$\mathcal{D}[v, a] \sqsupseteq \text{combine}^\# (\mathcal{D}[u, a], \mathcal{D}[f, \text{enter}^\# (\mathcal{D}[u, a])]),$$

$(u, f(), v)$ calling edge

$$\mathcal{D}[v, a] \sqsupseteq \llbracket lab \rrbracket^\# (\mathcal{D}[u, a]),$$

$k = (u, lab, v)$ normal edge

$$\mathcal{D}[f, a] \sqsupseteq \mathcal{D}[\text{stop}_f, a]$$

with $\mathcal{D}[f, a]$... abstract state when reaching program point v
of a function called in abstract state a ($\mathcal{D}[f, a] \sim \llbracket v \rrbracket^\# (a)$)

\Rightarrow compute $\mathcal{D}[\text{main}, \text{enter}^\# (d_0)]$

Demand-Driven Interprocedural Analysis

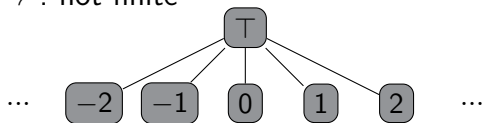
ex. Constant Propagation

Constant Propagation:

move as many computations as possible from runtime to compile time

complete lattice: $\mathbb{D} = (Vars \rightarrow \mathbb{Z}^T)_\perp$

→ ! not finite



$$\text{enter}^\# D = \begin{cases} \perp & D = \perp \\ D \oplus \{A \mapsto T \mid A \text{ local}\} & \text{otherwise} \end{cases}$$

$$\text{combine}^\# (D_1, D_2) = \begin{cases} \perp & D_1 = \perp \vee D_2 = \perp \\ D_1 \oplus \{b \mapsto D_2(b) \mid b \text{ global}\} & \text{otherwise} \end{cases}$$

Constant Propagation

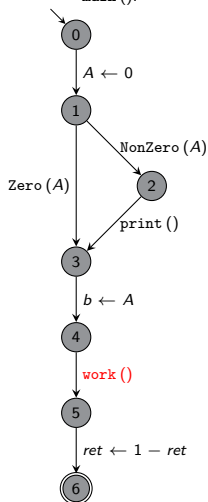
Abstract Edge Effects - intraprocedural

$$\begin{aligned}
 \llbracket ; \rrbracket^{\# D} &= D \\
 \llbracket \text{NonZero}(e) \rrbracket^{\# D} &= \begin{cases} \perp & \text{if } 0 = \llbracket e \rrbracket^{\# D} \\ D & \text{otherwise} \end{cases} \\
 \llbracket \text{Zero}(e) \rrbracket^{\# D} &= \begin{cases} \perp & \text{if } 0 \not\sqsubseteq \llbracket e \rrbracket^{\# D} \\ D & \text{if } 0 \sqsubseteq \llbracket e \rrbracket^{\# D} \end{cases} \\
 \llbracket x \leftarrow e \rrbracket^{\# D} &= D \oplus \{x \mapsto \llbracket e \rrbracket^{\# D}\} \\
 \llbracket x \leftarrow M[e] \rrbracket^{\# D} &= D \oplus \{x \mapsto \top\} \\
 \llbracket M[e_1] \leftarrow e_2 \rrbracket^{\# D} &= D
 \end{aligned}$$

Demand-Driven Interprocedural Analysis

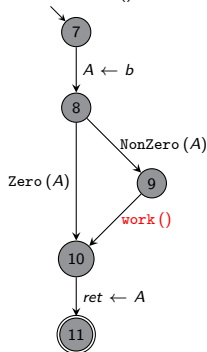
ex. Constant Propagation

$d_0 = \{A \mapsto \top, b \mapsto \top, ret \mapsto \top\}$
 main():



$d_1 = \{A \mapsto \top, b \mapsto 0, ret \mapsto \top\}$

work():



	A	b	ret
0, d_0	\top	\top	\top
1, d_0	0	\top	\top
2, d_0		\perp	
3, d_0	0	\top	\top
4, d_0	0	0	\top
7, d_1	\top	0	\top
8, d_1	0	0	\top
9, d_1		\perp	
10, d_1	0	0	\top
11, d_1	0	0	0
5, d_0	0	0	0
6, d_0	0	0	1
main, d_0	0	0	1

Call-String-Approach

- compute set of all reachable call stacks
- ! restrict call stacks to fixed size d
- (complexity increases with depth)

here: call stack of depth 0

- function call as unconditional jump

Call-String-Approach

system of inequalities

$$\mathcal{D}[start_{\text{main}}] \sqsupseteq \text{enter}^\#(d_0)$$

$$\mathcal{D}[start_{\text{f}}] \sqsupseteq \text{enter}^\#(\mathcal{D}[u]),$$

$(u, \text{f}(), v)$ calling edge

$$\mathcal{D}[v] \sqsupseteq \text{combine}^\#(\mathcal{D}[u], \mathcal{D}[v]),$$

$(u, \text{f}(), v)$ calling edge

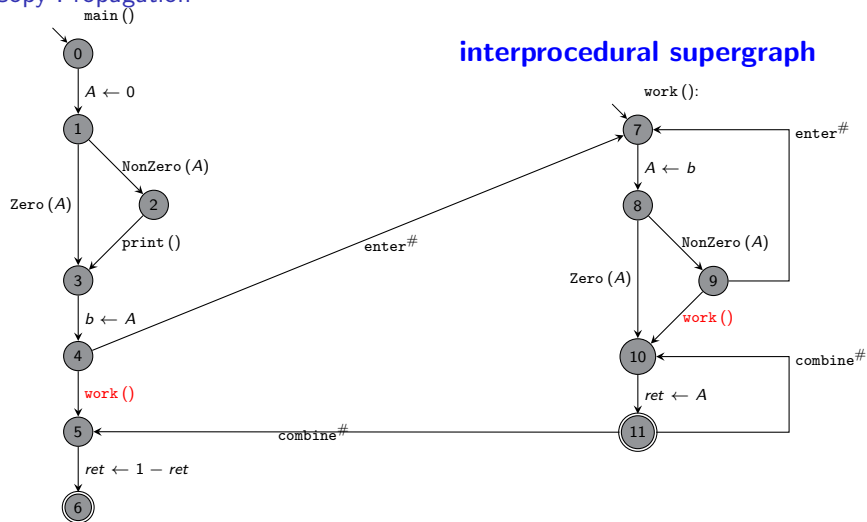
$$\mathcal{D}[v] \sqsupseteq \llbracket lab \rrbracket^\#(\mathcal{D}[u]),$$

$k = (u, lab, v)$ normal edge

$$\mathcal{D}[\text{f}] \sqsupseteq \mathcal{D}[stop_{\text{f}}]$$

Call-String-Approach

ex. Copy Propagation



Call-String-Approach

ex. Copy Propagation

$$\mathcal{D}[5] \sqsubseteq \text{combine}^\# (\mathcal{D}[4], \mathcal{D}[\text{work}])$$
$$\mathcal{D}[7] \sqsubseteq \text{enter}^\# (\mathcal{D}[4])$$
$$\mathcal{D}[7] \sqsubseteq \text{enter}^\# (\mathcal{D}[9])$$
$$\mathcal{D}[10] \sqsubseteq \text{combine}^\# (\mathcal{D}[9], \mathcal{D}[\text{work}])$$

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Summary

- ▶ Interprocedural Analysis is an extension of intraprocedural analysis which takes into account the calling context of functions.
- ▶ Interprocedural Analysis is more demanding than intraprocedural analysis, but yields more precise results.
- ▶ **Functional Approach:**
approximate abstract effect of function call by solving system of inequalities describing the edge effects within the function
- ▶ lattice of possible analysis solutions has to fulfill certain properties to ensure that the analysis terminates