#### Lecture 16: 24 March, 2022

Madhavan Mukund

https://www.cmi.ac.in/~madhavan

Data Mining and Machine Learning January–May 2022

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022 2

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)
- What if we have a mixture of two random processes

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin *N* times, *H T H H · · · T*
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)
- What if we have a mixture of two random processes
  - Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)
- What if we have a mixture of two random processes
  - Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
  - Repeat N times: choose  $c_i$  with probability 1/2 and toss it



- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)
- What if we have a mixture of two random processes
  - Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
  - Repeat N times: choose  $c_i$  with probability 1/2 and toss it
  - Outcome:  $N_1$  tosses of  $c_1$  interleaved with  $N_2$  tosses of  $c_2$ ,  $N_1 + N_2 = N$

- Probabilistic process parameters ⊖
  - Tossing a coin with  $\Theta = \{Pr(H)\} = \{p\}$
- Perform an experiment
  - Toss the coin N times,  $H T H H \cdots T$
- Estimate parameters from observations
  - From h heads, estimate p = h/N
  - Maximum Likelihood Estimator (MLE)
- What if we have a mixture of two random processes
  - Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
  - Repeat N times: choose  $c_i$  with probability 1/2 and toss it
  - Outcome:  $N_1$  tosses of  $c_1$  interleaved with  $N_2$  tosses of  $c_2$ ,  $N_1 + N_2 = N$
  - $\blacksquare$  Can we estimate  $p_1$  and  $p_2$ ?



#### Mixture models . . .

- Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
- Sequence of *N* interleaved coin tosses *H T H H · · · H H T*

#### Mixture models ...

- Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
- Sequence of *N* interleaved coin tosses *H T H H · · · H H T*
- If the sequence is labelled, we can estimate  $p_1$ ,  $p_2$  separately
  - $\blacksquare$  H T T H H T H T H T H T H T H T H T H T
  - $p_1 = 8/12 = 2/3, p_2 = 3/8$



#### Mixture models ...

- Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
- Sequence of *N* interleaved coin tosses *H T H H · · · H H T*
- If the sequence is labelled, we can estimate  $p_1$ ,  $p_2$  separately
  - $\blacksquare$  H T T H H T H T H T H T H T H T H T H T
  - $p_1 = 8/12 = 2/3, p_2 = 3/8$
- What the observation is unlabelled?
  - $\blacksquare$  H T T H H T H T H T H T H T H T H T H T

#### Mixture models ...

- Two coins,  $c_1$  and  $c_2$ , with  $Pr(H) = p_1$  and  $p_2$ , respectively
- Sequence of *N* interleaved coin tosses *H T H H · · · · H H T*
- If the sequence is labelled, we can estimate  $p_1$ ,  $p_2$  separately
  - $\blacksquare$  H T T H H T H T H T H T H T H T H T H T
  - $p_1 = 8/12 = 2/3, p_2 = 3/8$
- What the observation is unlabelled?
- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters



- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$ 
    - 12 14 2

P(H & C1)?
P(H & C2)?

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
  - $Pr(c_1 = T) = q_1 = 1/2, Pr(c_2 = T) = q_2 = 3/4,$

Blade split as 2:1

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- $\blacksquare$  H T T H H T H T H T H T H T H T H T
  - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
  - $Pr(c_1 = T) = q_1 = 1/2, Pr(c_2 = T) = q_2 = 3/4,$
  - For each H, likelihood it was  $c_i$ ,  $Pr(c_i \mid H)$ , is  $p_i/(p_1 + p_2)$

4/14

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- $\blacksquare$  H T T H H T H T H T H T H T H T H T
  - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
  - $Pr(c_1 = T) = q_1 = 1/2, Pr(c_2 = T) = q_2 = 3/4,$
  - For each H, likelihood it was  $c_i$ ,  $Pr(c_i \mid H)$ , is  $p_i/(p_1 + p_2)$
  - For each T, likelihood it was  $c_i$ ,  $Pr(c_i \mid T)$ , is  $q_i/(q_1 + q_2)$

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- $\blacksquare$  H T T H H T H T H T H T H T H T H T
  - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
  - $Pr(c_1 = T) = q_1 = 1/2, Pr(c_2 = T) = q_2 = 3/4,$
  - For each H, likelihood it was  $c_i$ ,  $Pr(c_i \mid H)$ , is  $p_i/(p_1 + p_2)$
  - For each T, likelihood it was  $c_i$ ,  $Pr(c_i \mid T)$ , is  $q_i/(q_1 + q_2)$
  - Assign fractional count  $Pr(c_i \mid H)$  to each  $H: 2/3 \times c_1, 1/3 \times c_2$

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022 4 / 14

- Iterative algorithm to estimate the parameters
  - Make an initial guess for the parameters
  - Compute a (fractional) labelling of the outcomes
  - Re-estimate the parameters
- - Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
  - $Pr(c_1 = T) = q_1 = 1/2, Pr(c_2 = T) = q_2 = 3/4,$
  - For each H, likelihood it was  $c_i$ ,  $Pr(c_i \mid H)$ , is  $p_i/(p_1 + p_2)$
  - For each T, likelihood it was  $c_i$ ,  $Pr(c_i \mid T)$ , is  $q_i/(q_1 + q_2)$
  - Assign fractional count  $Pr(c_i \mid H)$  to each  $H: 2/3 \times c_1$ ,  $1/3 \times c_2$
  - Likewise, assign fractional count  $Pr(c_i \mid T)$  to each  $T: 2/5 \times c_1$ ,  $3/5 \times c_2$

4/14

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022

- $\blacksquare$  H T T H H T H T H T H T H T H T H T
- Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
- Fractional counts: each H is  $2/3 \times c_1$ ,  $1/3 \times c_2$ , each T:  $2/5 \times c_1$ ,  $3/5 \times c_2$

5/14

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022



- Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
- Fractional counts: each H is  $2/3 \times c_1$ ,  $1/3 \times c_2$ , each T:  $2/5 \times c_1$ ,  $3/5 \times c_2$
- Add up the fractional counts
  - $c_1$ :  $11 \cdot (2/3) = 22/3$  heads,  $9 \cdot (2/5) = 18/5$  tails
  - $c_2$ :  $11 \cdot (1/3) = 11/3$  heads,  $9 \cdot (3/5) = 27/5$  tails

- $\blacksquare$  HTTHHTHTHHTHTHTHTHTHT
- Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
- Fractional counts: each H is  $2/3 \times c_1$ ,  $1/3 \times c_2$ , each T:  $2/5 \times c_1$ ,  $3/5 \times c_2$
- Add up the fractional counts
  - $c_1$ :  $11 \cdot (2/3) = 22/3$  heads,  $9 \cdot (2/5) = 18/5$  tails
  - $c_2$ :  $11 \cdot (1/3) = 11/3$  heads,  $9 \cdot (3/5) = 27/5$  tails
- Re-estimate the parameters

$$p_2 = \frac{11/3}{11/3 + 27/5} = 55/136 = 0.40, \ q_2 = 1 - p_2 = 0.60$$



- $\blacksquare$  HTTHHTHTHTHTHTHTHT
- Initial guess:  $p_1 = 1/2$ ,  $p_2 = 1/4$
- Fractional counts: each H is  $2/3 \times c_1$ ,  $1/3 \times c_2$ , each T:  $2/5 \times c_1$ ,  $3/5 \times c_2$
- Add up the fractional counts
  - $c_1$ :  $11 \cdot (2/3) = 22/3$  heads,  $9 \cdot (2/5) = 18/5$  tails
  - $c_2$ :  $11 \cdot (1/3) = 11/3$  heads,  $9 \cdot (3/5) = 27/5$  tails
- Re-estimate the parameters

  - $p_2 = \frac{11/3}{11/3 + 27/5} = 55/136 = 0.40, q_2 = 1 p_2 = 0.60$

0.33+06 0.35+06

Repeat until convergence

Madhavan Mukund Lecture 16: 24 March, 2022

DMML Jan-May 2022

■ Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$ 

- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$



6/14

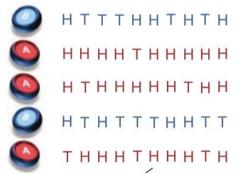
Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022

- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$
- Expectation step
  - Compute likelihoods  $Pr(M_i|o_j)$  for each  $M_i$ ,  $o_j$

- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$
- Expectation step
  - Compute likelihoods  $Pr(M_i|o_j)$  for each  $M_i$ ,  $o_j$
- Maximization step
  - **Recompute MLE** for each  $M_i$  using fraction of O assigned using likelihood

- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$
- Expectation step
  - Compute likelihoods  $Pr(M_i|o_j)$  for each  $M_i$ ,  $o_j$
- Maximization step
  - **Recompute MLE** for each  $M_i$  using fraction of O assigned using likelihood
- Repeat until convergence
  - Why should it converge?
  - If the value converges, what have we computed?

Two biased coins, choose a coin and toss 10 times, repeat 5 times



Two biased coins, choose a coin and toss 10 times, repeat 5 times







	Н	Т	Н	T	T	Т	H	Н	Т	T
--	---	---	---	---	---	---	---	---	---	---



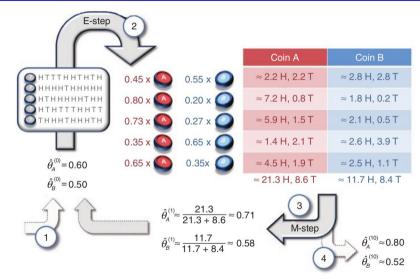
If we know the breakup, we can separately compute MLE for each coin

Coin A	Coin B				
	5 H, 5 T				
9 H, 1 T					
8 H, 2 T					
	4 H, 6 T				
7 H, 3 T					
24 H, 6 T	9 H, 11 T				

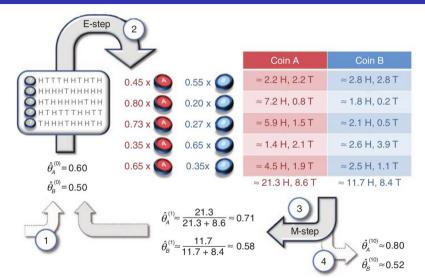
$$\hat{\theta}_{A} = \frac{24}{24+6} = 0.80$$

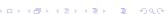
$$\hat{\theta}_{B} = \frac{9}{9 + 11} = 0.45$$

Expectation-Maximization

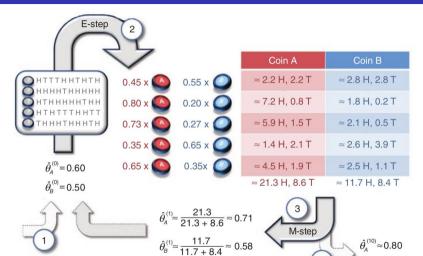


- Expectation-Maximization
- Initial estimates,  $\theta_A = 0.6$ ,  $\theta_B = 0.5$



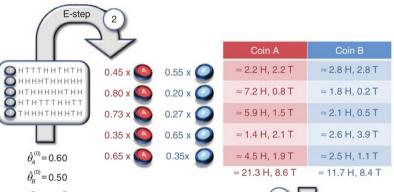


- Expectation-Maximization
- Initial estimates,  $\theta_A = 0.6$ ,  $\theta_B = 0.5$
- Compute likelihood of each sequence:  $\theta^{n_H}(1-\theta)^{n_T}$

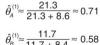


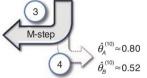


- Expectation-Maximization
- Initial estimates,  $\theta_A = 0.6$ ,  $\theta_B = 0.5$
- Compute likelihood of each sequence:  $\theta^{n_H}(1-\theta)^{n_T}$
- Assign each sequence proportionately



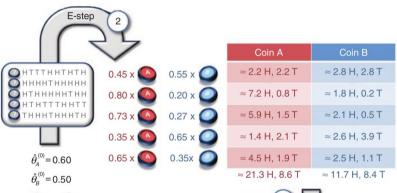


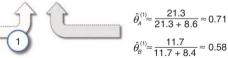


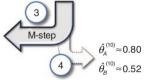


Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan

- Expectation-Maximization
- Initial estimates,  $\theta_A = 0.6$ ,  $\theta_B = 0.5$
- Compute likelihood of each sequence:  $\theta^{n_H}(1-\theta)^{n_T}$
- Assign each sequence proportionately
- Converge to  $\theta_A = 0.8$ ,  $\theta_B = 0.52$



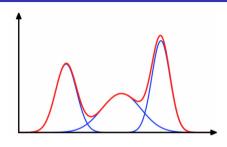




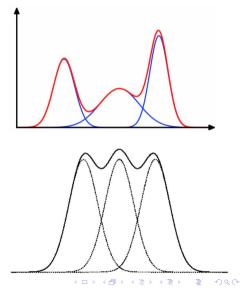
8/14

Madhavan Mukund Lecture 16: 24 March, 2022 DMML Jan-May 2022

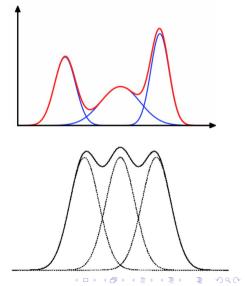
■ Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$ 



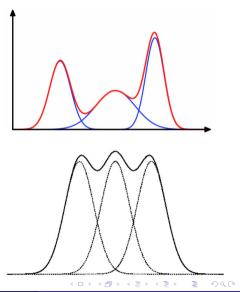
- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$



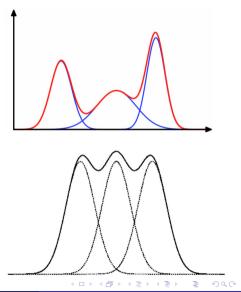
- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, \ldots, z_N$



- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, ..., z_N$
- Make an initial guess for each  $\mu_i$



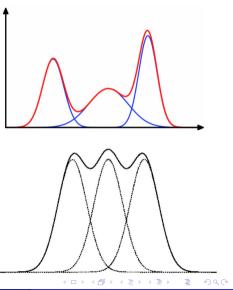
- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, \ldots, z_N$
- lacksquare Make an initial guess for each  $\mu_j$
- $Pr(z_i \mid \mu_j) = exp(-\frac{1}{2\sigma^2}(z_i \mu_j)^2)$



- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, ..., z_N$
- lacksquare Make an initial guess for each  $\mu_j$

• 
$$Pr(z_i \mid \mu_j) = exp(-\frac{1}{2\sigma^2}(z_i - \mu_j)^2)$$

$$Pr(\mu_j \mid z_i) = c_{ij} = \frac{Pr(z_i \mid \mu_j)}{\sum_k Pr(z_i \mid \mu_k)}$$

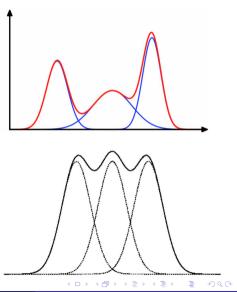


- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, \ldots, z_N$
- lacksquare Make an initial guess for each  $\mu_j$

• 
$$Pr(z_i \mid \mu_j) = exp(-\frac{1}{2\sigma^2}(z_i - \mu_j)^2)$$

$$Pr(\mu_j \mid z_i) = c_{ij} = \frac{Pr(z_i \mid \mu_j)}{\sum_k Pr(z_i \mid \mu_k)}$$

■ MLE of  $\mu_j$  is sample mean,  $\frac{\sum_i c_{ij}z_i}{\sum_i c_{ij}}$ 

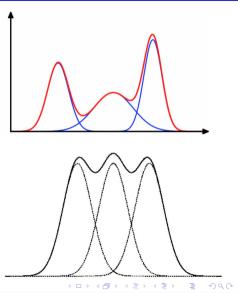


- Sample uniformly from multiple Gaussians,  $\mathcal{N}(\mu_i, \sigma_i)$
- For simplicity, assume all  $\sigma_i = \sigma$
- N sample points  $z_1, z_2, \ldots, z_N$
- lacksquare Make an initial guess for each  $\mu_j$

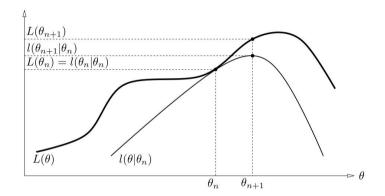
• 
$$Pr(z_i \mid \mu_j) = exp(-\frac{1}{2\sigma^2}(z_i - \mu_j)^2)$$

$$Pr(\mu_j \mid z_i) = c_{ij} = \frac{Pr(z_i \mid \mu_j)}{\sum_k Pr(z_i \mid \mu_k)}$$

- MLE of  $\mu_j$  is sample mean,  $\frac{\sum_i c_{ij} z_i}{\sum_i c_{ij}}$
- Update estimates for  $\mu_i$  and repeat



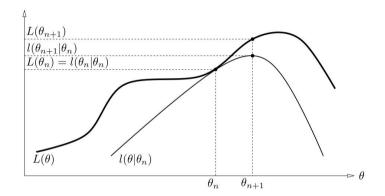
■ Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$ 



■ Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$ 

Observation

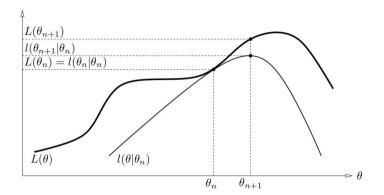
$$O = o_1 o_2 \dots o_N$$



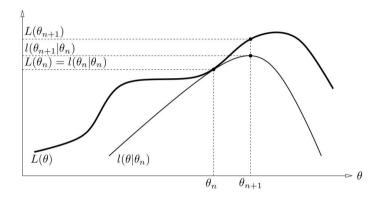
■ Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$ 

$$O = o_1 o_2 \dots o_N$$

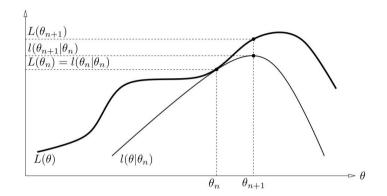
■ EM builds a sequence of estimates  $\Theta_1, \Theta_2, \dots, \Theta_n$ 



- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$
- EM builds a sequence of estimates  $\Theta_1, \Theta_2, \ldots, \Theta_n$
- $L(\Theta_j)$  log-likelihood function,  $\ln Pr(O \mid \Theta_j)$



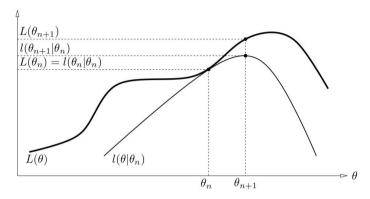
- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$ with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $Q = Q_1 Q_2 \dots Q_N$
- EM builds a sequence of estimates  $\Theta_1, \Theta_2, \dots, \Theta_n$
- $L(\Theta_j)$  log-likelihood function,  $\ln Pr(O \mid \Theta_j)$
- Want to extend the sequence with  $\Theta_{n+1}$  such that  $L(\Theta_{n+1}) > L(\Theta_n)$



- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$  with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation

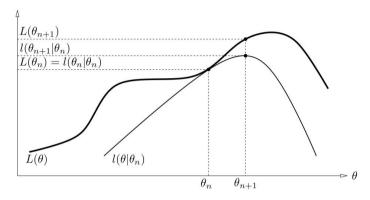
$$O = o_1 o_2 \dots o_N$$

- EM builds a sequence of estimates  $\Theta_1, \Theta_2, \dots, \Theta_n$
- $L(\Theta_j)$  log-likelihood function,  $\ln Pr(O \mid \Theta_j)$
- Want to extend the sequence with  $\Theta_{n+1}$  such that  $L(\Theta_{n+1}) > L(\Theta_n)$



■ EM performs a form of gradient descenct

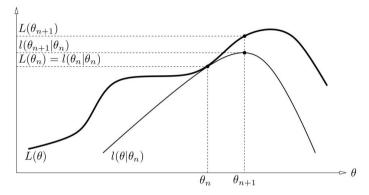
- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$ with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $Q = Q_1 Q_2 \dots Q_N$
- EM builds a sequence of estimates  $\Theta_1, \Theta_2, \dots, \Theta_n$
- $L(\Theta_j)$  log-likelihood function,  $\ln Pr(O \mid \Theta_j)$
- Want to extend the sequence with  $\Theta_{n+1}$  such that  $L(\Theta_{n+1}) > L(\Theta_n)$



- EM performs a form of gradient descenct
- If we update  $\Theta_n$  to  $\Theta'$  we get an new likelihood  $L(\Theta_n) + \Delta(\Theta', \Theta_n)$  which we call  $\ell(\Theta' \mid \Theta_n)$



- Mixture of probabilistic models  $(M_1, M_2, ..., M_k)$ with parameters  $\Theta = (\theta_1, \theta_2, ..., \theta_k)$
- Observation  $O = o_1 o_2 \dots o_N$
- EM builds a sequence of estimates  $\Theta_1, \Theta_2, \dots, \Theta_n$
- $L(\Theta_j)$  log-likelihood function,  $\ln Pr(O \mid \Theta_j)$
- Want to extend the sequence with  $\Theta_{n+1}$  such that  $L(\Theta_{n+1}) > L(\Theta_n)$



- EM performs a form of gradient descenct
- If we update  $\Theta_n$  to  $\Theta'$  we get an new likelihood  $L(\Theta_n) + \Delta(\Theta', \Theta_n)$  which we call  $\ell(\Theta' \mid \Theta_n)$
- Choose  $\Theta_{n+1}$  to maximize  $\ell(\Theta' \mid \Theta_n)$

Supervised learning requires labelled training data

- Supervised learning requires labelled training data
- What if we don't have enough labelled data?

- Supervised learning requires labelled training data
- What if we don't have enough labelled data?
- For a probabilistic classifier we can apply EM

11 / 14

- Supervised learning requires labelled training data
- What if we don't have enough labelled data?
- For a probabilistic classifier we can apply EM
  - Use available training data to assign initial probabilities

11 / 14

- Supervised learning requires labelled training data
- What if we don't have enough labelled data?
- For a probabilistic classifier we can apply EM
  - Use available training data to assign initial probabilities
  - Label the rest of the data using this model fractional labels

11 / 14

- Supervised learning requires labelled training data
- What if we don't have enough labelled data?
- For a probabilistic classifier we can apply EM
  - Use available training data to assign initial probabilities
  - Label the rest of the data using this model fractional labels
  - Add up counts and re-estimate the parameters

11 / 14

■ Each document is a multiset or bag of words over a vocabulary

$$V = \{w_1, w_2, \dots, w_m\}$$

$$N_{\mathbf{k}} - N_{\mathbf{k}}$$

Set of words
Ray/multiset of words

- Each document is a multiset or bag of words over a vocabulary  $V = \{w_1, w_2, \dots, w_m\}$
- Each topic c has probability Pr(c)

Madhayan Mukund Lecture 16: 24 March. 2022 DMML Jan-May 2022 12 / 14

- Each document is a multiset or bag of words over a vocabulary  $V = \{w_1, w_2, \dots, w_m\}$
- Each topic c has probability Pr(c)
- Each word  $w_i \in V$  has conditional probability  $Pr(w_i \mid c_j)$ , for  $c_j \in C$ 
  - Note that  $\sum_{i=1}^{m} Pr(w_i \mid c_j) = 1$

- Each document is a multiset or bag of words over a vocabulary  $V = \{w_1, w_2, \dots, w_m\}$
- Each topic c has probability Pr(c)
- Each word  $w_i \in V$  has conditional probability  $Pr(w_i \mid c_j)$ , for  $c_j \in C$ 
  - Note that  $\sum_{i=1}^{m} Pr(w_i \mid c_j) = 1$
- Assume document length is independent of the class

12 / 14

- Each document is a multiset or bag of words over a vocabulary  $V = \{w_1, w_2, \dots, w_m\}$
- Each topic c has probability Pr(c)
- Each word  $w_i \in V$  has conditional probability  $Pr(w_i \mid c_j)$ , for  $c_j \in C$ 
  - Note that  $\sum_{i=1}^{m} Pr(w_i \mid c_j) = 1$

- severate one word
- Assume document length is independent of the class
- Only a small subset of documents is labelled
  - Use this subset for initial estimate of Pr(c),  $Pr(w_i \mid c_j)$

last nord

■ Current model Pr(c),  $Pr(w_i | c_j)$ 

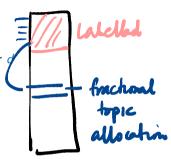
- Current model Pr(c),  $Pr(w_i | c_j)$
- Compute  $Pr(c_i \mid d)$  for each unlabelled document d
  - Normally we assign the maximum among these as the class for d
  - Here we keep fractional values

13 / 14

- Current model Pr(c),  $Pr(w_i | c_j)$
- Compute  $Pr(c_j \mid d)$  for each unlabelled document d
  - Normally we assign the maximum among these as the class for
  - Here we keep fractional values

Recompute 
$$Pr(c_j) = \frac{\sum_{d \in D} Pr(c_j \mid D)}{|D|}$$

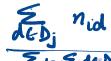
- For labelled d,  $Pr(c_j \mid d) \in \{0, 1\}$
- For unlabelled d,  $Pr(c_i \mid d)$  is fractional value computed from current parameters



13 / 14

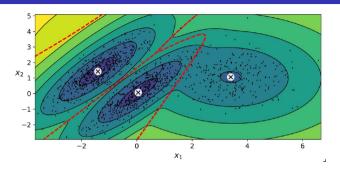
- Current mode  $(Pr(c), Pr(w_i \mid c_j))$
- Compute  $Pr(c_j \not\mid d)$  for each unlabelled document d
  - Normally we assign the maximum among these as the class for d
  - Here we keep fractional values
- Recompute  $Pr(c_j) = \frac{\sum_{d \in D} Pr(c_j \mid D)}{|D|}$ 
  - For labelled d,  $P_r(c_i \mid d) \in \{0, 1\}$
  - For unlabelled d,  $Pr(c_j \mid d)$  is fractional value computed from current parameters
- Recompute  $Pr(y_i \mid c_j)$  fraction of occurrences of  $w_i$  in documents labelled  $c_j$ 
  - $\blacksquare$   $n_{id}$  occurrences of  $w_i$  in d

$$Pr(w_i \mid c_j) = \frac{\sum_{d \in D} n_{id} Pr(c_j \mid d)}{\sum_{t=1}^{m} \sum_{d \in L} n_{td} Pr(c_j \mid d)}$$

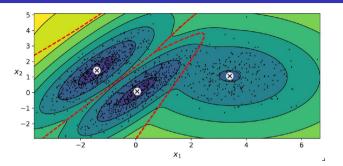


es ntd

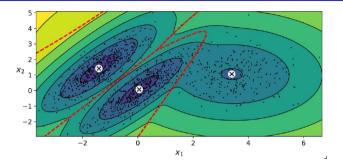
 Data points from a mixture of Gaussian distributions



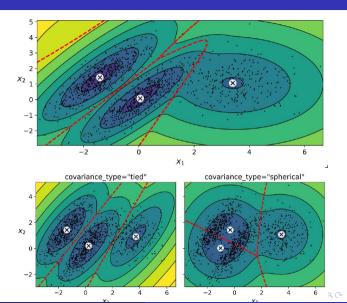
- Data points from a mixture of Gaussian distributions
- Use EM to estimate the parameters of each Gaussian distribution



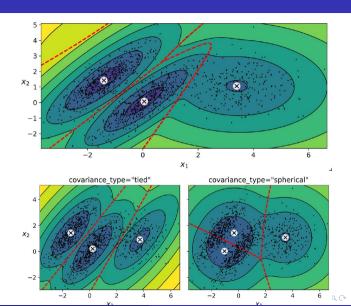
- Data points from a mixture of Gaussian distributions
- Use EM to estimate the parameters of each Gaussian distribution
- Assign each point to "best" Gaussian



- Data points from a mixture of Gaussian distributions
- Use EM to estimate the parameters of each Gaussian distribution
- Assign each point to "best"
   Gaussian
- Can tweak the shape of the clusters by constraining the covariance matrix



- Data points from a mixture of Gaussian distributions
- Use EM to estimate the parameters of each Gaussian distribution
- Assign each point to "best"
   Gaussian
- Can tweak the shape of the clusters by constraining the covariance matrix
- Outliers are those that are outside  $k\sigma$  for all the Gaussians



- Data points from a mixture of Gaussian distributions
- Use EM to estimate the parameters of each Gaussian distribution
- Assign each point to "best"
   Gaussian
- Can tweak the shape of the clusters by constraining the covariance matrix
- Outliers are those that are outside  $k\sigma$  for all the Gaussians

