Opacity Control

joint work with

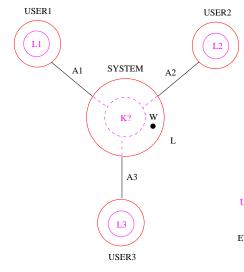
E. Badouel M. Bednarczyk A. Borzyszkowski B. Caillaud JDEDS 2007

J. Dubreil H. Marchand *Wodes 2008 + new paper*

January 2009

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A Confidentiality Problem



Li IN Ai*

UNCONTROLLED BEHAVIOUR L INCLUDED IN (A1+A2+A3) * W IN L (RUN OF THE SYSTEM)

FIND MAXIMAL PERMISSIVE CONTROL K INCLUDED IN L SUCH THAT USERS i +1 AND i +2 MAY NEVER KNOW THAT THE Ai PROJECTION OF W IS IN Li EVEN THOUGH THEY TALK TO EACH OTHER

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Formalization

SECRET SETADVERSARY'S ALPHABET $S_1 = (L_1 \parallel (A_2 + A_3)^*) \cap L$ $\Sigma_1 = A_2 \cup A_3$ $S_2 = (L_2 \parallel (A_1 + A_3)^*) \cap L$ $\Sigma_2 = A_1 \cup A_3$ $S_3 = (L_3 \parallel (A_1 + A_2)^*) \cap L$ $\Sigma_3 = A_1 \cup A_2$

 $S = \{(S_1, \Sigma_1), (S_2, \Sigma_2), (S_3, \Sigma_3)\}$ is a CONCURRENT SECRET

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Definition

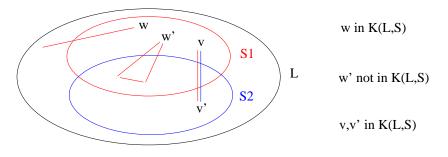
 \mathcal{S} is opaque if $\forall w \in L \ \forall i$ $w \in S_i \Rightarrow \Pi_{\Sigma_i}(w) = \Pi_{\Sigma_i}(w')$ for some $w' \in L \setminus S_i$

introduced by Laurent Mazare (with a single secret)

Safe Kernels

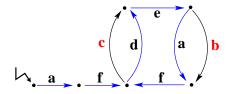
Definition

The safe kernel K(L, S) of L is the subset of all words $w \in L$ such that for every prefix u of w and for every i $\Pi_{\Sigma_i}(u) = \Pi_{\Sigma_i}(u')$ for some $u' \in L \setminus S_i$



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But using K(L, S) as a controller does not solve our problem ... because users know the system and the controller!



 $S_1 = \Sigma^* afc(\Sigma \setminus \{c\})^*$ (last *c* follows *af*), $\Sigma_1 = \{c, f\}$, $S_2 = \Sigma^* deb(\Sigma \setminus \{b\})^*$ (last *b* follows *de*), $\Sigma_2 = \{b, e\}$

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$$egin{aligned} & \mathcal{K}(L,\mathcal{S}) = L \setminus \mathsf{af} \, m{c} \Sigma^* \ & \mathcal{K}(\mathcal{K}(L,\mathcal{S}),\mathcal{S}) = \mathcal{K}(L,\mathcal{S}) \setminus \mathsf{afde} m{b} \Sigma^* \end{aligned}$$

What remains in the end is (afde)*

Supremal Safe Sublanguage

 $K(\bullet, S)$ is monotone in first argument

Definition

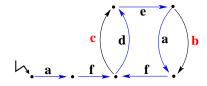
Let SupK(L, S) be the greatest fixpoint of the operator $K(\bullet, S)$ included in *L*

Theorem

SupK(L, S) is the union of all controls enforcing the opacity of concurrent secret S

Sufficient conditions under which SupK(L, S) is regular and computable ?

$K(\bullet, S)$ may have a transfinite closure ordinal



 $\begin{array}{l} S_1 = \Sigma^* afc (\Sigma \setminus \{c\})^* \text{ (last } c \text{ follows } af), \ \Sigma_1 = \{c, f\}, \\ S_2 = \Sigma^* deb (\Sigma \setminus \{b\})^* \text{ (last } b \text{ follows } de), \ \Sigma_2 = \{b, e\} \\ S_3 = L \setminus (\Sigma^* c \Sigma^*) \text{ (there is no } c), \ \Sigma_3 = \emptyset \\ S_3 \text{ safe w.r.t. any } L' \subseteq L \text{ with at least one word with } c \end{array}$

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$$\lim_{i\to\omega} K^i(L,S) = Pref((afde)^{\omega})$$

 $K^{\omega+1}(L,\mathcal{S})=\emptyset$

$SupK(\bullet, S)$ may be not regular

$$\Sigma = \{a, b, x, y\} \quad L = Pref((ax)^*(\varepsilon + ab)(yb)^*$$

$$\begin{split} \Sigma_1 &= \{a, b\}, \ \ \mathbb{C}S_1 = \varepsilon + (ax)^* ab(yb)^* + \{a, x, y\}^* \\ \Sigma_2 &= \{x, y\}, \ \ \mathbb{C}S_2 = (ax)^* (yb)^* \\ \Sigma_3 &= \{a, b, x, y\}, \ \ \mathbb{C}S_3 = \varepsilon + a\Sigma^* \end{split}$$

 $S_1 = \rightarrow$ $S_2 = \rightarrow \rightarrow$ S_2 forces to start with *y*

 $SupK(L, S) = Pref(\cup_{n \in \mathbb{N}} (ax)^n (\varepsilon + ab) (yb)^n)$

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Some sufficient conditions

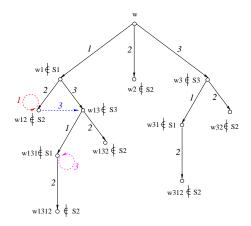
language theoretic conditions (i) and (ii)

i) system language L closed under prefix

ii) secrets closed under suffix $(S_i \Sigma^* \subseteq S_i)$

structural conditions (iii) or (iv) or (v)	
iii) $\Sigma_1 \subseteq \Sigma_2 \ldots \subseteq \Sigma_n$	chain of alphabets
iv) $S_1 \subseteq S_2 \ldots \subseteq S_n$	chain of secrets
v) $(\forall i \neq j) \ (\forall w, w' \in L)$	observers \perp secrets
$\Pi_{\Sigma_j}(w) = \Pi_{\Sigma_j}(w') \Rightarrow w \in S_i \text{ iff } w' \in S_i$	true in first Example

$S_1 \subseteq S_2$ $\Sigma_3 \subseteq \Sigma_2$ $Obs_1 \perp S_3$ (mixed case)



Finite pattern of proofs for $w \in SupK(L, S)$ $w, w_i, w_{ij}, w_{ijk}, w_ijkl \in L$

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Theorem

It is decidable whether there exists a finite uniform pattern of proofs for all $w \in SupK(L, S)$

Under this condition, one can construct a finite automaton accepting SupK(L, S)

Moreover SupK(L, S) is totally determined by its projections on the Σ_i , hence we obtain

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Decentralized Control

Ramadge and Wonham supervisory control

Partial Observation: $\Sigma = \Sigma_o \cup \Sigma_{uo}$ Partial Controllability: $\Sigma = \Sigma_c \cup \Sigma_{uc}$ Special Case: $\Sigma_c \subseteq \Sigma_o$

 $K \subseteq L$ is an admissible controller if K is prefix-closed K is controllable w.r.t. L: $K\Sigma_{uc} \cap L \subseteq K$ K is normal w.r.t. L: $K = \pi_o^{-1} \circ \pi_o(K) \cap L$

if $L' \subseteq L$ are regular, the most permissive controller $K = \frac{SupCN}{L', L}$ such that $L \cap K \subseteq L'$ is regular

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Supervisory control for simple opacity

 $S \subseteq L \subseteq \Sigma^*$ SECRET $\Sigma_a \subseteq \Sigma$ ADVERSARY'S ALPHABET $\Sigma_c \subseteq \Sigma_o \subseteq \Sigma$ CONTROLLER'S ALPHABETS

The family of prefix-closed Controllable and Normal sublanguages K of L such that S is Opaque w.r.t. K has a Supremum SupCNO(L, S)

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How computing SupCNO(L, S)?

Alternated greatest fixpoint iterations ... SupCN • SupO • SupCN • SupO ...

An Example

$$\Sigma_a = \{C, X, Y\}$$

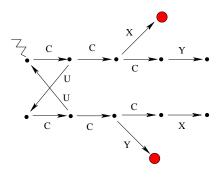
$$\Sigma_o = \{C, X, Y, U\}$$

$$\Sigma_c = \{C\}$$

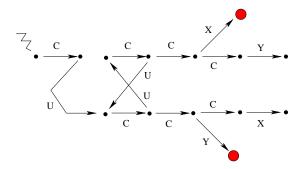
SECRET disclosed by CCX but not by CUCCY

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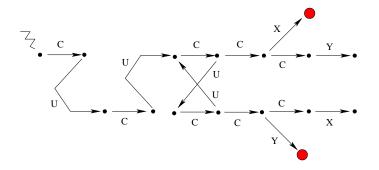
First Iteration



SECRET disclosed by CUCCY but not by CUCUCCX

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Second Iteration



SECRET disclosed by CUCUCCX but not by CUCUCUCCY

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The alternated iteration terminates if $\Sigma_c \subseteq \Sigma_o \subseteq \Sigma_a$ or $\Sigma_a \subseteq \Sigma_c \subseteq \Sigma_o$

Different method proposed for the case $\Sigma_c \subseteq \Sigma_a \subseteq \Sigma_o$

Given an automaton G on Σ generating L and recognizing S, replace G with $G \times Det_{\Sigma_a}(G)$ and apply Ramadge and Wonham methods

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States of the controller are pairs (q, E) $q \in Q$ state of G $E \subseteq Q$ adversary's estimate of the state of G.

Further results

Does not work when Σ_c not included in Σ_a

the estimate of the state of *G* reached after *w* depends on the controller *K* and not only on *G* and the Σ_a projection of *w*

Consider all pairs (q, E) even though not accessible in $G \times Det_{\Sigma_a}(G)$

Revise the estimation *E* of *q* after *w* for all *w* at each step in the computation of K^{\dagger}

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Yields a finite controller as desired

PERSPECTIVES

Deal with simple opacity in the case where Σ_a and Σ_o do not compare

Deal with concurrent secrets $S = \{(S_1, \Sigma_1), \dots, (S_i, \Sigma_i)\}$ where user *i* observes $\Sigma_i \subseteq \Sigma$ and controls $\Sigma_{c,i} \subseteq \Sigma_i$

Strategies for disclosing the secrets of the others while keeping one's secret safe?

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Opacity not expressible in MSO (Alur)!