

# Lecture 23: 28 April, 2022

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Data Mining and Machine Learning  
January–May 2022

# D-Separation

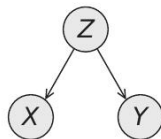
- Check if  $X \perp Y \mid Z$
- Dependence should be blocked on every trail from  $X$  to  $Y$ 
  - Each undirected path from  $X$  to  $Y$  is a sequence of basic trails
  - For (a), (b), (c), need  $Z$  present
  - For (d), need  $Z$  absent
  - In general, V-structure includes descendants of the bottom node



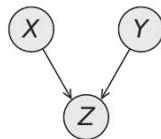
(a)



(b)



(c)

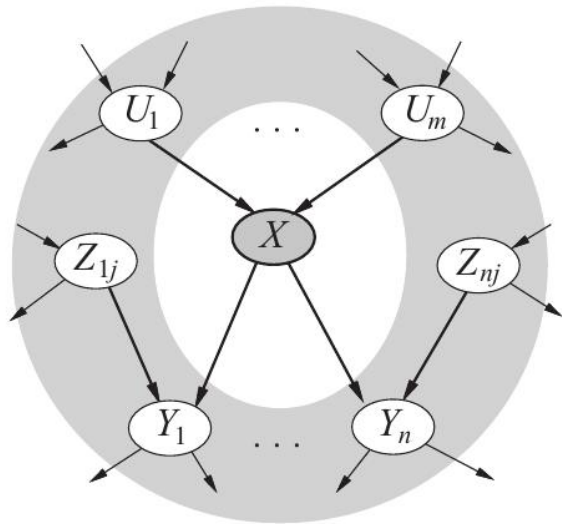


(d)

- $x$  and  $y$  are **D-separated** given  $z$  if all trails are blocked
- Variation of **breadth first search (BFS)** to check if  $y$  is reachable from  $x$  through some trail
- Extends to sets — each  $x \in X$  is D-separated from each  $y \in Y$

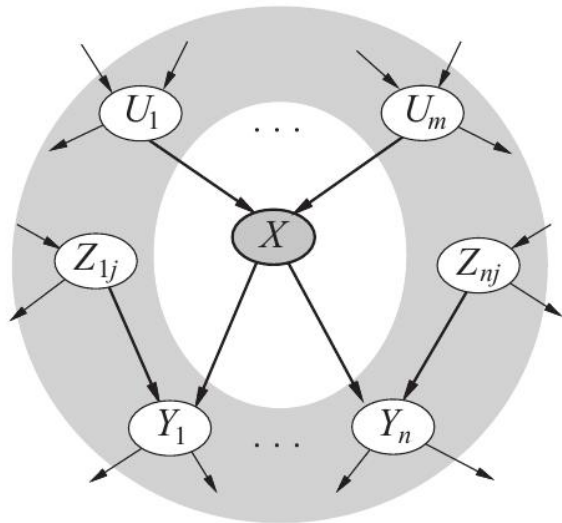
# Markov blanket

- $MB(X)$  — Markov blanket of  $X$



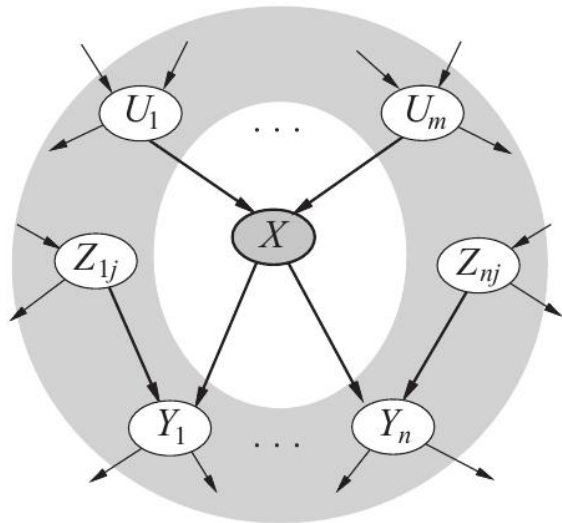
# Markov blanket

- $MB(X)$  — Markov blanket of  $X$ 
  - $Parents(X)$



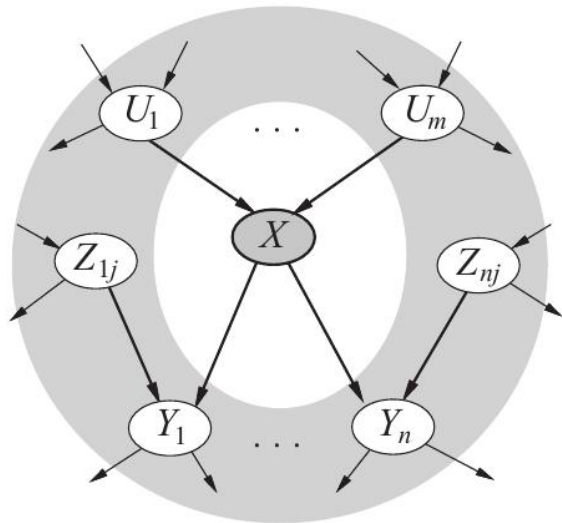
# Markov blanket

- $MB(X)$  — Markov blanket of  $X$ 
  - $Parents(X)$
  - $Children(X)$



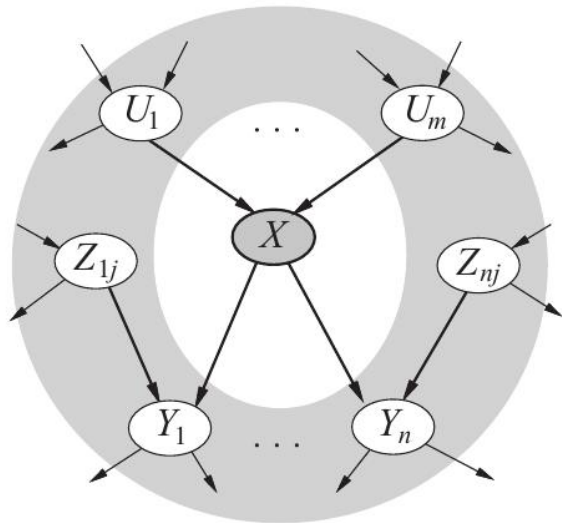
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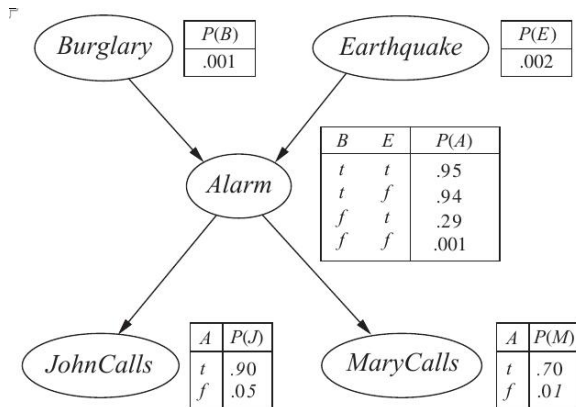
# Markov blanket

- $MB(X)$  — Markov blanket of  $X$ 
  - $Parents(X)$
  - $Children(X)$
  - $Parents\ of\ Children(X)$
- $X \perp \neg MB(X) \mid MB(X)$



# Computing with probabilistic graphical models

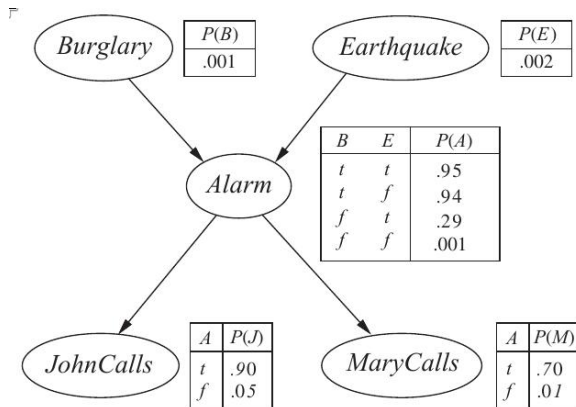
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- Want  $P(b \mid m, j)$

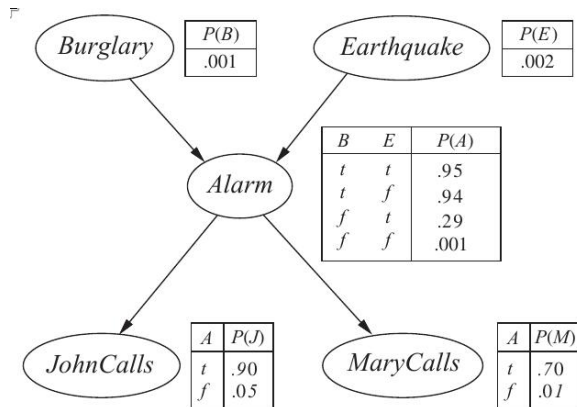


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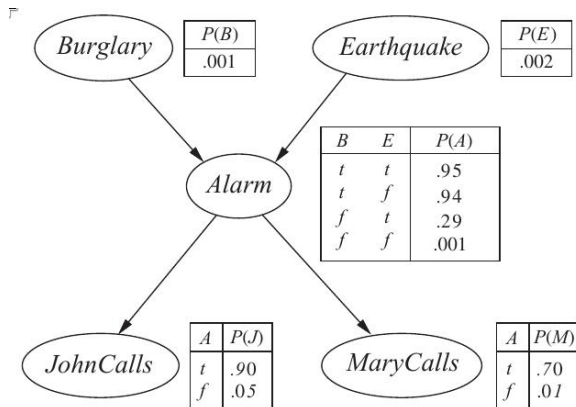
- Want  $P(b \mid m, j)$

- $$\frac{P(b, m, j)}{P(m, j)}$$



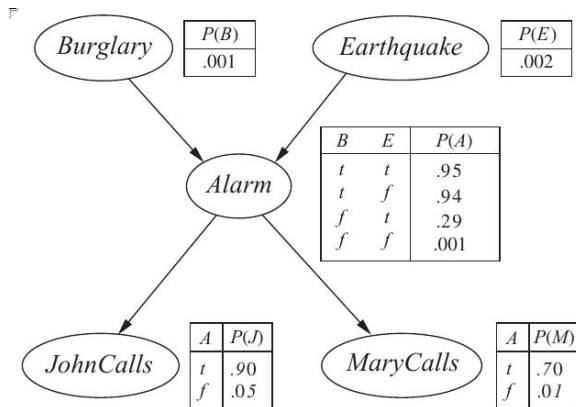
# Computing with probabilistic graphical models

- John and Mary call Pearl. What is the probability that there has been a burglary?
- Want  $P(b | m, j)$
- $\frac{P(b, m, j)}{P(m, j)}$
- Use chain rule to evaluate joint probabilities



# Computing with probabilistic graphical models

- John and Mary call Pearl. What is the probability that there has been a burglary?
- Want  $P(b \mid m, j)$
- $\frac{P(b, m, j)}{P(m, j)}$
- Use chain rule to evaluate joint probabilities
- Reorder variables appropriately, topological order of graph



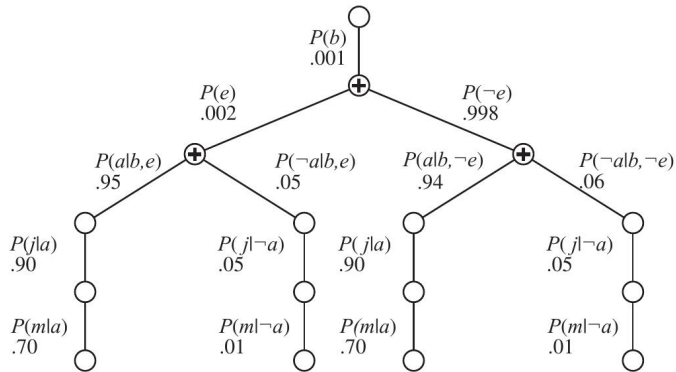
# Computing with probabilistic graphical models

- $$P(m, j, b) = P(b) \sum_{e=0}^1 P(e) \sum_{a=0}^1 P(a | b, e) P(m | a) P(j | a)$$

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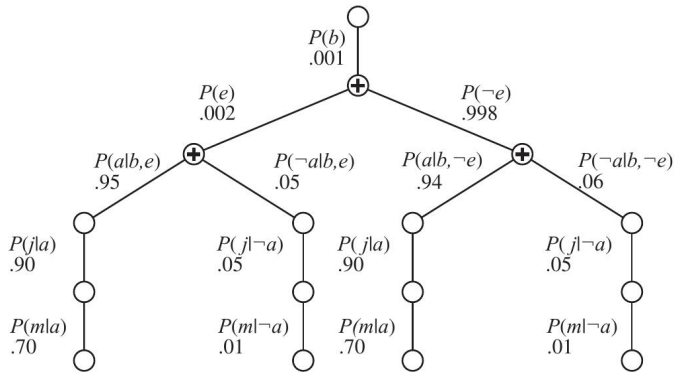
- Construct the computation tree



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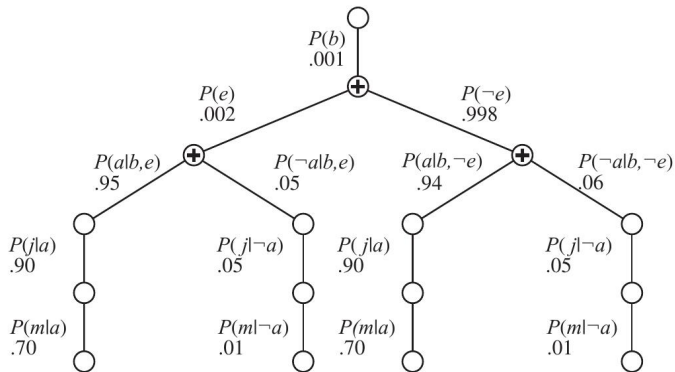
- Construct the computation tree
- Use dynamic programming to avoid duplicated computations



# Computing with probabilistic graphical models

- $$P(m, j, b) = P(b) \sum_{e=0}^1 P(e) \sum_{a=0}^1 P(a | b, e) P(m | a) P(j | a)$$

- Construct the computation tree
- Use dynamic programming to avoid duplicated computations
- However, **exact inference** is NP-complete, in general

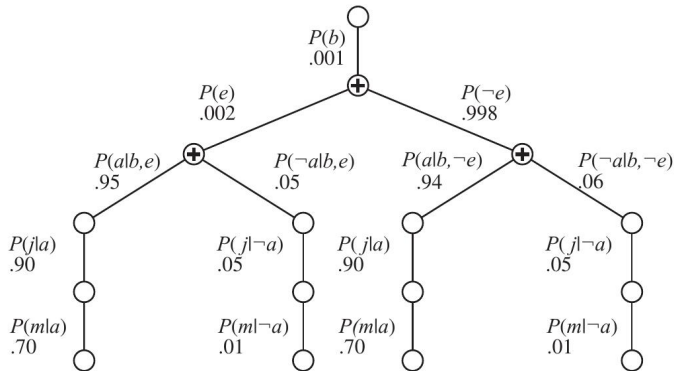




# Computing with probabilistic graphical models

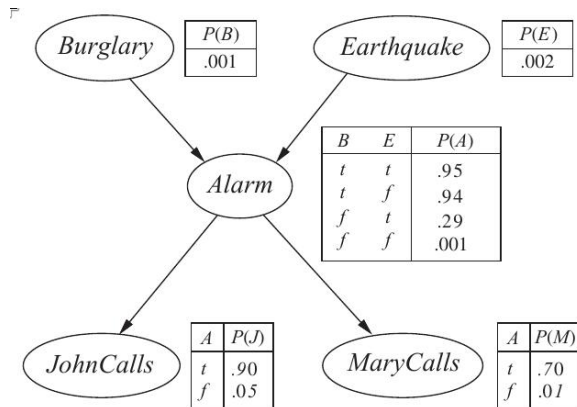
- $$P(m, j, b) = P(b) \sum_{e=0}^1 P(e) \sum_{a=0}^1 P(a | b, e) P(m | a) P(j | a)$$

- Construct the computation tree
- Use dynamic programming to avoid duplicated computations
- However, **exact inference** is NP-complete, in general
- Instead, **approximate inference** through sampling



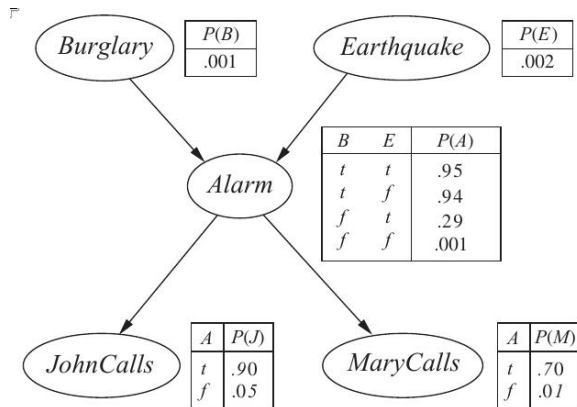
# Approximate inference

- Generate random samples  $(b, e, a, m, j)$ , count to estimate probabilities



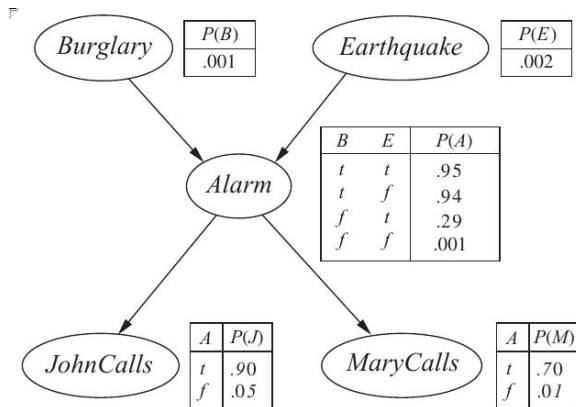
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- Generate random samples  $(b, e, a, m, j)$ , count to estimate probabilities
- Random samples should respect conditional probabilities



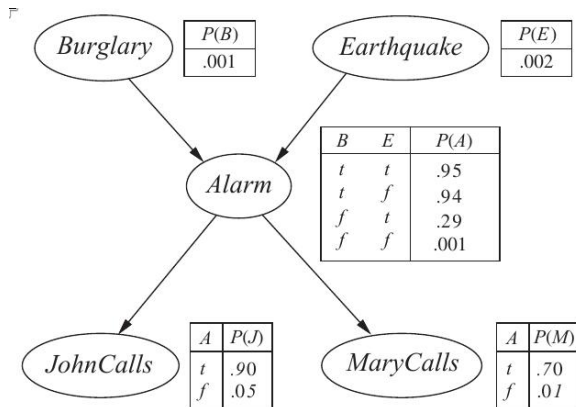
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- Generate random samples  $(b, e, a, m, j)$ , count to estimate probabilities
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- Fix  $MB(x)$  before generating  $x$



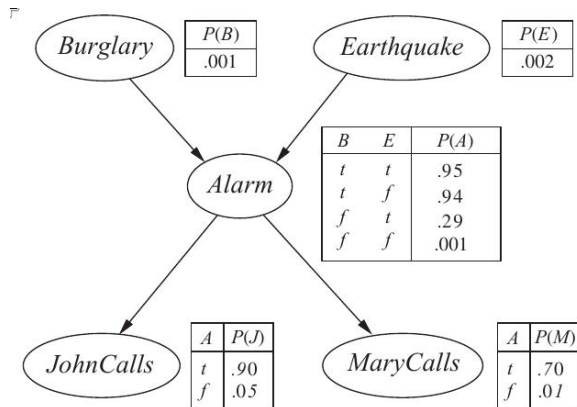
# Approximate inference

- Generate random samples  $(b, e, a, m, j)$ , count to estimate probabilities
- Random samples should respect conditional probabilities
- Fix  $MB(x)$  before generating  $x$
- Generate in topological order
  - Generate  $b, e$  with probabilities  $P(b)$  and  $P(e)$
  - Generate  $a$  with probability  $P(a | b, e)$
  - Generate  $j, m$  with probabilities  $P(j | a)$ ,  $P(m | a)$



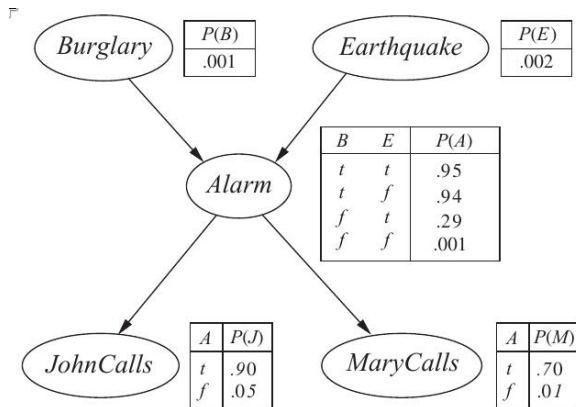
# Approximate inference

- We are interested in  $P(b | j, m)$



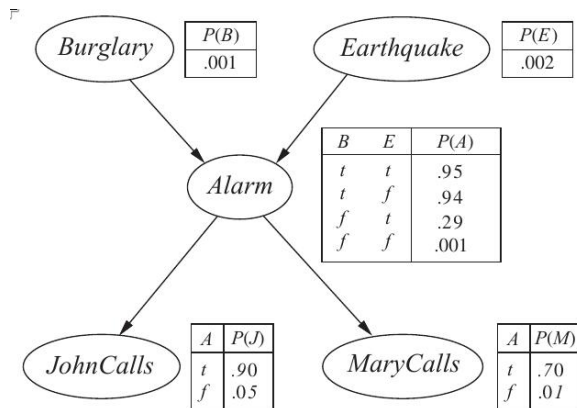
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- We are interested in  $P(b | j, m)$
- Samples with  $\neg j$  or  $\neg m$  are useless



# Approximate inference

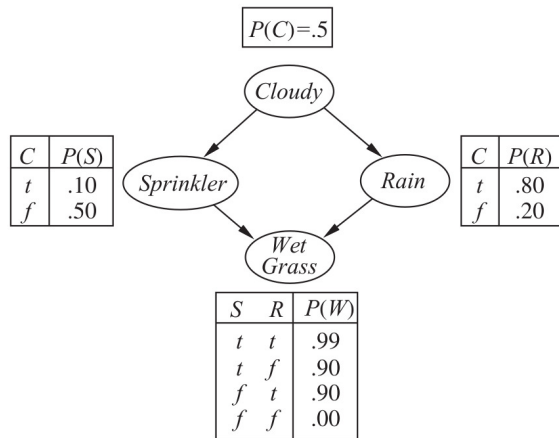
- We are interested in  $P(b | j, m)$
- Samples with  $\neg j$  or  $\neg m$  are useless
- Can we sample more efficiently?





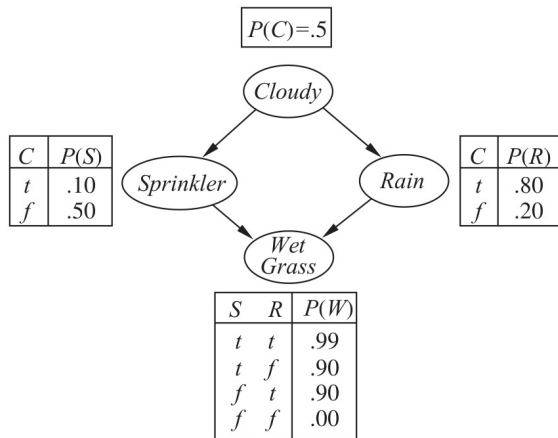
# Rejection sampling

- $P(\text{Rain} \mid \text{Cloudy}, \text{Wet Grass})$



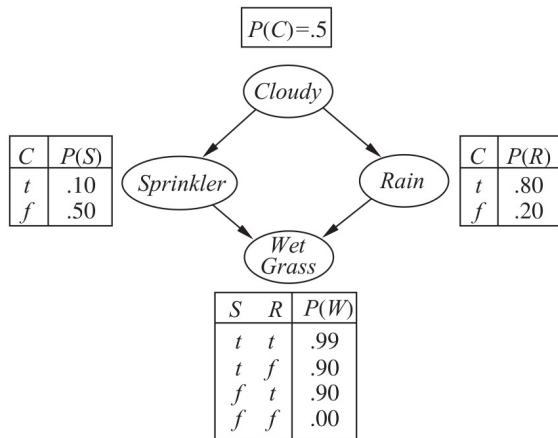
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- $P(\text{Rain} \mid \text{Cloudy}, \text{Wet Grass})$
- Topological order
  - Generate *Cloudy*
  - Generate *Sprinkler*, *Rain*
  - Generate *Wet Grass*



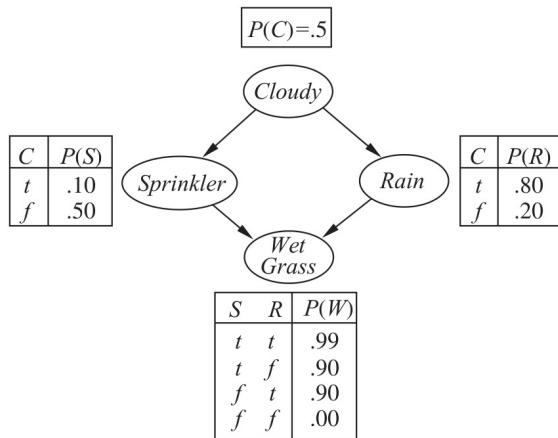
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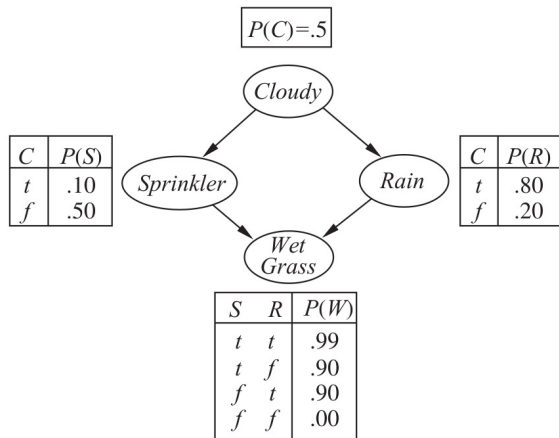
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- Immediately stop and reject this sample — **rejection sampling**



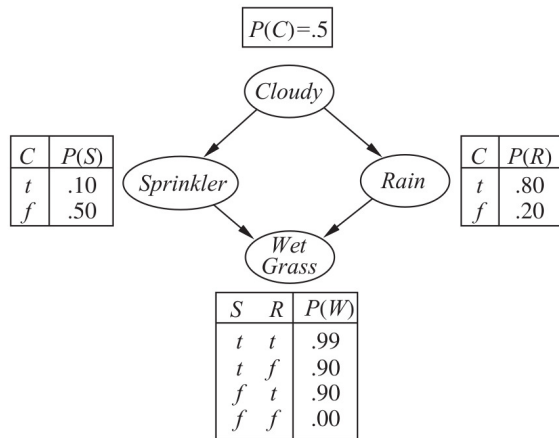
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- If we start with  $\neg\text{Cloudy}$ , sample is useless
- Immediately stop and reject this sample — **rejection sampling**
- General problem with low probability situation — lots of samples



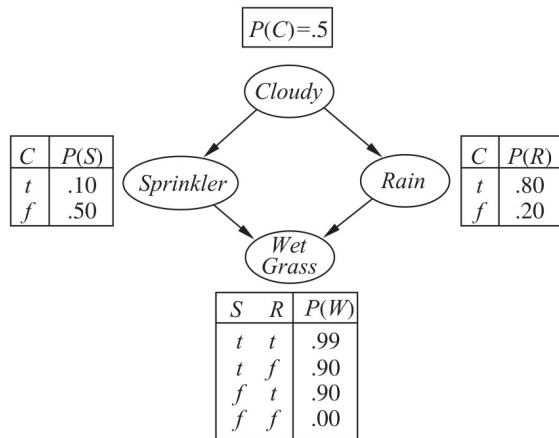
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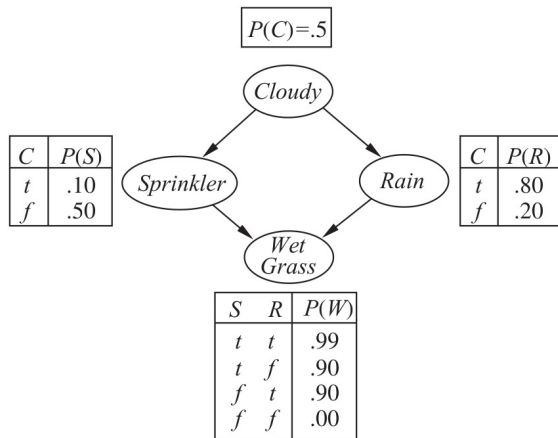
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# Likelihood weighted sampling

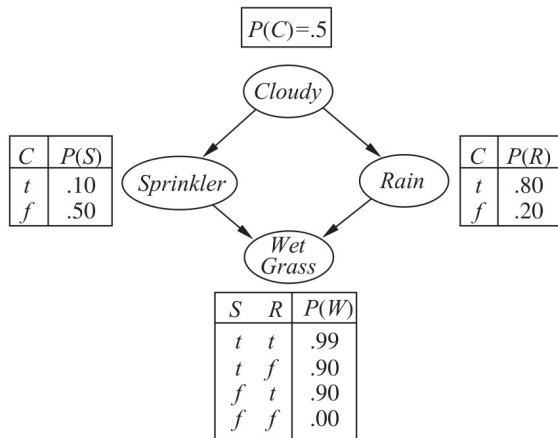
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- Then generate the other variables





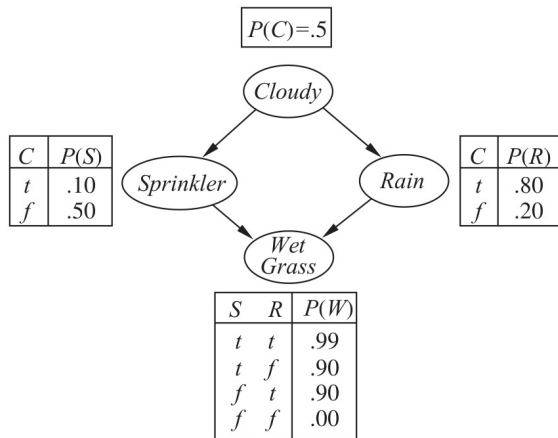
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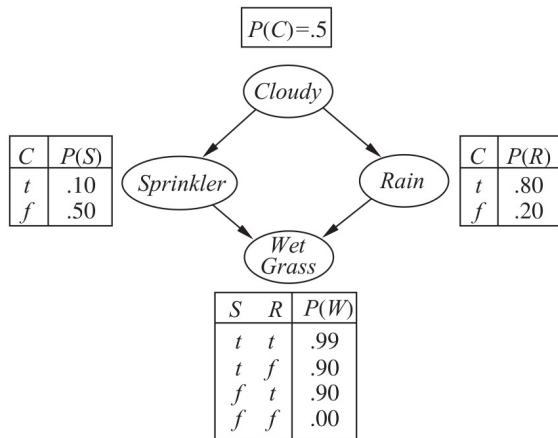
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 $0.5 \times 0.9 = 0.45$



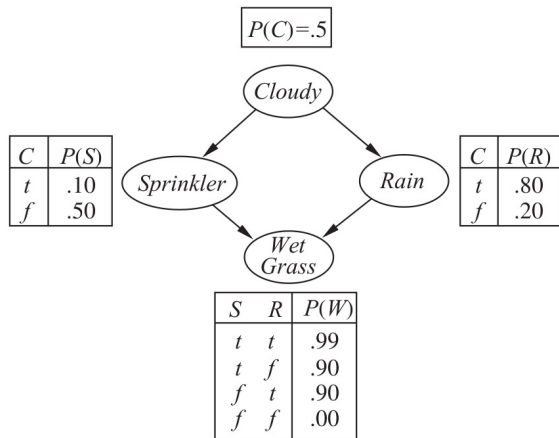
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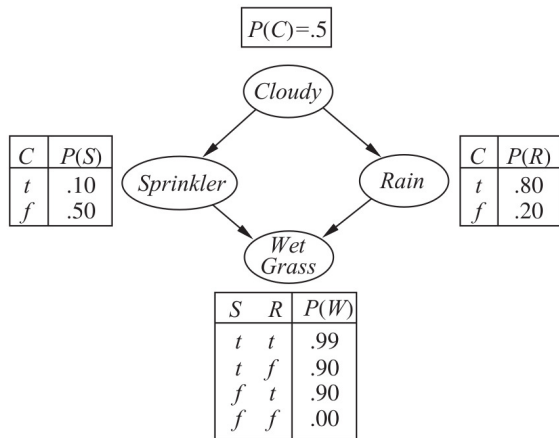
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- Samples  $s_1, s_2, \dots, s_N$  with weights  
 $w_1, w_2, \dots, w_N$



# Likelihood weighted sampling

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$$\blacksquare P(r \mid c, w) = \frac{\sum_{s_i \text{ has rain}} w_i}{\sum_{1 \leq j \leq N} w_j}$$



# Markov chains