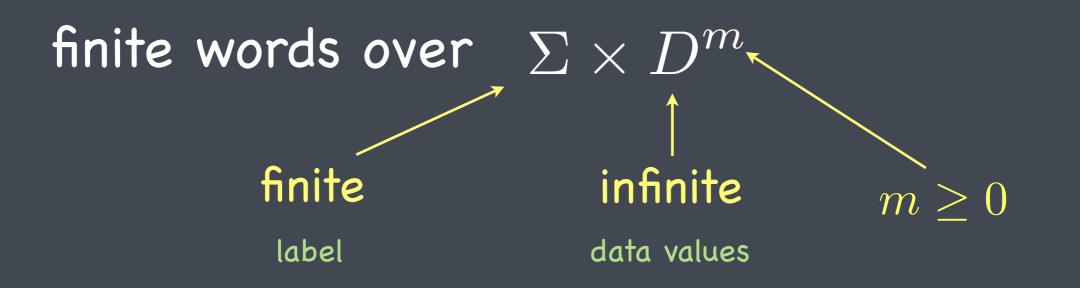
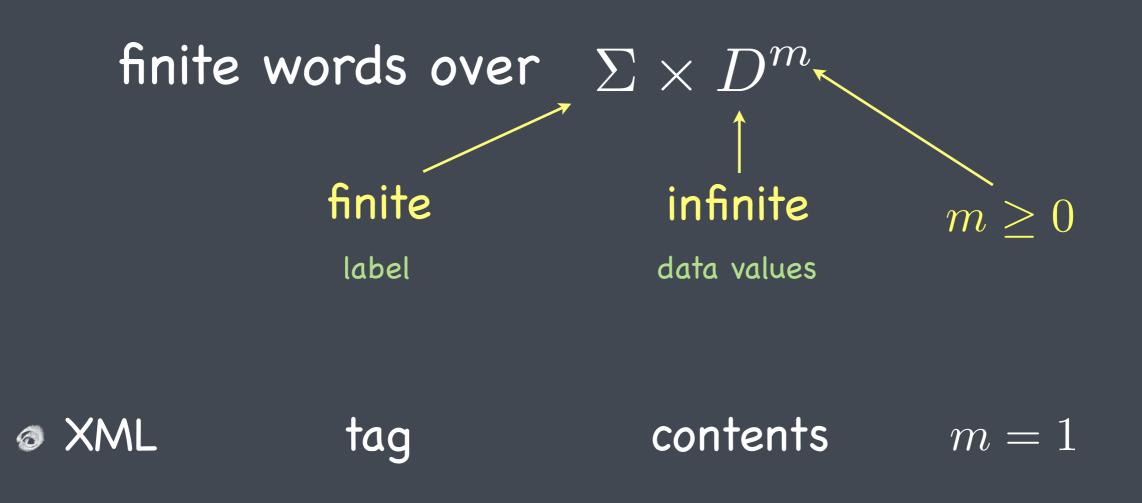
An automaton over data words that captures EMSO logic

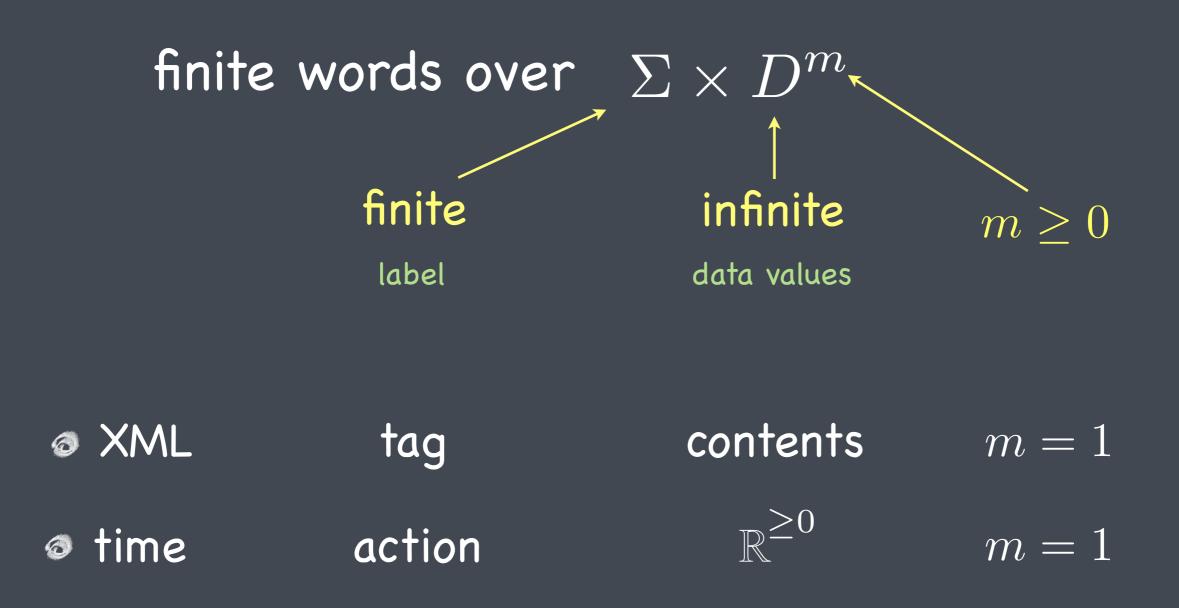
Benedikt Bollig LSV, ENS Cachan & CNRS

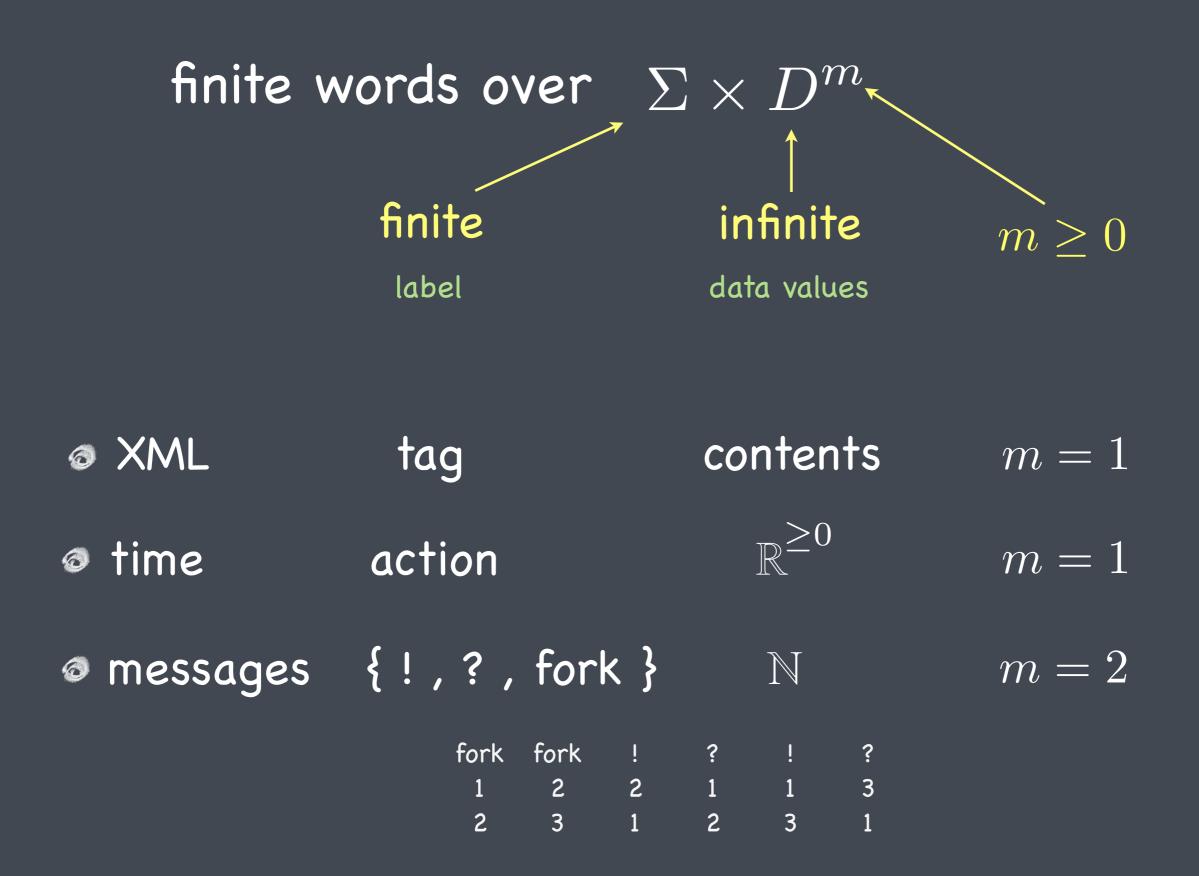
Automata, Concurrency and Timed Systems (ACTS) III

Chennai Mathematical Institute, January 27–29, 2011









Logic

Specifying properties

Ø Declarative (what should happen)

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- Automata
 - Implementation model (how it should happen)
 - Tool for checking satisfiability

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- Specifying properties
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 Tool for checking satisfiability

Looking for an expressive logic with reasonable implementation model (one-way, non-deterministic)



- a(x) position x carries $a \in \Sigma$ • $x \prec_{+1} y$ y is direct successor of x
- $\varphi_1 \lor \varphi_2$ $\neg \varphi$ $\exists x \varphi$ $\exists X \varphi$ $x \in X$

a(x) position x carries $a \in \Sigma$ $x \prec_{+1} y$ y is direct successor of x $\varphi_1 \lor \varphi_2 \quad \neg \varphi \quad \exists x \varphi \quad \exists X \varphi \quad x \in X$ $d^k(x) = d^l(y)$ k-th data value at x $d^k(x) = d^l(y)$ k-th data value at x

- a(x) position x carries a ∈ Σ
 x ≺₊₁ y y is direct successor of x
 φ₁ ∨ φ₂ ¬φ ∃xφ ∃Xφ x ∈ X
 d^k(x) = d^l(y) _______ k_=th data value at x
 - $k,l \in \{1, \dots, m\}$ equals l -th data value at y

too expressive

- => restrict access to data values
- => relate positions that automaton can access

Signature: finite set of relation symbols \lhd such that

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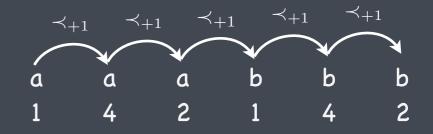
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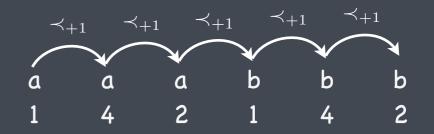
for all *i* there is at most one *j* such that $j \triangleleft^w i$

monotonicity

 $i \triangleleft^{w} j \land i' \triangleleft^{w} j' \land w_{i} = w_{i'} \land w_{j} = w_{j'}$ $\implies i < i' \quad \text{iff} \quad j < j'$

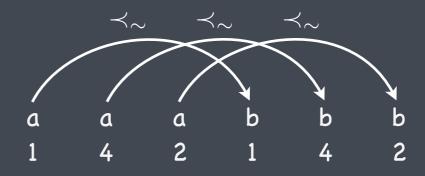
 \odot direct successor relation \prec_{+1}

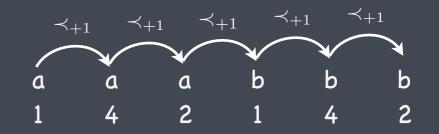




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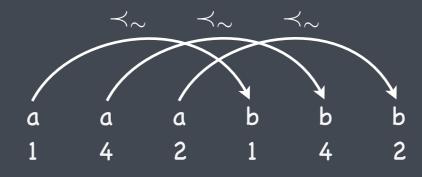
 ${\it I}$ successive positions with the same data value $\,\prec_{\sim}\,$



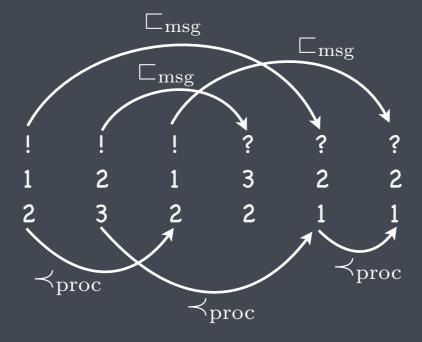


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message-passing system (m=2)



EMSO(S) where S is any signature

- a(x) position x carries $a \in \Sigma$ • $x \triangleleft y$ $\triangleleft \in S$
- $d^k(x) = d^l(x)$ <u>local</u> reasoning about data values
- x = y $\varphi_1 \lor \varphi_2$ $\neg \varphi$ $\exists x \varphi$ $x \in X$

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Formula: $\exists X_1 \dots \exists X_n \varphi$

req	req	req	ack	ack	req
	4				

there is a request that is acknowledged

 $\exists x \exists y \, (req(x) \land ack(y) \land x \prec_{\sim} y)$

req req req ack ack req 4 4 2 1 4 2

there is a request that is acknowledged

 $\exists x \exists y \left(req(x) \land ack(y) \land x \prec_{\sim} y \right) \quad \exists$



 \prec_{\sim}

réq

4

ack

ack

4

req

2

req

2 1

• there is a request that is acknowledged $\exists x \exists y \, (req(x) \land ack(y) \land x \prec_{\sim} y) \; \exists \; \mathsf{req}_{4}$

every request is acknowledged (before next request)

 $\forall x \exists y \, (req(x) \to ack(y) \land x \prec_{\sim} y)$

 \prec_{\sim}

rèq

ack

req

4 2 1

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4

req

2

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- two successive requests are acknowledged in the order they were received
- $\forall x \forall y \, (req(x) \land req(y) \land x \prec_{+1} y \\ \rightarrow \exists x' \exists x' \, (ack(x') \land ack(y') \land x \prec_{\sim} x' \prec_{+1} y' \land y \prec_{\sim} y'))$

 \prec_{\sim}

rèq

4

req

2

ack

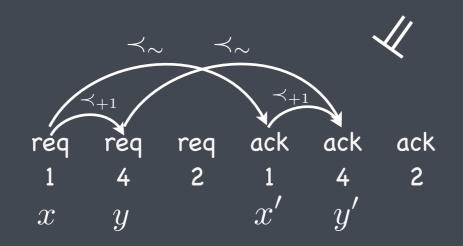
ack

4

req

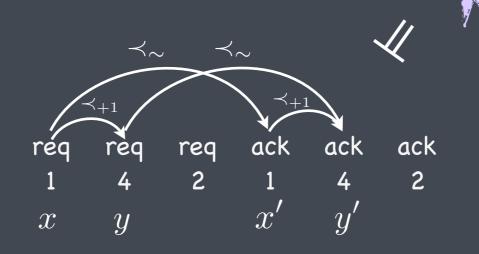
2

- there is a request that is acknowledged $\exists x \exists y \, (req(x) \land ack(y) \land x \prec_{\sim} y) \; \exists \; \mathsf{req}_{4}$
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- There is a request that is acknowledged
 $\exists x \exists y \, (req(x) \land ack(y) \land x \prec_{\sim} y) = dx$
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 - $\forall x \exists y \, (req(x) \to ack(y) \land x \prec_{\sim} y)$
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 $\forall x \forall y \, (\qquad req(x) \land req(y) \land x \prec_{+1} y \\ \rightarrow \exists x' \exists x' \, (ack(x') \land ack(y') \land x \prec_{\sim} x' \prec_{+1} y' \land y \prec_{\sim} y'))$



Goal: non-deterministic one way automaton for this kind of property

ack

req

2

ack

4

req

2

 \prec_{\sim}

req

réq

[related works, most of them for m=1]

MSO → register automata (restricted use of variables)
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From Logic to Automata

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- MSO → register automata (restricted use of variables)
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- MSO vs. two-way and pebble automata [Neven, Schwentick, Vianu 2004]
- EMSO² (≺~, ≺+1, <, ≺*) → data automata/class memory automata
 </p>

 [Bojanczyk, David, Muscholl, Schwentick, Segoufin 2006]

 [Björklund, Schwentick 2007]
- Ø Regular XPath → class automata [Bojanczyk, Lasota 2010]

Automata

[Kaminski & Francez, 1994]

 $\mathcal{A} = (Q, \overline{R}, \longrightarrow, q_0, \overline{F})$

• Q finite set of states

• q_0, F initial state, set of final states

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 $(q, guard) \xrightarrow{a} (q', upd)$

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 $(q, guard) \stackrel{a}{\longrightarrow} (q', upd)$
guard $\in \mathcal{B}(R)$

current value is in 1st but not in 2nd register:

$$r_1 \wedge \neg r_2$$

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- transition relation:

 $(q, guard) \xrightarrow{a} (q', upd)$ $guard \in \mathcal{B}(R) \qquad upd \subseteq R$

current value is in 1st but not in 2nd register:

write current value in both registers:

$$r_1 \wedge \neg r_2$$

$$\{r_1, r_2\}$$

[Kaminski & Francez, 1994]

 $\Sigma = \{ \mathsf{req}, \mathsf{ack} \}$ $D = \mathbb{N}$ $F = \{q_1\}$

\mathcal{A}	source	guard	label	target	update
,ack}	q_0		req , ack	q_0	
	q_0		req	q_0	$\{r\}$
	q_0	r	ack	q_1	
}	q_1		req , ack	q_1	

 $L(\mathcal{A}) =$ "some request is acknowledged"

[Kaminski & Francez, 1994]

 $\Sigma = \{ req, ack \}$ $D = \mathbb{N}$ $F = \{q_1\}$

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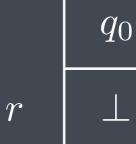
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sourceguardlabeltargetupdate
$$q_0$$
req , ack q_0 q_0 req q_0 $\{r\}$ q_0 r ack q_1 q_1 req , ack q_1

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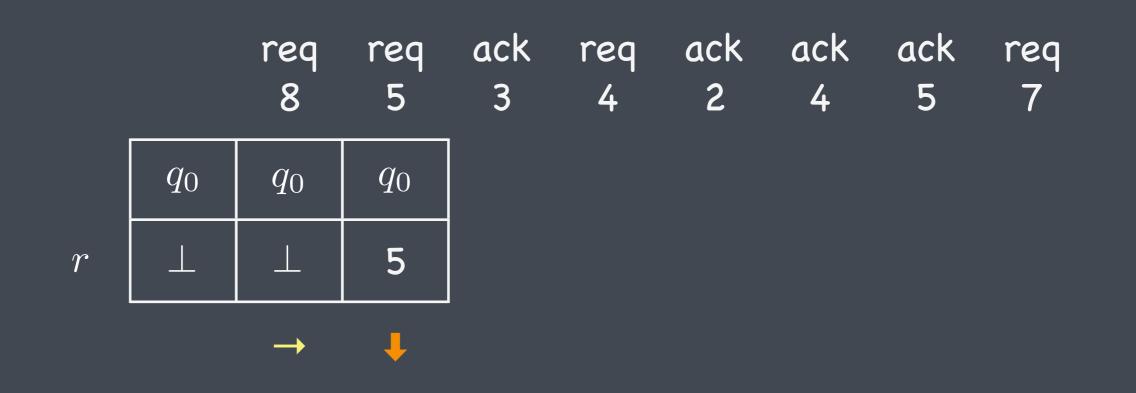
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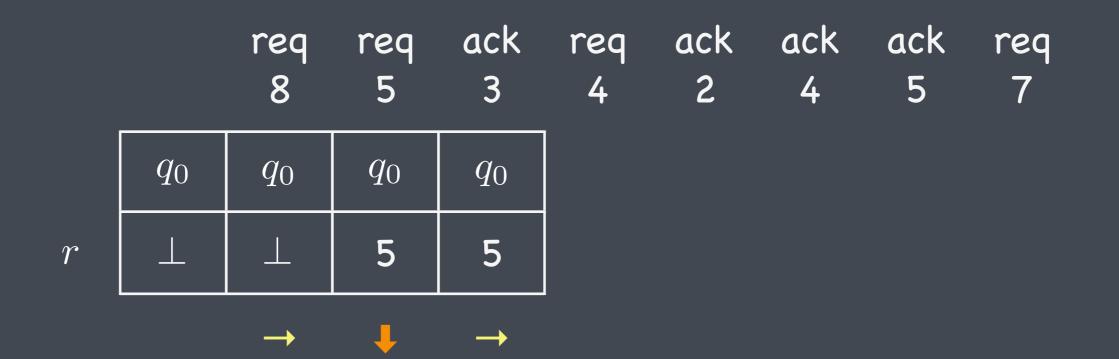
+ ~

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/

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13

+ ~

[Kaminski & Francez, 1994]

 $\Sigma = \{ { t req}, { t ack} \}$ $D = \mathbb{N}$ $F = \{ q_1 \}$

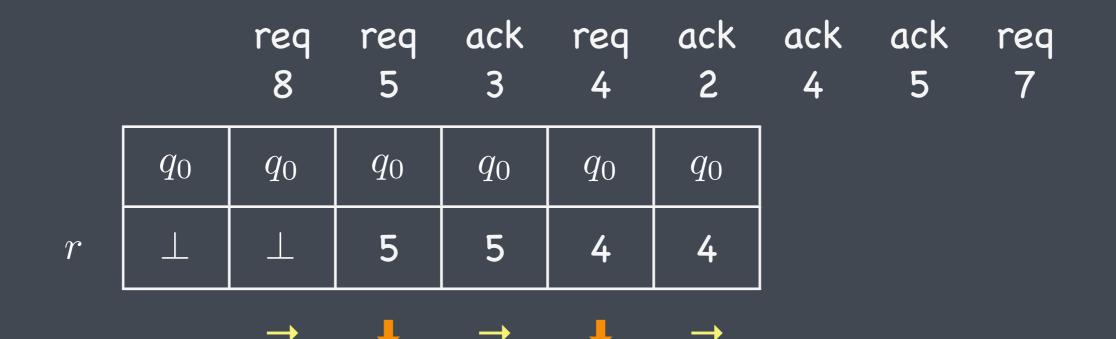
sourceguardlabeltargetupdate
$$q_0$$
req , ack q_0 q_0 req q_0 $\{r\}$ q_0 r ack q_1 q_1 req , ack q_1

~

 \Rightarrow

13

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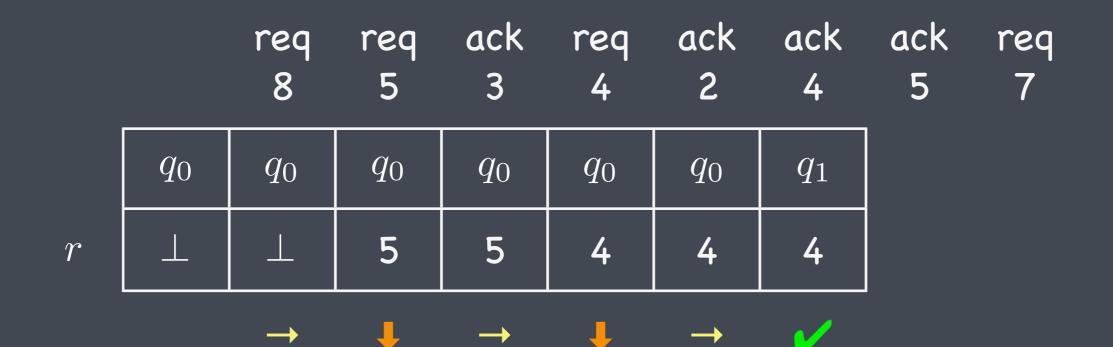


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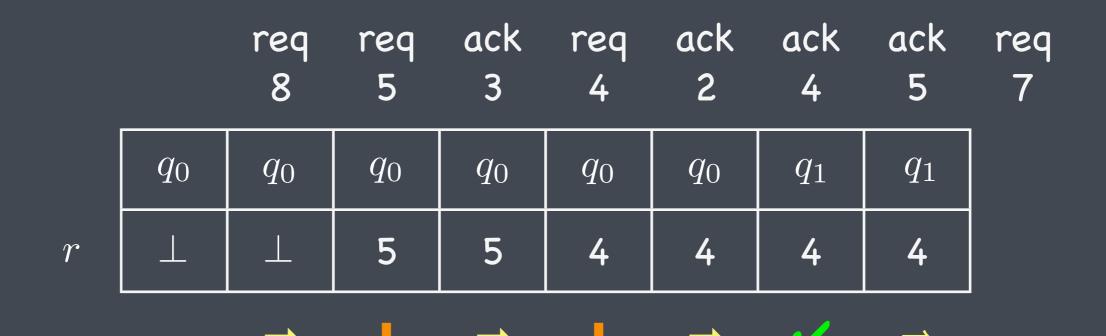
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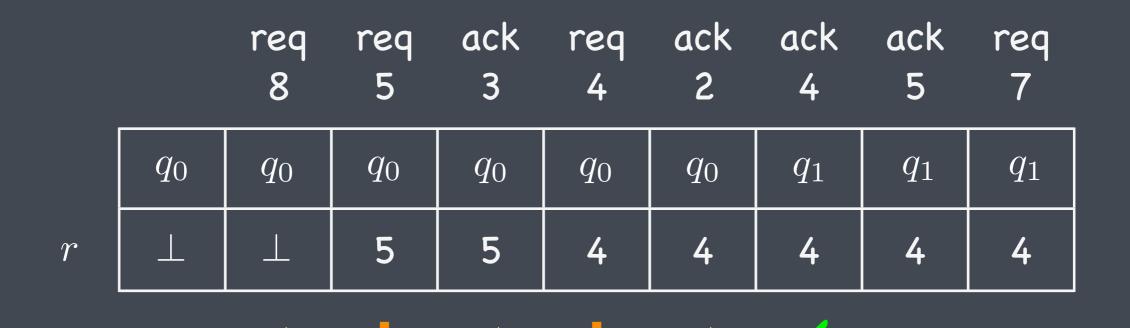


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13

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Asourceguardlabeltargetupdate
$$q_0$$
req , ack q_0 q_0 req q_0 $\{r\}$ q_0 r ack q_1 q_1 req , ack q_1

 $L(\mathcal{A}) =$ "some request is acknowledged" every ?

		req 8	req 5	ack 3	req 4	ack 2	ack 4	ack 5	req 7
	q_0	q_0	q_0	q_0	q_0	q_0	q_1	q_1	q_1
r		\perp	5	5	4	4	4	4	4

 $\boldsymbol{\gamma}$

[Kaminski & Francez, 1994]

 $\Sigma = \{ \mathsf{req}, \mathsf{ack} \}$ $D = \mathbb{N}$ $F = \{q_1\}$

$$L(\mathcal{A}) =$$
 "some request is acknowledged"
every ?
=> class memory autom

reqreqackreqackackackackreq85342457
$$q_0$$
 q_0 q_0 q_0 q_0 q_1 q_1 q_1 \perp \perp 554444

 γ

ata

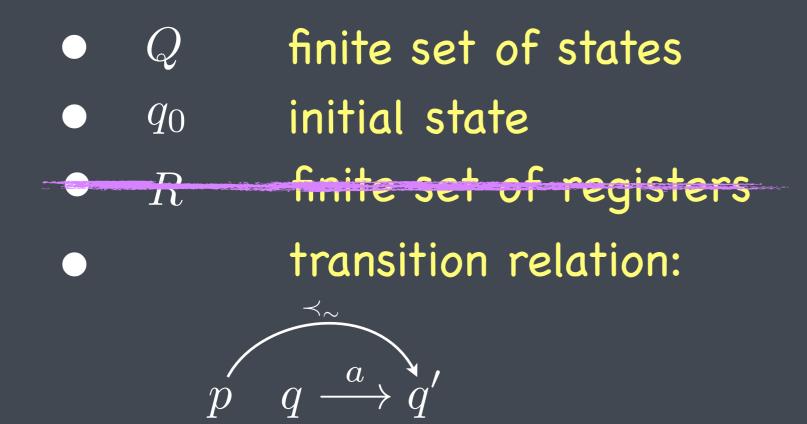
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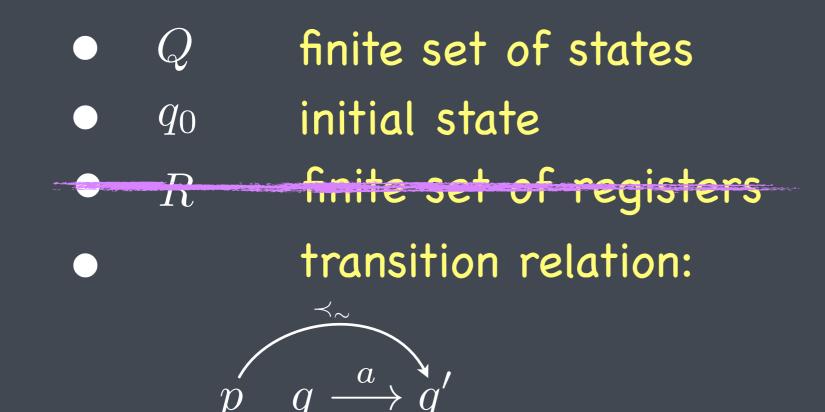
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q is current state p is state after last position with same data value

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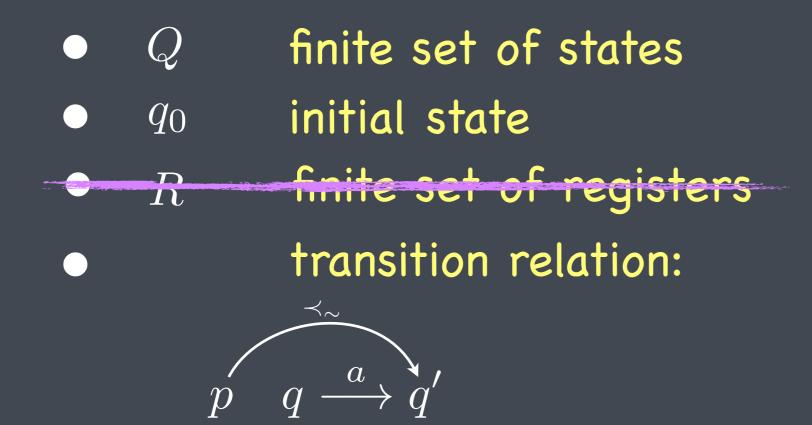
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\mathcal{A}	\prec_{\sim}	\prec_{+1}	guard	label	target	update
		q_0		req	q_0	
$F_{\sim} = \{q_1\}$	q_0	q_0		ack	q_1	
$T_{+1} = \{q_1\}$	q_0	q_1		ack	q_1	

F

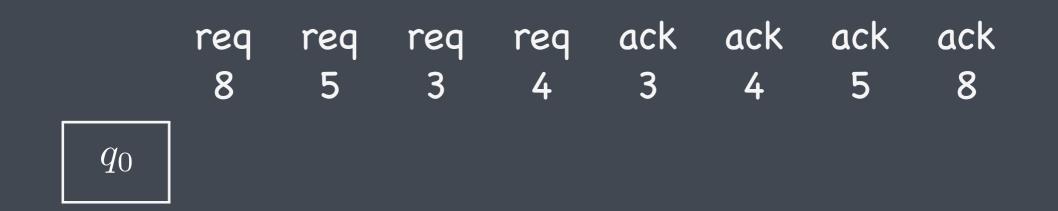
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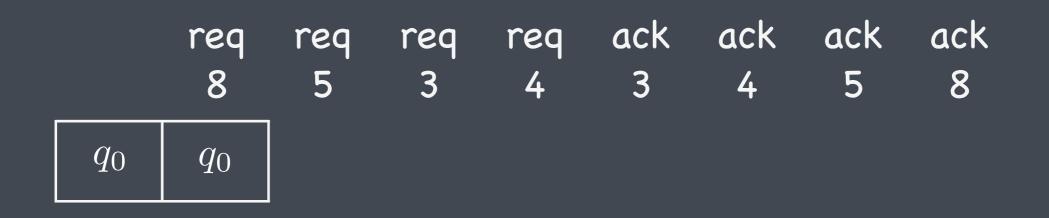


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R

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F

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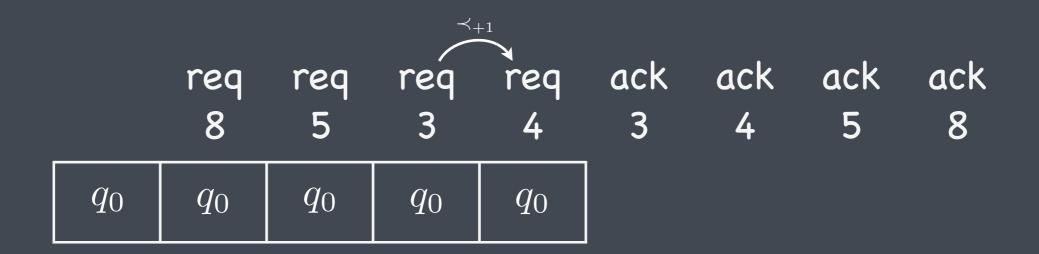


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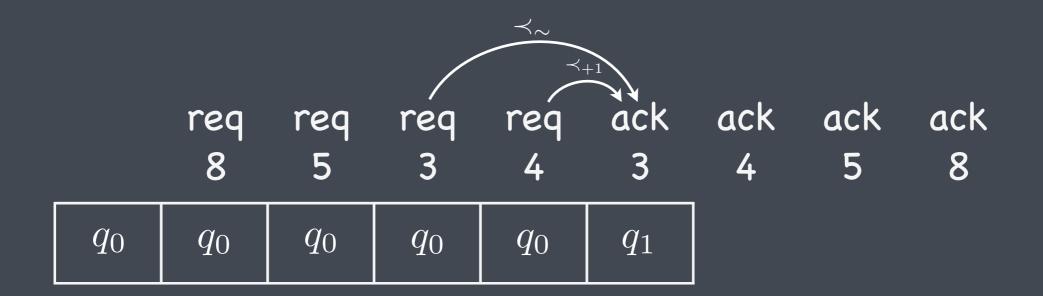


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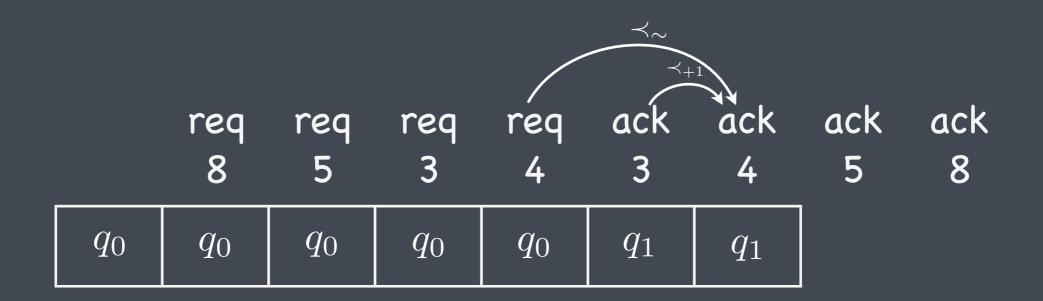


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F

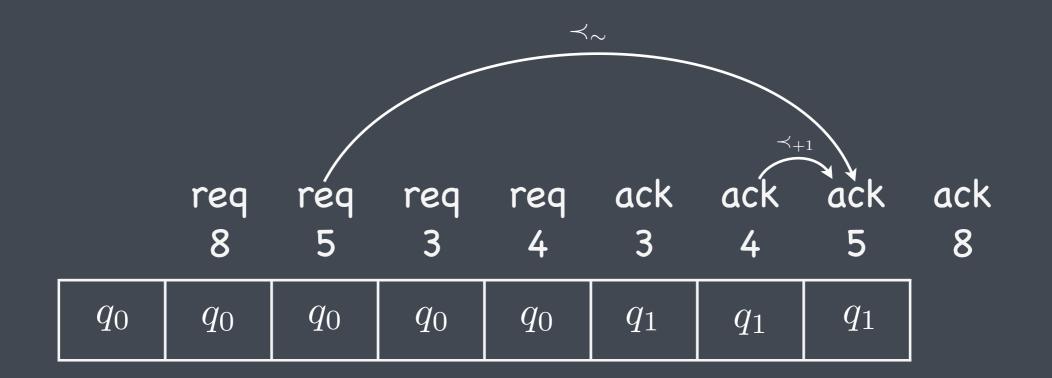
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 $L(\mathcal{A}) =$



Class Memory Automata

[Björklund & Schwentick, 2007]

${\cal A}$	-	$\prec \sim$	\prec_{+1}	-	uard-	label	tar	get 🛛	update	
			q_0			req	Q	0		
$F_{\sim} = \{q_1\}$	(<i>2</i> 0	q_0			ack	Q	/1		
$F_{+1} = \{q_1\}$	(20	q_1			ack	Q q	1		
$L(\mathcal{A})=$ " every process sends one request, which is acknowledged, every acknowledgment is preceded by a request, and req*ack* " \prec_\sim										
		\prec_{+1}								
		req	req	req	req	ack	ack	ack	àck	
		8	5	3	4	3	4	5	8	
	q_0	q_0	q_0	q_0	q_0	q_1	q_1	q_1	q_1	

Class Memory Automata

[Björklund & Schwentick, 2007]

\mathcal{A}	\prec_{\sim}	\prec_{+1}	guard	label	target	update
		q_0		req	q_0	
$F_{\sim} = \{q_1\}$	q_0	q_0		ack	q_1	
$F_{+1} = \{q_1\}$	q_0	q_1		ack	q_1	

 $L(\mathcal{A}) = \begin{tabular}{l} `` every process sends one request, which is acknowledged, every acknowledgment is preceded by a request, and $$ req^*ack* "$$ "$

	•	•	•	U	ack 3			
q_0	q_0	q_0	q_0	q_0	q_1	q_1	q_1	q_1

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" every process sends one request, which is acknowledged, every acknowledgment is preceded by a request, and req*ack* "

... and requests are acknowledged in the order they are received ?

 $L(\mathcal{A}) =$

=> class register automata

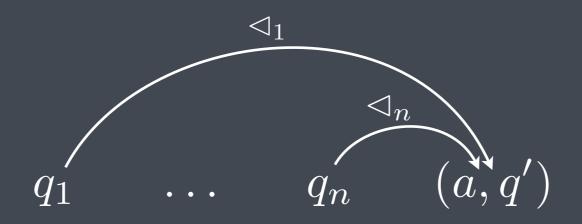
	•	•	req 3	•				
q_0	q_0	q_0	q_0	q_0	q_1	q_1	q_1	q_1

$$\mathcal{A} = (Q, \mathbb{X}, \longrightarrow, q_0, F)$$

- Q finite set of states
- $\sim R$ finite set of registers
- transition relation:

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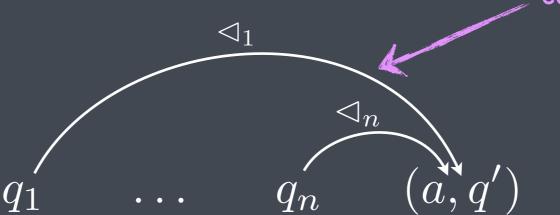
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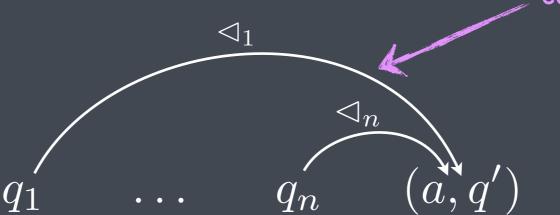
can be missing



$$\mathcal{A} = (Q, \mathbb{X}, \longrightarrow, \mathbb{Y}_{0}, F)$$

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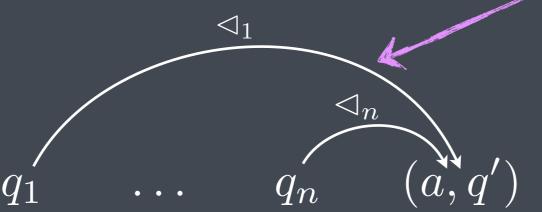


Class Register Automata over S = { \lhd_1, \ldots, \lhd_n } $\mathcal{A} = (Q, \mathbb{X}, \longrightarrow, \mathbb{Y}, F)$ • $F = (F_{\triangleleft_1}, \ldots, F_{\triangleleft_n})$ finite set of states Qfinite set of registers $\frac{1}{1}$ transition relation: can be missing \triangleleft_1 \triangleleft_n (a, a') $\dot{q_n}$ Q_1

$\mathcal{A} = (Q, \mathbb{X}, \overline{\longrightarrow}, \mathbb{Y}, F) \ G$

• Q finite set of states • R finite set of registers • $G \in \mathcal{B}("q \le N")$ • transition relation:

can be missing

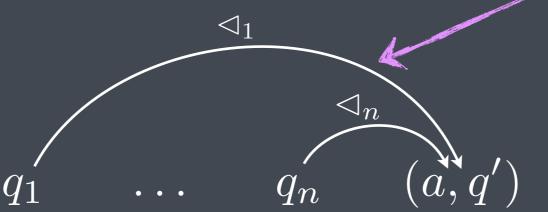


$$\mathcal{A} = (Q, R, \longrightarrow, \mathcal{K}, F) G$$

- Q finite set of states
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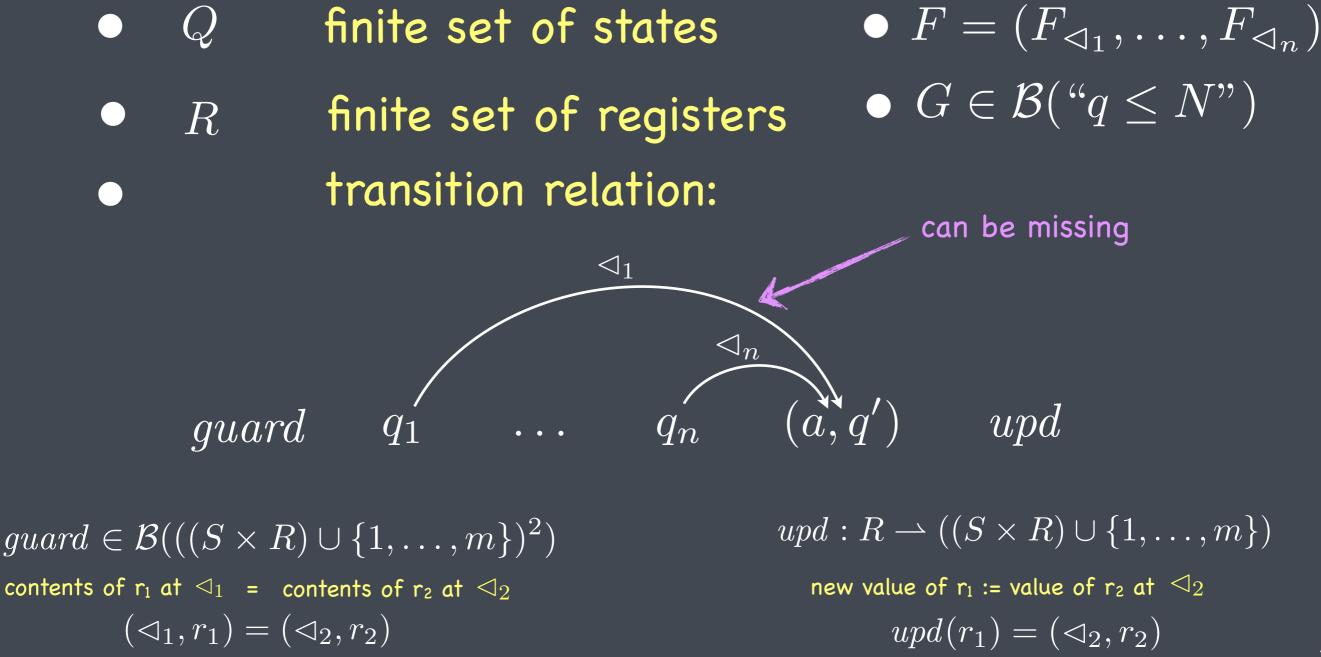
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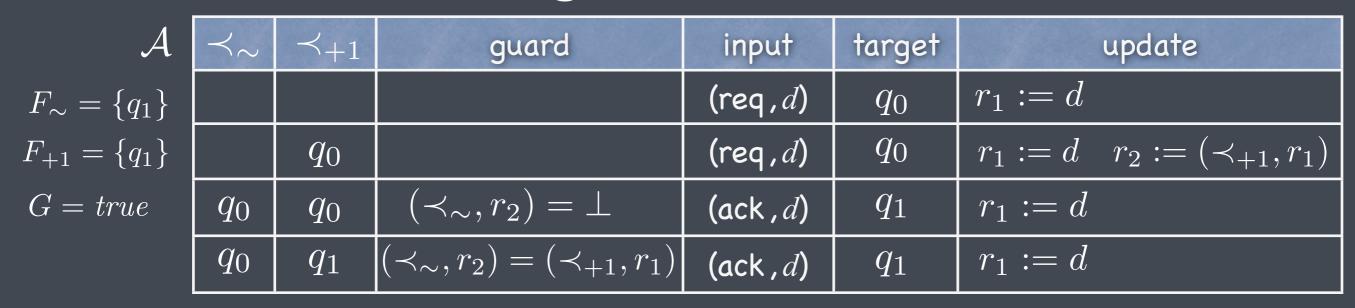
• Q finite set of states • R finite set of registers • T transition relation: \triangleleft_1 • $F = (F_{\triangleleft_1}, \dots, F_{\triangleleft_n})$ • $G \in \mathcal{B}(``q \le N")$



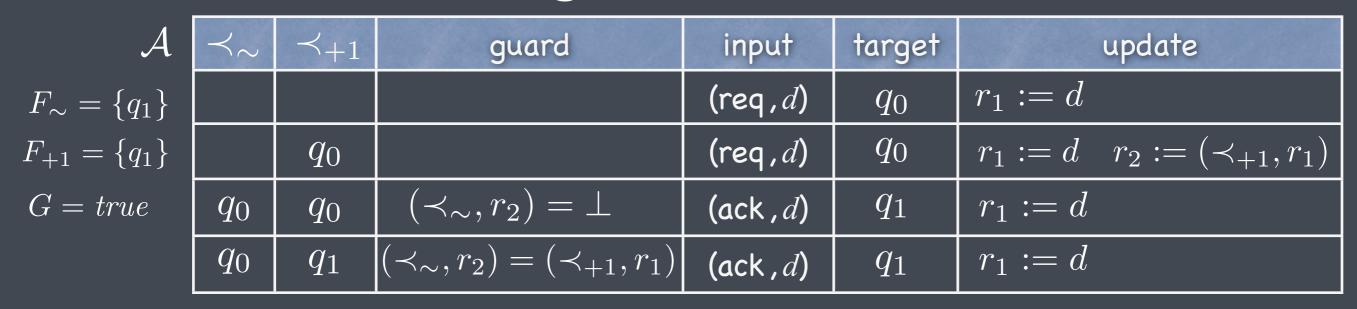
 $\begin{array}{l} guard \in \mathcal{B}(((S \times R) \cup \{1, \dots, m\})^2) \\ \text{contents of } r_1 \text{ at } \triangleleft_1 \ = \ \text{contents of } r_2 \text{ at } \triangleleft_2 \\ (\triangleleft_1, r_1) = (\triangleleft_2, r_2) \end{array}$

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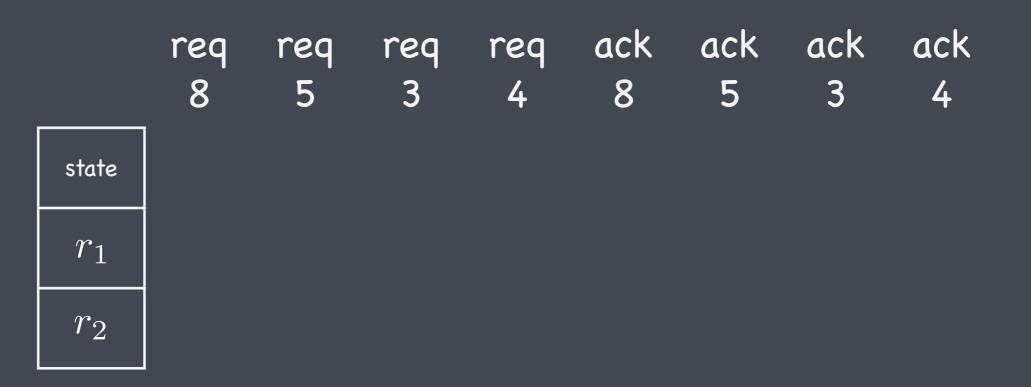


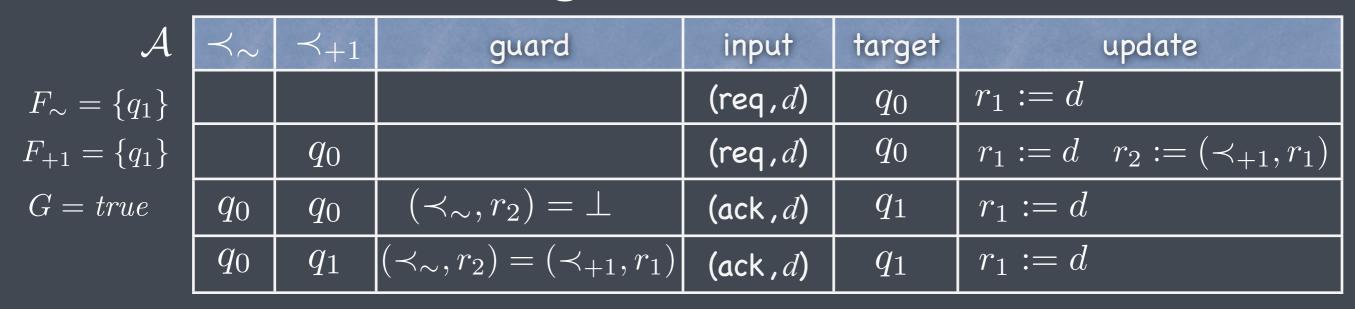


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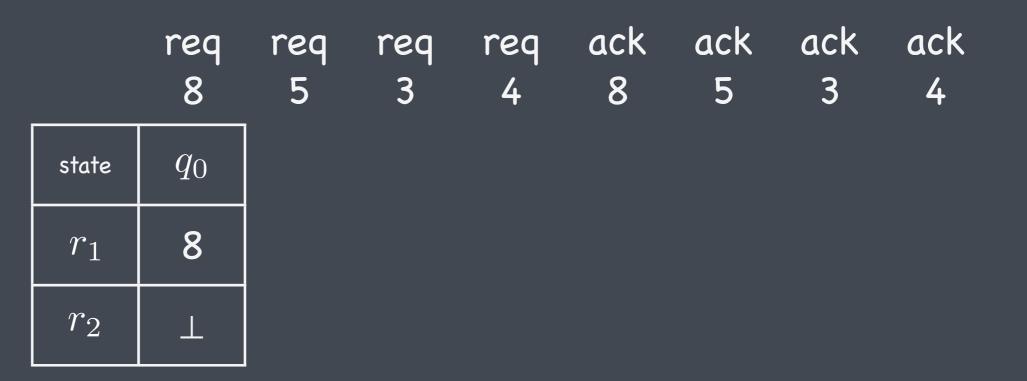


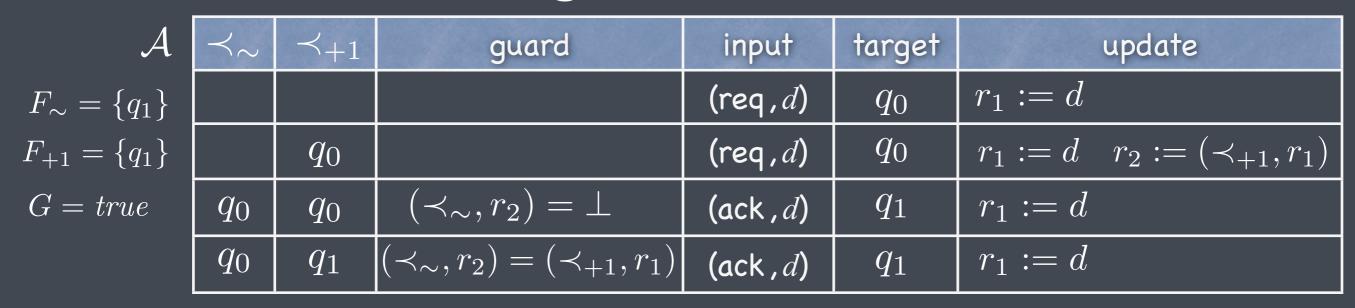
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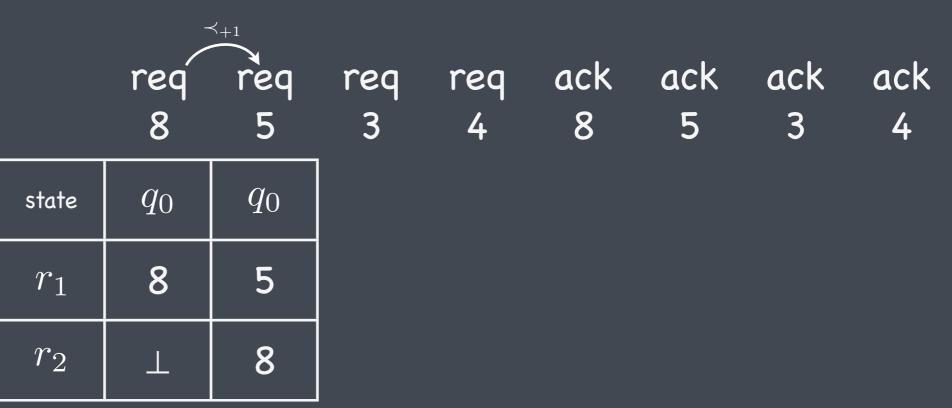


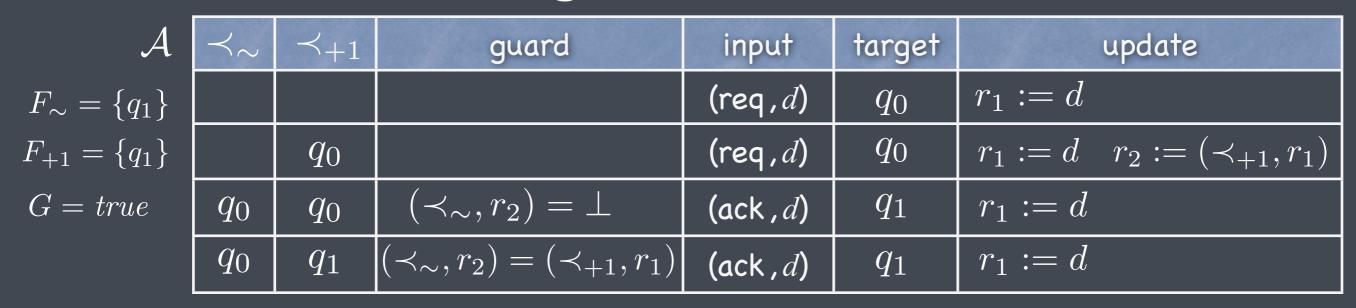
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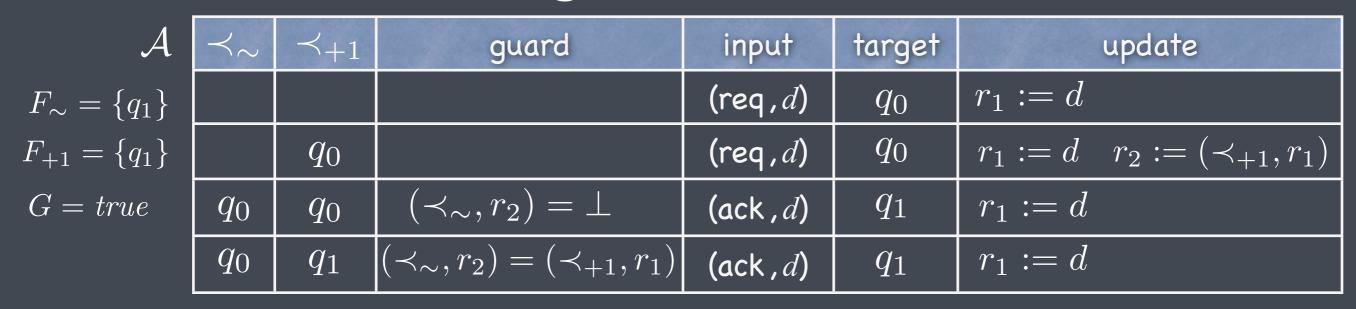
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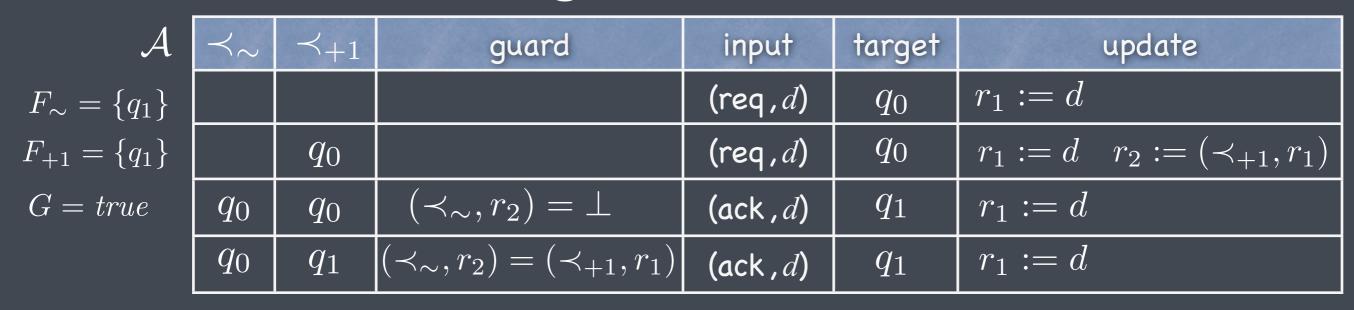
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	req 8	req 5	req 3	req 4	ack 8	ack 5	ack 3	ack 4
state	q_0	q_0	q_0					
r_1	8	5	3					
r_2	⊥	8	5					



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r_1	8	5	3	4				
r_2	⊥	8	5	3				



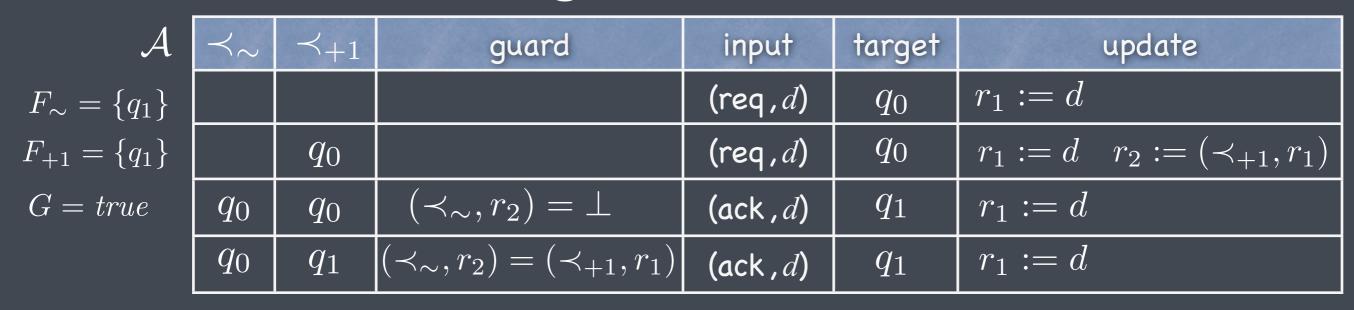
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 \prec_{\sim}

... and requests are acknowledged in the order they are received !

àck ack ack ack req req req req 3 8 5 3 4 8 5 4

state	q_0	q_0	q_0	q_0	q_1
r_1	8	5	3	4	8
r_2	T	8	5	3	

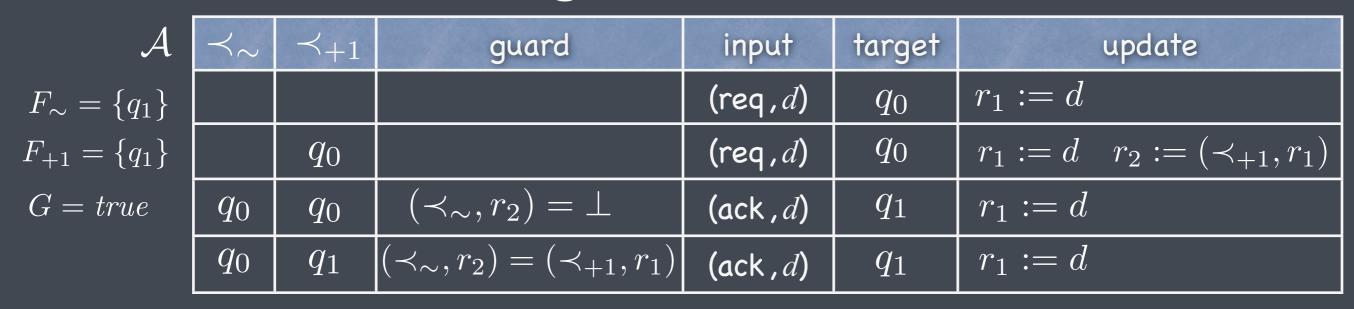


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state	q_0	q_0	q_0	q_0	q_1	q_1
r_1	8	5	3	4	8	5
r_2	上	8	5	3	T	1

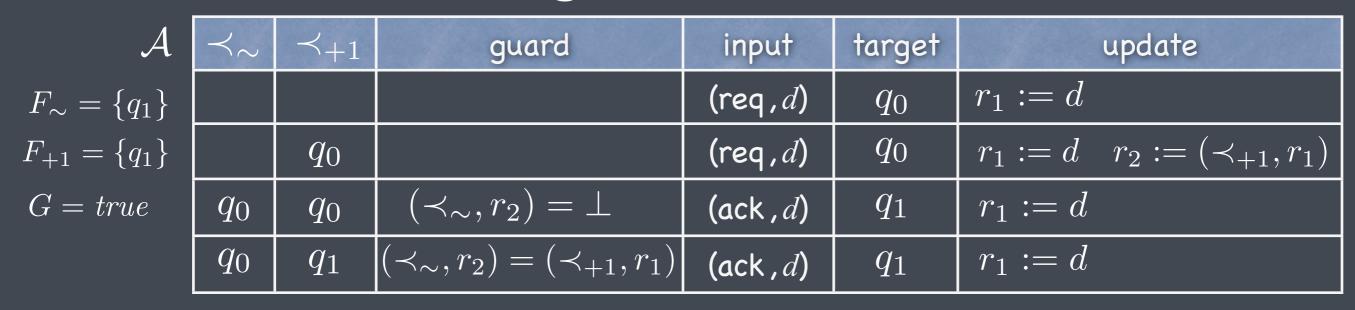


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ack ack ack ack req req req req 8 5 3 4 8 5 3 4 q_0 q_1 q_0 q_0 q_0 q_1 q_1 state 3 5 8 5 8 3 4 r_1 5 8 3 r_2 \bot

 \prec_{\sim}



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	req 8	req 5	req 3	req 4	ack 8	ack 5	ack 3	ack 4
state	q_0	q_0	q_0	q_0	q_1	q_1	q_1	q_1
r_1	8	5	3	4	8	5	3	4
r_2	⊥	8	5	3	\bot	T	\bot	\bot

 $\prec \sim$

 $\odot \text{EMSO}^2(\prec_{\sim},\prec_{+1},<,\prec_{\sim}^*) = \text{class memory automata}$

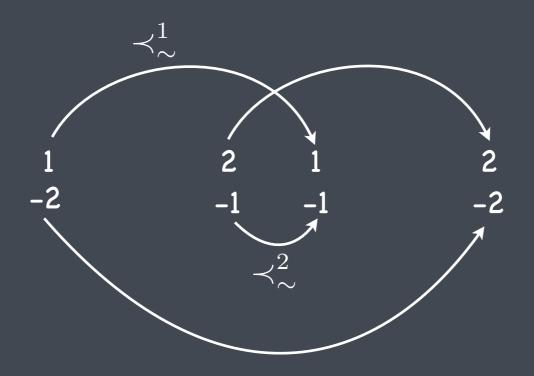
[Bojanczyk, David, Muscholl, Schwentick, Segoufin 2006] [Björklund, Schwentick 2007]

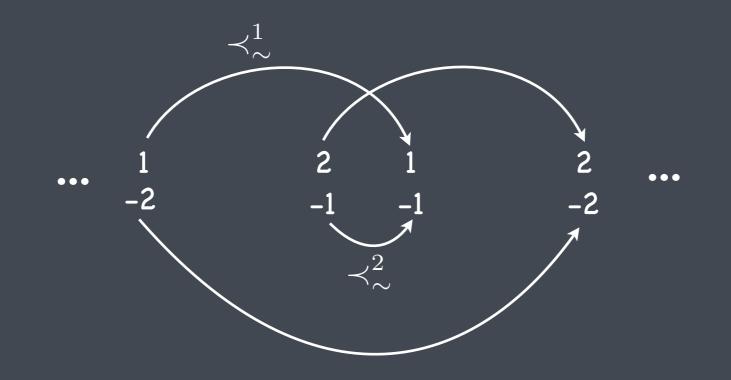
EMSO(S) \rightarrow class register automata ?

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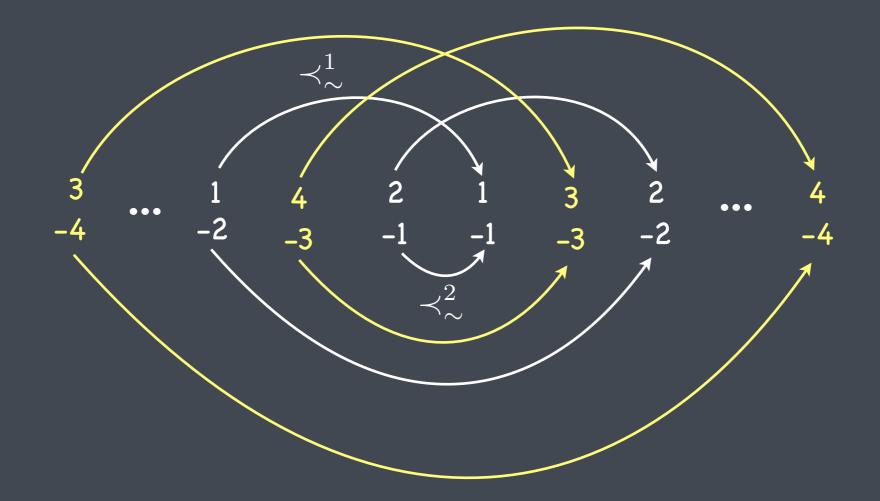
Ø EMSO(S) → class register automata ?

• $\mathsf{FO}(\prec^1_\sim,\prec^2_\sim) \not\subseteq \mathsf{CRA}(\prec^1_\sim,\prec^2_\sim)$





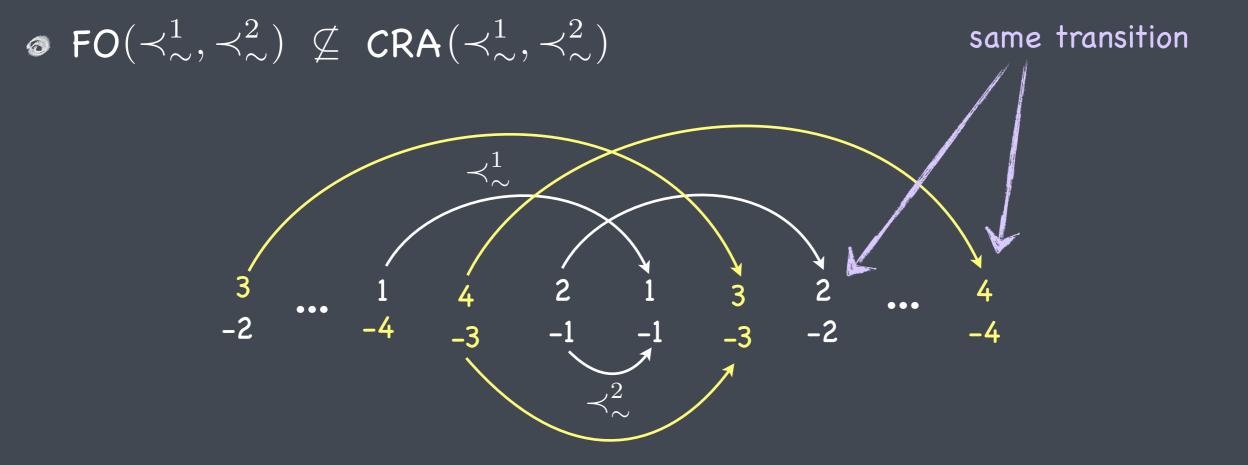
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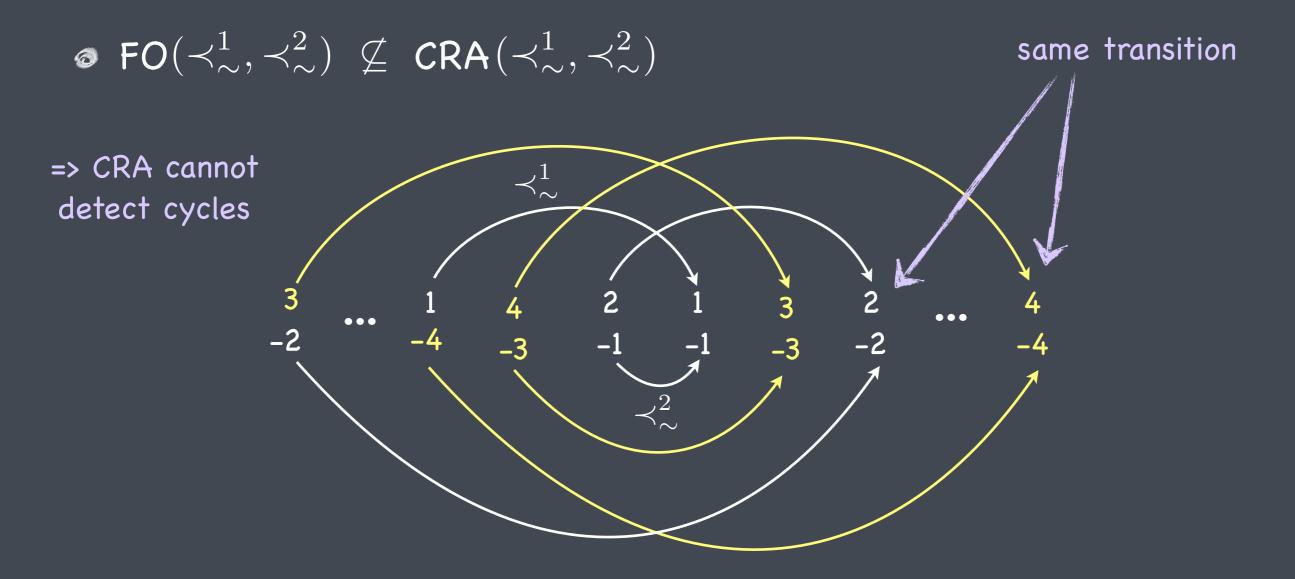
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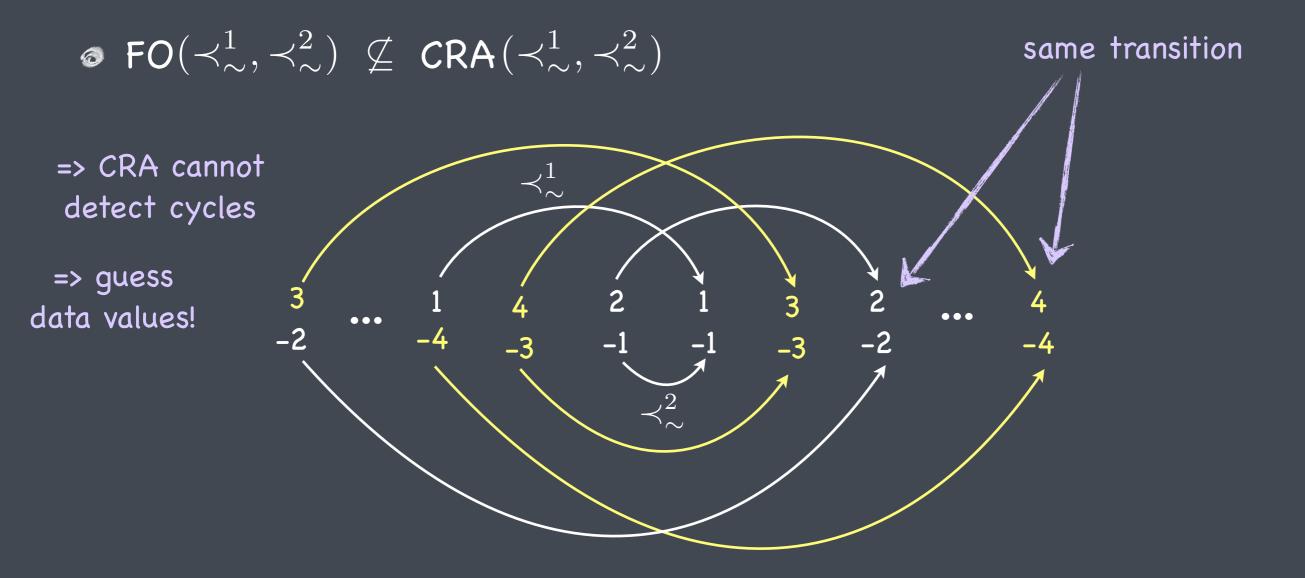
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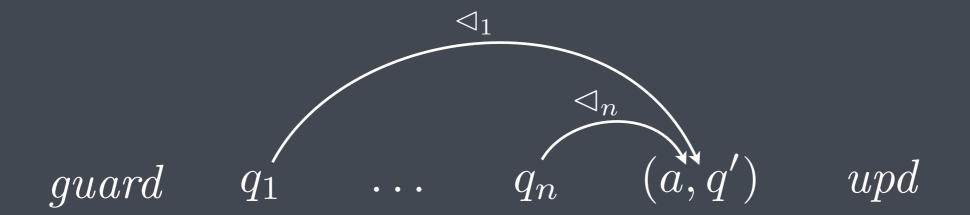
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Class Register Automata (with guess) over S = { \lhd_1, \dots, \lhd_n } $\mathcal{A} = (Q, R, \longrightarrow, F, G)$

- Q finite set of states
- R finite set of registers
 - transition relation:

• $F = (F_{\triangleleft_1}, \dots, F_{\triangleleft_n})$ • $G \in \mathcal{B}(``q \le N'')$



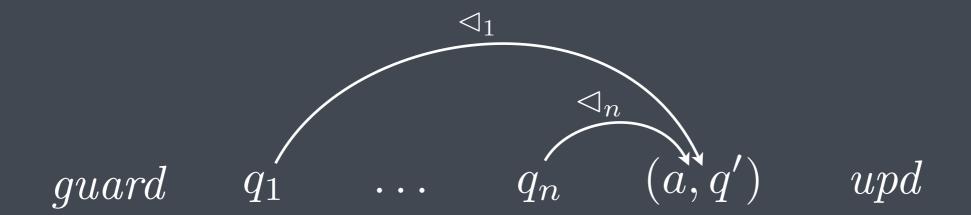
 $upd: R \rightarrow ((S \times R) \cup \{1, \dots, m\})$

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transition relation:

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 $upd : R \rightharpoonup ((S \times R) \cup \{1, \dots, m\})$ $\cup \{guess\}$

guessing register automata: [Kaminski, Zeitlin 2010]

Theorem: For every signature S, EMSO(S) \subseteq gCRA(S).

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Proof:

Use Hanf's Theorem (1965): normal form of first-order formulas

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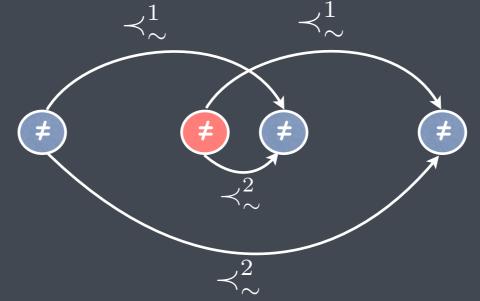
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- Sufficient to detect local patterns and count them up to some threshold

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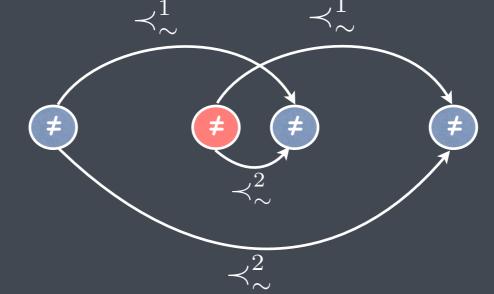


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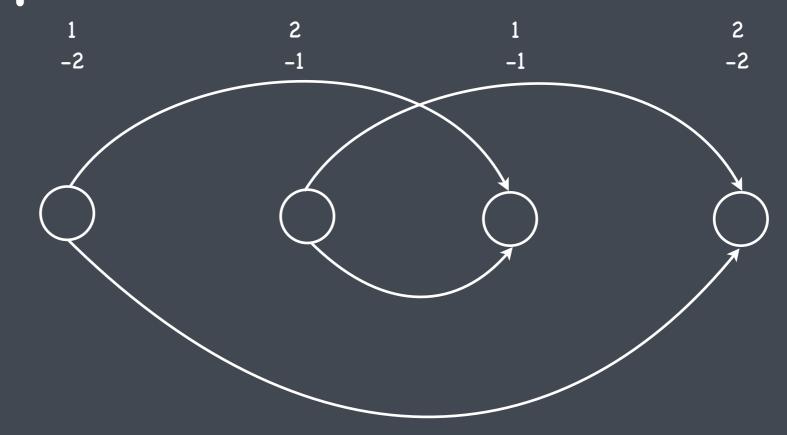
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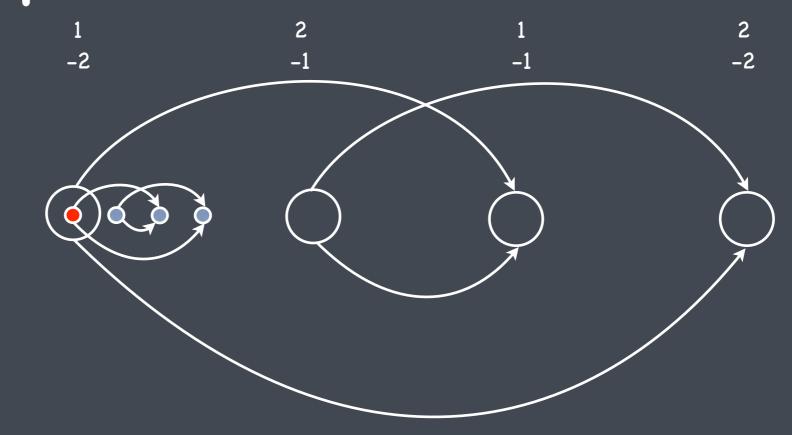
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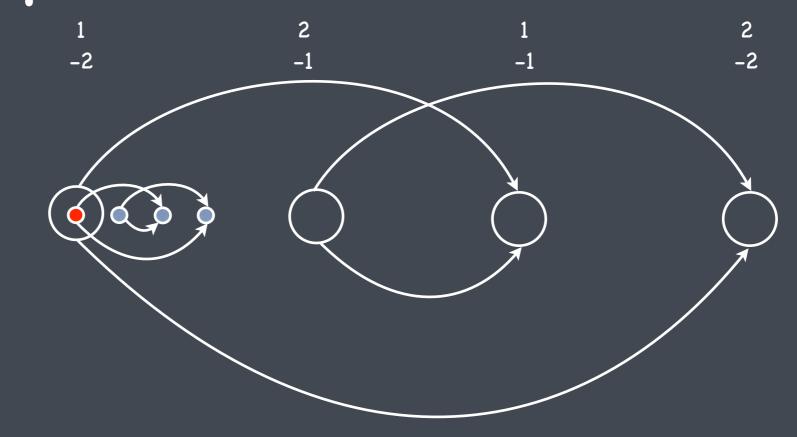




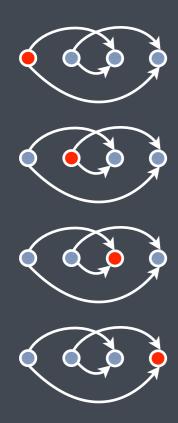
Suild class register automaton that detects spheres

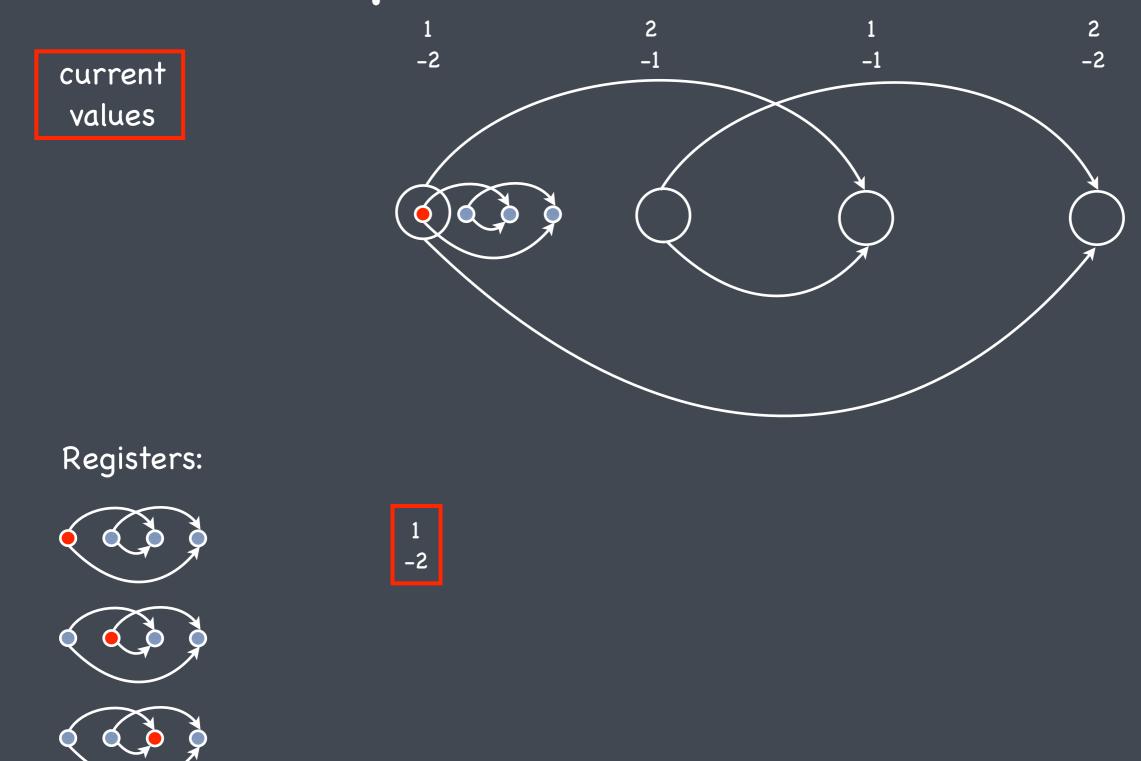


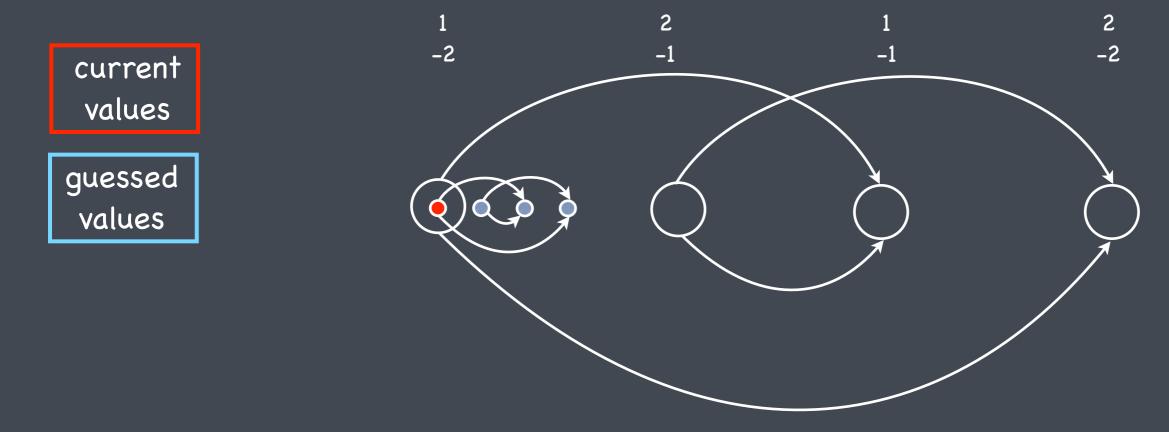




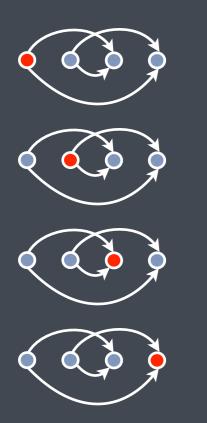




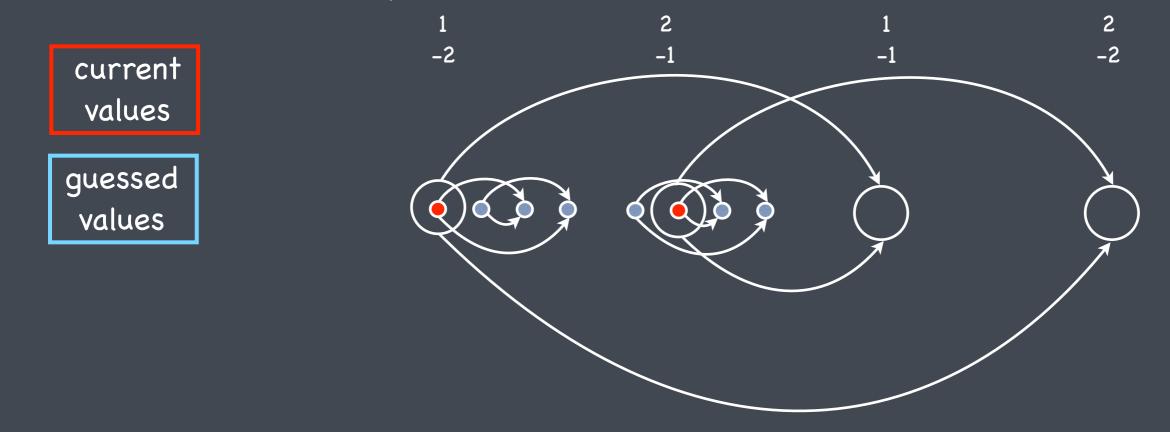




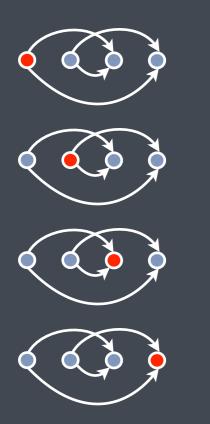
Registers:



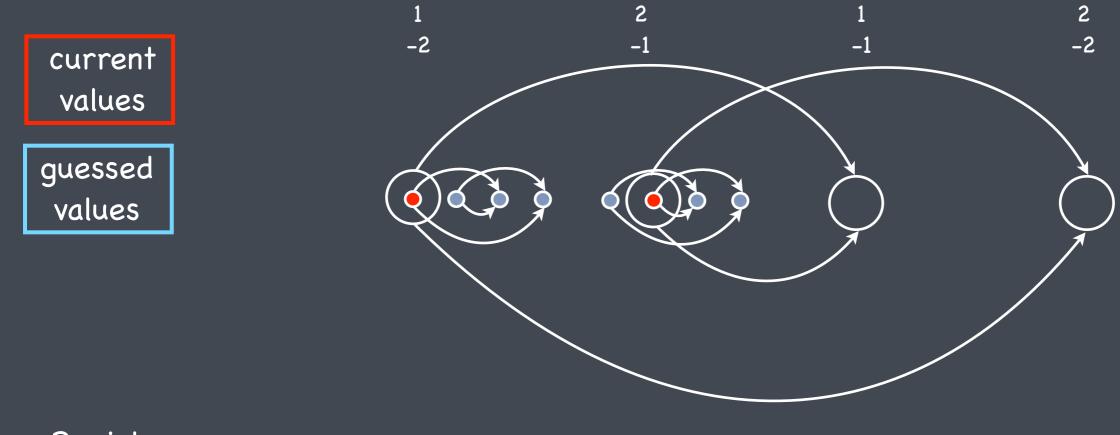




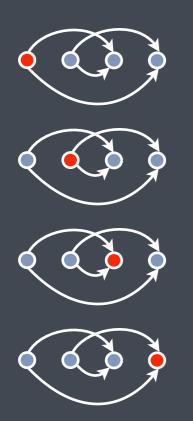
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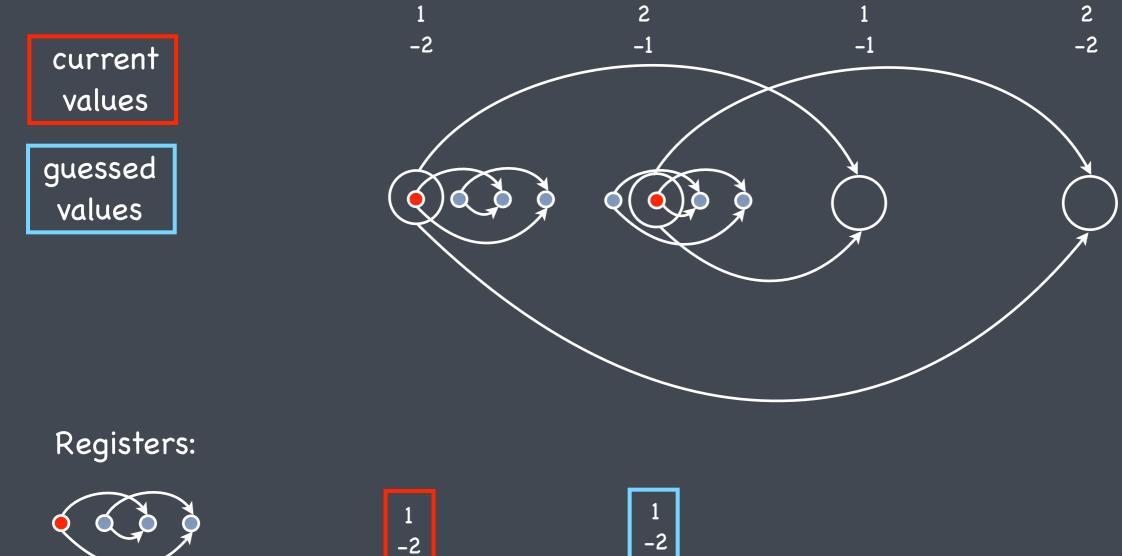


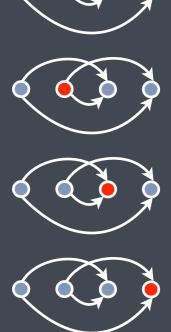
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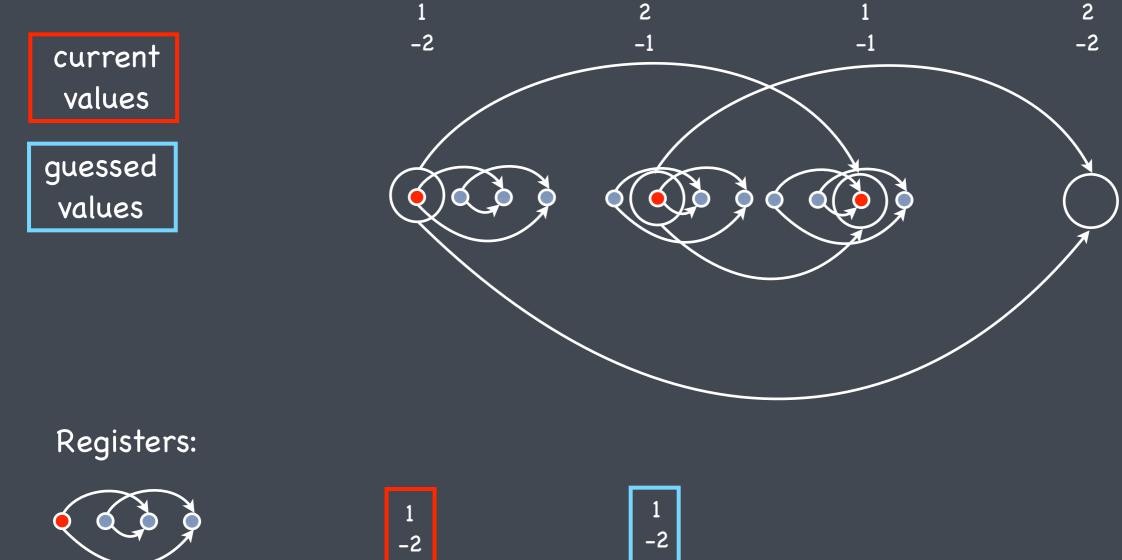


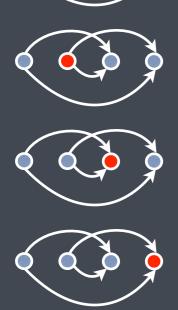






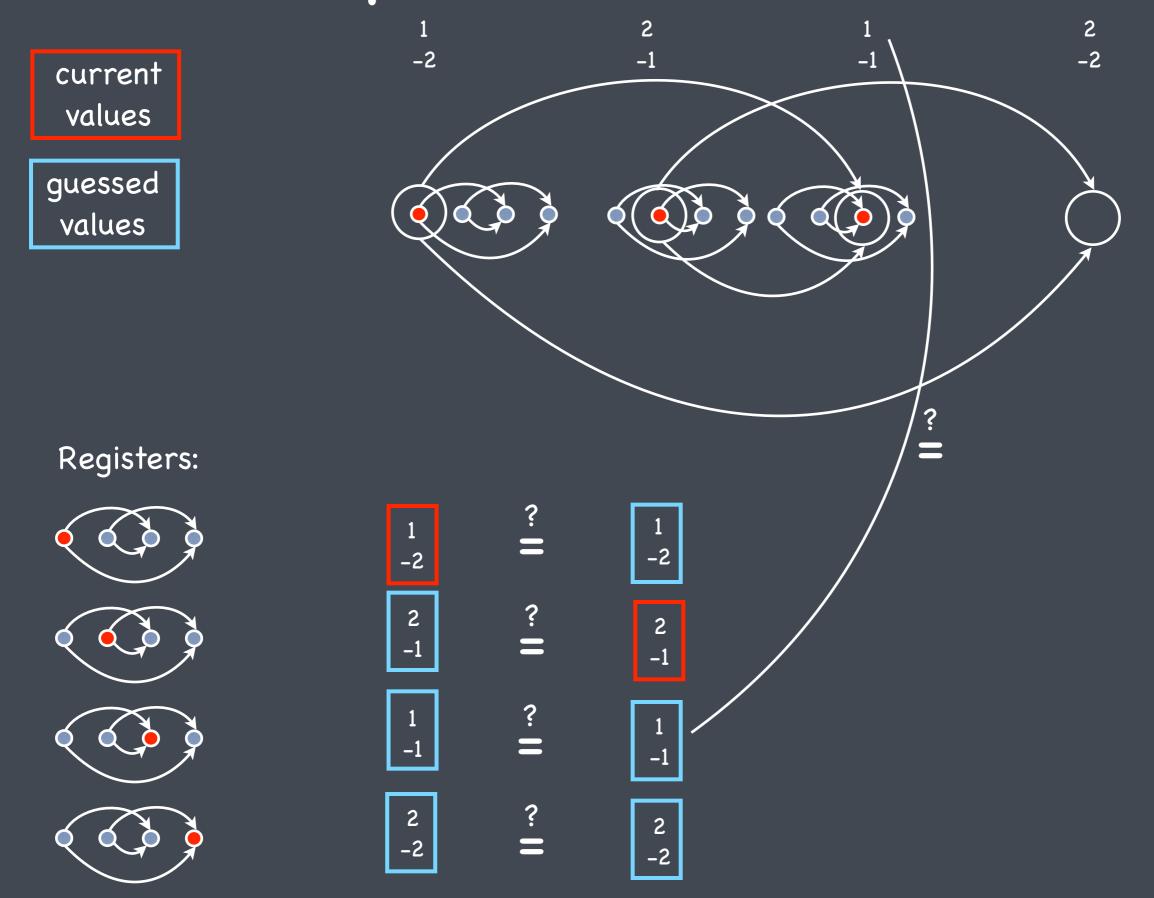


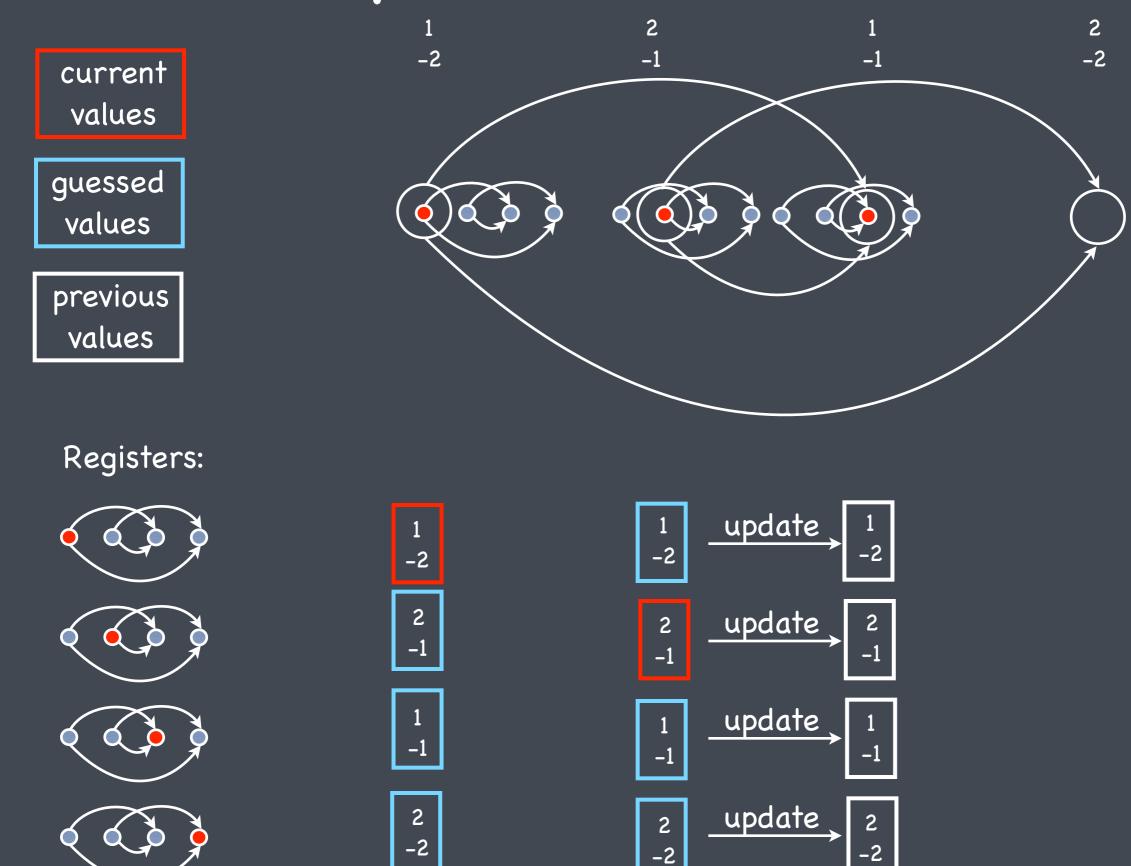


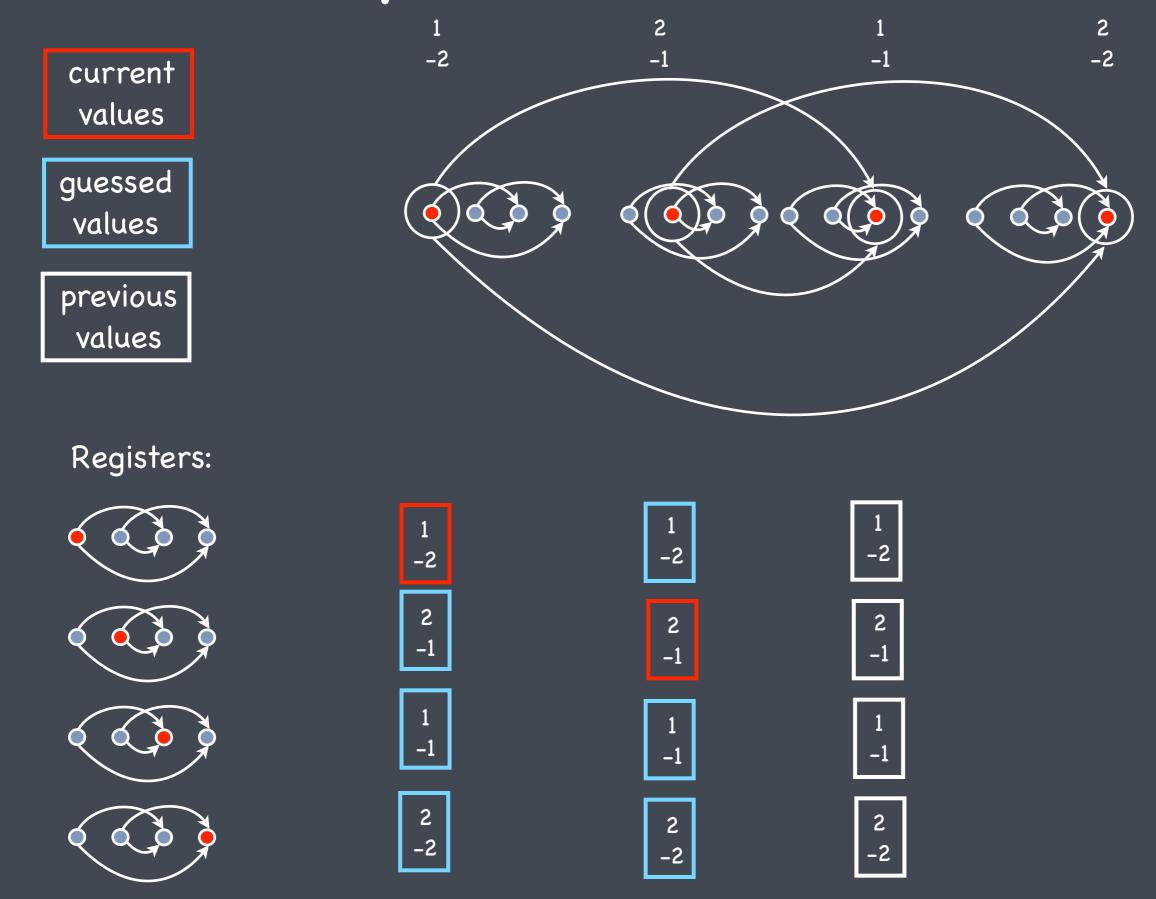


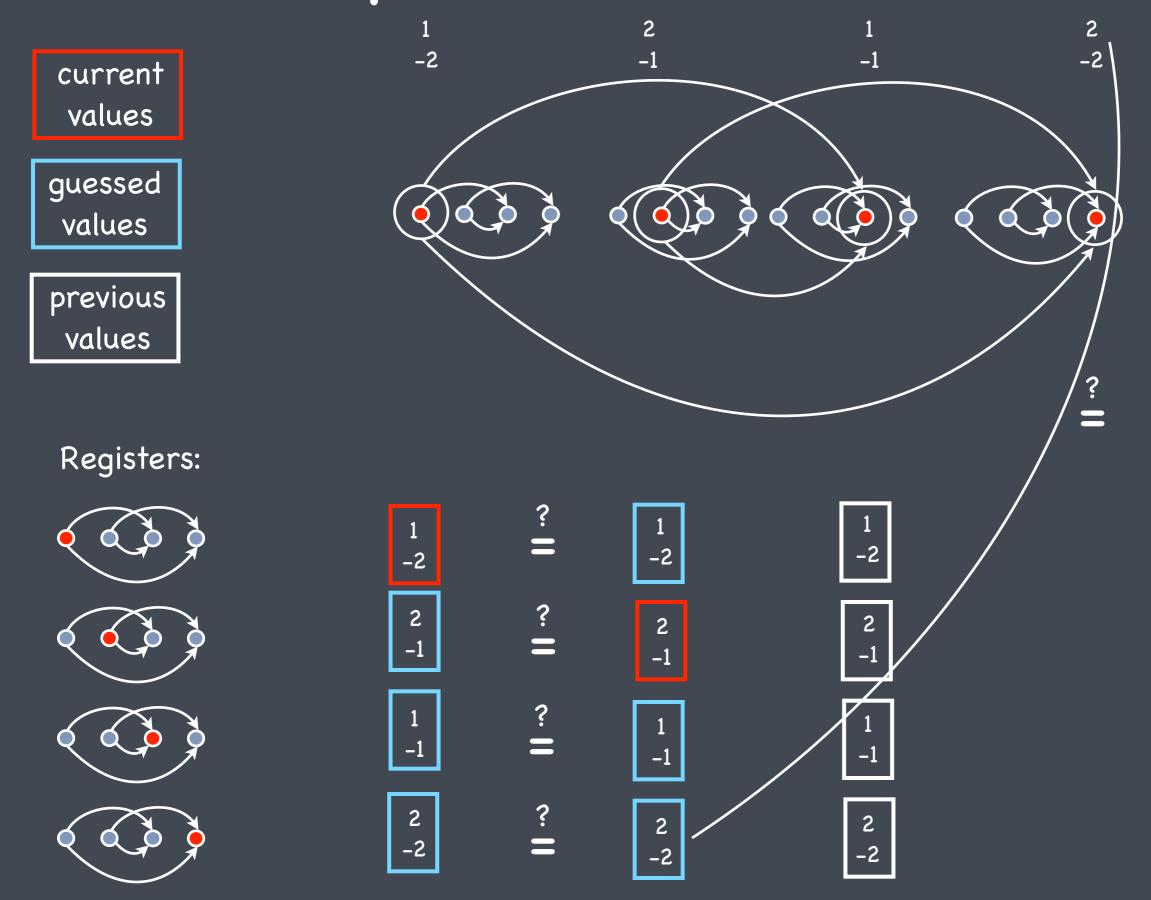


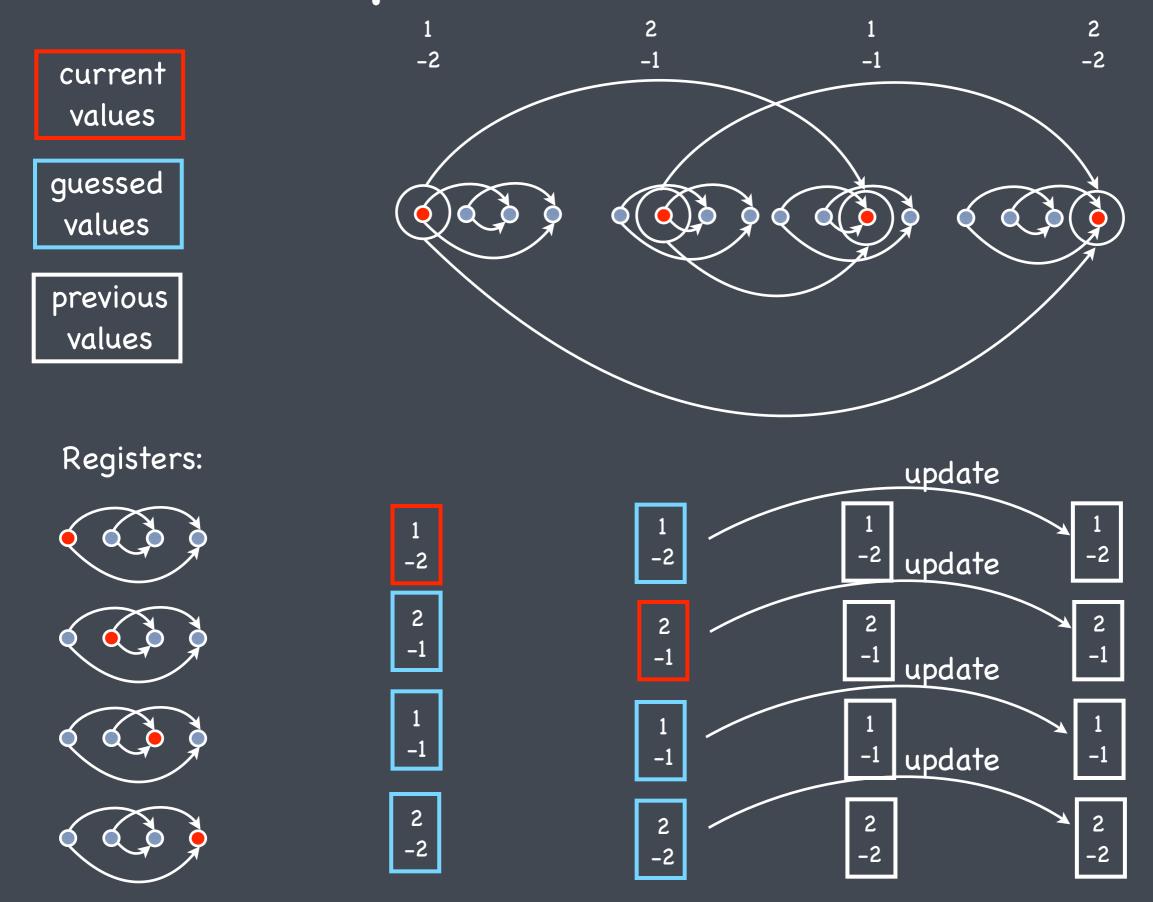


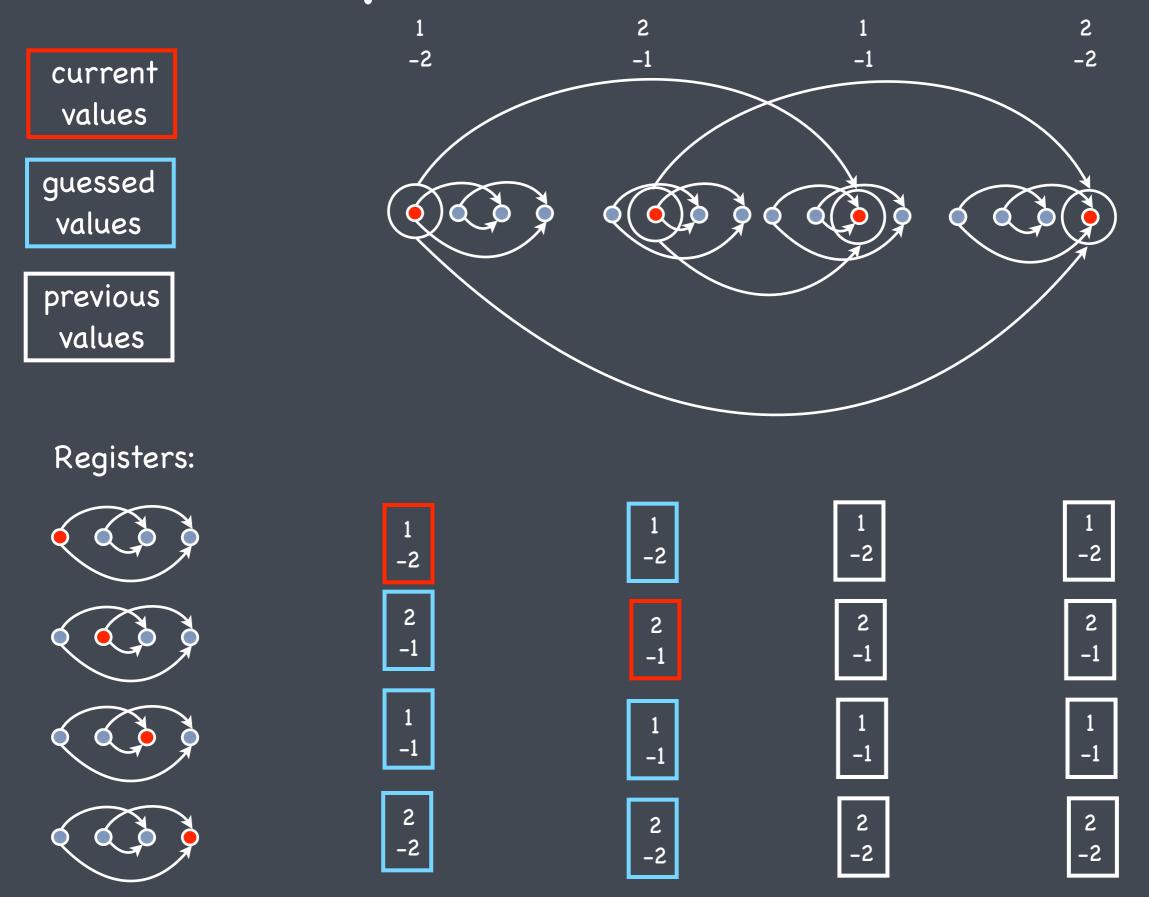


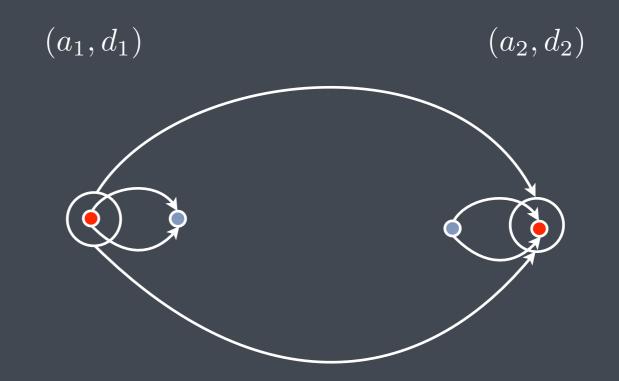




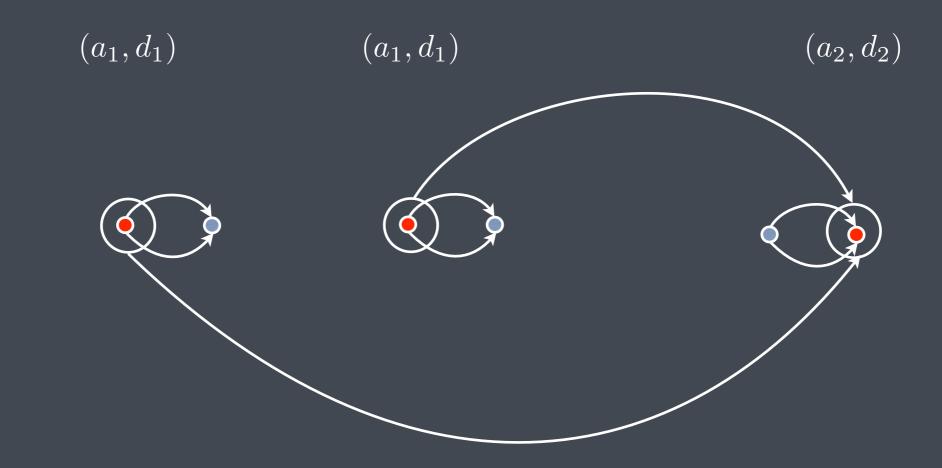




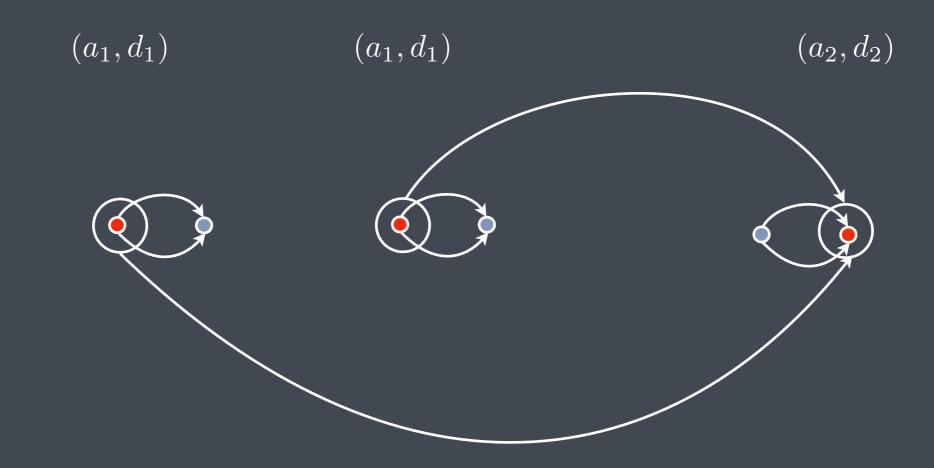




How can we be sure that a cycle is closed?



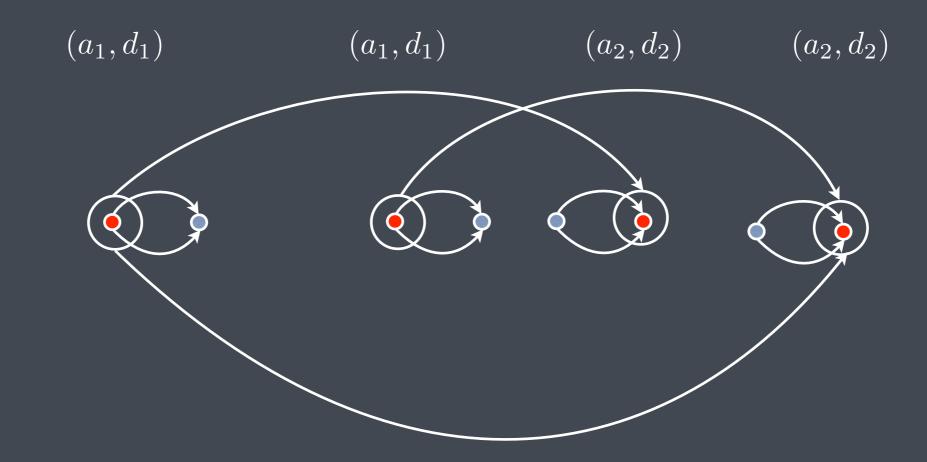
How can we be sure that a cycle is closed? Suppose it is not closed.



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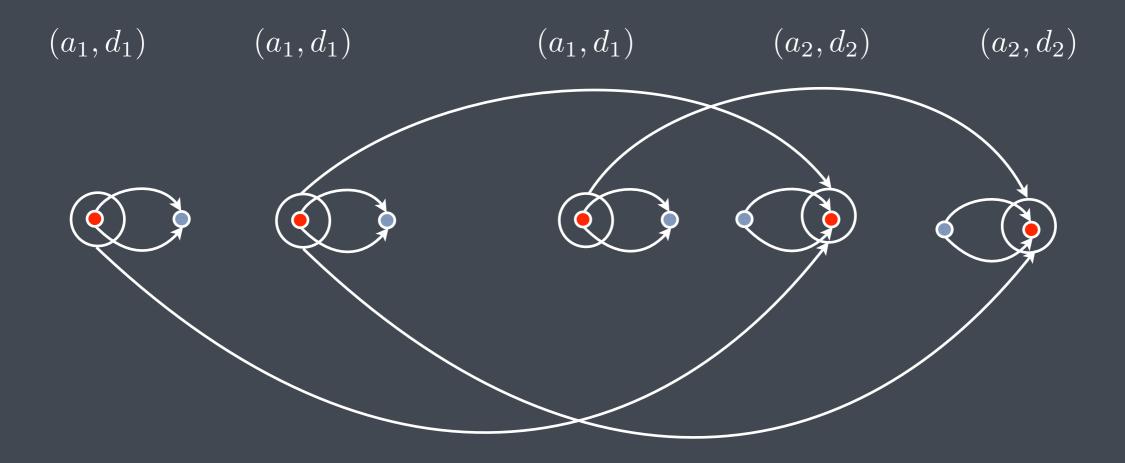
- 1) we carry along labels and data values
- 2) relations are monotone



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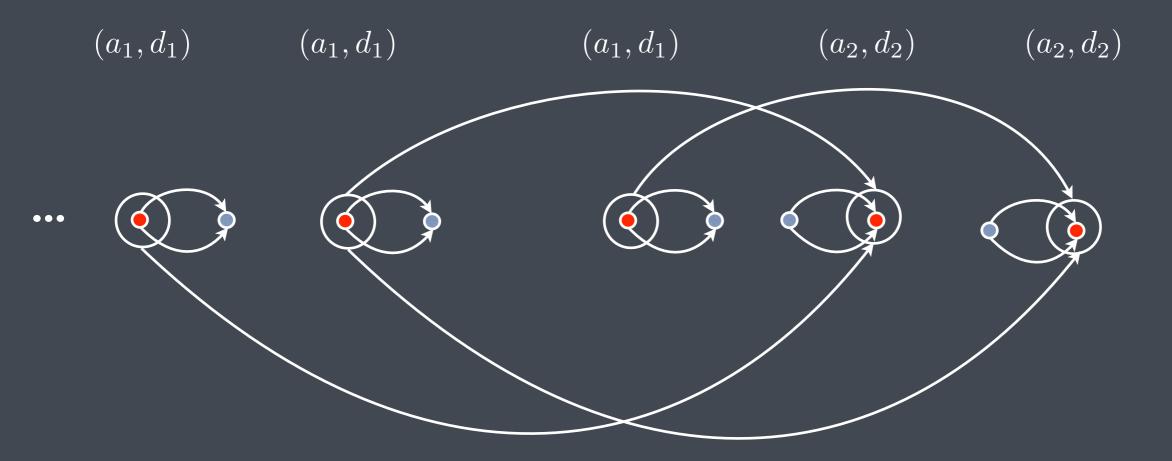
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=> infinite descending chain 4

• $MSO(\prec_{+1}) \subseteq RA$

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- \circ gCRA $(\prec_{+1},\prec_{\sim}) \subseteq$ MSO $(\prec_{+1},\prec_{\sim})$?

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Synthesis of dynamic communicating systems

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- Class register automata subsume dynamic communicating automata [B., Hélouët, 2010]

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- Study of combined expressive power of existing concepts

General framework for specification and implementation of data-word languages

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Synthesis of dynamic communicating systems

- General framework for specification and implementation of data-word languages
- Synthesis of dynamic communicating systems
- Next: synthesize more practical automata
 => restricted specification languages
 => temporal logics