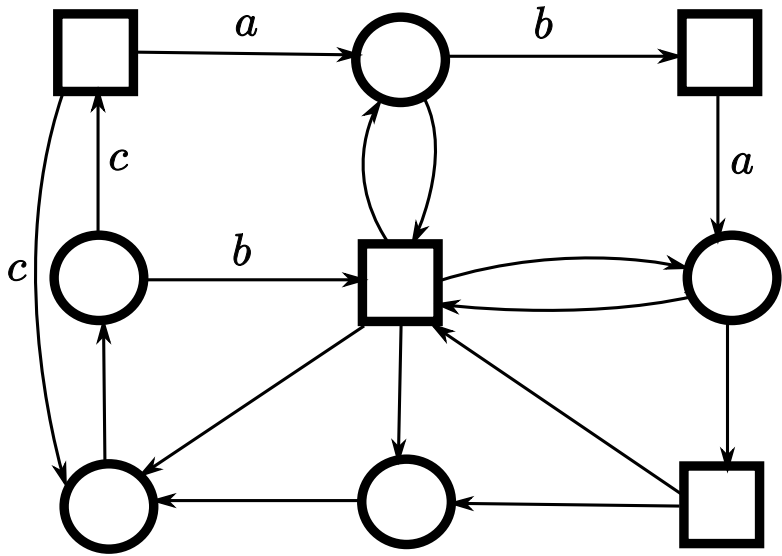


Positional equilibria in infinite perfect information games

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ACTS



Transition systems

$$\mathcal{A} = (S, \Delta)$$

S — a finite set of states,

C — a set of colors,

$\Delta \subset S \times C \times S$ — a finite set of *actions*.

$$e = (s, c, t) \in \Delta$$

$s = \text{source}(e)$ — the *source*,

$t = \text{target}(e)$ — the *target*,

$c = \gamma_C(e)$ — the colour of e .

$$\Delta(s) = \{e \in \Delta \mid \text{source}(e) = s\}$$

the set of actions *available at* s .

s a *sink state* if $\Delta(s) \neq \emptyset$.

Paths/Plays

$$p = e_1 e_2 e_3 \dots \quad \forall i \geq 0, \text{target}(e_i) = \text{source}(e_{i+1}).$$

$$\gamma_C(p) = \gamma_C(e_1 e_2 \dots) = \gamma_C(e_1) \gamma_C(e_2) \dots$$

Arenas

$$\mathcal{A} = (S, \Delta, \pi)$$

- (S, Δ) – a transition system without sink states,
- $\pi : S \rightarrow \{\text{Min}, \text{Max}\}$ is a mapping designating for each state s the player $\pi(s)$ controlling s .

Outcomes

An outcome of an infinite play p is the $\gamma_C(p)$.

The set of outcomes

$$\mathcal{O}(C) = \bigcup_{\substack{B \subset C \\ B \text{ finite nonempty}}} B^\omega.$$

Preference relation

A binary relation \succeq over the set $\mathcal{O}(C)$ of outcomes

- reflexive, i.e. $u \succeq u$, for all $u \in \mathcal{O}(C)$,
- transitive, i.e. $u \succeq v$ and $v \succeq w$ imply $u \succeq w$, for $u, v, w \in \mathcal{O}(C)$ and
- total, either $u \succeq v$ or $v \succeq u$, for all $u, v \in \mathcal{O}(C)$.

A preference relation = a total preorder relation over the set $\mathcal{O}(C)$ of outcomes.

Meaning

$$u \succeq v, \quad u, v \in \mathcal{O}(C).$$

u is no worse than v .

A player *strictly prefers* u to v , $u \succ v$, if

$$u \succeq v \quad \text{but not} \quad v \succeq u.$$

If $u \succeq v$ and $v \succeq u$ — a player is indifferent between u and v .

\sqsubseteq — the inverse of \succeq .

Two-person strictly antagonistic game

$$(\mathcal{A}, \sqsupseteq),$$

where \mathcal{A} is an arena and \sqsupseteq is a preference relation for Max the preference relation for player Min is \sqsubseteq .

The obvious aim of each player is to obtain the most advantageous outcome with respect to his preference relation.

Preferences versus payoff mappings

Payoff mapping

$$f : \mathcal{O}(C) \rightarrow \mathbb{R} \cup \{-\infty, +\infty\}$$

induces preference \succeq_f ,

$$u \succeq_f v \quad \text{if} \quad f(u) \geq f(v).$$

Strategies and equilibria

$\mathcal{A} = (S, \Delta, \pi)$ – an arena.

$$S_{\text{Max}} = \{s \in S \mid \pi(s) = \text{Max}\}$$

states controlled by player Max

$$S_{\text{Min}} = S \setminus S_{\text{Max}}$$

states controlled by player Min.

A *strategy* for player $\mu \in \{\text{Max}, \text{Min}\}$ is a mapping

$$\sigma_\mu : \{p \in \mathcal{P}(\mathcal{A}) \mid \text{target}(p) \in S_\mu\} \rightarrow \Delta,$$

such that $\sigma_\mu(p) \in \Delta(s)$, where $s = \text{target}(p)$.

Plays consistent with a strategy

$p = e_0e_1e_2\dots$ is *consistent* with player μ 's strategy σ_μ if, for each factorization $p = p'p''$, such that

- p'' is nonempty
- and $\text{target}(p') = \text{source}(p'')$ is controlled by player μ ,

$\sigma_\mu(p')$ is the first action in p'' .

Positional strategies

A *positional* (or memoryless) strategy for player μ

$$\sigma_\mu : S_\mu \rightarrow \Delta$$

such that, for all $s \in S_\mu$,

$$\sigma_\mu(s) \in \Delta(s)$$

A *strategy profile* is a pair (σ, τ) of strategies.

$$p_{\mathcal{A},s}(\sigma, \tau)$$

unique play with source s consistent with σ and τ .

Equilibria

A Nash equilibrium $(\sigma^\#, \tau^\#)$ if for all states $s \in S$ and all strategies σ and τ ,

$$\gamma_C(p_{\mathcal{A},s}(\sigma^\#, \tau)) \sqsupseteq \gamma_C(p_{\mathcal{A},s}(\sigma^\#, \tau^\#)) \sqsupseteq \gamma_C(p_{\mathcal{A},s}(\sigma, \tau^\#)) .$$

An equilibrium $(\sigma^\#, \tau^\#)$ is said to be *positional* if the strategies $\sigma^\#$ and $\tau^\#$ are positional.

Mean-payoff games

$$C = \mathbb{R} \times \mathbb{R}_+$$

$$(r_1, t_1)(r_2, t_2)(r_3, t_3) \dots \sqsupseteq (r'_1, t'_1)(r'_2, t'_2)(r'_3, t'_3) \dots$$

if

$$\lim_n \frac{r_1 t_1 + r_2 t_2 + \dots + r_n t_n}{t_1 + t_2 + \dots + t_n} \geq \lim_n \frac{r'_1 t'_1 + r'_2 t'_2 + \dots + r'_n t'_n}{t'_1 + t'_2 + \dots + t'_n}$$

But then

$$1000, 1000, \dots, 1000, 0^\omega \approx 0^\omega$$

Overtaking

$$(r_1, t_1)(r_2, t_2)(r_3, t_3) \dots \supseteq (r'_1, t'_1)(r'_2, t'_2)(r'_3, t'_3) \dots$$

if

$$\exists N, \forall n > N, \quad \frac{r_1 t_1 + r_2 t_2 + \dots + r_n t_n}{t_1 + t_2 + \dots + t_n} \geq \frac{r'_1 t'_1 + r'_2 t'_2 + \dots + r'_n t'_n}{t'_1 + t'_2 + \dots + t'_n}$$

Weighted limits

$$C = \mathbb{R}, \quad \alpha \in [0, 1]$$

$$f_\alpha(r_1 r_2 r_3 \dots) = \alpha \cdot \limsup_i r_i + (1 - \alpha) \cdot \liminf_i r_i$$

Extended preference relation and \succeq - equilibria

The *extended preference relation* \succeq is defined as follows:

$$\text{for } x, y \in \mathcal{O}(C), \quad x \succeq y \quad \text{if} \quad \forall u \in C^*, ux \sqsupseteq uy.$$

Obviously, if $x \succeq y$ then $x \sqsupseteq y$.

\succeq is transitive and reflexive, but maybe not total.

\succeq -equilibria

A strategy profile $(\sigma^\#, \tau^\#)$ is a \succeq -*equilibrium* if for all strategies σ, τ

$$\gamma_C(p_{\mathcal{A},s}(\sigma^\#, \tau)) \succeq \gamma_C(p_{\mathcal{A},s}(\sigma^\#, \tau^\#)) \succeq \gamma_C(p_{\mathcal{A},s}(\sigma, \tau^\#)) .$$

Adherence operator

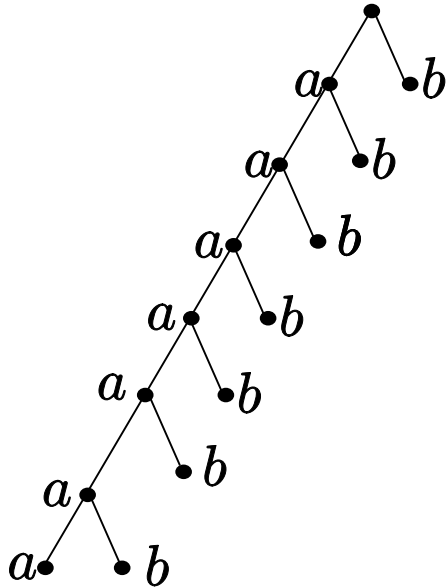
$$\llbracket \cdot \rrbracket : 2^{C^*} \rightarrow 2^{C^\omega}$$

For $L \subseteq C^*$,

$$\llbracket L \rrbracket = \{u \in C^\omega \mid \text{Pref}(u) \subset \text{Pref}(L)\} .$$

Exercise

$$\llbracket a^*b \rrbracket = \{a^\omega\}$$



Why adherence?

$\mathcal{A} = (S, \Delta)$ an arena. Then

$$L_s^\omega(\mathcal{A}) = \llbracket L_s(\mathcal{A}) \rrbracket$$

If $L \in \text{Rec}(C^*)$ then $L_s^\omega(\mathcal{A}) = \llbracket L \rrbracket$ for some arena \mathcal{A} .

Properties of the adherence

Lemma 1. *Let $L, M \subseteq C^*$ be finitely generated and $u \in C^*$. Then*

$$\llbracket uL \rrbracket = u \llbracket L \rrbracket , \quad (1)$$

$$\llbracket \text{Pref}(\llbracket M \rrbracket) \rrbracket = \llbracket M \rrbracket , \quad (2)$$

$$\llbracket L \cup M \rrbracket = \llbracket L \rrbracket \cup \llbracket M \rrbracket , \quad (3)$$

$$\llbracket LM \rrbracket = \llbracket L \rrbracket \cup L \llbracket M \rrbracket , \quad (4)$$

$$\llbracket L^* \rrbracket = (L \setminus \epsilon)^\omega \cup L^* \llbracket L \rrbracket . \quad (5)$$

Conditions for positional equilibria

Let $u \in \mathcal{O}(C)$ and $X \subset \mathcal{O}(C)$.

Notation.

$$u \succeq X$$

if, for all $x \in X$, $u \succeq x$.

Ultimately periodic infinite words

Let $u, w \in C^*$ and $v \in C^+$.

An infinite word of the form

$$uv^\omega,$$

is called *ultimately periodic*.

Simple periodic languages

Let $u, w \in C^*$ and $v \in C^+$.

$$uv^*$$

Note

$$\llbracket uv^* \rrbracket = \{uv^\omega\}$$

Union selection.

\succsim satisfies *union selection* condition if, for all ultimately periodic words $u_1u_2^\omega$ and $v_1v_2^\omega$, either

$$u_1u_2^\omega \succsim v_1v_2^\omega$$

or

$$v_1v_2^\omega \succsim u_1u_2^\omega$$

We can rewrite this condition as

$$\exists x \in \{u_1u_2^\omega, v_1v_2^\omega\}, \quad x \succsim \llbracket u_1u_2^* \cup v_1v_2^* \rrbracket.$$

Product selection.

We say that \succsim satisfies *product selection* condition for player Max if, for all $u, v, w, z \in C^*$ such that $|v| > 0$ and $|w| > 0$,

$$\exists x \in \{uv^\omega, uwz^\omega\}, \quad x \succsim \llbracket uv^*wz^* \rrbracket.$$

Note that

$$\{uv^\omega, uwz^\omega\} \subset uv^\omega \cup uv^*wz^\omega = \llbracket uv^*wz^* \rrbracket.$$

Star selection.

\succsim satisfies *star selection* condition for player Max if for each nonempty language $L \in \text{Rec}(C^+)$

$$\exists x \in \llbracket L \rrbracket \cup \{u^\omega \mid u \in L\}, \quad x \succsim \llbracket L^* \rrbracket.$$

Note

$$\llbracket L \rrbracket \cup \{u^\omega \mid u \in L\} \subset \llbracket L \rrbracket \cup L^\omega = \llbracket L^* \rrbracket$$

Remark

If \succeq satisfies all three selection conditions then for each $L \in \text{Rec}(C)$, if $\llbracket L \rrbracket \neq \emptyset$ then

$$\exists uv^\omega \in \llbracket L \rrbracket \quad \text{such that} \quad uv^\omega \succeq \llbracket L \rrbracket$$

One player Max games

\succeq satisfies all three selection conditions
if and only if

one-player Max games have optimal positional strategies for player Max.

Dual conditions.

$$\| \cdot \| \leftrightarrow \| \cdot \| .$$

Main result

Theorem 2. *Let \sqsubseteq be a preference relation over $\mathcal{O}(C)$ and let \succeq be the corresponding extended preference relation. The following conditions are equivalent:*

- (1) There exist positional equilibria for all games $(\mathcal{A}, \sqsubseteq)$ over finite arenas.*
- (2) There exist positional \succeq -equilibria for all games $(\mathcal{A}, \sqsubseteq)$ over finite arenas.*
- (3) \succeq satisfies union selection, product selection and star selection conditions for player Max and player Min.*

- (4) *For all one-player games $(\mathcal{A}, \sqsupseteq)$ the player controlling the arena \mathcal{A} has an optimal positional strategy.*
- (5) *For all one-player games $(\mathcal{A}, \sqsupseteq)$ the player controlling the arena \mathcal{A} has a \succeq -optimal positional strategy.*