

#### 4(a)

We will modify Edmonds-Karp algorithm to get a polynomial time algorithm for the given problem. Given a network  $G$ , and a valid flow  $f$  on  $G$ , define a new residual graph  $G_f$  as follows: First, define the residual weights as

$$w_f(u, v) = \begin{cases} f(u, v) - w(u, v) & \text{if } (u, v) \in E \\ \infty & \text{if } (v, u) \in E \\ -1 & \text{otherwise} \end{cases}$$

Here, we are assuming that  $(u, v) \in E \Leftrightarrow (v, u) \notin E$ .

Now, define the residual graph  $G_f = (V, E_f)$ , where  $E_f = \{(u, v) \in V \times V \mid w_f(u, v) > 0\}$

Define a *decrementing path* to be a simple path from  $s$  to  $t$  in  $G_f$ . Now, given any *decrementing path*, say  $p$ , we can decrease the net flow on this path by an amount:  $w_f(p) = \min\{w_f(u, v) \mid (u, v) \in p\}$ , thus reducing the flow by  $w_f(p)$ .

Initial flow can be setup using DFS repeatedly (Note that initial flow is not 0, as was the case in the original max-flow min-cut case). It can be checked that setting up the initial flow takes polytime. Use Edmonds-Karp to decrease the flow along *decrementing paths*. The proof of the termination of this algorithm is similar to that of Edmonds-Karp.

#### 4(b)

It is not hard to find a counter example for min-flow = max-cut. Now, define a *forward cut* to be a cut  $c(S, T)$  such that  $\nexists t_1 \in T, t_2 \in S$  with  $(t_1, t_2) \in E$

*Analogue of max-flow min-cut theorem*

The following are equivalent:

1.  $f$  is a minimum flow.
2. The residual network  $G_f$  contains no *decrementing path*.
3.  $|f| = c(S, T)$  for some *forward cut*  $c(S, T)$  of  $G$ .

The proof of this proceeds along similar lines to that of the proof of max-flow min-cut theorem as given in CLRS.

Note that such a cut does not exist  $\Leftrightarrow$  then there is no minimum flow.