

Net : $N = (P, T, F)$

P : places

T : transitions - unlabelled

F : Flow relation

$F \subseteq (P \times T) \cup (T \times P)$ - bipartite

$x \in P \cup T$ $\bullet x = \{y \mid (y, x) \in F\}$

$x^\circ = \{y \mid (x, y) \in F\}$

$x \in P \cup T$ $\bullet x, x^\circ$

Labelled transitions

(s, s')

(s_1, s'_1)

$t_1 \downarrow a$

$t_2 \downarrow a$

(t, t')

(t_1, t'_1)

Dynamics of a net

Marking

$$M: P \rightarrow \mathbb{N}_0$$

"Case"

$$M: P \rightarrow \{0,1\}$$

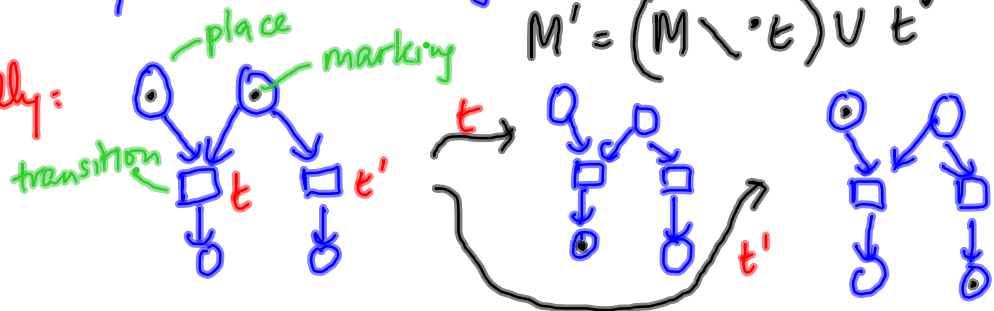
$$M \subseteq P$$

$$\hookrightarrow C \subseteq P \text{ or } C \subseteq P$$

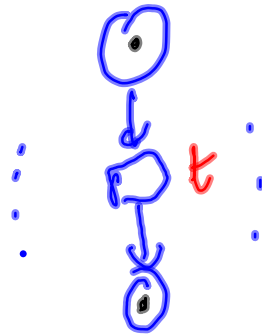
Distributed
StateInitial marking: M_{in}
 $t \in T$ being enabled at a marking M $\cdot t \subseteq M$
 t occurs/fires and changes M to M'

$$M' = (M \setminus \cdot t) \cup t'$$

Graphically:



Dynamics:

Is t enabled?Elementary
Net
SystemsDisable t t enabled at M

$$t \in M \wedge t' \cap M = \emptyset$$

$$\text{effect: } M' = (M \setminus t) \cup t'$$

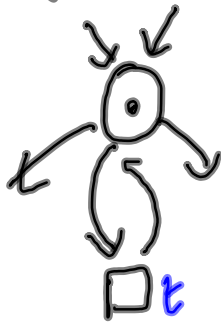
Place/Transition net
"Petri nets"Enable t , allow arbitrary
markings

$$\forall p \in {}^*t \quad M(p) > 0$$

$$\text{effect: } \forall p \in {}^*t, M'(p) = M(p) - 1$$

$$\text{Then } \forall p \in t', M'(p) = M(p) + 1$$

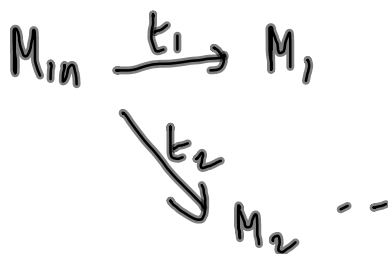
Elementary net systems : $ENS = (N, Min)$, $N = (P, T, F)$



t is "dead"

$$M \xrightarrow{t} M'$$

t enabled at M
& produces M'



Reachable markings from Min

$Reach(Min)$:

$$Min \in Reach(Min)$$

$$M \in Reach(Min), M \xrightarrow{t} M'$$

$$\Rightarrow M' \in Reach(Min)$$

$M \xrightarrow{t} M'$ is written as $M[t > M'$

$M \xrightarrow{t}$ t is enabled at M $M[t >$

t on M " t has concession at M "

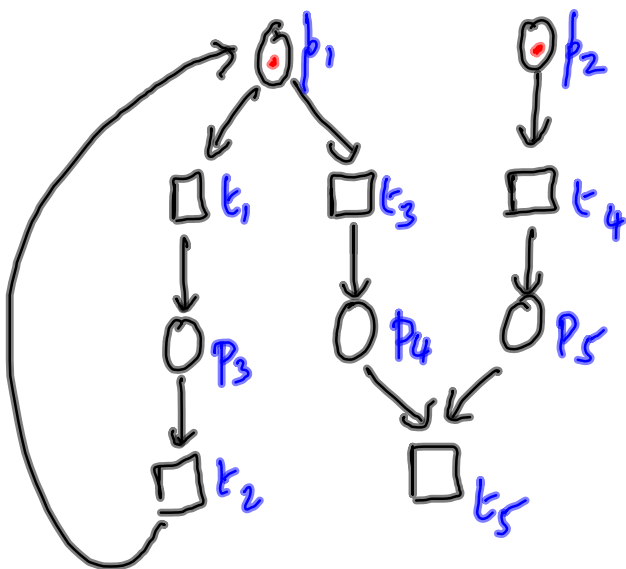
t is "useful" if $\exists M \in \text{Reach}(\text{Min})$, $M[t >$

Assume all transitions are useful

M is a "deadlocked" marking if $\nexists t$ $M[t >$

t is live if from every $M \in \text{Reach}(\text{Min})$
 t is useful in (N, M)

(N, M) is live if wty $\dagger \in T$ is live



$M_{in}[t_1]$

$M_{in}[t_3]$

$M_{in}[t_4]$

t_1 & t_4 are "independent"

$${}^{\circ}t_1 \cap {}^{\circ}t_4 = \emptyset$$

t_1 & t_3 are "in conflict"

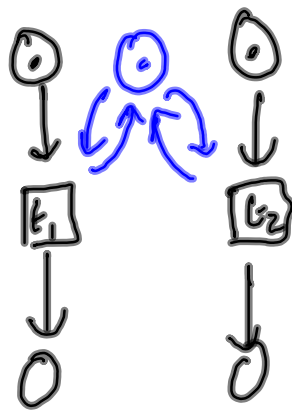
$$M_{in}[t_1] M_1, M_1 \cancel{[t_3]}$$

$$M_{in}[t_3] M_3, M_3 \cancel{[t_1]}$$

$M[t_1] M_1 \quad \& \quad M_2[t_1] \& M_1[t_2]$
 $M[t_2] M_2$
 $\Rightarrow t_1 \& t_2$ are independent

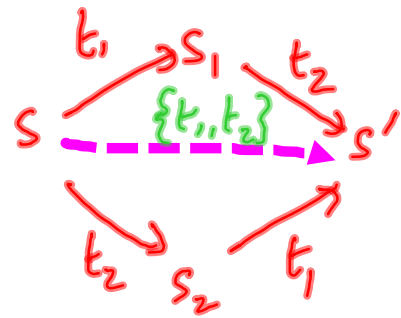
$M \xrightarrow{t_1} M_1 \xrightarrow{t_2} M'$
 $M \xrightarrow{t_2} M_2 \xrightarrow{t_1} M'$

Not true for P/T nets



Marking graph (or case graph) of (N, Min) $N = (P, T, F)$
 $TS = (S, \rightarrow, s_{in})$ $S = Reach(Min)$
 $s_{in} = Min$
 $\rightarrow \subseteq S \times T \times S$ $M \xrightarrow{t} M'$ if net permits it

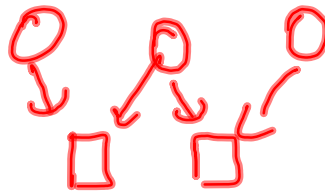
Extended marking graph
 $\rightarrow \subseteq S \times 2^T \times S$



"Fundamental" situations

t_1 & t_2 can occur concurrently
independence

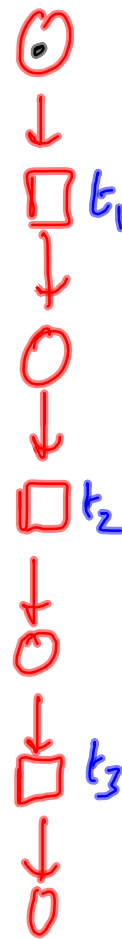
t_1 & t_2 are in conflict



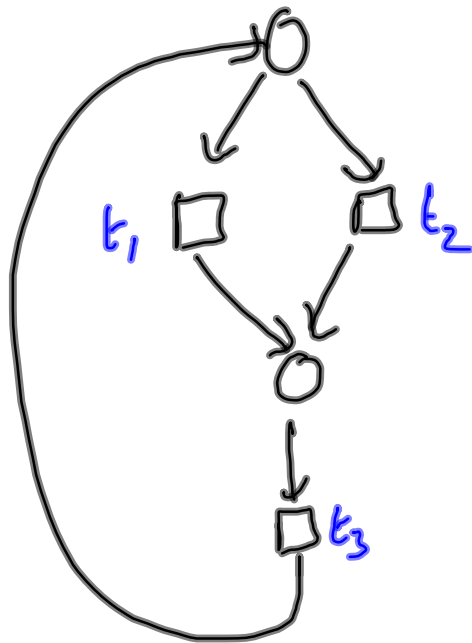
t_2 causally depends on t_1

define wrt a sequence of
executed transitions

firing
sequence



Difficult to define causality abstractly based on structure of net

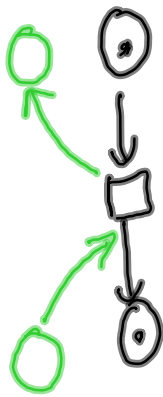


Is t_3 causally dependent on t_1 or t_2 ?

Or wrt marking (cf. Engelfriet, Rozenberg)

t_2 is causally dep on t_1 at M if
 $M \not\rightarrow t_2$ but $M \xrightarrow{t_1} M_1 \xrightarrow{t_2}$

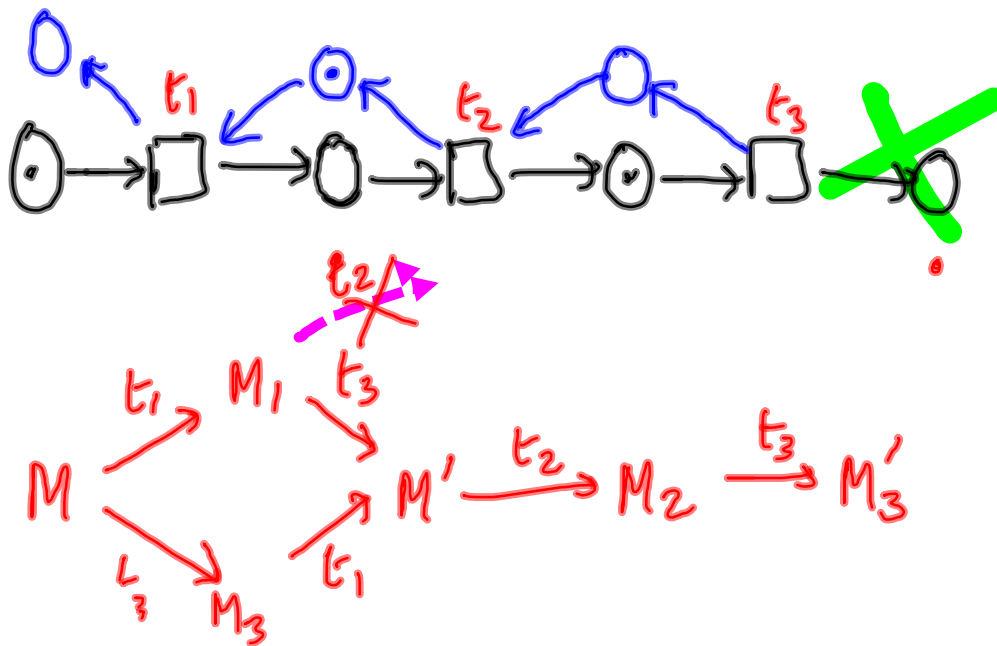
t is disabled at M only because $t^* \cap M \neq \emptyset$



"Contact"

Can make all ENS contact free by
adding complementary places

(equivalent nets have
isomorphic marking graphs)



Proof? Ex for Precede

Language of net = set of firing sequences

$FS(ENS)$

prefix closed

$w \in FS(ENS)$
 $v \preceq w \Rightarrow v \in FS(ENS)$

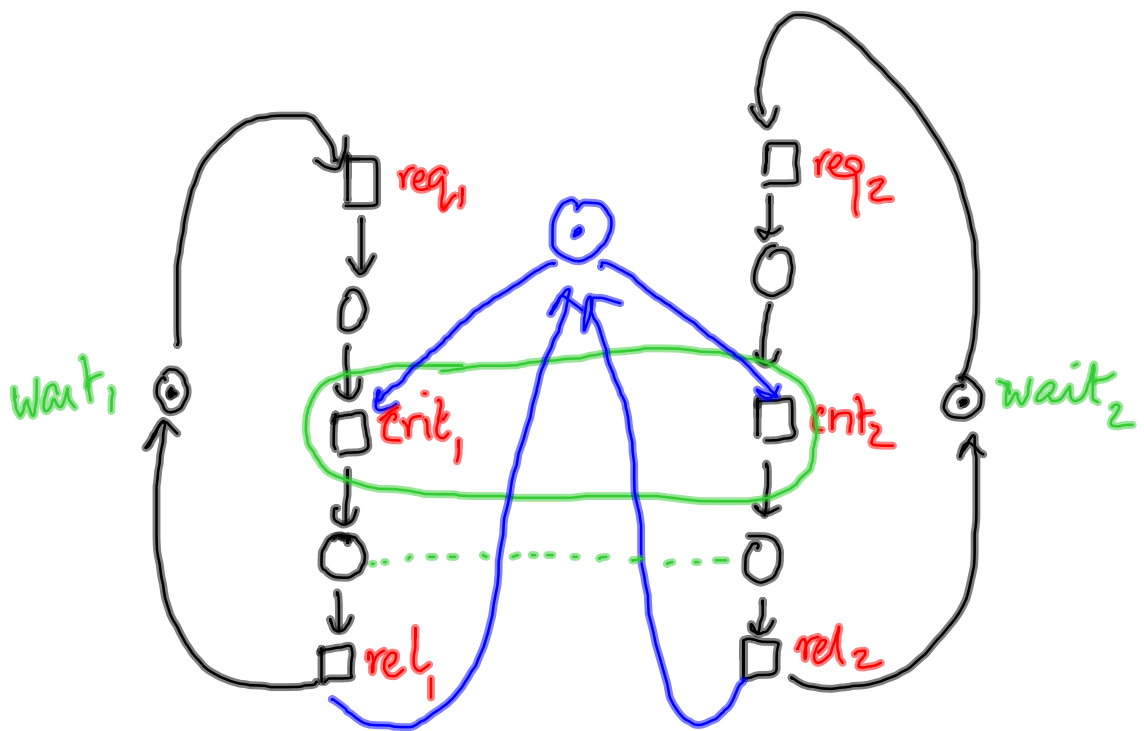
regular (because Reach(Min)
 is always finite)

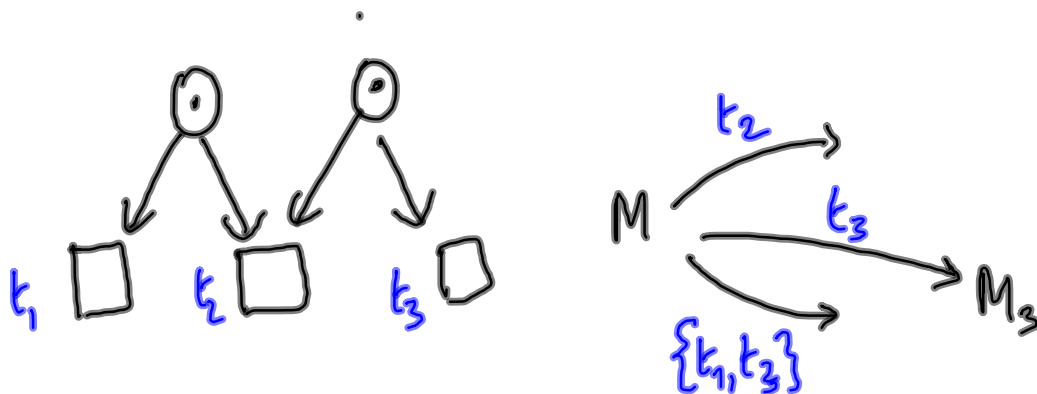
Recovering info from $FS(ENS)$

$w_1, w_2 \in FS$
 $w_2, w_1 \in FS$ > independent!

Note: Unlabelled nets are deterministic!

Example: Mutual Exclusion





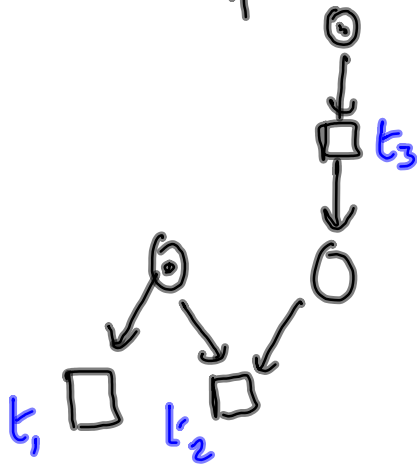
At M : t_1 & t_2 in conflict
 t_2 & t_3 in conflict

At M_3 t_1 & t_2 are no longer in conflict

"Confusion"

(M, t_1, t_2) is a confusion
 of $M \xrightarrow{t_1}$, $M \xrightarrow{t_2}$ and firing t_2
 changes conflict set of t_1

Symmetric ~~conflict~~: (M, t_1, t_2) & (M, t_2, t_1) are both
 confusion



(M, t_1, t_3) is a confusion

(M, t_3, t_1) is not a confusion

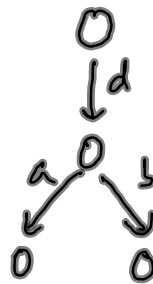
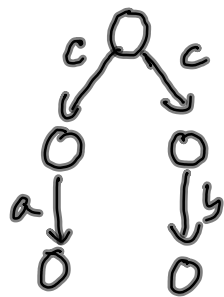
Asymmetric

Confusion-free systems are "easier"
 to analyse

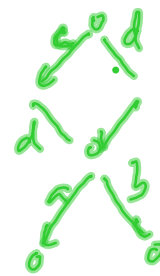
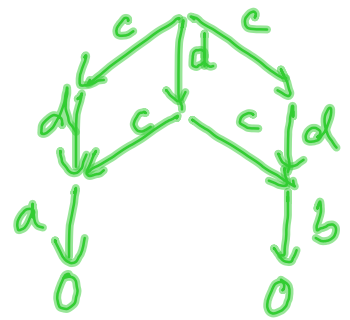
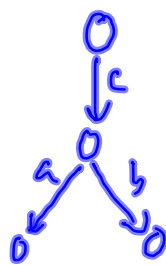
Automata — languages

$\{a, b, c, \dots\}$

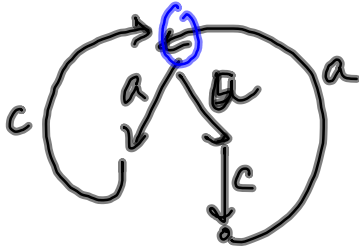
$\{a, b, d, \dots\}$



$=$



Automaton \rightarrow unfolding



Tree

