

Probabilistic Graphical Models

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Conditional probabilities

- Boolean variables x_1, x_2, \dots, x_n

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- Naïve Bayes assumption — complete independence
 - $P(x_i = 1)$ for each x_i
 - n parameters

Conditional probabilities

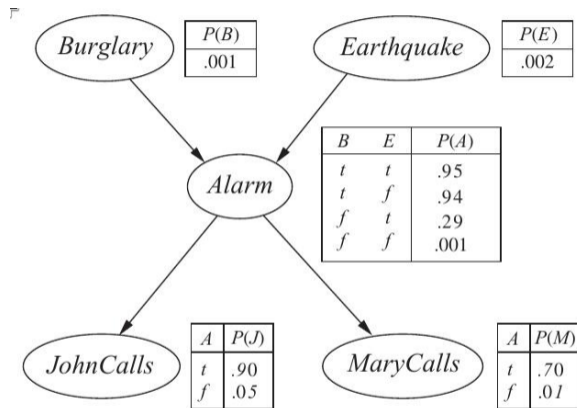
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- Naïve Bayes assumption — complete independence
 - $P(x_i = 1)$ for each x_i
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- Can we strive for something in between?
 - “Local” dependencies between some variables

Probabilistic graphical models

- Judea Pearl [[Turing Award 2011](#)]
- Represent local dependencies using directed graph

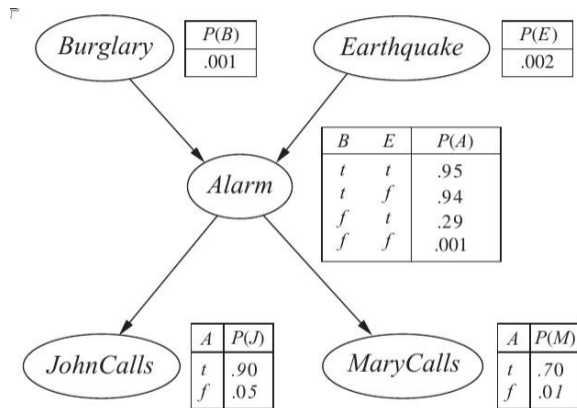
Probabilistic graphical models

- Judea Pearl [Turing Award 2011]
- Represent local dependencies using directed graph
- Example: Burglar alarm
 - Pearl's house has a burglar alarm
 - Neighbours John and Mary call if they hear the alarm
 - John is prone to mistaking ambulances etc for the alarm
 - Mary listens to loud music and sometimes fails to hear the alarm
 - The alarm may also be triggered by an earthquake (California!)



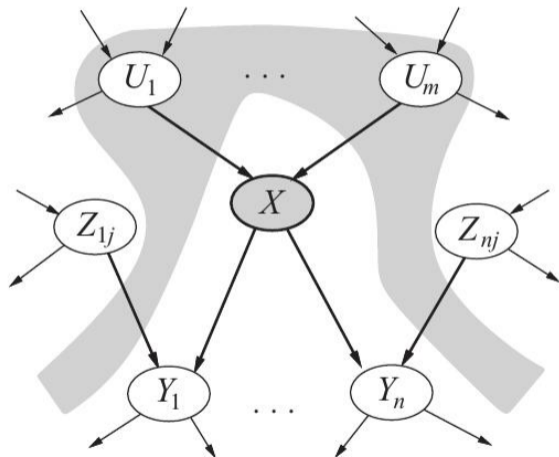
Probabilistic graphical models

- Each node has a local (conditional) probability table



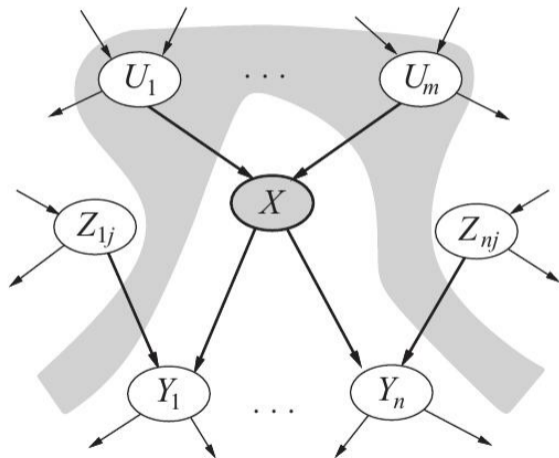
Probabilistic graphical models

- Each node has a local (conditional) probability table
- Fundamental assumption:
A node is conditionally independent of non-descendants, given its parents



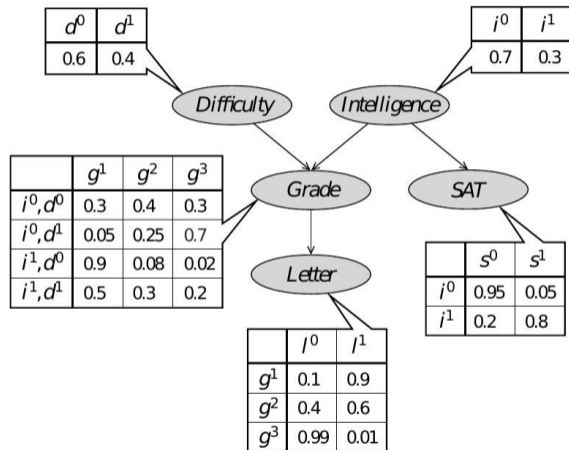
Probabilistic graphical models

- Each node has a local (conditional) probability table
- Fundamental assumption:
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- Graph is a DAG, no cyclic dependencies



Student example

- Example due to Nir Friedman and Daphne Koller
- Student asks teacher for a reference letter
- Teacher has forgotten the student, so letter is entirely based on student's grade in the course



Evaluating a network

- John and Mary call Pearl. What is the probability that there has been a burglary?

- $P(b, m, j)$, where b : burglary, j : John calls, m : Mary calls

- $P(b, m, j) = \sum_{a=0}^1 \sum_{e=0}^1 P(b, j, m, a, e)$, where a : alarm rings, e : earthquake

- Bayes Rule: $P(A, B) = P(A | B)P(B)$

- $P(x_1, x_2, \dots, x_n) = P(x_1 | x_2, \dots, x_n)P(x_2, x_3, \dots, x_n)$

- Recursively:

$$P(x_1, x_2, \dots, x_n) = P(x_1 | x_2, \dots, x_n)P(x_2 | x_3, \dots, x_n) \cdots P(x_{n-1} | x_n)P(x_n)$$

Evaluating a network

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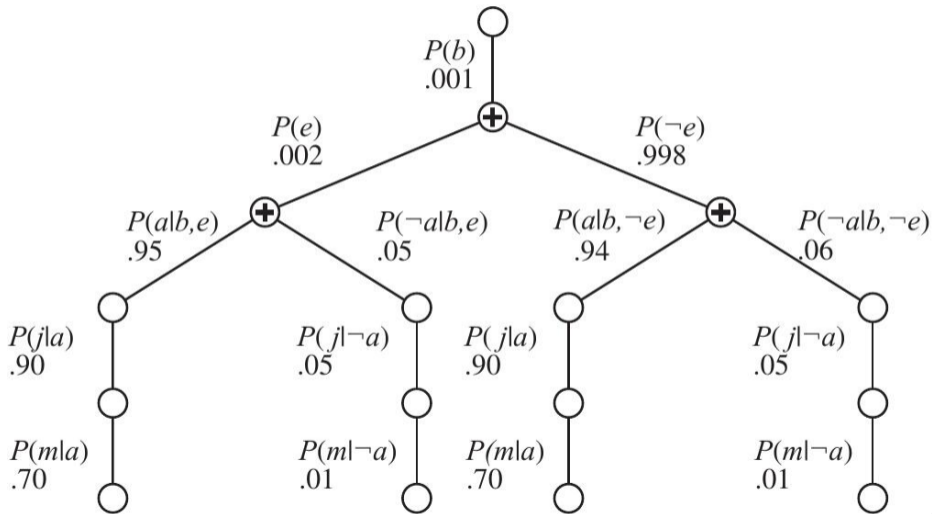
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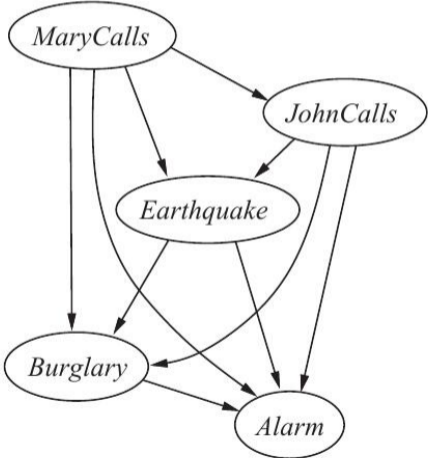
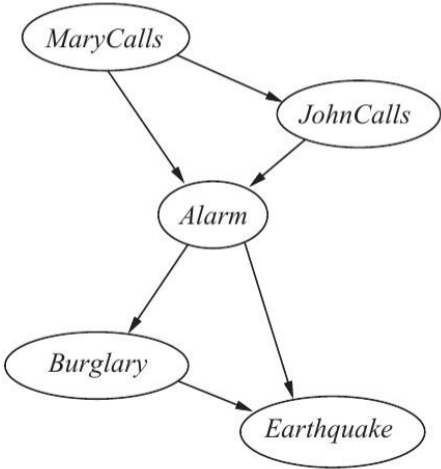
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- $$P(m, j, b) = P(b) \sum_{e=0}^1 P(e) \sum_{a=0}^1 P(m | a)P(j | a)P(a | b, e)$$

Evaluation tree



Alternative networks



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- How does dependence “flow” through a network?
- Construct **trails** between nodes
 - Path in the underlying undirected graph

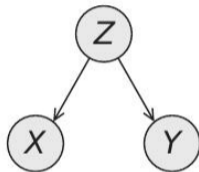
Basic trails



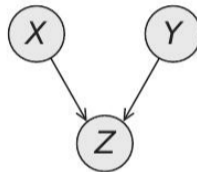
(a)



(b)



(c)



(d)

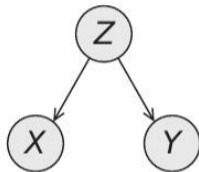
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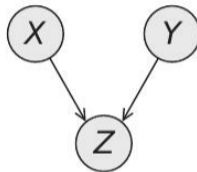
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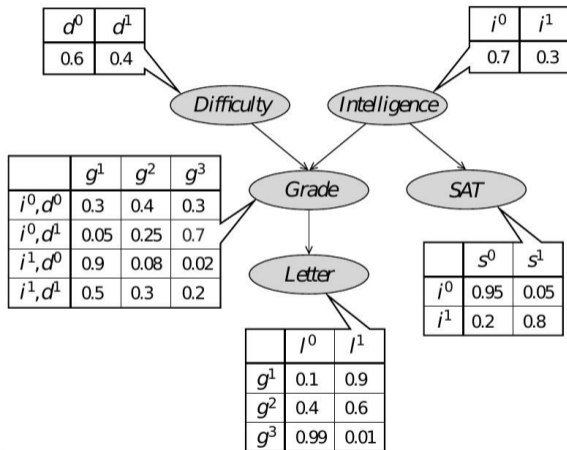
- V-structure in (d) allows influence to flow
- In all other cases, Z blocks flow between X and Y

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 - $P(X \cup Y) = P(X)P(Y)$
- $X \perp Y \mid Z$ — X and Y are independent if Z is known
- How does dependence “flow” through a network?
- Construct **trails** between nodes
 - Path in the underlying undirected graph
- X and Y are conditionally independent given Z if Z blocks every trail between X and Y
 - Adapt breadth-first search to check this

Conditional independence, example

- Is **SAT** independent of **Difficulty** given **Intelligence**?
- Yes, **Difficulty** – **Grade** – **Intelligence** – **SAT** trail is blocked at **Grade** (V-structure)



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 - Yes, **Difficulty** – **Grade** – **Intelligence** – **SAT** trail is blocked at **Grade** (V-structure)
- Is **SAT** independent of **Difficulty** given **Grade**?
 - No, **Difficulty** – **Grade** – **Intelligence** – **SAT** trail is open because **Grade** is known (V-structure)

