

Lecture 6: 10 February, 2022

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Data Mining and Machine Learning
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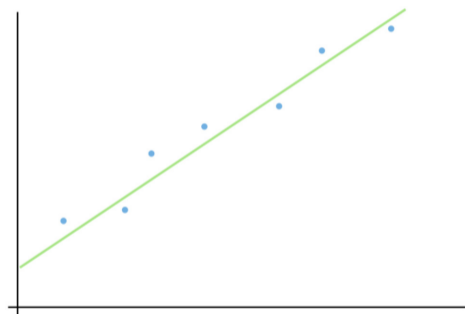
Finding the best fit line

- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
 - Each input x_i is a vector (x_i^1, \dots, x_i^k)
 - Add $x_i^0 = 1$ by convention
 - y_i is actual output
- How far away is our prediction $h_\theta(x_i)$ from the true answer y_i ?

- Define a cost (loss) function

$$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h_\theta(x_i) - y_i)^2$$

- Essentially, the sum squared error (SSE)
- Divide by n , mean squared error (MSE)



Minimizing SSE

- Write x_i as row vector $[1 \ x_i^1 \ \cdots \ x_i^k]$

- $$X = \begin{bmatrix} 1 & x_1^1 & \cdots & x_1^k \\ 1 & x_2^1 & \cdots & x_2^k \\ & & \cdots & \\ 1 & x_i^1 & \cdots & x_i^k \\ & & \cdots & \\ 1 & x_n^1 & \cdots & x_n^k \end{bmatrix}, y = \begin{bmatrix} y_1 \\ y_2 \\ \cdots \\ y_i \\ \cdots \\ y_n \end{bmatrix}$$

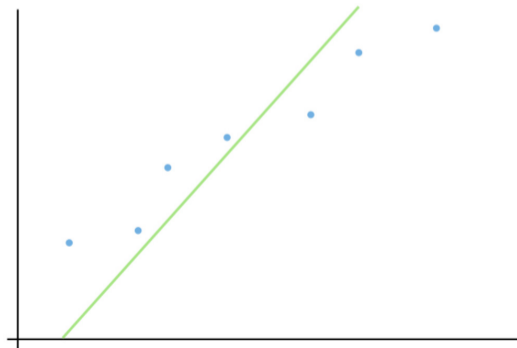
- Write θ as column vector, $\theta^T = [\theta_0 \ \theta_1 \ \cdots \ \theta_k]$

- $$J(\theta) = \frac{1}{2} \sum_{i=1}^n (h_{\theta}(x_i) - y_i)^2 = \frac{1}{2} (X\theta - y)^T (X\theta - y)$$

- Minimize $J(\theta)$ — set $\nabla_{\theta} J(\theta) = 0$

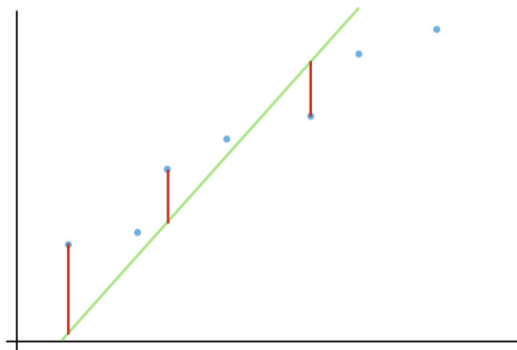
Minimizing SSE iteratively

- Normal equation $\theta = (X^T X)^{-1} X^T y$ is a closed form solution
- Computational challenges
 - Slow if n large, say $n > 10^4$
 - Matrix inversion $(X^T X)^{-1}$ is expensive, also need invertibility
- Iterative approach, make an initial guess



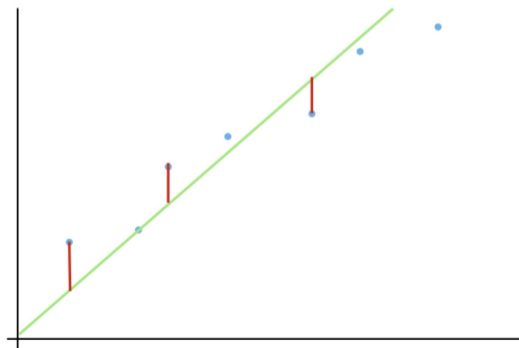
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- Keep adjusting the line to reduce SSE



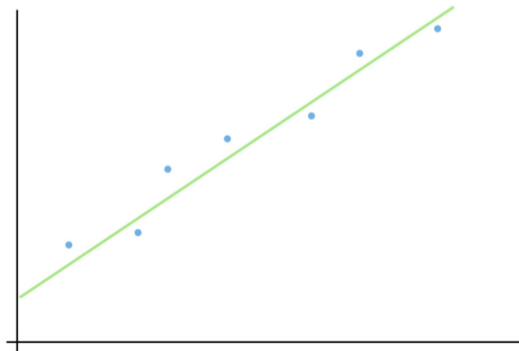
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- Iterative approach, make an initial guess
- Keep adjusting the line to reduce SSE
- Stop when we find the best fit line
- How do we adjust the line?



Gradient descent

- How does cost vary with parameters

$$\theta = (\theta_0, \theta_1, \dots, \theta_k)?$$

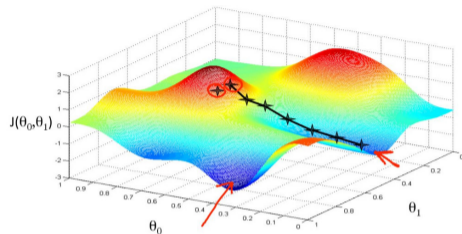
- Gradients $\frac{\partial}{\partial \theta_i} J(\theta)$

- Adjust each parameter against gradient

- $\theta_i = \theta_i - \alpha \frac{\partial}{\partial \theta_i} J(\theta)$

- For a single training sample (x, y)

$$\begin{aligned} \frac{\partial}{\partial \theta_i} J(\theta) &= \frac{\partial}{\partial \theta_i} \frac{1}{2} (h_{\theta}(x) - y)^2 \\ &= 2 \cdot \frac{1}{2} (h_{\theta}(x) - y) \frac{\partial}{\partial \theta_i} (h_{\theta}(x) - y) \\ &= (h_{\theta}(x) - y) \frac{\partial}{\partial \theta_i} \left[\left(\sum_{j=0}^k \theta_j x_j \right) - y \right] = (h_{\theta}(x) - y) \cdot x_i \end{aligned}$$



Gradient descent

- For a single training sample (x, y) , $\frac{\partial}{\partial \theta_i} J(\theta) = (h_\theta(x) - y) \cdot x_i$
- Over the entire training set, $\frac{\partial}{\partial \theta_i} J(\theta) = \sum_{j=1}^n (h_\theta(x_j) - y_j) \cdot x_j^i$

Batch gradient descent

- Compute $h_\theta(x_j)$ for entire training set $\{(x_1, y_1), \dots, (x_n, y_n)\}$

- Adjust each parameter

$$\begin{aligned}\theta_i &= \theta_i - \alpha \frac{\partial}{\partial \theta_i} J(\theta) \\ &= \theta_i - \alpha \cdot \sum_{j=1}^n (h_\theta(x_j) - y_j) \cdot x_j^i\end{aligned}$$

- Repeat until convergence

Stochastic gradient descent

- For each input x_j , compute $h_\theta(x_j)$
- Adjust each parameter —
 $\theta_i = \theta_i - \alpha \cdot (h_\theta(x_j) - y) \cdot x_j^i$

Pros and cons

- Faster progress for large batch size
- May oscillate indefinitely

Regression and SSE loss

- Training input is $\{(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)\}$
 - Noisy outputs from a linear function
 - $y_i = \theta^T x_i + \epsilon$
 - $\epsilon \sim \mathcal{N}(0, \sigma^2)$: Gaussian noise, mean 0, fixed variance σ^2
 - $y_i \sim \mathcal{N}(\mu_i, \sigma^2)$, $\mu_i = \theta^T x_i$
- Model gives us an estimate for θ , so regression learns μ_i for each x_i
- Want **Maximum Likelihood Estimator (MLE)** — maximize

$$\mathcal{L}(\theta) = \prod_{i=1}^n P(y_i | x_i; \theta)$$

- Instead, maximize **log likelihood**

$$\ell(\theta) = \log \left(\prod_{i=1}^n P(y_i | x_i; \theta) \right) = \sum_{i=1}^n \log(P(y_i | x_i; \theta))$$

Log likelihood and SSE loss

- $y_i = \mathcal{N}(\mu_i, \sigma^2)$, so $P(y_i | x_i; \theta) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\mu_i)^2}{2\sigma^2}} = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\theta^T x_i)^2}{2\sigma^2}}$

- Log likelihood (assuming natural logarithm)

$$\ell(\theta) = \sum_{i=1}^n \log \left(\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-\theta^T x_i)^2}{2\sigma^2}} \right) = n \log \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right) - \sum_{i=1}^n \frac{(y - \theta^T x_i)^2}{2\sigma^2}$$

- To maximize $\ell(\theta)$ with respect to θ , ignore all terms that do not depend on θ

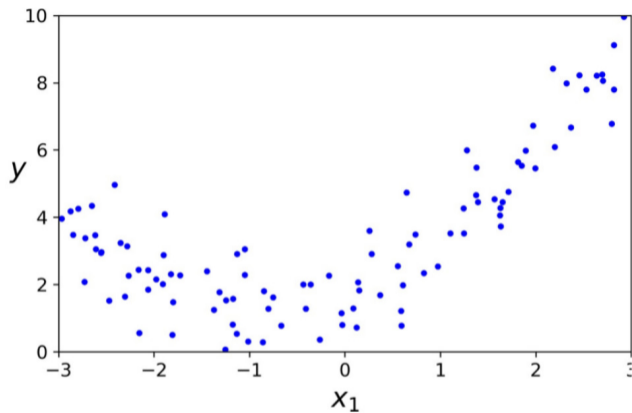
- Optimum value of θ is given by

$$\hat{\theta}_{\text{MSE}} = \arg \max_{\theta} \left[- \sum_{i=1}^n (y_i - \theta^T x_i)^2 \right] = \arg \min_{\theta} \left[\sum_{i=1}^n (y_i - \theta^T x_i)^2 \right]$$

- Assuming data points are generated by linear function and then perturbed by Gaussian noise, SSE is the “correct” loss function to maximize likelihood

The non-linear case

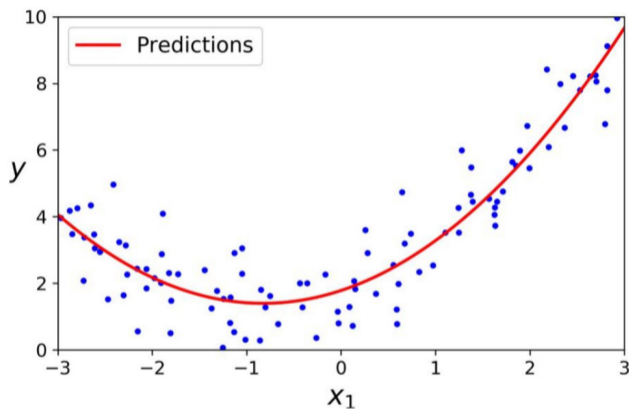
- What if the relationship is not linear?



The non-linear case

- What if the relationship is not linear?
- Here the best possible explanation seems to be a quadratic
- Non-linear : cross dependencies
- Input $x_i : (x_{i_1}, x_{i_2})$
- Quadratic dependencies:

$$y = \theta_0 + \theta_1 x_{i_1} + \theta_2 x_{i_2} + \theta_{11} x_{i_1}^2 + \theta_{22} x_{i_2}^2 + \theta_{12} x_{i_1} x_{i_2}$$



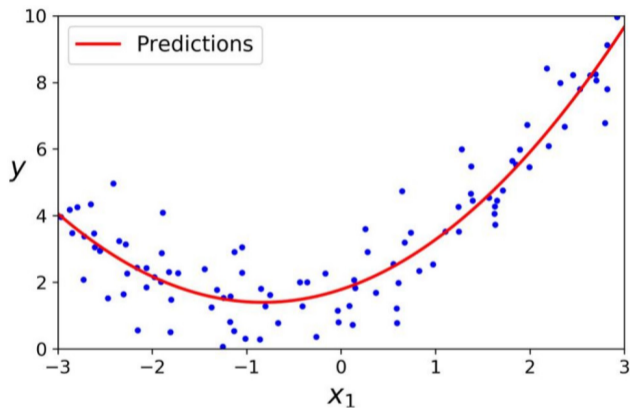
The non-linear case

- Recall how we fit a line

$$\begin{bmatrix} 1 & x_i \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \end{bmatrix}$$

- For quadratic, add new coefficients and expand parameters

$$\begin{bmatrix} 1 & x_i & x_i^2 \end{bmatrix} \begin{bmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{bmatrix}$$



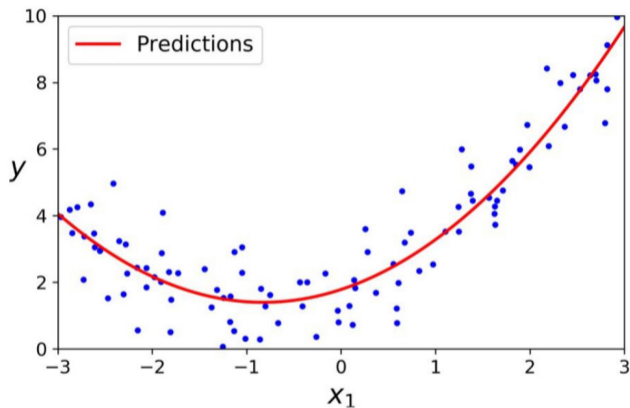
The non-linear case

- Input (x_{i_1}, x_{i_2})
- For the general quadratic case, we are adding new derived “features”

$$x_{i_3} = x_{i_1}^2$$

$$x_{i_4} = x_{i_2}^2$$

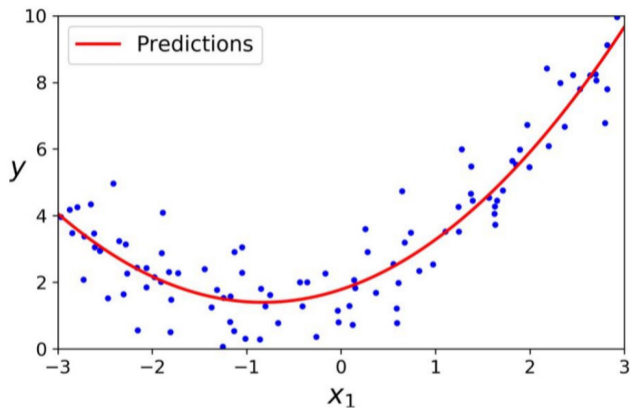
$$x_{i_5} = x_{i_1} x_{i_2}$$



The non-linear case

- Original input matrix

$$\begin{bmatrix} 1 & x_{1_1} & x_{1_2} \\ 1 & x_{2_1} & x_{2_2} \\ & \dots & \\ 1 & x_{i_1} & x_{i_2} \\ & \dots & \\ 1 & x_{n_1} & x_{n_2} \end{bmatrix}$$

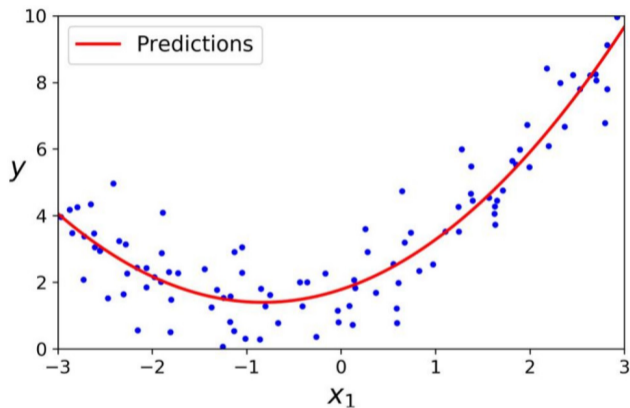


The non-linear case

- Expanded input matrix

$$\begin{bmatrix} 1 & x_{1_1} & x_{1_2} & x_{1_1}^2 & x_{1_2}^2 & x_{1_1}x_{1_2} \\ 1 & x_{2_1} & x_{2_2} & x_{2_1}^2 & x_{2_2}^2 & x_{2_1}x_{2_2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{i_1} & x_{i_2} & x_{i_1}^2 & x_{i_2}^2 & x_{i_1}x_{i_2} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ 1 & x_{n_1} & x_{n_2} & x_{n_1}^2 & x_{n_2}^2 & x_{n_1}x_{n_2} \end{bmatrix}$$

- New columns are computed and filled in from original inputs



Exponential parameter blow-up

■ Cubic derived features

$$x_{i_1}^3, x_{i_2}^3, x_{i_3}^3,$$

$$x_{i_1}^2 x_{i_2}, x_{i_1}^2 x_{i_3},$$

$$x_{i_2}^2 x_{i_1}, x_{i_2}^2 x_{i_3},$$

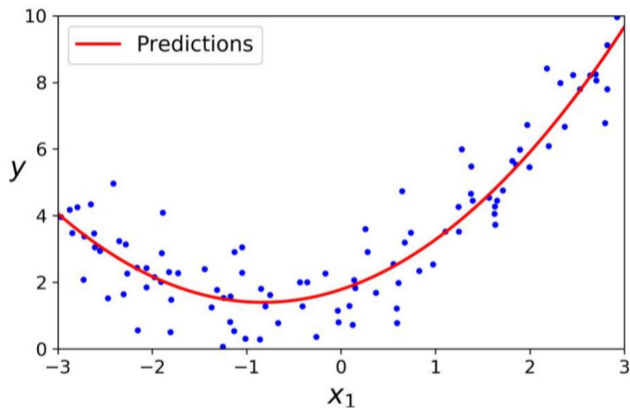
$$x_{i_3}^2 x_{i_1}, x_{i_3}^2 x_{i_2},$$

$$x_{i_1} x_{i_2} x_{i_3},$$

$$x_{i_1}^2, x_{i_2}^2, x_{i_3}^2,$$

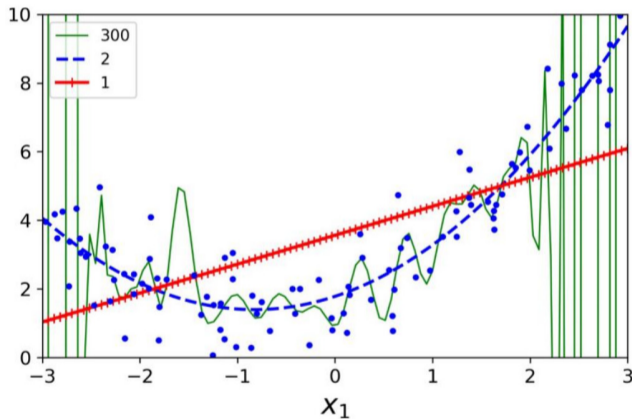
$$x_{i_1} x_{i_2}, x_{i_1} x_{i_3}, x_{i_2} x_{i_3},$$

$$x_{i_1}, x_{i_2}, x_{i_3}.$$



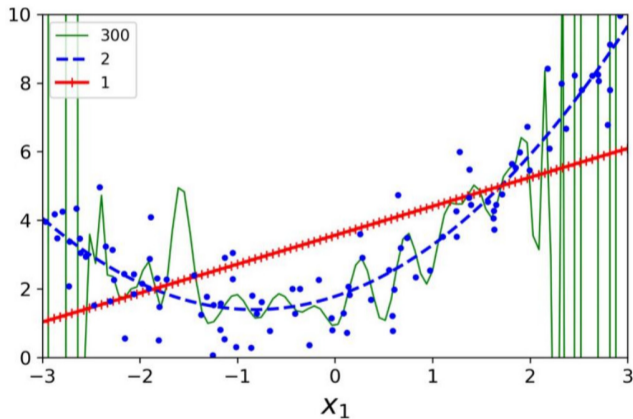
Higher degree polynomials

- How complex a polynomial should we try?
- Aim for degree that minimizes SSE
- As degree increases, features explode exponentially



Overfitting

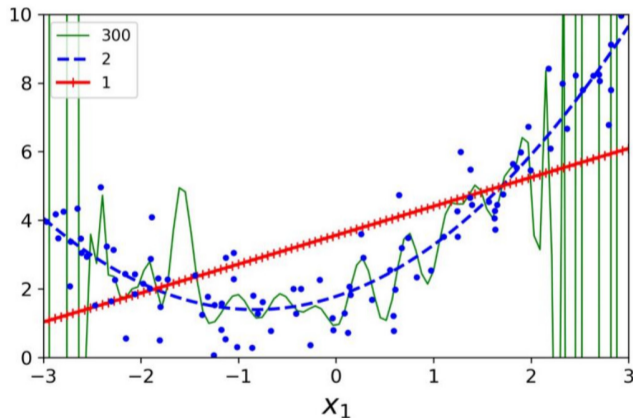
- Need to be careful about adding higher degree terms
- For n training points, can always fit polynomial of degree $(n - 1)$ exactly
- However, such a curve would not generalize well to new data points
- **Overfitting** — model fits training data well, performs poorly on unseen data



Regularization

- Need to trade off SSE against curve complexity
- So far, the only cost has been SSE
- Add a cost related to parameters $(\theta_0, \theta_1, \dots, \theta_k)$
- Minimize, for instance

$$\frac{1}{2} \sum_{i=1}^n (z_i - y_i)^2 + \sum_{j=1}^k \theta_j^2$$



Regularization

$$\frac{1}{2} \sum_{i=1}^n (z_i - y_i)^2 + \sum_{j=1}^k \theta_j^2$$

- Second term penalizes curve complexity
- Variations on regularization

- Ridge regression: $\sum_{j=1}^k \theta_j^2$

- LASSO regression: $\sum_{j=1}^k |\theta_j|$

- Elastic net regression: $\sum_{j=1}^k \lambda_1 |\theta_j| + \lambda_2 \theta_j^2$

