Two-player Reachability Games with Partial Observation on Both Sides

Hugo Gimbert, CNRS, LaBRI, Bordeaux

January 30, 2009

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Hugo Gimbert, CNRS, LaBRI, Bordeaux Games with Partial Observation

Qualitative Determinacy What is known Memory Requirements Decidability Results

Playing with Actions Partial Observation via Signals

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Motivations

Controller synthesis.

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- Controller synthesis.
- System interacting with both the controller and the user.

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- Controller synthesis.
- System interacting with both the controller and the user.
- $\blacktriangleright \implies$ two-player game

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- Partial observation for both the controller and the user.
- Avoids implementation of full monitoring.

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- Controller synthesis.
- System interacting with both the controller and the user.
- $\blacktriangleright \implies$ two-player game
- Partial observation for both the controller and the user.
- Avoids implementation of full monitoring.
- First step towards distributed synthesis.

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- First step towards distributed synthesis.
- Reachability, safety (+Büchi) conditions.

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- Controller synthesis.
- System interacting with both the controller and the user.
- ► ⇒ two-player game
- Partial observation for both the controller and the user.
- Avoids implementation of full monitoring.
- First step towards distributed synthesis.
- Reachability, safety (+Büchi) conditions.
- Determinacy, decidability. With Nathalie Bertrand and Blaise Genest, Rennes.

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Two-players games with reachability condition.

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- Two-players games with reachability condition.
- ► Discrete-time systems. System goes through a sequence of states k₀, k₁,... ∈ K*.

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- Two-players games with reachability condition.
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- Two decision makers = player 1 and player 2.

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- Two-players games with reachability condition.
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- They interact synchronously.

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- ▶ Initial state k_0 . Players 1 and 2 choose simultaneously actions i_{n+1} and j_{n+1} .

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- They interact synchronously.
- ▶ Initial state k_0 . Players 1 and 2 choose simultaneously actions i_{n+1} and j_{n+1} .
- ▶ This determines the new state k_{n+1} depending on the current state k_n and the actions i_{n+1} and j_{n+1} .

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- Transitions may be probabilistic.

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- ▶ This determines the new state k_{n+1} depending on the current state k_n and the actions i_{n+1} and j_{n+1} .
- Transitions may be probabilistic.
- Goal of player 1: reaching a set of target states $T \subseteq K$.

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- ▶ This determines the new state k_{n+1} depending on the current state k_n and the actions i_{n+1} and j_{n+1} .
- Transitions may be probabilistic.
- Goal of player 1: reaching a set of target states $T \subseteq K$.
- Goal of player 2: the opposite.

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Only one player.

• States $K = \{ini, 1, 2, 3, Lose, Win\}$

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Only one player.

- States $K = {ini, 1, 2, 3, Lose, Win}$
- Actions $I = \{a, g_1, g_2, g_3\}$

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Partial observation via signals

Set of states *K*, set of actions *I* and *J* for player 1 and 2.

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- ► Set of states *K*, set of actions *I* and *J* for player 1 and 2.
- Set of signals C and D for player 1 and 2.

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- Set of states K, set of actions I and J for player 1 and 2.
- ▶ Set of signals *C* and *D* for player 1 and 2.
- Current state k.

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- Set of states K, set of actions I and J for player 1 and 2.
- ▶ Set of signals *C* and *D* for player 1 and 2.
- Current state k.
- Players choose actions i and j

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Playing with Actions Partial Observation via Signals

- Set of states K, set of actions I and J for player 1 and 2.
- ▶ Set of signals *C* and *D* for player 1 and 2.
- Current state k.
- Players choose actions i and j
- ▶ Players receive signals *c* and *d*.

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- ► Set of states *K*, set of actions *I* and *J* for player 1 and 2.
- ▶ Set of signals *C* and *D* for player 1 and 2.
- Current state k.
- Players choose actions i and j
- Players receive signals c and d.
- ▶ New state k' and signals c and d with probability $0 \le p(k', c, d \mid k, i, j) \le 1$.

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- Set of states K, set of actions I and J for player 1 and 2.
- Set of signals C and D for player 1 and 2.
- Current state k.
- Players choose actions i and j
- Players receive signals c and d.
- New state k' and signals c and d with probability 0 ≤ p(k', c, d | k, i, j) ≤ 1.
- ► A play is an infinite sequence of states, actions and signals in (KIJCD)^ω

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Only one player.

- States $K = \{ini, 1, 2, 3, Lose, Win\}$
- Actions $I = \{a, g_1, g_2, g_3\}$
- Signals $C = \{\alpha, \beta, \gamma\}$

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Strategies

▶ After a finite play (k₀,

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Strategies

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Strategies

• After a finite play $(k_0, i_0, j_0, c_0, d_0, d_0)$

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Strategies

• After a finite play $(k_0, i_0, j_0, c_0, d_0, k_1, d_0, k_1)$

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Strategies

• After a finite play $(k_0, i_0, j_0, c_0, d_0, k_1, i_1, j_1, d_0, k_1, i_1, j_1, d_0)$

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Strategies

► After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁,

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Strategies

▶ After a finite play (*k*₀, *i*₀, *j*₀, *c*₀, *d*₀, *k*₁, *i*₁, *j*₁, *c*₁, *d*₁, ...,
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Strategies

▶ After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁, ..., k_n)

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- After a finite play $(k_0, i_0, j_0, c_0, d_0, k_1, i_1, j_1, c_1, d_1, ..., k_n)$, players choose actions i_n and j_n .
- Choices are made using strategies.

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- ► After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁, ..., k_n), players choose actions i_n and j_n.
- Choices are made using strategies.
- In games with perfect information: choices depend on the whole play.

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- ► After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁, ..., k_n), players choose actions i_n and j_n.
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- In games with perfect information: choices depend on the whole play.
- In games with partial observation: choices depend only on signals.

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- ► After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁, ..., k_n), players choose actions i_n and j_n.
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- In games with perfect information: choices depend on the whole play.
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- Strategy σ for player 1: σ_δ : C^{*} → D(I), C signals of player 1 and D(I) probability distributions on actions of 1.

Qualitative Determinacy What is known Memory Requirements Decidability Results

Playing with Actions Partial Observation via Signals

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- After signals $c_0 c_1 \dots c_n$ player 1 plays action *i* with proba $\sigma_{\delta}(i)$.

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- After signals $c_0 c_1 \dots c_n$ player 1 plays action *i* with proba $\sigma_{\delta}(i)$.
- ▶ Initial state: initial probability distribution $\delta \in \mathcal{D}(K)$.

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- ► After a finite play (k₀, i₀, j₀, c₀, d₀, k₁, i₁, j₁, c₁, d₁, ..., k_n), players choose actions i_n and j_n.
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- After signals $c_0 c_1 \dots c_n$ player 1 plays action *i* with proba $\sigma_{\delta}(i)$.
- ▶ Initial state: initial probability distribution $\delta \in \mathcal{D}(K)$.
- Signals contain actions.

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Winning probability

▶ Initial distribution δ and strategies σ and τ . Markov chain. Probability measure $\mathbb{P}^{\sigma,\tau}_{\delta}(\cdot)$ on the set of infinite plays $(KIJCD)^{\omega}$.

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Winning probability

- ▶ Initial distribution δ and strategies σ and τ . Markov chain. Probability measure $\mathbb{P}^{\sigma,\tau}_{\delta}(\cdot)$ on the set of infinite plays $(KIJCD)^{\omega}$.
- Player 1 wants the probability to reach a target state

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$

to be as close to 1 as possible.

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Winning probability

- ▶ Initial distribution δ and strategies σ and τ . Markov chain. Probability measure $\mathbb{P}^{\sigma,\tau}_{\delta}(\cdot)$ on the set of infinite plays $(KIJCD)^{\omega}$.
- Player 1 wants the probability to reach a target state

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to be as close to 1 as possible.

Player 2 has the opposite goal.

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Two players.

- States $K = \{ini, 1, 2, Lose, Win\}$
- Actions $I = \{0, 1, g_1, g_2\}$ and $J = \{0, 1\}$
- Player 2 is blind.
- Signals $C = \{\alpha, \beta, \gamma\}$ and $D = \{\cdot\}$

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collisions occur on ethernet networks,



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- collisions occur on ethernet networks,
- controllers choose to stay idle for some randomly chosen delay.



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Playing with Actions Partial Observation via Signals

Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

Qualitative Solution Concepts Qualitative Determinacy

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Winning almost-surely, surely and positively

Player 1 wants $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$ to be as close to 1 as possible.

Qualitative Solution Concepts Qualitative Determinacy

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Winning almost-surely, surely and positively

Player 1 wants $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$ to be as close to 1 as possible.

Player 1 wins almost-surely: if player 1 has a strategy σ such that for every strategy τ of player 2,

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 1$.

Qualitative Solution Concepts Qualitative Determinacy

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Winning almost-surely, surely and positively

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Player 1 wins almost-surely: if player 1 has a strategy σ such that for every strategy τ of player 2,

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 1$.

▶ Player 2 wins almost-surely: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 0$.

Qualitative Solution Concepts Qualitative Determinacy

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Winning almost-surely, surely and positively

Player 1 wants $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$ to be as close to 1 as possible.

Player 1 wins almost-surely: if player 1 has a strategy σ such that for every strategy τ of player 2,

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 1$.

- ▶ Player 2 wins almost-surely: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 0$.
- Player 1 wins positively:

$$\exists \sigma \ \forall \tau \ \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) > 0$$
.

Qualitative Solution Concepts Qualitative Determinacy

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Winning almost-surely, surely and positively

Player 1 wants $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$ to be as close to 1 as possible.

Player 1 wins almost-surely: if player 1 has a strategy σ such that for every strategy τ of player 2,

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 1$.

- ▶ Player 2 wins almost-surely: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 0$.
- Player 1 wins positively:

$$\exists \sigma \ \forall \tau \ \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) > 0$$
.

▶ Player 2 wins positively: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) < 1$.

Qualitative Solution Concepts Qualitative Determinacy

Winning almost-surely, surely and positively

Player 1 wants $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T)$ to be as close to 1 as possible.

Player 1 wins almost-surely: if player 1 has a strategy σ such that for every strategy τ of player 2,

 $\mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 1$.

- ▶ Player 2 wins almost-surely: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = 0$.
- Player 1 wins positively:

$$\exists \sigma \ \forall \tau \ \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) > 0$$
.

- ▶ Player 2 wins positively: if $\exists \tau \forall \sigma \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) < 1$.
- Randomized strategies are necessary, in practice (ethernet) and in theory (determinacy).

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Qualitative Determinacy

• Player 1 wins positively $(\exists \sigma \forall \tau > 0)$

 \implies Player 2 does not win almost-surely $\neg(\exists \tau \forall \sigma = 0)$.

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively $(\exists \tau \forall \sigma < 1)$
 - \implies Player 1 does not win almost-surely $\neg(\exists \sigma \forall \tau = 1)$.

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively (∃τ∀σ < 1)
 ⇒ Player 1 does not win almost-surely ¬(∃σ∀τ = 1).
- Converse?

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively (∃τ∀σ < 1)
 ⇒ Player 1 does not win almost-surely ¬(∃σ∀τ = 1).
- Converse?

$$\blacktriangleright (\forall \tau \exists \sigma > 0) \implies (\exists \sigma \forall \tau > 0)?$$

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively (∃τ∀σ < 1)
 ⇒ Player 1 does not win almost-surely ¬(∃σ∀τ = 1).
- Converse?

$$\blacktriangleright (\forall \tau \exists \sigma > 0) \implies (\exists \sigma \forall \tau > 0)?$$

$$\blacktriangleright (\forall \sigma \exists \tau < 1) \implies (\exists \tau \forall \sigma < 1)?$$

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively (∃τ∀σ < 1)
 ⇒ Player 1 does not win almost-surely ¬(∃σ∀τ = 1).
- Converse?

$$\blacktriangleright (\forall \tau \exists \sigma > 0) \implies (\exists \sigma \forall \tau > 0)?$$

- $\blacktriangleright (\forall \sigma \exists \tau < 1) \implies (\exists \tau \forall \sigma < 1)?$
- Yes, it holds.

Qualitative Solution Concepts Qualitative Determinacy

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- Player 1 wins positively (∃σ∀τ > 0)
 ⇒ Player 2 does not win almost-surely ¬(∃τ∀σ = 0).
- Player 2 wins positively (∃τ∀σ < 1)
 ⇒ Player 1 does not win almost-surely ¬(∃σ∀τ = 1).
- Converse?

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$$\blacktriangleright \ (\forall \sigma \exists \tau < 1) \implies (\exists \tau \forall \sigma < 1)?$$

- Yes, it holds.
- Requires knowledge about almost-surely and positively winning strategies.

Qualitative Solution Concepts Qualitative Determinacy

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Qualitative Determinacy

Determinacy Theorem: [Bertrand, Genest, G.] A partial observation reachability games with finitely many states, actions and signals is either:

• almost-surely winning for player 1,

Qualitative Solution Concepts Qualitative Determinacy

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Determinacy Theorem: [Bertrand, Genest, G.] A partial observation reachability games with finitely many states, actions and signals is either:

- almost-surely winning for player 1,
- surely winning for player 2,

Qualitative Solution Concepts Qualitative Determinacy

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Determinacy Theorem: [Bertrand, Genest, G.] A partial observation reachability games with finitely many states, actions and signals is either:

- almost-surely winning for player 1,
- surely winning for player 2,
- or positively winning for both player 1 and 2.

Qualitative Solution Concepts Qualitative Determinacy

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Remarks:

 Generalizes result of [deAlfaro, Henzinger 00] for full monitoring.

Qualitative Solution Concepts Qualitative Determinacy

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Qualitative Solution Concepts Qualitative Determinacy

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- or positively winning for both player 1 and 2.

Remarks:

- Generalizes result of [deAlfaro, Henzinger 00] for full monitoring.
- ► Holds for perfect-info, prefix-independent games [G., Horn 08].
- False for Büchi games.
Qualitative Solution Concepts Qualitative Determinacy

Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

Values

Definition: a game has a value $0 \le v \le 1$, if player 1 can defend probability $v + \epsilon$ and player 2 can secure probability $v - \epsilon$, for every ϵ .

$$\sup_{\sigma} \inf_{\tau} \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T) = \leq \mathbf{v} \leq \inf_{\tau} \sup_{\sigma} \mathbb{P}^{\sigma,\tau}_{\delta}(\exists n, K_n \in T).$$

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 Proposition [Renaut, Sorin, G.]: two players zero-sum reachability games with partial observation have a value.

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- Proposition [Renaut, Sorin, G.]: two players zero-sum reachability games with partial observation have a value.
- Theorem [Paz 71, Bertoni 75]: values are not computable, even for one player and no observations.

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Full monitoring: players observe everything.

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Decidable cases

- ► Full monitoring: players observe everything.
- Values are computable (2-EXPTIME) (Chatterjee, Henzinger).

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Decidable cases

- ► Full monitoring: players observe everything.
- Values are computable (2-EXPTIME) (Chatterjee, Henzinger).
- Existence of almost-surely or positively winning strategies decidable in polynomial time (deAlfaro, Henzinger, 00).
- One player perfectly informed + deterministic transitions: Existence of almost-surely or positively strategies decidable in EXPTIME (Chatterjee, Doyen, Henzinger, Raskin 03).

Positive winning for Büchi games

Theorem [Baier, Bertrand, Groesser, 07]: Büchi games. It is undecidable whether player 1 has a positively winning strategy.

Positive winning for Büchi games

- Theorem [Baier, Bertrand, Groesser, 07]: Büchi games. It is undecidable whether player 1 has a positively winning strategy.
- Holds even for player 1 blind and alone.

Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

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Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

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From no memory to doubly-exponential memory Doubly exponential memory is needed

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Memory requirements

Memory necessary for implementing the strategies?

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Memory necessary for implementing the strategies?
- Player 1 needs no memory for winning positively: play randomly all actions.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Memory necessary for implementing the strategies?
- Player 1 needs no memory for winning positively: play randomly all actions.
- ▶ Player 2 needs memory $\mathcal{P}(K)$ for winning surely.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Beliefs: set L ⊆ K of possible current states according to signals sequence.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Beliefs: set L ⊆ K of possible current states according to signals sequence.
- Player 2 play an action s.t. her next belief is surely winning.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Player 2 play an action s.t. her next belief is surely winning.
- ▶ Player 1 needs memory $\mathcal{P}(K)$ for winning almost-surely.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Plays all actions s.t. his next belief is almost-surely winning.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Not very surprising, true for one-player games.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Player 1 needs no memory for winning positively: play randomly all actions.
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- Player 2 play an action s.t. her next belief is surely winning.
- ▶ Player 1 needs memory $\mathcal{P}(K)$ for winning almost-surely.
- Plays all actions s.t. his next belief is almost-surely winning.
- ► Not very surprising, true for one-player games.
- Upper bounds for time and lower bounds for probabilities.

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Memory requirements, the element of surprise

What about player 2 winning positively?

From no memory to doubly-exponential memory Doubly exponential memory is needed

- What about player 2 winning positively?
- She wants to ensure that with positive probability, the game will never reach a target state.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- What about player 2 winning positively?
- She wants to ensure that with positive probability, the game will never reach a target state.
- ► Player 2 needs doubly-exponential memory P (P (K) × K) for winning positively.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- What about player 2 winning positively?
- She wants to ensure that with positive probability, the game will never reach a target state.
- ► Player 2 needs doubly-exponential memory P (P (K) × K) for winning positively.
- Player 2 remembers the set of possible beliefs of player 1.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- What about player 2 winning positively?
- She wants to ensure that with positive probability, the game will never reach a target state.
- ► Player 2 needs doubly-exponential memory P (P (K) × K) for winning positively.
- Player 2 remembers the set of possible beliefs of player 1.
- Beliefs of 2 about beliefs of 1. When player 2 receives signal d, she makes hypothesis about signal c received by player 1.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- What about player 2 winning positively?
- She wants to ensure that with positive probability, the game will never reach a target state.
- ► Player 2 needs doubly-exponential memory P (P (K) × K) for winning positively.
- Player 2 remembers the set of possible beliefs of player 1.
- Beliefs of 2 about beliefs of 1. When player 2 receives signal d, she makes hypothesis about signal c received by player 1.
- Very different from perfect-information games, concurrent games, even games with a perfectly informed opponent.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Doubly exponential memory is needed

Proposition: Player 2 needs double-exponential memory for winning positively.

Special case: exponential memory if player 1 perfectly informed, because guessing current state = guessing belief of 1.

Special case: exponential memory if player 2 observes signals of player 1 because player 2 can compute the belief of player 1.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Proposition: Player 2 needs double-exponential memory for winning positively. Example:

▶ Randomly choose among *n* objects a set *E* of n/2 objects.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Proposition: Player 2 needs double-exponential memory for winning positively.

- ▶ Randomly choose among *n* objects a set *E* of n/2 objects.
- Reveal *E* to player 1 but not to player 2.

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Proposition: Player 2 needs double-exponential memory for winning positively.

- Randomly choose among n objects a set E of n/2 objects.
- Reveal *E* to player 1 but not to player 2.
- ▶ Player 1 reveals to player 2 sets E₁,..., E_{1/2}Cⁿ_{n/2} of n/2 objects, different from E.

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- Whenever player 1 cheats or player 2 gets wrong, it gives positive probability to win to the opponent.

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- Whenever player 1 cheats or player 2 gets wrong, it gives positive probability to win to the opponent.
- Start again.

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- Reveal *E* to player 1 but not to player 2.
- ▶ Player 1 reveals to player 2 sets E₁,..., E_{1/2}Cⁿ_{n/2} of n/2 objects, different from E.
- ▶ Player 2 has $\frac{1}{2}C_{n/2}^n$ tries for guessing correctly *E*.
- Whenever player 1 cheats or player 2 gets wrong, it gives positive probability to win to the opponent.
- Start again.
- Implementable with polynomial number of states.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

Choosing randomly the set *E* of n/2 objects, revealing it to player 1 but not to player 2.

• Two counters from 1 to n and from 1 to n/2 are used.
From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

Choosing randomly the set *E* of n/2 objects, revealing it to player 1 but not to player 2.

- Two counters from 1 to n and from 1 to n/2 are used.
- ► They are used for generating randomly a sequence of signals in {0,1}ⁿ with exactly n/2 letters 1.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

Choosing randomly the set *E* of n/2 objects, revealing it to player 1 but not to player 2.

- Two counters from 1 to n and from 1 to n/2 are used.
- ► They are used for generating randomly a sequence of signals in {0,1}ⁿ with exactly n/2 letters 1.
- Moreover a counter is used for storing one of the positions m where a "1" was sent.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

Forcing player 1 to reveal to player 2 $\frac{1}{2}C_{n/2}^n$ sets different from *E*.

Player 1 is a cheater if a set F he reveals is exactly E, i.e. if every object in F is in E as well.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

- Player 1 is a cheater if a set F he reveals is exactly E, i.e. if every object in F is in E as well.
- ▶ For revealing set *F*, player 1 sends *n* signals in {0,1} to player 2, 1001 means "objects 1 and 4".

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Player 1 is a cheater if a set F he reveals is exactly E, i.e. if every object in F is in E as well.
- ▶ For revealing set F, player 1 sends n signals in {0,1} to player 2, 1001 means "objects 1 and 4".
- At one of the moments where he sends a "1", player 1 announce secretly to the system that the current object m is not in the set E.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- In case *m* coincides with the position stored previously, player 1 is a cheater and he is punished by losing for sure.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- At one of the moments where he sends a "1", player 1 announce secretly to the system that the current object m is not in the set E.
- In case *m* coincides with the position stored previously, player 1 is a cheater and he is punished by losing for sure.
- Player 1 may cheat without being caught, but he has positive probability to get caught.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

Forcing player 1 to reveal to player 2 $\frac{1}{2}C_{n/2}^n$ sets different from *E*.

Player 1 may cheat by revealing less than ¹/₂Cⁿ_{n/2} sets to player 2, in that case ¹/₂Cⁿ_{n/2} tries are not enough for player 2 for guessing *E*.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

- Player 1 may cheat by revealing less than ¹/₂Cⁿ_{n/2} sets to player 2, in that case ¹/₂Cⁿ_{n/2} tries are not enough for player 2 for guessing *E*.
- We need to count from 1 to $\frac{1}{2}C_{n/2}^{n}$.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- Player 1 may cheat by revealing less than ¹/₂Cⁿ_{n/2} sets to player 2, in that case ¹/₂Cⁿ_{n/2} tries are not enough for player 2 for guessing *E*.
- We need to count from 1 to $\frac{1}{2}C_{n/2}^{n}$.
- ► A simple counter would use exponentially many states.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

- Player 1 may cheat by revealing less than ¹/₂Cⁿ_{n/2} sets to player 2, in that case ¹/₂Cⁿ_{n/2} tries are not enough for player 2 for guessing *E*.
- We need to count from 1 to $\frac{1}{2}C_{n/2}^{n}$.
- A simple counter would use exponentially many states.
- Instead we force player 1 to count himself, by sending to the system the value of the counter, in binary form, using actions in {0,1}*.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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Implementing the example

- Player 1 may cheat by revealing less than ¹/₂Cⁿ_{n/2} sets to player 2, in that case ¹/₂Cⁿ_{n/2} tries are not enough for player 2 for guessing *E*.
- We need to count from 1 to $\frac{1}{2}C_{n/2}^{n}$.
- A simple counter would use exponentially many states.
- Instead we force player 1 to count himself, by sending to the system the value of the counter, in binary form, using actions in {0,1}*.
- The system is able to detect with positive probability whenever player 1 is cheating with the counter.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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▶ If player 1 cheats once, player 2 has positive probability to win.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- ▶ If player 1 cheats once, player 2 has positive probability to win.
- ► If player 1 never cheats, and player 2 remembers all ¹/₂Cⁿ_{n/2} sets revealed by player 1, then player 2 wins surely.

From no memory to doubly-exponential memory Doubly exponential memory is needed

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- ▶ If player 1 cheats once, player 2 has positive probability to win.
- ► If player 1 never cheats, and player 2 remembers all ¹/₂Cⁿ_{n/2} sets revealed by player 1, then player 2 wins surely.
- ► If player 2 does not remember all ¹/₂Cⁿ_{n/2} sets revealed by player 1, with positive probability she will guess wrongly the set *E*.

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- Infinitely often \implies player 1 wins almost-surely.

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- Infinitely often \implies player 1 wins almost-surely.
- ▶ \implies Player 2 wins positively, for that she needs to remember $\frac{1}{2}C_{n/2}^{n}$ sets among $C_{n/2}^{n}$.

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- ► If player 2 does not remember all ¹/₂Cⁿ_{n/2} sets revealed by player 1, with positive probability she will guess wrongly the set *E*.
- Infinitely often \implies player 1 wins almost-surely.
- ▶ \implies Player 2 wins positively, for that she needs to remember $\frac{1}{2}C_{n/2}^n$ sets among $C_{n/2}^n$.
- $\blacktriangleright \implies$ Player 2 needs doubly-exponential memory.

From no memory to doubly-exponential memory Doubly exponential memory is needed

Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

Deciding Almost-sure, Sure and Positive Winning

Deciding almost-sure, sure and positive winning

Theorem: [Bertrand, Genest, G.] there is an algorithm running in exponential time $(G \cdot 2^K)$ for deciding whether the game is winning positively for player 1 or surely for player 2.

Theorem: [Bertrand, Genest, G.] there is an algorithm running in doubly exponential time $(2^{G \cdot 2^{\kappa}})$ for deciding whether the game is winning almost-surely for player 1 or positively for player 2.

Previous Work: [Chatterjee, Doyen, Henzinger, Raskin, 07] One player perfectly informed. No determinacy result. EXPTIME algorithm for deciding whether player 1 can win almost-surely a Büchi objective.

Lower bounds: EXPTIME and 2-EXPTIME complete.

Hugo Gimbert, CNRS, LaBRI, Bordeaux G

Games with Partial Observation

Deciding Almost-sure, Sure and Positive Winning

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Deciding almost-sure, sure and positive winning

Theorem: [Bertrand, Genest, G.] there is an algorithm running in doubly exponential time for deciding whether the game is winning almost-surely for player 1, surely for 2 or positively for both.

 Computation of smallest and greatest fix-points of monotonic operators.

Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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- Deciding almost-surely winning for player 1 or positive winning for player 2 in 2-EXPTIME: operator P(K × P(K)) → P(K × P(K)), iteration computable in doubly-exponential time.

Deciding Almost-sure, Sure and Positive Winning

Partial Observation Games

Playing with Actions Partial Observation via Signals

Qualitative Determinacy

Qualitative Solution Concepts Qualitative Determinacy

What is known

Memory Requirements

From no memory to doubly-exponential memory Doubly exponential memory is needed

Decidability Results

Deciding Almost-sure, Sure and Positive Winning

Deciding Almost-sure, Sure and Positive Winning

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Conclusion

 We solved qualitative questions about a very general model of reachability games with partial observation.

Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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- Deciding whether the value is 1.



Deciding Almost-sure, Sure and Positive Winning

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Beliefs and pessimistic beliefs

• A signal c contains the action i(c) that has just been played.

Deciding Almost-sure, Sure and Positive Winning

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Beliefs and pessimistic beliefs

- A signal c contains the action i(c) that has just been played.
- Definition: Let L ⊆ K and c a signal. The belief of player 1 after L and signal c is:

$$\mathcal{B}^1(L,c) = \{k \in S \mid \exists l \in L, \exists d \in D, p(k,c,d \mid l,i(c),j(d)) > 0\}.$$

The pessimistic belief of player 1 after *L* and signal *c* is:

 $\mathcal{B}_p^1(L,c) = \{k \in S \setminus T \mid \exists I \in L \setminus T, \exists d \in D, p(k,c,d \mid I,i(c),j(d)) > 1\}$

Deciding Almost-sure, Sure and Positive Winning

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Proposition: if player 1 plays an almost-surely winning strategy, his pessimistic beliefs are almost-surely winning. If player 2 plays a surely winning strategy, her beliefs are surely winning.

Deciding Almost-sure, Sure and Positive Winning

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Player 2 has a belief strategy for winning surely

Proposition: For winning surely, player 2 has a strategy with finite memory of exponential size.

▶ Monotonic operator Φ on $\mathcal{P}(\mathcal{P}(S \setminus T))$ with $\Phi(\mathcal{L}) = \{L \in \mathcal{L} \mid \exists j_L \in J, \forall d \in D, (j = j(d)) \implies (\mathcal{B}(L, d) \in \mathcal{L})\}$.

Deciding Almost-sure, Sure and Positive Winning

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- Let \mathcal{L}_{∞} be the largest fix-point of Φ .

Deciding Almost-sure, Sure and Positive Winning

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- Let \mathcal{L}_{∞} be the largest fix-point of Φ .
- ► Strategy for player 2 consisting in playing actions j_L such that her belief L stays in L_∞.
Deciding Almost-sure, Sure and Positive Winning

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- Let \mathcal{L}_{∞} be the largest fix-point of Φ .
- ► Strategy for player 2 consisting in playing actions j_L such that her belief L stays in L_∞.
- Conversely, playing randomly, player 1 wins positively from any support in Φⁿ(P(K)) \ Φⁿ⁺¹(P(K)).

Deciding Almost-sure, Sure and Positive Winning

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Player 2 has a double exponential memory strategy for wining positively

Proposition: Let $\mathcal{L} \subseteq \mathcal{P}(\mathcal{K})$ be a set of supports. Suppose player 1 can enforce his pessimistic beliefs to stay outside \mathcal{L} . Then,

(i) either every $L \not\in \mathcal{L}$ is almost-surely winning for player 1,

Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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- (ii) or there exists $\mathcal{L}' \subseteq \mathcal{P}(K)$ such that
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Deciding Almost-sure, Sure and Positive Winning

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- (ii) or there exists $\mathcal{L}' \subseteq \mathcal{P}(\mathcal{K})$ such that
 - (a) \mathcal{L}' is not empty and does not intersect \mathcal{L} ,
 - (b) player 1 can enforce his pessimistic beliefs to stay outside $\mathcal{L} \cup \mathcal{L}',$
 - (c) player 2 has a strategy τ such that for every σ and initial distribution δ with support in \mathcal{L}' ,

 $\mathbb{P}^{\sigma,\tau}_{\delta}\big(\forall n \in \mathbb{N}, K_n \not\in T \mid \forall n \in \mathbb{N}, \mathcal{B}^1_p(L, C_1, \ldots, C_n) \not\in \mathcal{L}\big) > 0 \ .$

Deciding Almost-sure, Sure and Positive Winning

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Positively winning strategy of player 2

► The collection L_∞ of positively winning supports for player 2 is computed as a smallest fix-point Ø = L₀ ⊂ L₁ ⊂ ... ⊂ L_∞.

Deciding Almost-sure, Sure and Positive Winning

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- The collection L_∞ of positively winning supports for player 2 is computed as a smallest fix-point Ø = L₀ ⊂ L₁ ⊂ ... ⊂ L_∞.
- \blacktriangleright Player 2 has the following positively winning strategy from $\mathcal{L}_{\infty}.$

Deciding Almost-sure, Sure and Positive Winning

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 - Play randomly for some time.

Deciding Almost-sure, Sure and Positive Winning

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- \blacktriangleright Player 2 has the following positively winning strategy from $\mathcal{L}_{\infty}.$
 - Play randomly for some time.
 - Guess wildly the pessimistic belief $L \in \mathcal{L}_{n+1} \setminus \mathcal{L}_n$ of player 1.

Deciding Almost-sure, Sure and Positive Winning

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 - ► Win surely against player 1, under the hypothesis that his pessimistic belief will stay in L_{n+1} \ L_n.

Deciding Almost-sure, Sure and Positive Winning

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Deciding Almost-sure, Sure and Positive Winning

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 - ▶ Win surely against player 1, under the hypothesis that his pessimistic belief will stay in L_{n+1} \ L_n.
 - Requires to make hypotheses about pessimistic beliefs of player 1, doubly-exponential size memory is required.
- ► For winning almost-surely from the complement of L_∞, player 1 plays randomly any action that ensures his pessimistic belief stays in the complement of L_∞.

Deciding Almost-sure, Sure and Positive Winning

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