

Lecture 19: 3 April, 2025

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Data Mining and Machine Learning
January–April 2025

Support Vector Machines

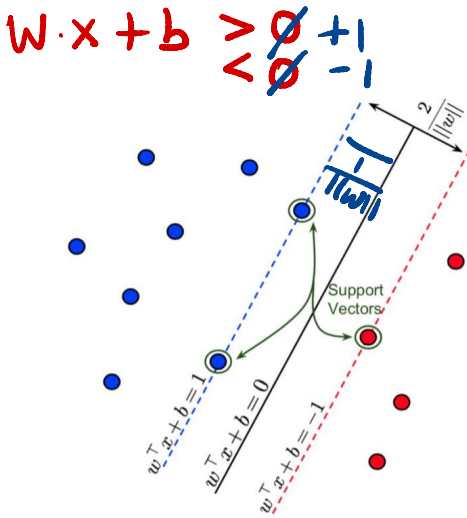
$$\text{Minimize } \frac{|w|}{2}$$

Subject to

$$w_1 x_1^i + w_2 x_2^i + \cdots w_n x_n^i + b > 1, \text{ if } y_i = 1$$

$$w_1 x_1^i + w_2 x_2^i + \cdots w_n x_n^i + b < -1, \text{ if } y_i = -1$$

- The constraints are linear
- The objective function is not linear
$$|w| = \sqrt{w_1^2 + w_2^2 + \cdots + w_n^2}$$
- This is a **quadratic optimization problem**, not linear programming

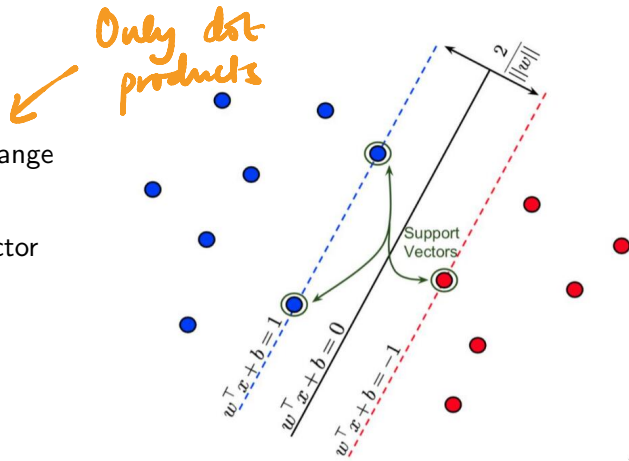


Support Vector Machines

- Convex optimization theory
- Can be solved using computational techniques
- Solution expressed in terms of Lagrange multipliers $\alpha_1, \alpha_2, \dots, \alpha_N$
- α_i is non-zero iff x_i is a support vector
- Final classifier for new input z

$$\text{sign} \left[\sum_{i \in \text{sv}} y_i \alpha_i (\underbrace{x_i \cdot z}_{=}) + b \right]$$

- sv is set of support vectors



Soft margin optimization

$$\text{Minimize } \frac{\|w\|}{2} + \sum_{i=1}^N \xi_i^2$$

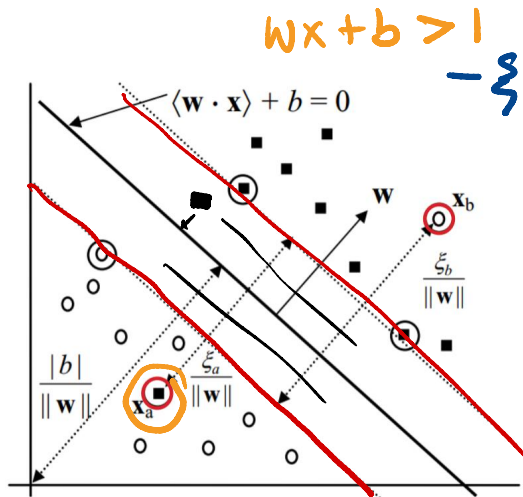
Subject to

$$\xi_i \geq 0$$

$$w \cdot x_i + b > 1 - \xi_i, \text{ if } y_i = 1$$

$$w \cdot x_i + b < -1 + \xi_i, \text{ if } y_i = -1$$

- Constraints include requirement that error terms are non-negative
- Again the objective function is quadratic

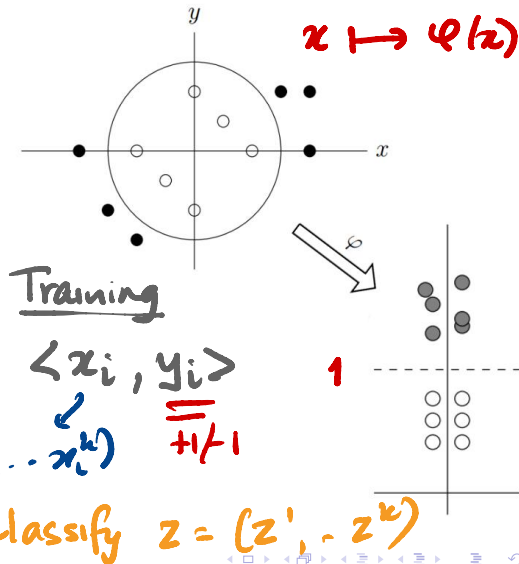


Kernels

- K is a **kernel** for transformation φ if
 $K(x, z) = \varphi(x) \cdot \varphi(z)$
- If we have a kernel, we don't need to explicitly compute transformed points
- All dot products can be computed implicitly using the kernel on original data points

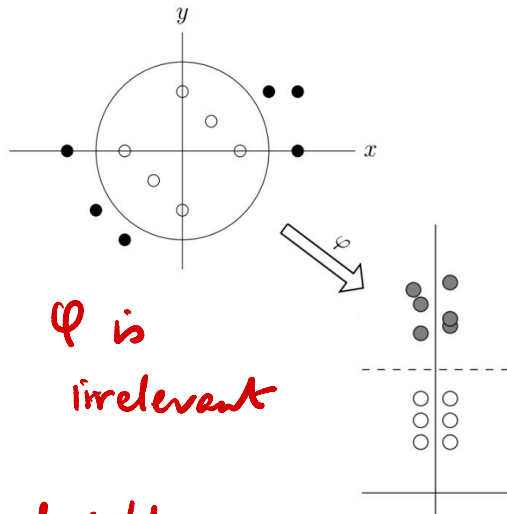
$$\sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i,j=1}^N y_i y_j \alpha_i \alpha_j \underbrace{\varphi(x_i) \cdot \varphi(x_j)}_{\text{Dual}}$$

$$\text{sign} \left[\sum_{i \in \text{sv}} y_i \alpha_i \underbrace{(\varphi(x_i) \cdot \varphi(z))}_{\text{Solve}} + b \right]$$



Kernels

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$$\sum_{i=1}^N \alpha_i - \frac{1}{2} \sum_{i,j=1}^N y_i y_j \alpha_i \alpha_j \underline{K(x_i, x_j)}$$

↙ Dual optimum

φ is irrelevant

$$\text{sign} \left[\sum_{i \in \text{sv}} y_i \alpha_i \underline{K(x_i, z)} + b \right]$$

← Dual solution

Known kernels

- Fortunately, there are many known kernels

- Polynomial kernels

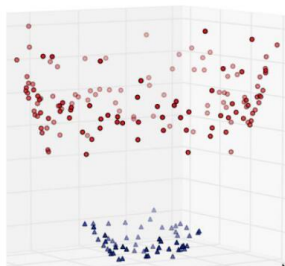
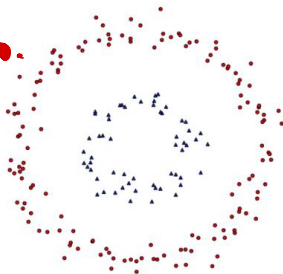
$$K(x, z) = (1 + x \cdot z)^k$$

- Any $K(x, z)$ representing a similarity measure

- Gaussian radial basis function — similarity based on inverse exponential distance

$$K(x, z) = e^{-c|x-z|^2}$$

any real no.
 $(r + x \cdot z)^k$



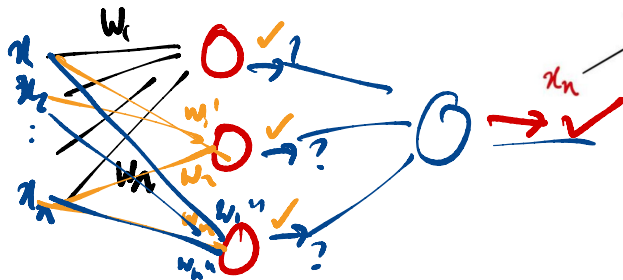
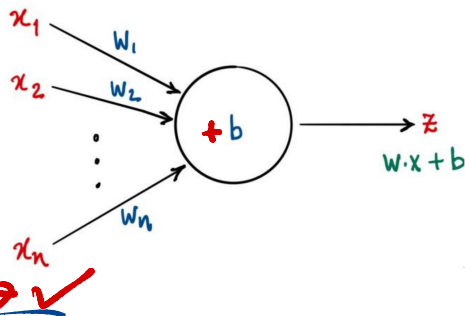
Linear separators and Perceptrons

$$x = \langle x_1, x_2, \dots, x_n \rangle$$

- Perceptrons define linear separators $w \cdot x + b$

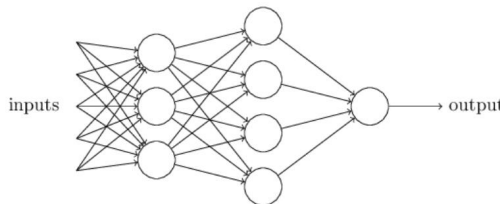
- $w \cdot x + b > 0$, classify Yes (+1)

- $w \cdot x + b < 0$, classify No (-1)



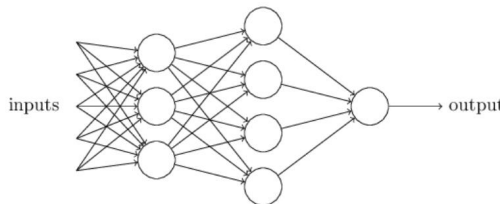
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- What if we cascade perceptrons?



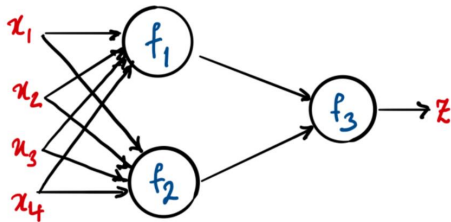
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- Result is still a linear separator



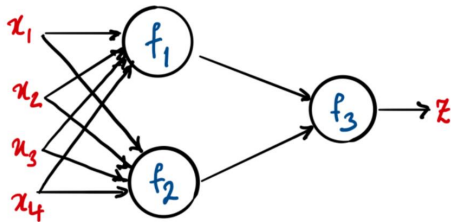
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 - $f_1 = w_1 \cdot x + b_1, f_2 = w_2 \cdot x + b_2$



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 - $f_3 = w_3 \cdot \langle f_1, f_2 \rangle + b_3$



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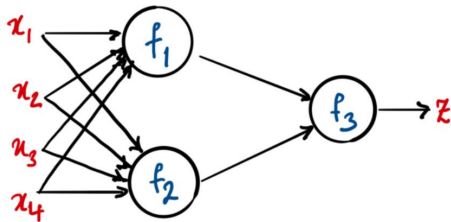
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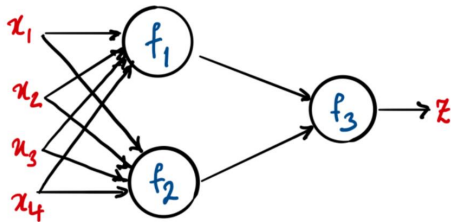
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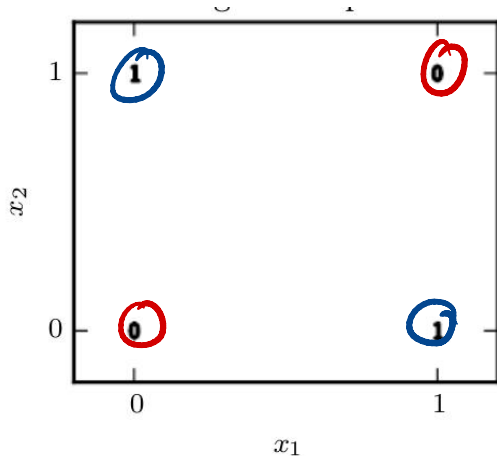
- $f_3 = w_3 \cdot \langle w_1 \cdot x + b_1, w_2 \cdot x + b_2 \rangle + b_3$

- $f_3 = \sum_{i=1}^4 (w_{31} w_{1i} + w_{32} w_{2i}) \cdot x_i + (w_{31} b_1 + w_{32} b_2 + b_3)$



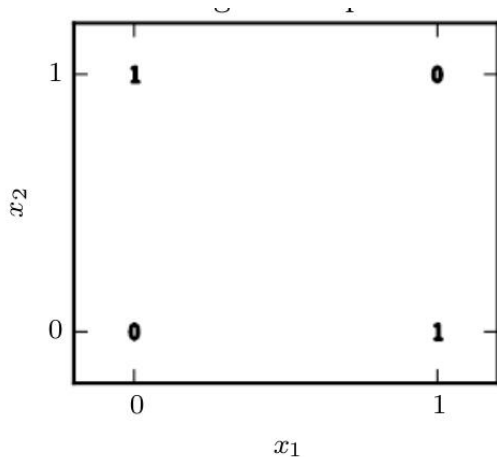
Limits of linearity

- Cannot compute *exclusive-or* (XOR)
- $XOR(x_1, x_2)$ is true if exactly one of x_1, x_2 is true (not both)



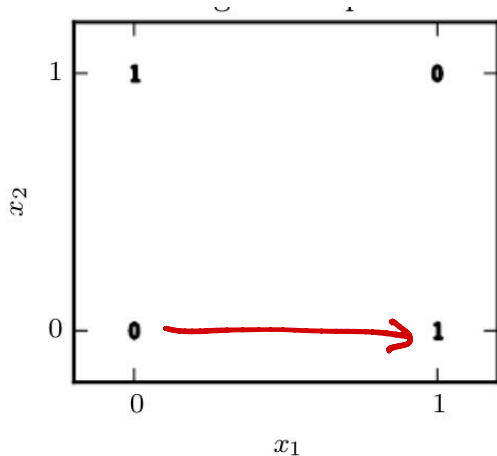
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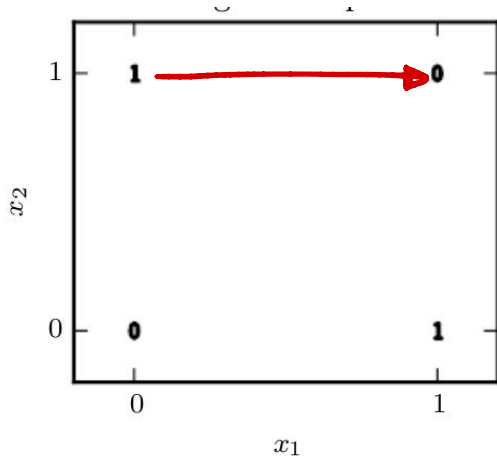
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- $x_2 = 0$: As x_1 goes from 0 to 1, output goes from 0 to 1, so $u > 0$



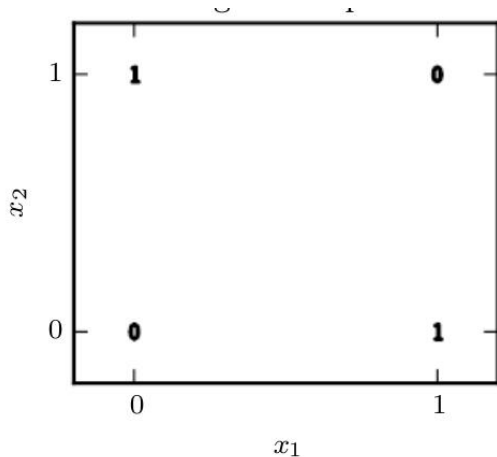
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- Observed by Minsky and Papert, 1969, first “AI Winter”

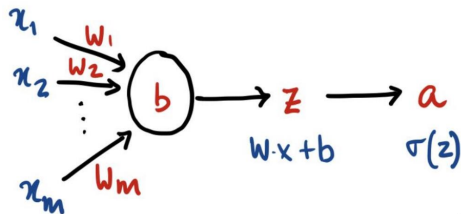
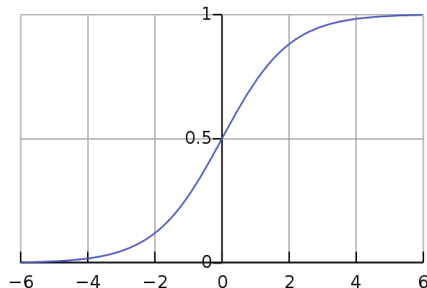


Non-linear activation

- Transform linear output z through a non-linear activation function
- Sigmoid function $\frac{1}{1 + e^{-z}}$

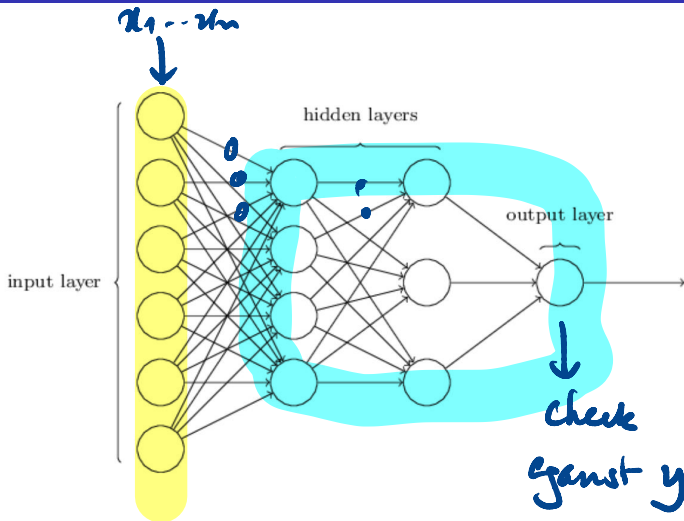
$a = \text{activation}$

$z = \text{linear output}$



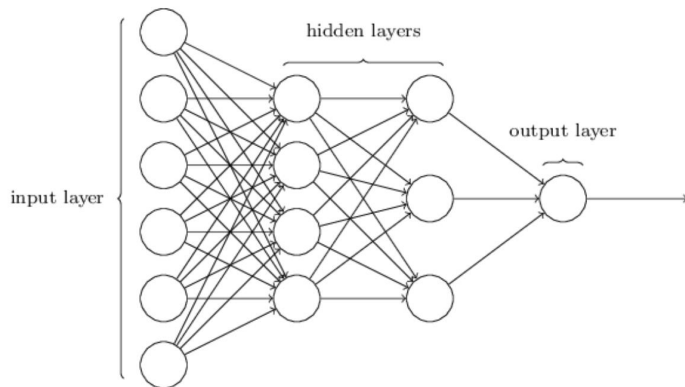
Structure of a neural network

- Acyclic
- Input layer, hidden layers, output layer



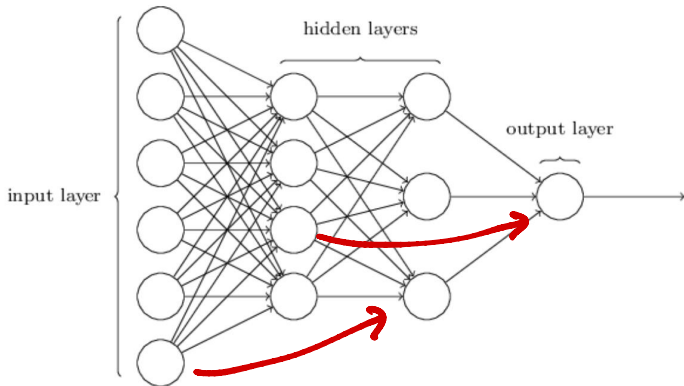
Structure of a neural network

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- Assumptions



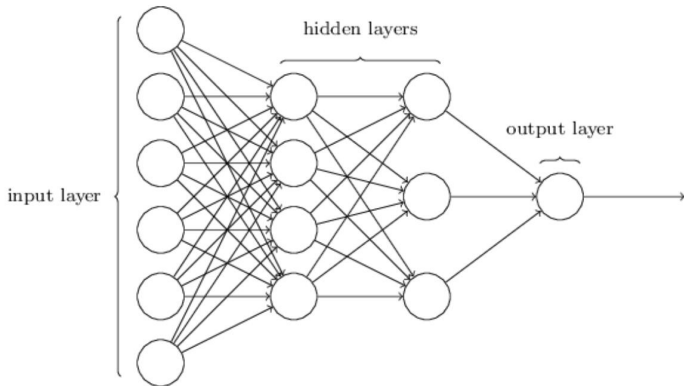
Structure of a neural network

- Acyclic
- Input layer, hidden layers, output layer
- Assumptions
 - Hidden neurons are arranged in layers



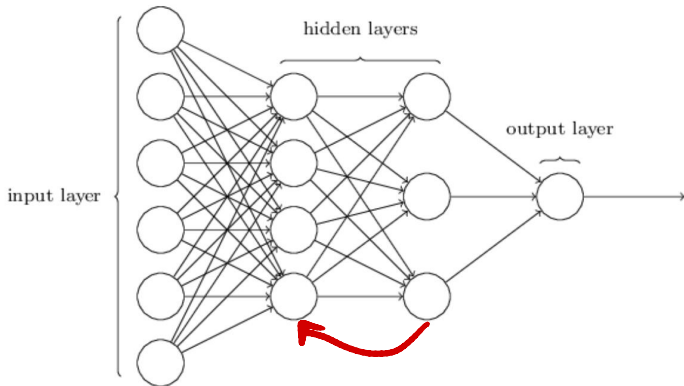
Structure of a neural network

- Acyclic
- Input layer, hidden layers, output layer
- Assumptions
 - Hidden neurons are arranged in layers
 - Each layer is fully connected to the next



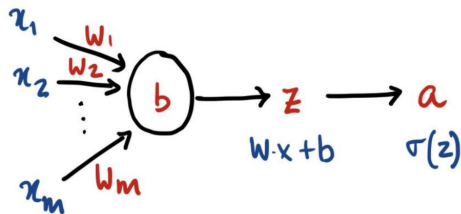
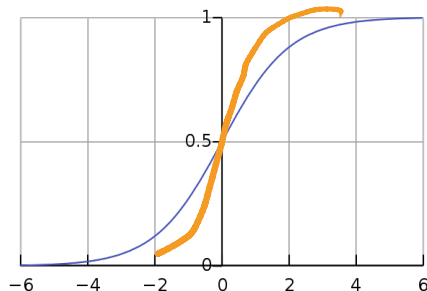
Structure of a neural network

- Acyclic
- Input layer, hidden layers, output layer
- Assumptions
 - Hidden neurons are arranged in layers
 - Each layer is fully connected to the next
 - Set weight to zero to remove an edge

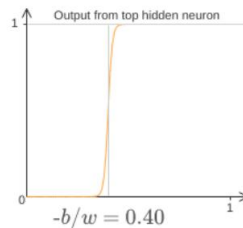
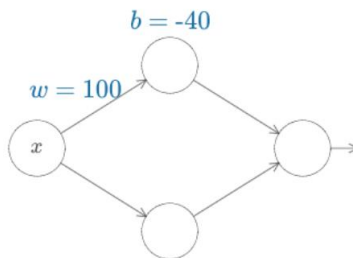


Non-linear activation

- Transform linear output z through a non-linear activation function
- Sigmoid function $\frac{1}{1 + e^{-z}}$
- Step is at $z = 0$
 - $z = wx + b$, so step is at $x = -b/w$
 - Increasing w makes step steeper
 - Shift step by adjusting b

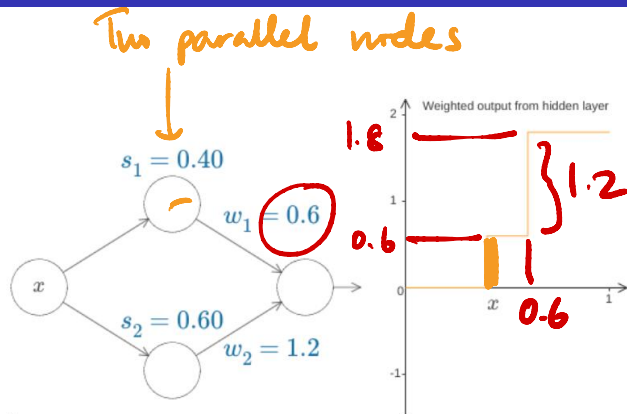


- Create a step at $x = -b/w$
 - Use s to denote $-b/w$
 - Step position



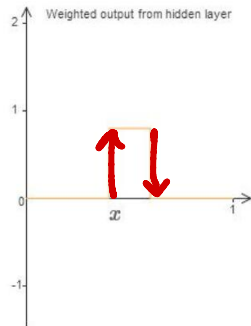
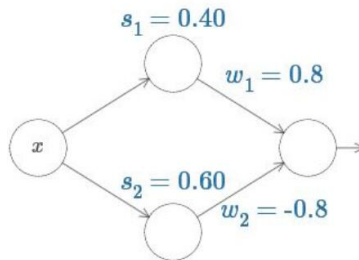
Universality

- Create a step at $x = -b/w$
 - Use s to denote $-b/w$
 - Step position
- Cascade steps



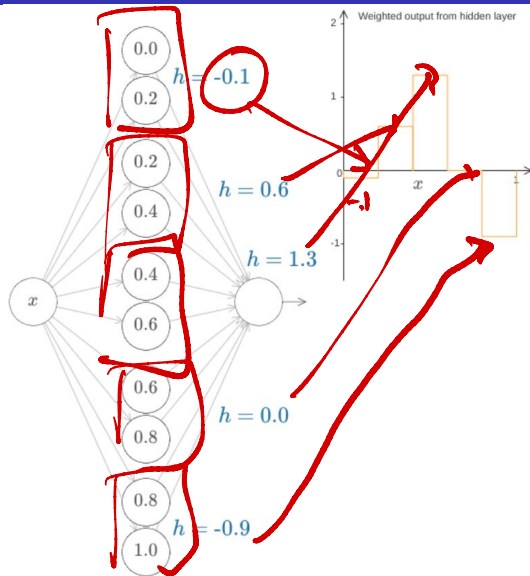
Universality

- Create a step at $x = -b/w$
 - Use s to denote $-b/w$
 - Step position
- Cascade steps
- Subtract steps to create a box



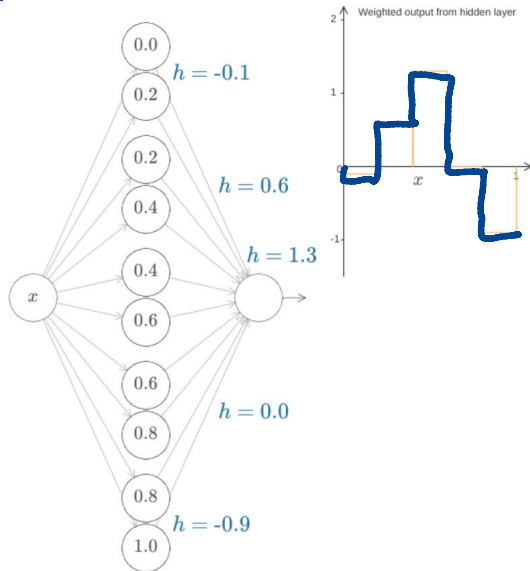
Universality

- Create a step at $x = -b/w$
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 - Step position
- Cascade steps
- Subtract steps to create a box
- Create many boxes



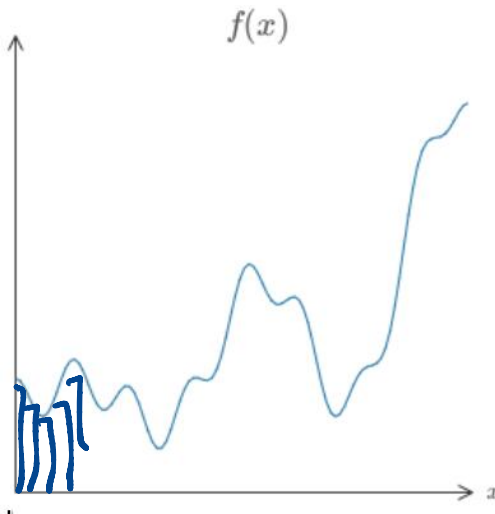
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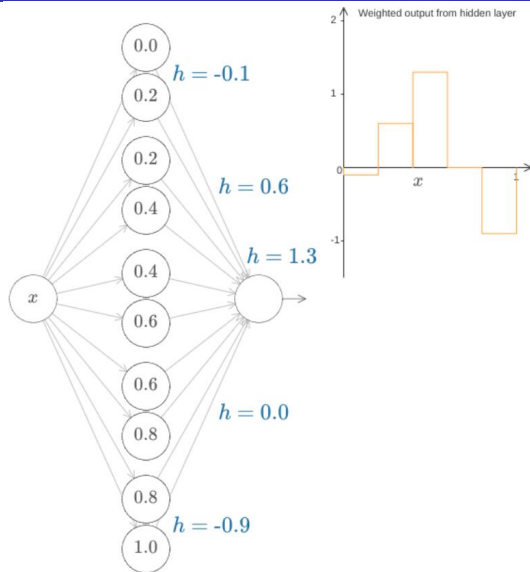
Universality

- Create a step at $x = -b/w$
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 - Step position
- Cascade steps
- Subtract steps to create a box
- Create many boxes
- Approximate any function



Universality

- Create a step at $x = -b/w$
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- Cascade steps
- Subtract steps to create a box
- Create many boxes
- Approximate any function
- Need only one hidden layer!

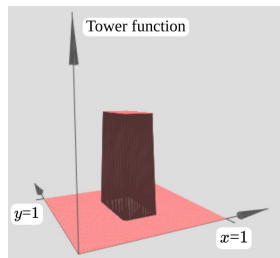


Non-linear activation

- With non-linear activation, network of neurons can approximate any function

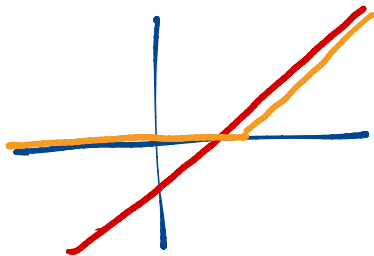
Non-linear activation

- With non-linear activation, network of neurons can approximate any function
 - Can build “rectangular” blocks



Non-linear activation

- With non-linear activation, network of neurons can approximate any function
 - Can build “rectangular” blocks
 - Combine blocks to capture any classification boundary



Rectified
Linear Unit
 ReLU

