

## Nonlinear Dynamics, Spring 2019 CMI

### Problem set 3

Due at the beginning of lecture on Monday Feb 18, 2019

### Picard iteration and Bifurcations of 1d vector fields

1. **(10)** Picard iteration is a method to solve the IVP  $\dot{x} = v(x)$ ,  $x(0) = x_0$  and to prove the existence-uniqueness theorem when  $v$  is continuously differentiable. It proceeds by defining a sequence of functions  $x_k(t)$  for  $k = 0, 1, 2, \dots$  inductively via

$$x_0(t) = x_0 \quad \text{and} \quad x_{k+1}(t) = x_0 + \int_0^t v(x_k(t')) dt'. \quad (1)$$

which converge to the solution. Let us illustrate the method with two simple examples.

- (a) **(4)** Obtain the Picard iterates  $x_k(t)$  for  $\dot{x} = ax$  subject to the IC  $x(0) = x_0$ . To which function do they converge as  $k \rightarrow \infty$ ?
  - (b) **(6)** Obtain the Picard iterates  $\mathbf{x}_k(t)$  for  $\dot{\mathbf{x}} = A\mathbf{x}$  where  $A = \sigma_1 = (01|10)$  with IC  $\mathbf{x}(0) = (1, 0)^t$ . To which  $\mathbf{x}(t)$  do they converge as  $k \rightarrow \infty$ ?
2. **(10)** Consider the family of 1D vector fields  $\dot{x} = v(x) = \beta \tanh x - x$  with real  $\beta$  a control parameter. Sketch the phase portraits and plot  $v(x)$  for three qualitatively different  $\beta$ . Show that it displays a bifurcation (what type of bifurcation is it?) and find the bifurcation point  $\beta_c$  and the fixed point  $x_*$  at  $\beta_c$ . Draw a bifurcation diagram and explain how the character of the phase portrait changes.