### Lecture 17: 14 March, 2023

Madhavan Mukund https://www.cmi.ac.in/~madhavan

Data Mining and Machine Learning January–April 2023

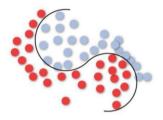
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## A geometric view of supervised learning

- Think of data as points in space
- Find a separating curve (surface)

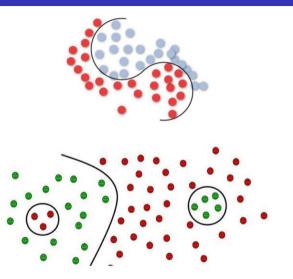
# A geometric view of supervised learning

- Think of data as points in space
- Find a separating curve (surface)
- Separable case
  - Each class is a connected region
  - A single curve can separate them

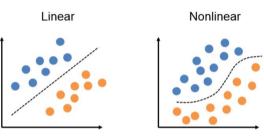


# A geometric view of supervised learning

- Think of data as points in space
- Find a separating curve (surface)
- Separable case
  - Each class is a connected region
  - A single curve can separate them
- More complex scenario
  - Classes form multiple connected regions
  - Need multiple separators

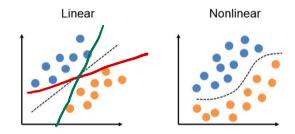


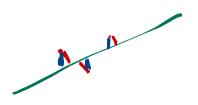
Simplest case — linearly separable data



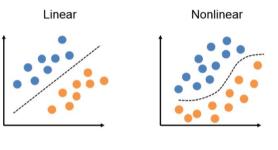
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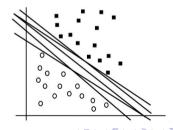
- Simplest case linearly separable data
- Dual of linear regression
  - Find a line that passes close to a set of points
  - Find a line that separates the two sets of points



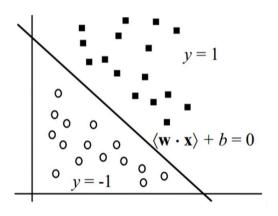


- Simplest case linearly separable data
- Dual of linear regression
  - Find a line that passes close to a set of points
  - Find a line that separates the two sets of points
- Many lines are possible
  - How do we find the best one?
  - What is a good notion of "cost" to optimize?



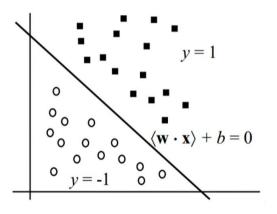


■ Each input *x* has *n* attributes ⟨*x*<sub>1</sub>, *x*<sub>2</sub>,...,*x*<sub>n</sub>⟩

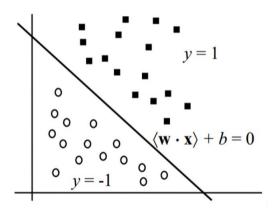


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- Each input x has n attributes ⟨x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>⟩
- Linear separator has the form  $w_1x_1 + w_2x_2 + \cdots + w_nx_n + b$

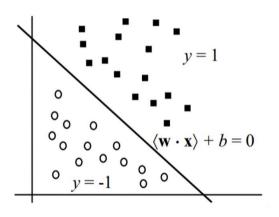


- Each input x has n attributes ⟨x<sub>1</sub>, x<sub>2</sub>,...,x<sub>n</sub>⟩
- Linear separator has the form  $w_1x_1 + w_2x_2 + \cdots + w_nx_n + b$
- Classification criterion
  - $w_1 x_1 + w_2 x_2 + \cdots + w_n x_n + b > 0$ , classify yes, +1
  - $w_1 x_1 + w_2 x_2 + \cdots + w_n x_n + b < 0$ , classify no, -1



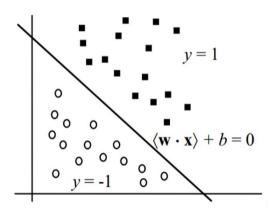
Dot product  $w \cdot x$ 

 $\langle w_1, w_2, \ldots, w_n \rangle \cdot \langle x_1, x_2, \ldots, x_n \rangle =$  $w_1 x_1 + w_2 x_2 + \cdots + w_n x_n$ 



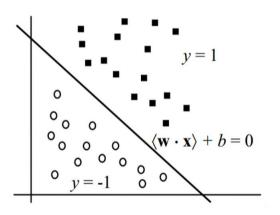
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- Collapsed form  $w \cdot x + b > 0, w \cdot x + b < 0$

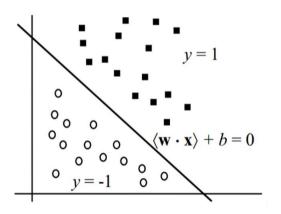


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- Collapsed form  $w \cdot x + b > 0, w \cdot x + b < 0$
- Rename bias b as  $w_0$  , create fictitious  $x_0 = 1$



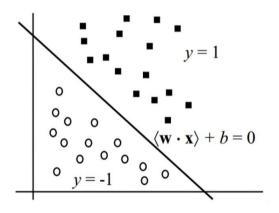
- Dot product  $w \cdot x$  $\langle w_1, w_2, \dots, w_n \rangle \cdot \langle x_1, x_2, \dots, x_n \rangle =$  $w_1 x_1 + w_2 x_2 + \dots + w_n x_n$
- Collapsed form  $w \cdot x + b > 0, w \cdot x + b < 0$
- Rename bias b as  $w_0$  , create fictitious  $x_0 = 1$
- Equation becomes w · x > 0, w · x < 0



## Perceptron algorithm

### (Frank Rosenblatt, 1958)

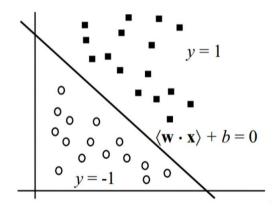
- Each training input is  $(x_i, y_i)$ , where  $x_i = \langle x_{i_1}, x_{i_2}, \dots, x_{i_n} \rangle$  and  $y_i = +1$  or -1
- Need to find  $w = \langle w_0, w_1, \dots, w_n \rangle$ 
  - Recall  $x_{i_0} = 1$ , always



### (Frank Rosenblatt, 1958)

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- Need to find  $w = \langle w_0, w_1, \dots, w_n \rangle$ 
  - Recall  $x_{i_0} = 1$ , always
  - Initialize  $w = \langle 0, 0, \dots, 0 \rangle$

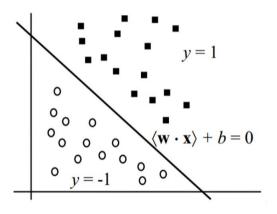
While there exists  $x_i$ ,  $y_i$  such that  $y_i = +1$  and  $w \cdot x_i < 0$ , or  $y_i = -1$  and  $w \cdot x_i > 0$ 



Update w to  $w + x_i y_i$ 

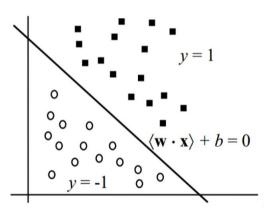
# Perceptron algorithm ....

- Keep updating w as long as some training data item is misclassified
- Update is an offset by misclassified input



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- Keep updating w as long as some training data item is misclassified
- Update is an offset by misclassified input
- Need not stabilize, potentially an infinite loop

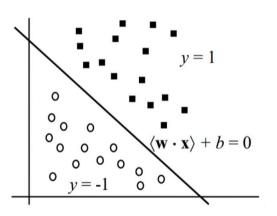


# Perceptron algorithm ...

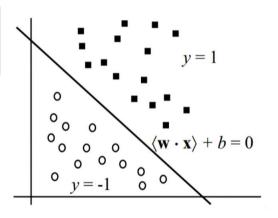
- Keep updating w as long as some training data item is misclassified
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### Theorem

If the points are linearly separable, the Perceptron algorithms always terminates with a valid separator

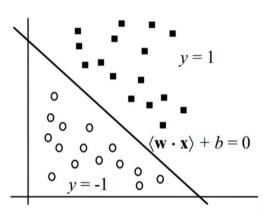


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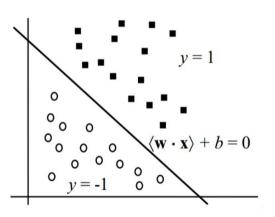
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Termination time depends on two factors



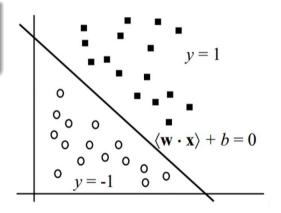
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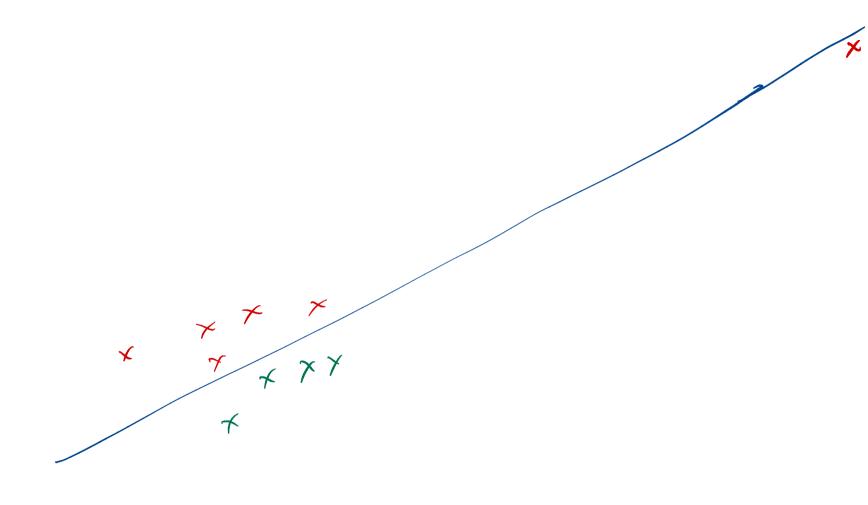
- Termination time depends on two factors
  - Width of the band separating the positive and negative points
    - Narrow band takes longer to converge



If the points are linearly separable, the Perceptron algorithms always terminates with a valid separator

- Termination time depends on two factors
  - Width of the band separating the positive and negative points
    - Narrow band takes longer to converge
  - Magnitude of the x values
    - Larger spread of points takes longer to converge





If there is  $w^*$  satisfying  $(w^* \cdot x_i)y_i \ge 1$  for all *i*, then the Perceptron Algorithm finds a solution w with  $(w \cdot x_i)y_i > 0$  for all i in at most  $r^2 |w^*|^2$  updates, where  $r = \max |x_i|$ . W\* X2 5-1 hidh ~ \_\_\_\_

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• Assume  $w^*$  exists. Keep track of two quantities:  $w^{\top}w^*$ ,  $|w|^2$ .

If there is  $w^*$  satisfying  $(w^* \cdot x_i)y_i \ge 1$  for all *i*, then the Perceptron Algorithm finds a solution *w* with  $(w \cdot x_i)y_i > 0$  for all *i* in at most  $r^2|w^*|^2$  updates, where  $r = \max_i |x_i|$ .

■ Assume  $w^*$  exists. Keep track of two quantities:  $w^\top w^*$ ,  $|w|^2$ . ■ Each update increases  $w^\top w^*$  by at least 1.  $(w + x_i y_i)^\top w^* = w^\top w^* + x_i^\top y_i w^* \ge w^\top w^* + 1$   $y_{\iota} = -1$  but  $W \cdot x_i \ge 0$   $y_{\iota} = -1$  but  $W \cdot x_i \ge 0$  $y_{\iota} = -1$  but  $W \cdot x_i \ge 0$ 

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• Assume  $w^*$  exists. Keep track of two quantities:  $w^\top w^*$ ,  $|w|^2$ .

• Each update increases  $w^{\top}w^*$  by at least 1.

$$(w + x_i y_i)^{\top} w^* = w^{\top} w^* + x_i^{\top} y_i w^* \ge w^{\top} w^* + 1$$

Each update increases  $|w|^2$  by at most  $r^2$   $(w + x_i y_i)^\top (w + x_i y_i) = |w|^2 + 2x_i^\top y_i w + |x_i y_i|^2 \le |w|^2 + |x_i|^2 \le |w|^2 + r^2$ Note that we update only when  $x_i^\top y_i w < 0$ 

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Assume Perceptron Algorithm makes *m* updates

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- Assume Perceptron Algorithm makes *m* updates
- Then,  $w^{\top}w^* \geq m$ ,  $|w|^2 \leq mr^2$

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- Assume Perceptron Algorithm makes *m* updates
- Then,  $w^{\top}w^* \ge m$ ,  $|w|^2 \le mr^2$  $m \le |w||w^*|$

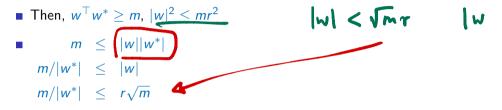
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- Assume Perceptron Algorithm makes *m* updates
- Then,  $w^{\top}w^* \ge m$ ,  $|w|^2 \le mr^2$   $m \le |w||w^*|$   $m/|w^*| \le |w|$  $w \le \Theta \le 1$

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Assume Perceptron Algorithm makes *m* updates



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Assume Perceptron Algorithm makes *m* updates

Then, 
$$w^{\top}w^* \ge m$$
,  $|w|^2 \le mr^2$   
 $m \le |w||w^*|$   
 $m/|w^*| \le |w|$   
 $m/|w^*| \le r\sqrt{m}$   
 $\sqrt{m} \le r|w^*|$ 

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  m/|w^*| \leq r\sqrt{m} 
  \sqrt{m} \leq r|w^*| 
  m \leq r^2|w^*|^2
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- Assume Perceptron Algorithm makes *m* updates
- Then,  $w^{\top}w^* \ge m$ ,  $|w|^2 \le mr^2$
- $m \leq |w||w^*|$   $m/|w^*| \leq |w|$   $m/|w^*| \leq r\sqrt{m}$   $\sqrt{m} \leq r|w^*|$   $m \leq r^2|w^*|^2$

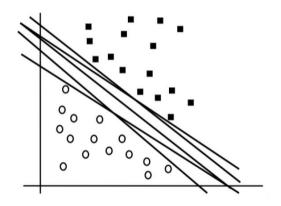
• Note (for later) that final w is of the form  $\sum n_i x_i$ 



#### Linear separators

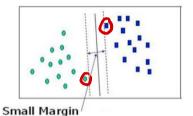
Simplest case — linearly separable data

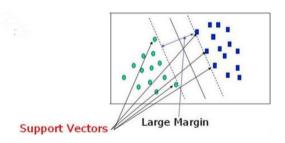
- Perceptron algorithm is a simple procedure to find a linear separator, if one exists
- Many lines are possible
  - Does the Perceptron algorithm find the best one?
  - What is a good notion of "cost" to optimize?



## Margin

- Each separator defines a margin
  - Empty corridor separating the points
  - Separator is the centre line of the margin
- Wider margin makes for a more robust classifier
  - More gap between the classes
- Optimum classifier is one that maximizes the width of its margin
- Margin is defined by the training data points on the boundary
  - Support vectors

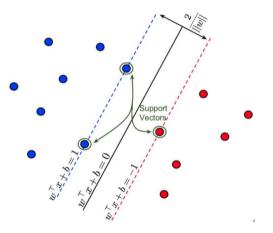




## Finding a maximum margin classifier

- Recall our original linear classifier w<sub>1</sub>x<sub>1</sub> + w<sub>2</sub>x<sub>2</sub> + ··· w<sub>n</sub>x<sub>n</sub> + b > 0, classify yes, +1 w<sub>1</sub>x<sub>1</sub> + w<sub>2</sub>x<sub>2</sub> + ··· w<sub>n</sub>x<sub>n</sub> + b < 0, classify no, -1
- Scale margin so that separation is 1 on either side

```
w_1x_1 + w_2x_2 + \cdots + w_nx_n + b > 1, classify
yes, +1
w_1x_1 + w_2x_2 + \cdots + w_nx_n + b < -1, classify
no, -1
```

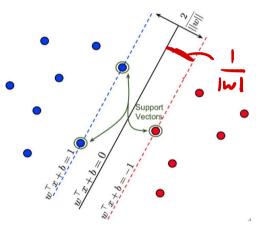


# Finding a maximum margin classifier

 Scale margin so that separation is 1 on either side

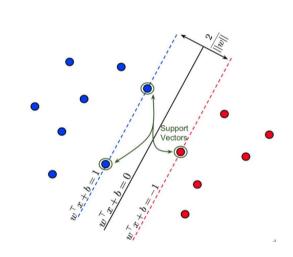
```
 \begin{split} &w_1x_1+w_2x_2+\cdots w_nx_n+b>1, \text{ classify}\\ &\text{yes, }+1\\ &w_1x_1+w_2x_2+\cdots w_nx_n+b<-1, \text{ classify}\\ &\text{no, }-1 \end{split}
```

• Using Pythagoras's theorem, perpendicular distance to nearest support vector is  $\frac{1}{\|w\|}$ , where  $\|w\| = \sqrt{w_1^2 + w_2^2 + \dots + w_n^2}$ 



## Optimization problem

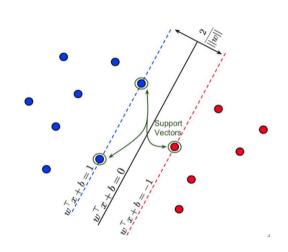
• Want to maximize the overall margin  $\frac{2}{||w||}$ 



## Optimization problem

• Want to maximize the overall margin  $\frac{2}{\|W\|}$ 

• Equivalently, minimize  $\frac{\|w\|}{2}$ 

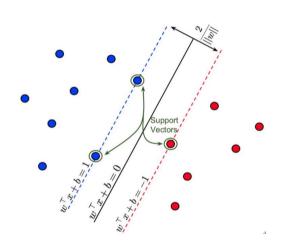


## Optimization problem

• Want to maximize the overall margin  $\frac{2}{\|w\|}$ 

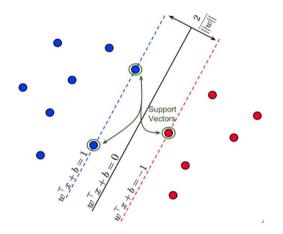
- Equivalently, minimize  $\frac{\|w\|}{2}$
- Also, w should classify each (x<sub>i</sub>, y<sub>i</sub>) correctly

 $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b > 1,$ if  $y_i = 1$  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b < -1,$ if  $y_i = -1$ 



Minimize  $\frac{\|w\|}{2}$ 

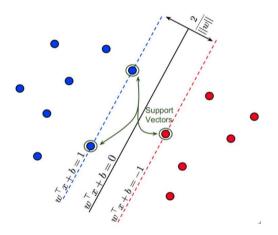
Subject to  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b > 1$ , if  $y_i = 1$  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b < -1$ , if  $y_i = -1$ 



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Minimize  $\frac{\|w\|}{2}$ Subject to  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b > 1$ , if  $y_i = 1$  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b < -1$ , if  $y_i = -1$ 

The constraints are linear

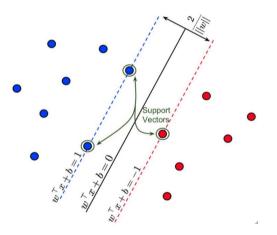


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Minimize  $\frac{||w||}{2}$ Subject to

 $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b > 1$ , if  $y_i = 1$  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b < -1$ , if  $y_i = -1$ 

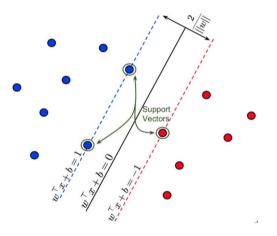
- The constraints are linear
- The objective function is not linear  $||w|| = \sqrt{w_1^2 + w_2^2 + \dots + w_n^2}$



Minimize  $\frac{\|w\|}{2}$ 

Subject to  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b > 1$ , if  $y_i = 1$  $w_1 x_1^i + w_2 x_2^i + \cdots + w_n x_n^i + b < -1$ , if  $y_i = -1$ 

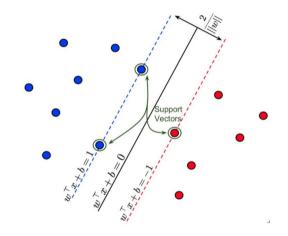
- The constraints are linear
- The objective function is not linear  $||w|| = \sqrt{w_1^2 + w_2^2 + \dots + w_n^2}$
- This is a quadratic optimization problem, not linear programming



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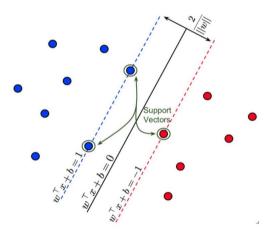
## Solution to optimization problem

- Convex optimization theory
- Can be solved using computational techniques



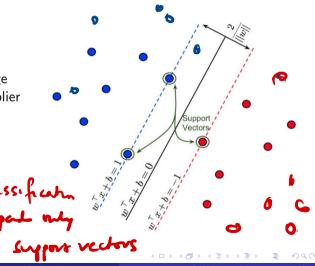
## Solution to optimization problem

- Convex optimization theory
- Can be solved using computational techniques
- Solution expressed in terms of Lagrange multipliers α<sub>1</sub>, α<sub>2</sub>, ..., α<sub>N</sub>, one multiplier per training input
- $\alpha_i$  is non-zero iff  $x_i$  is a support vector



# Solution to optimization problem

- Convex optimization theory
- Can be solved using computational techniques
- Solution expressed in terms of Lagrange multipliers α<sub>1</sub>, α<sub>2</sub>, ..., α<sub>N</sub>, one multiplier per training input
- $\alpha_i$  is non-zero iff  $x_i$  is a support vector
- Final classifier for new input z  $sign\left[\sum_{i \in sv} y_i \alpha_i (x_i \cdot z) + b\right]$
- *sv* is set of support vectors



Madhavan Mukund

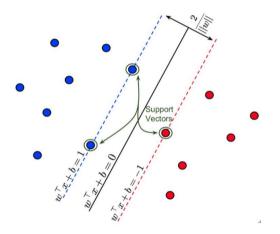
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## Support Vector Machine (SVM)

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i (x_i \cdot z) + b\right]$$

Solution depends only on support vectors

 If we add more training data away from support vectors, separator does not change

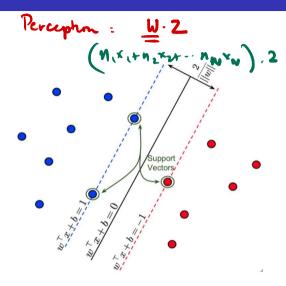


# Support Vector Machine (SVM)

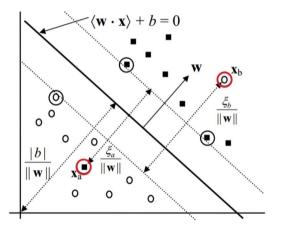
sign 
$$\left[\sum_{i \in sv} y_i \alpha (x_i \cdot z) + b\right]$$

Solution depends only on support vectors

- If we add more training data away from support vectors, separator does not change
- Solution uses dot product of support vectors with new point
  - Will be used later, in the non-linear case



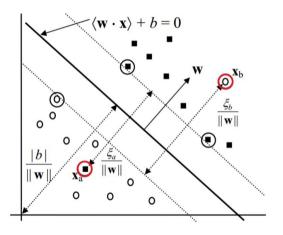
- Some points may lie on the wrong side of the classifier
- How do we account for these?



- Some points may lie on the wrong side of the classifier
- How do we account for these?
- Add an error term to the classifier requirement
- Instead of
  - $w \cdot x + b > 1$ , if  $y_i = 1$  $w \cdot x + b < -1$ , if  $y_i = -1$

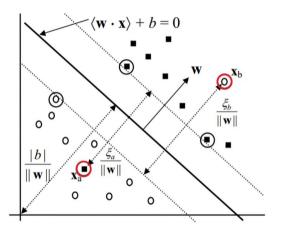
we have

 $w \cdot x + b > 1 - \xi_i$ , if  $y_i = 1$  $w \cdot x + b < -1 + \xi_i$ , if  $y_i = -1$ 

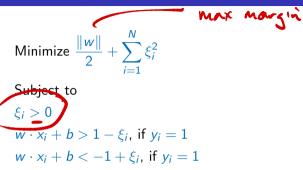


 $w \cdot x + b > 1 - \xi_i$ , if  $y_i = 1$  $w \cdot x + b < -1 + \xi_i$ , if  $y_i = -1$ 

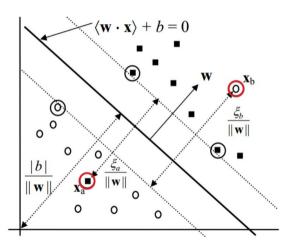
- Error term always non-negative,
- If the point is correctly classified, error term is 0
- Soft margin some points can drift across the boundary
- Need to account for the errors in the objective function
  - Minimize the need for non-zero error terms



## Soft margin optimization



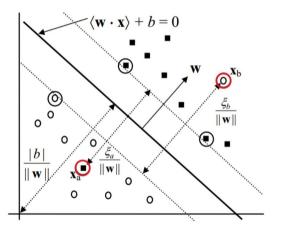
- Constraints include requirement that error terms are non-negative
- Again the objective function is quadratic



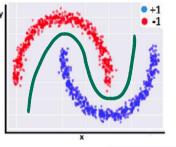
## Soft margin optimization

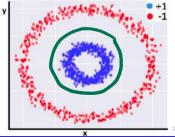
- Can again be solved using convex optimization theory
- Form of the solution turns out to be the same as the hard margin case
  - Expression in terms of Lagrange multipliers α<sub>i</sub>
  - Only terms corresponding to support vectors are actively used

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i (x_i \cdot z) + b\right]$$

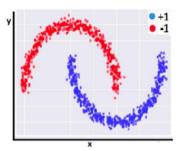


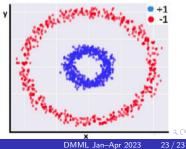
How do we deal with datasets where the separator is a complex shape?





- How do we deal with datasets where the separator is a complex shape?
- Geometrically transform the data
  - Typically, add dimensions





- How do we deal with datasets where the separator is a complex shape?
- Geometrically transform the data
  - Typically, add dimensions
- For instance, if we can "lift" one class, we can find a planar separator between levels

