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Soft margin optimization

 $w \cdot x_i + b > 1 - \xi_i$, if $y_i = 1$ $w \cdot x_i + b < -1 + \xi_i$, if $y_i = 1$

- Constraints include requirement that error terms are non-negative
- Again the objective function is quadratic



Dualization



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Soft margin optimization

- Can again be solved using convex optimization theory
- Form of the solution turns out to be the same as the hard margin case
 - Expression in terms of Lagrange multipliers α_i

sign $\sum_{i \in sv} y_i \alpha_i (x_i \cdot z) + b$

Only terms corresponding to support vectors are actively used



The non-linear case

- How do we deal with datasets where the separator is a complex shape?
- Geometrically transform the data
 - Typically, add dimensions
- For instance, if we can "lift" one class, we can find a planar separator between levels





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 $\varphi: (x, y) \mapsto (x, y, x^2 + y^2)$



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- Transformation
 - $\varphi:(x,y)\mapsto(x,y,x^2+y^2)$
- Points inside circle lie below z = 1
- Point outside circle lifted above z = 1



SVM after transformation

SVM in original space

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i (x_i \cdot z) + b\right]$$



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After transformation

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i (\varphi(x_i) \cdot \varphi(z)) + b\right]$$



SVM after transformation

SVM in original space

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- After transformation $\operatorname{sign}\left[\sum_{i \in sv} y_i \alpha_i (\varphi(x_i) \cdot \varphi(z)) + b\right]$
- All we need to know is how to compute dot products in transformed space



Dot products



Dot products



Dot products

Consider the transformation

 $\varphi:(x_1,x_2)\mapsto (1,\sqrt{2}x_1,\sqrt{2}x_2,x_1^2,\sqrt{2}x_1x_2,x$

Dot product in transformed space

$$\begin{aligned} \varphi(x) \cdot \varphi(z) &= 1 + 2x_1z_1 + 2x_2z_2 + x_1^2z \\ &+ 2x_1x_2z_1z_2 + x_2^2z_2^2 \\ &= (1 + x_1z_1 + x_2z_2)^2 \end{aligned}$$

 Transformed dot product can be expressed in terms of original inputs

$$\varphi(x)\cdot\varphi(z)=K(x,z)=(1+x_1z_1+x_2z_2)^2$$



• *K* is a kernel for transformation φ if $K(x, z) = \varphi(x) \cdot \varphi(z)$



- K is a kernel for transformation φ if
 K(x, z) = φ(x) ⋅ φ(z)
- If we have a kernel, we don't need to explicitly compute transformed points
- All dot products can be computed implicitly using the kernel on original data points

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i \left(\varphi(x_i) \cdot \varphi(z)\right) + b\right]$$



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sign $\sum_{i \in sv} y_i \alpha_i K(x_i, z) + b$

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Also

 If we know K is a kernel for some transformation φ, we can blindly use K without even knowing what φ looks like!

K(xi,xj) in training K(n, 2) for classification



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- When is a function a valid kernel?



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- Has been studied in mathematics Mercer's Theorem
 - Criteria are non-constructive



- If we know K is a kernel for some transformation φ, we can blindly use K without even knowing what φ looks like!
- When is a function a valid kernel?
- Has been studied in mathematics Mercer's Theorem
 - Criteria are non-constructive
- Can define sufficient conditions from linear algebra





• Entries are values $K(x_i, x_j)$



 Kernel over training data x₁, x₂,..., x_N can be represented as a gram matrix

- Entries are values $K(x_i, x_j)$
- Gram matrix should be positive semi-definite for all x₁, x₂,..., x_N



Fortunately, there are many known kernels



- Fortunately, there are many known kernels
- Polynomial kernels

 $K(x,z) = (1+x \cdot z)^k$

 $(1 + x_1 z_1 + x_2 z_2)^2$ $(1 + x_2 z_2)^2$





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- Any K(x, z) representing a similarity measure
- Gaussian radial basis function similarity based on inverse exponential distance

$$K(x,z) = e^{-c|x-z|^2}$$



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Till about 2010