Lecture 18: 04 April, 2022

Madhavan Mukund https://www.cmi.ac.in/~madhavan

Data Mining and Machine Learning January–May 2022

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 - のへで

Soft margin optimization

Minimize
$$\frac{||w||}{2} + \sum_{i=1}^{N} \xi_i^2$$

Subject to

$$\begin{array}{ll} \xi_i \geq 0 \\ \langle w \cdot x \rangle + b > 1 - \xi_i, & \text{if } y_i = 1 \\ \langle w \cdot x \rangle + b < -1 + \xi_i, & \text{if } y_i = -1 \end{array}$$

- Constraints include requirement that error terms are non-negative
- Again the objective function is quadratic



★□> ★@> ★E> ★E>

æ



The non-linear case

 How do we deal with datasets where the separator is a complex shape?

- Geometrically transform the data
 - Typically, add dimensions •
- For instance, if we can "lift" one class, we can find a planar separator between levels





Geometric tranformation

- Consider two sets of points separated by a circle of radius 1
- Equation of circle is $x^2 + y^2 = 1$
- Points inside the circle $\,x^2+y^2<1\,$
- Points outside circle $x^2 + y^2 > 1$
- Transformation

 $\varphi:(x,y)\mapsto (x,y,x^2+y^2)$

- Points inside circle lie below z = 1
- Point outside circle lifted above z = 1



SVM after transformation

• SVM in original space

$$\operatorname{sign}\left[\sum_{i\in sv} y_i \alpha_i \langle x_i \cdot z \rangle + b\right]$$

• After transformation

sign
$$\left[\sum_{i \in sv'} y_i \alpha_i \langle \varphi(x_i) \cdot \varphi(z) \rangle + b\right]$$



(日) (日) (日) (日) (日)

- 2

• All we need to know is how to compute dot products in transformed space



Dot products

• Consider the transformation

$$\varphi: (x_1, x_2) \mapsto (1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, \sqrt{2}x_1x_2, x_2^2)$$

• Dot product in transformed space

$$\begin{aligned} \langle \varphi(x) \cdot \varphi(z) \rangle &= 1 + 2x_1 z_1 + 2x_2 z_2 + x_1^2 z_1^2 \\ &+ 2x_1 x_2 z_1 z_2 + x_2^2 z_2^2 \\ &= (1 + x_1 z_1 + x_2 z_2)^2 \end{aligned}$$

• Transformed dot product can be expressed in terms of original inputs

$$\langle \varphi(x) \cdot \varphi(z) \rangle = K(x,z) = (1+x_1z_1+x_2z_2)^2$$





æ

• $K \, {\rm is} \, {\rm a} \, {\it kernel} \,$ for transformation $\varphi \,$ if

$$K(x,z) = \langle \varphi(x) \cdot \varphi(z) \rangle$$

- If we have a kernel, we don't need to explicitly compute transformed points
- All dot products can be computed implicitly using the kernel on original data points

$$\operatorname{sign}\left[\sum_{i \in sv'} y_i \alpha_i \langle \varphi(x_i) \cdot \varphi(z) \rangle + b\right]$$



• $K \, {\rm is} \, {\rm a} \, {\it kernel} \,$ for transformation $\varphi \,$ if

$$K(x,z) = \langle \varphi(x) \cdot \varphi(z) \rangle$$

- If we have a kernel, we don't need to explicitly compute transformed points
- All dot products can be computed implicitly using the kernel on original data points

$$\operatorname{sign}\left[\sum_{i\in sv'} y_i \alpha_i K(x_i, z) + b\right]$$





- If we know K is a kernel for some transformation φ , we can blindly use K without even knowing what φ looks like!
- When is a function a valid kernel?
- Has been studied in mathematics Mercer's Theorem
 - Criteria are non-constructive
- Can define sufficient conditions from linear algebra





• Kernel over training data x_1, x_2, \ldots, x_N can be represented as a *gram matrix*

| | | x_1 | x_2 | ••• | x_N |
|-----|-------|-------|-------|-----|-------|
| | x_1 | Γ | | |] |
| K = | x_2 | | | | |
| | : | | | | |
| | x_n | L | | | |

- Entries are values $K(x_i, x_j)$
- Gram matrix should be *positive semi*definite for all x_1, x_2, \ldots, x_N



Known kernels

- Fortunately, there are many known kernels
- Polynomial kernels

 $K(x,z) = (1 + \langle x \cdot z \rangle)^k$

- Any K(x,z) representing a similarity measure
- Gaussian radial basis function similarity based on inverse exponential distance

$$K(x,z) = e^{-c|x-z|^2}$$

