

## Classical Mechanics 1, Autumn 2025 CMI

### Assignment 2

Due by 6pm Friday 22 Aug, 2025

Levi-Civita symbol, spherical polar coordinates

1. **⟨4 + 3⟩** (a) Starting from  $\hat{x} \times \hat{y} = \hat{z}$  and its cyclic permutations, express the Cartesian components of the cross product  $\mathbf{a} \times \mathbf{b}$  in terms of those of  $\mathbf{a} = a_x\hat{x} + a_y\hat{y} + a_z\hat{z}$  and  $\mathbf{b} = b_x\hat{x} + b_y\hat{y} + b_z\hat{z}$ . (b) Use this to obtain an expression for the scalar triple product  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c})$  in terms of the components of  $\mathbf{a}, \mathbf{b}, \mathbf{c}$ . Mention a geometric interpretation of the scalar triple product.
2. **⟨3⟩** Define the Levi-Civita symbol (a real number)  $\epsilon_{ijk}$  for integers  $1 \leq i, j, k \leq 3$  (not necessarily distinct) by the conditions (i)  $\epsilon_{123} = 1$  and (ii)  $\epsilon_{ijk}$  reverses sign under exchange of any pair of indices [e.g.  $\epsilon_{ijk} = -\epsilon_{jik}$ ]. Find  $\epsilon_{213}$ ,  $\epsilon_{312}$ ,  $\epsilon_{321}$ ,  $\epsilon_{112}$ ,  $\epsilon_{313}$  and  $\epsilon_{222}$ .
3. **⟨4⟩** Verify that  $\mathbf{a} \cdot (\mathbf{b} \times \mathbf{c}) = \sum_{1 \leq i, j, k \leq 3} \epsilon_{ijk} a_i b_j c_k$  where  $a_i, b_j, c_k$  are the Cartesian components of three vectors in  $\mathbb{R}^3$ . Here  $a_1 = a_x, a_2 = a_y, a_3 = a_z$ , etc.
4. **⟨4 + 4⟩** Recall the spherical polar coordinates in 3d  $z = r \cos \theta, x = r \sin \theta \cos \phi$  and  $y = r \sin \theta \sin \phi$ . Let  $\hat{r}, \hat{\theta}, \hat{\phi}$  be defined as

$$\begin{aligned}\hat{r} &= \cos \theta \hat{z} + \sin \theta (\cos \phi \hat{x} + \sin \phi \hat{y}), \\ \hat{\theta} &= -\sin \theta \hat{z} + \cos \theta (\cos \phi \hat{x} + \sin \phi \hat{y}) \quad \text{and} \\ \hat{\phi} &= -\sin \phi \hat{x} + \cos \phi \hat{y}.\end{aligned}\tag{1}$$

- (a) With the help of figures (3d and suitable projections), explain why the formula for  $\hat{\theta}$  gives a unit vector in the direction of increasing  $\theta$  holding  $r, \phi$  fixed. (b) Verify that  $(\hat{r}, \hat{\theta}, \hat{\phi})$  is a right-handed orthonormal system.