

Inductive definitions

$$0! = 1$$

$$n! = n * (n-1)!$$

$$4! ? \rightarrow 4 * 3!$$

$$\rightarrow 4 * (3 * 2!)$$

$$\rightarrow 4 * (3 * (2 * (1!)))$$

$$\rightarrow 4 * (3 * (2 * (1 * 0!)))$$

Base case

$$f(0) = v$$

$$f(n) = g(n, f(n-1))$$

↑ simple fn.

→ known = 1

$$f(0) = 0$$

$$f(1) = 1$$

$$f(n) = f(n-1) + f(n-2)$$

0	1	2	3	4
0	1	1	2	3

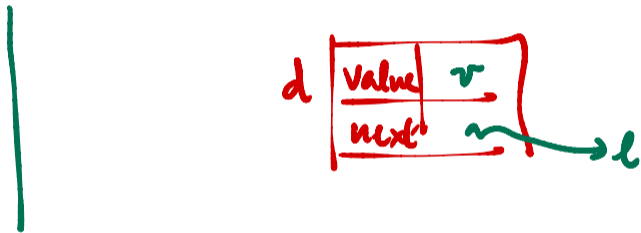
$$\begin{aligned} f(4) &= f(3) + f(2) \\ &= (f(2) + f(1)) + (f(1) + f(0)) \\ &= \underbrace{(f(1) + f(0))}_1 + \underbrace{(f(1) + f(0))}_1 = 3 \end{aligned}$$

$f(1) + f(0)$
0 1

Induction on structures

List

Dictionary implementation



$$l = \begin{matrix} l[:1] & + & l[1:] \\ l[0] & & \text{rest} \end{matrix}$$

$$[l[0]] + l[1:]$$

Base Case: l

Length of a list

$$\text{length}([]) = 0$$

$$\text{length}(\underbrace{[l[0]]}_{\text{wavy}} + l[1:]) = 1 + \text{length}(l[1:])$$

$$\text{length}([1, 2, 3]) \rightsquigarrow 1 + \text{length}([2, 3])$$

$$\rightarrow 1 + 1 + \text{length}([3])$$

$$\rightsquigarrow 1 + 1 + 1 + \text{length}([]) = 3$$

Sum

$$\text{sum}([\]) = 0$$

$$\text{sum}(l) = l[0] + \text{sum}(l[1:])$$

Ascending order

$l[0] < l[1] < \dots$

if $\text{len}(l) \leq 1$:

return (True)

else:

return ($l[0] < l[1]$ and
ascending($l[1:]$))

$[\underbrace{<, <, <, <}_{0, 1, 2, 3, 4}]$

for i in range($\text{len}(l)-1$):

if $l[i] \geq l[i+1]$:

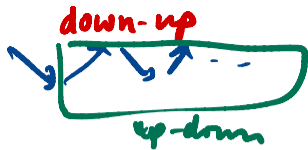
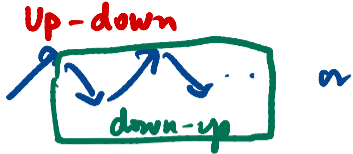
return (False)

return (True)

empty list : len is 0

Singleton

Zigzag



Base Case(s) ?

len = 0 ✓

Time

len = 1 ✓

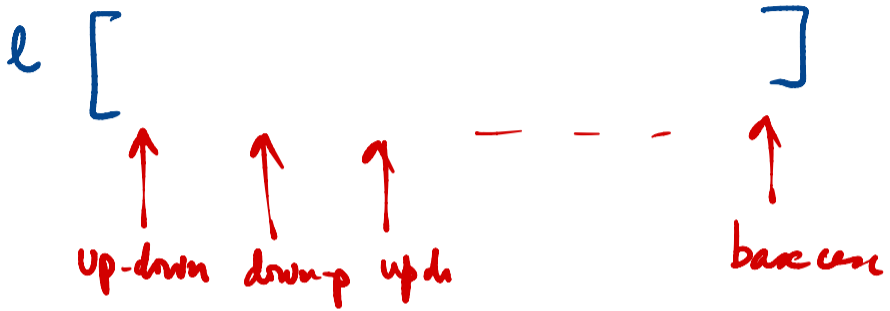
Time

len = 2 ?

Check $l[0] == l[1]$!

$l[0] < l[1] \rightarrow \text{down-up } (l[1:])$

$l[0] > l[1] \rightarrow \text{up-down } (l[1:])$



Classes and objects

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Programming and Data Structures with Python

Lecture 10, 14 Sep 2023

Classes and objects

- **Abstract datatype**

- Stores some information
- Designated functions to manipulate the information
- For instance, list: `append()`, `insert()`, `delete()`, ...

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- **Class**
 - Template for a data type
 - How data is stored
 - How public functions manipulate data

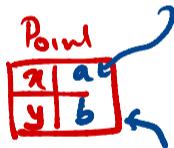

Classes and objects

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 - Designated functions to manipulate the information
 - For instance, list: `append()`, `insert()`, `delete()`, ...
- Separate the (private) implementation from the (public) specification
- **Class**
 - Template for a data type
 - How data is stored
 - How public functions manipulate data
- **Object**
 - Concrete instance of template

Example: 2D points

- A point has coordinates (x, y)
 - `__init__()` initializes internal values `x, y`
 - First parameter is always `self`

```
class Point:
    def __init__(self, a, b):
        self.x = a
        self.y = b
```



Example: 2D points

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- Translation: shift a point by $(\Delta x, \Delta y)$
 - $(x, y) \mapsto (x + \Delta x, y + \Delta y)$

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class Point:
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```
def __init__(self, a, b):
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```
    self.x = a
```

```
    self.y = b
```

```
def translate(self, deltax, deltay):
```

```
    self.x += deltax
```

```
    self.y += deltay
```

$x = x + \text{deltax}$

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- Distance from the origin
 - $d = \sqrt{x^2 + y^2}$

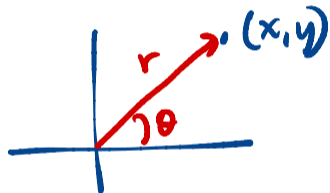
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class Point:
    def __init__(self, a, b):
        self.x = a
        self.y = b

    def translate(self, deltax, deltay):
        self.x += deltax
        self.y += deltay

    def odistance(self):
        import math
        d = math.sqrt(self.x*self.x +
                      self.y*self.y)
        return(d)
```


Polar coordinates

- (r, θ) instead of (x, y)
 - $r = \sqrt{x^2 + y^2}$
 - $\theta = \tan^{-1}(y/x)$



Internal
change
due to
implementation
change

```
import math
class Point:
    def __init__(self, a, b):
        self.r = math.sqrt(a*a + b*b)
        if a == 0:
            if b >= 0:
                self.theta = math.pi/2
            else:
                self.theta = 3*math.pi/2
        else:
            self.theta = math.atan(b/a)
```

(x,y) coord

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- (r, θ) instead of (x, y)
 - $r = \sqrt{x^2 + y^2}$
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- Distance from origin is just r
- Translation
 - Convert (r, θ) to (x, y)
 - $x = r \cos \theta, y = r \sin \theta$
 - Recompute r, θ from $(x + \Delta x, y + \Delta y)$

```
def translate(self, deltax, deltay):
    x = self.r*math.cos(self.theta)
    y = self.r*math.sin(self.theta)
    x += deltax
    y += deltay
    self.r = math.sqrt(x*x + y*y)
    if x == 0:
        self.theta = math.pi/2
    else:
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- Translation
 - Convert (r, θ) to (x, y)
 - $x = r \cos \theta, y = r \sin \theta$
 - Recompute r, θ from $(x + \Delta x, y + \Delta y)$
- Interface has not changed
 - User need not be aware whether representation is (x, y) or (r, θ)

```
def translate(self, deltax, deltay):  
    x = self.r*math.cos(self.theta)  
    y = self.r*math.sin(self.theta)  
    x += deltax  
    y += deltay  
    self.r = math.sqrt(x*x + y*y)  
    if x == 0:  
        self.theta = math.pi/2  
    else:  
        self.theta = math.atan(y/x)
```

$p1 = \text{Point}(5, 4)$
 $p2 = \text{Point}(3, 5, 6.7)$