

$\mathbb{R}^2 \subset \mathbb{C} \subset \mathbb{R}^3$ $\phi_X(p) = \sqrt{z}$, $\phi_N(p) = \frac{z}{|z|}$

$\phi_S^2 : S^2 \rightarrow \mathbb{C}^*$ // S^2 is the 1-point compactification of \mathbb{C}

at input $a \cup \{\infty\}$ 1 point compactification
 K-1 point a + origin to itself

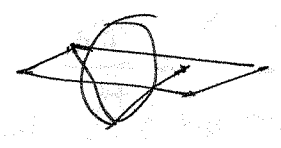
ϕ_S is also a diffeomorphism $\mathbb{R}^2 \rightarrow \mathbb{R}^3$
 ϕ_S is a restriction of ϕ_S on U_S (diffeomorphism)
 (logarithm + constant)

ϕ_S is a homeomorphism

$$= \left(\frac{z+\bar{z}}{2z+1}, \frac{z-\bar{z}}{\sqrt{z^2+1}}, \frac{2z-1}{2z+1} \right)$$

$$\phi_S^{-1}(x,y) = \left(\frac{2x}{2z^2+1}, \frac{y}{2z}, \frac{2z^2+y^2-1}{2z^2+y^2+1} \right)$$

$\phi_S^{-1} : \mathbb{R}^2 \rightarrow U_S$
 ϕ_S is continuous, 1-to-1 + has an inverse.



$$\phi_S(p) = \left(\frac{p}{|p|}, \frac{1-p^2}{2|p|^2} \right)$$

$\phi_S : U_S \rightarrow \mathbb{R}^2$

$$U_S = S^2 - \{(0,0,1)\}, U_N = S^2 - \{(0,0,-1)\}$$

S^2

$m(\frac{\phi}{z})$, $x_2 = \dim(\frac{\phi}{z})$



Topology
 mapping between manifolds $M \times \mathbb{Q} \rightarrow \mathbb{Q}$
 S^1 is a Lie group

S^1 is closed under multiplication
 $e^{i\theta_1} \cdot e^{i\theta_2} = e^{i(\theta_1+\theta_2)}$
 $(e^{i\theta})^{-1} = e^{-i\theta}$

$$S^1 = \{ e^{i\theta} : \theta \in \mathbb{R} \}$$

with one studyer continuous maps between spaces
 $\mathbb{Z}^2 = \mathbb{Z}$

$x_2 + i y_2$

~~Handwritten text, possibly a title or introduction.~~

$$\boxed{f \Delta + (d) \phi^N = (d) \phi^S}$$

$$f = \frac{1}{2} \int \frac{2x}{2x+y^2} dx = \frac{1}{2} \ln(x^2+y^2) + g(y)$$

$$g'(y) = \frac{2y}{y^2} = \frac{2}{y}$$

$$\frac{2x}{2x+y^2} = \frac{A}{2x+y^2} + \frac{B}{y}$$

$$f = \frac{1}{2} \int \frac{2x}{2x+y^2} dx = \frac{1}{2} \ln(x^2+y^2) + g(y)$$

$$\frac{1}{2} \int \frac{2x}{2x+y^2} dx = \frac{1}{2} \ln(x^2+y^2) + g(y)$$

$$\frac{2x}{2x+y^2} - \frac{1}{y} = \frac{A}{2x+y^2} + \frac{B}{y}$$

$$\Delta f = \left(x \left(1 - \frac{1}{2x+y^2} \right) \right) + y \left(1 - \frac{2x}{2x+y^2} \right)$$

$$\phi^S(p) - \phi^N(p) = \left(x - \frac{x}{2x+y^2} \right) + \left(y - \frac{2xy}{2x+y^2} \right)$$

$$\phi^N(p) = \frac{x-iy}{1} = \frac{x}{2x+y^2} + i \frac{y}{2x+y^2}$$

$$\phi^S(p) = \frac{x}{2x+y^2} + i \frac{y}{2x+y^2}$$

$p \in U_S \cup U_N$

$$(ii) \quad \frac{z}{\phi} = \frac{z}{1}$$

$$(i) \quad \frac{z}{\phi} = \frac{z}{1}$$

$$(2) \quad \frac{z}{1}$$

Consider

$$K_1 =$$

* Consider the

$$S^3 := \{ (r_1, r_2, r_3, r_4) \mid r_1^2 + r_2^2 + r_3^2 + r_4^2 = 1 \}$$

We identify \mathbb{R}^4 with \mathbb{C}^2 as follows.

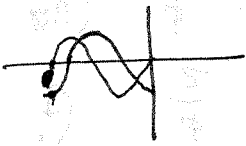
$$(x_1, y_1, x_2, y_2) \longleftrightarrow (x_1 + iy_1, x_2 + iy_2)$$

$$\therefore S^3 = \{ (z_1, z_2) \in \mathbb{C}^2 \mid |z_1|^2 + |z_2|^2 = 1 \}$$

we parametrize S^3 as follows:

$$z_1 = r_1 e^{i\theta_1}, \quad z_2 = r_2 e^{i\theta_2}$$

$$r_1^2 + r_2^2 = 1 \quad \& \quad r_1, r_2 \geq 0 \quad \text{but not simultaneously } = 0$$



$$\rightarrow \exists \text{ non } \phi \in [0, \pi] \text{ s.t. } r_1 = \cos(\frac{\phi}{2}), \quad r_2 = \sin(\frac{\phi}{2})$$

$$S^3 = \{ (\cos \frac{\phi}{2} e^{i\theta_1}, \sin \frac{\phi}{2} e^{i\theta_2}) \mid 0 \leq \phi \leq \pi, \theta_1, \theta_2 \in \mathbb{R} \}$$

By some abuse of notation we can think of S^3 as a 1st countable dim \mathbb{R}^3 i.e. $(\mathbb{R}^3)^* = \mathbb{R}^3 \cup \{\infty\}$.
 But we shall not do so.

Consider a subset T of S^3 as follows

$$T = \{ (z_1, z_2) \in S^3 \mid |z_1| = |z_2| \}$$

$$|z_1|^2 + |z_2|^2 = 1, \quad |z_1| = |z_2|$$

$$\Rightarrow |z_1|^2 = 1 \Rightarrow |z_1| = \frac{1}{\sqrt{2}} = \frac{\sqrt{2}}{2}$$

$$= \{ (\frac{\sqrt{2}}{2} e^{i\theta_1}, \frac{\sqrt{2}}{2} e^{i\theta_2}) : \theta_1, \theta_2 \in \mathbb{R} \} \rightarrow \text{1.3. is true}$$

A torus in $\mathbb{R}^3 \subset S^3$



* Consider the subset

$$K_1 = \{ (z_1, z_2) \in S^3 \mid |z_1| < |z_2| \}$$

$$\cos \frac{z}{2} \leq \sin \frac{z}{2}$$

$$\Rightarrow \frac{z}{2} \leq \frac{\pi}{2} \leq \frac{z}{2}$$

(+) $\frac{z}{2} = \frac{\pi}{2}$ gives the ~~torus~~ $T \subset K_1 \subset S^3$

(ii) $\frac{z}{2} = \frac{\pi}{2} \Rightarrow (0, e^{i\pi/2}) \in S^3$ a copy of $S^1 \subset S^3$



(iii) Any pair $\frac{z}{2} \in (\frac{\pi}{2}, \frac{\pi}{2})$ gives a torus.

K_1 is a solid torus with boundary as T

+ and as ϕ increases for $\frac{\pi}{2} < \frac{z}{2} < \frac{\pi}{2}$ at collapse to the central circle.

* Consider the subset

$$K_2 = \{ (z_1, z_2) \in S^3 \mid |z_1| \geq |z_2| \}$$

$$0 \leq \phi \leq \frac{\pi}{2}$$

Another set of solid tori collapse to K_1 + boundary ∇

$$\therefore S^3 = K_1 \cup K_2$$

Action of S^1 on S^3

At $p = (z_1, z_2) \in S^3$ A $g \in U(1)$ ~~circle~~ S^1

S^1 acts on the "gauge group".
we define an action S^1 on S^3 as:

$$p \cdot g = (z_1, z_2) \cdot g = (gz_1, gz_2) =$$

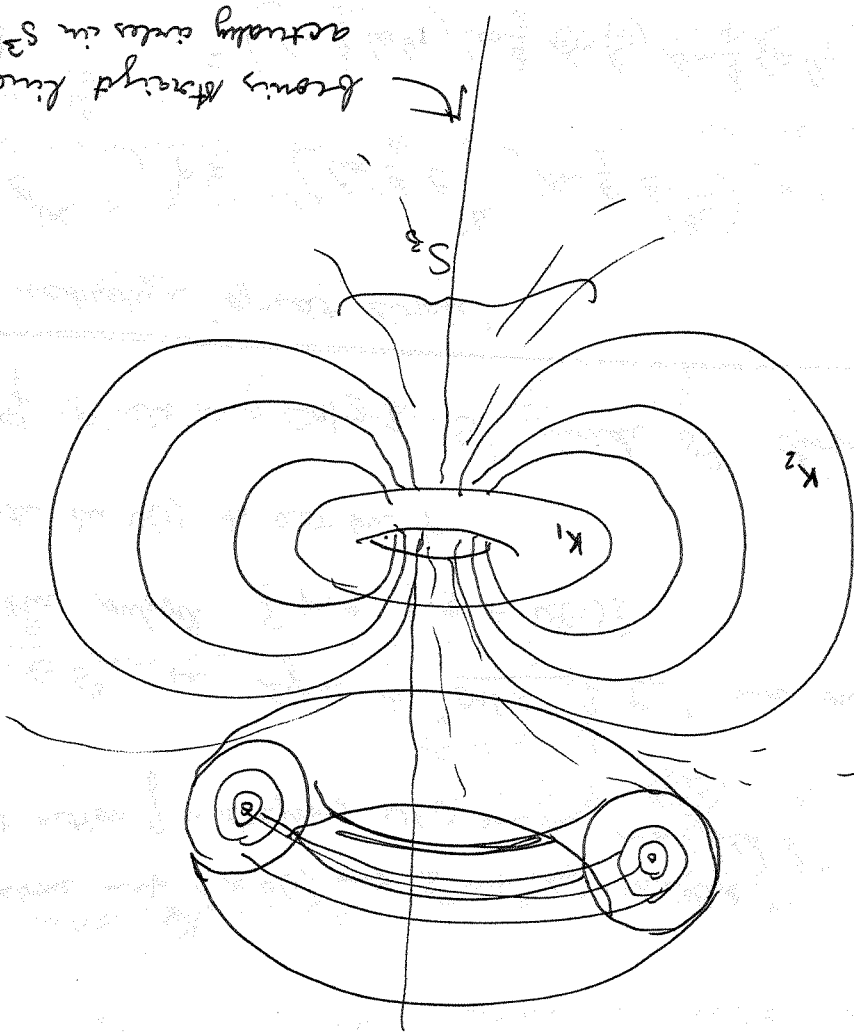
it is obvious that $p \cdot g$ is also in S^3

→ we look at the map

$$S^3 \times U(1) \rightarrow S^3$$

in C^0

→ e in the identity class $\neq U(1)$ is $e^{i\theta}$



brown straight line in R^3 which are
actually circles in S^3 through the lift of ∞

→ there naturally an action map $S^3 \times U(1) \rightarrow S^3$ to be called a "right action" of a Lie group $U(1)$ on the manifold S^3

→ for a fixed $p \in S^3$ we define the "orbit \mathcal{O}_p " under this

action to be the subset $\{p \cdot g \mid g \in U(1)\}$

by letting $U(1)$ act on p .

→ as the orbit of p is a copy of S^1 inside S^3 through p .

Each orbit is actually a "great circle"

$g = e^{ix}$, $p = (\cos \frac{x}{2} e^{i\theta_1}, \sin \frac{x}{2} e^{i\theta_2})$

$p \cdot e^{i\theta} \rightarrow -p = (\cos \frac{\theta}{2} \cos \theta_1, \cos \frac{\theta}{2} \sin \theta_1, \sin \frac{\theta}{2} \cos \theta_2, \sin \frac{\theta}{2} \sin \theta_2)$

$= (-\cos \frac{\theta}{2} \cos \theta_1, -\cos \frac{\theta}{2} \sin \theta_1, \sin \frac{\theta}{2} \cos \theta_2, \sin \frac{\theta}{2} \sin \theta_2)$

No anti-podal pts are present thus

$p = (-\cos \frac{\theta}{2} e^{i\theta_1}, -\sin \frac{\theta}{2} e^{i\theta_2})$

$p_1 \cdot g_1 = p_3 = p_2 \cdot g_2$

$p_1 \cdot (g_1 g_2^{-1}) = p_2 \quad \therefore p_2 \in \text{orbit } p_1$

\therefore the orbits are disjoint or identical

\therefore No all these orbits can be thought of as equivalence classes of some symmetric relation in

→ we would try to identify these orbits in S^3 to points in another space & here the structure of S^3 is clear.

↓ $(z_1^2, z_2^2) + (w_1^2, w_2^2)$ lie in the same orbit \mathcal{S}

$z_1 \cdot q = w_1$
 $z_2 \cdot q = w_2$

$\therefore \frac{z_1}{w_1} = \frac{z_2}{w_2}$

we take $\frac{z_1}{z_2} = \infty \in \mathbb{C}^*$ if $z_2 = 0$

Conversely:

$\frac{z_1}{z_2} = \frac{w_1}{w_2}$ then $\exists q \in U(1)$ s.t.

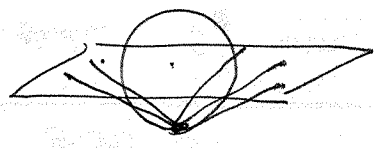
$(w_1, w_2) = (z_1 q, z_2 q) = (z_1, z_2) \cdot q$

\therefore the orbits in S^3 under the right action of $U(1)$ are in one-to-one correspondence with clumps in $U(1)$

$\therefore \frac{z_1}{z_2} \in \mathbb{R}^{2*}$

We recall that

$\phi_*^g : S^2 \rightarrow \mathbb{R}^{2*}$
 $(v_1, v_2, v_3) \mapsto \left(\frac{v_1}{1-v_3}, \frac{1-v_3}{v_2} \right)$
 $(0, 0, 1) \mapsto \{\infty\}$



$\phi_*^{-1} : \mathbb{R}^{2*} \rightarrow S^2$

$(z) \mapsto \left(\frac{z+1}{z-1}, \frac{z-1}{z+1} \right)$
 $\{0\} \mapsto (0, 0, 1)$

$z = \frac{z_1}{z_2}$ then $\frac{z+1}{z-1} = \frac{z_1+1}{z_1-z_2}$
 $\frac{z-1}{z+1} = \frac{z_1-z_2}{z_1+z_2}$

* similarly

\therefore we define.

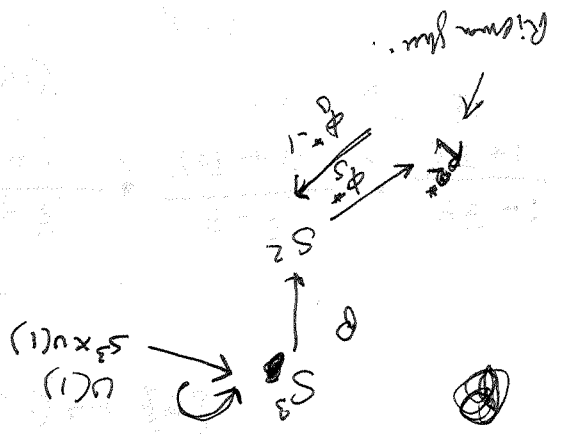
$\rho : S^3 \rightarrow S^2$

$\rho(z_1, z_2) = \left(\phi_*^{-1} \right) \left(\frac{z_1}{z_2} \right)$

for each

$\rho(x_1, y_1, z_1, z_2) = (2x_1x_2 + 2y_1y_2, 2x_2y_1 - 2x_1y_2, (x_1^2 + y_1^2) - (x_2^2 + y_2^2))$
 $\rho(\phi(\theta_1, \theta_2)) = (\sin \phi \cos(\theta_1 - \theta_2), \dots)$

Fix the Hopf map.



$\therefore P$ identifies each orbit in S^3 under the right action of S^1 as a point in S^2 .
 $\therefore P$ identifies each orbit in S^3 under the right action of S^1 as a point in S^2 .
 a "principal $U(1)$ -bundle" structure over S^2 .

$\therefore P^{-1}(x) = \{ (z_1, z_2) \cdot q \mid q \in S^1 \}$ is a copy of S^1 in S^3 and maps to a pt in S^2 .

So let $x \in S^2$
 $\wedge (z_1, z_2) \in x$ at $P(z_1, z_2) = x$

$P(x_1, y_1, x_2, y_2) = z$ is a C^∞ map from \mathbb{R}^4 to \mathbb{R}^3 .
 matrix + S^3 is a C^∞ .

$\therefore \theta_1 - \theta_2 = \theta$
 the $P(\theta, \theta_1, \theta_2) = (\sin \theta \cos \theta, \sin \theta \sin \theta, \cos \theta)$

$\uparrow S$

$$\begin{aligned} \Psi_S^{-1} : \mathbb{R}^{-1}(U_S) &\rightarrow U_S \times U(1) \quad , \quad \mathbb{P}^{-1} : \mathbb{R}^{-1}(U_N) \rightarrow U_N \times U(1) \\ \Psi_S^{-1}(z_1, z_2) &\mapsto (\rho(z_1, z_2), \frac{z_1}{z_2}) \quad , \quad \mathbb{P}^{-1}(z_1, z_2) = (\rho(z_1, z_2), \frac{z_1}{z_2}) \\ \Psi_S^{-1}(x, y) &\mapsto (z_1, z_2) \quad , \quad \mathbb{P}^{-1}(x, y) = (z_1, z_2) \end{aligned}$$

each in the complement of either of the degenerate tori in the two disks

$$\mathbb{P}^{-1}(U_N) = \{ (z_1, z_2) \in S^3 \mid z_1 \neq 0 \}$$

$$\mathbb{P}^{-1}(U_S) = \{ (z_1, z_2) \in S^3 \mid z_2 \neq 0 \}$$

$$U_S = S^2 - (0, 0, 1) \quad , \quad U_N = S^2 - (0, 0, -1)$$

We consider the chart on S^2 as:

one locally the name e .

As either $S^3 + S^2 \times U(1)$ are not globally the same but

but there are tied up differently in $S^3 + S^2 \times U(1)$

also each pt on S^2 there is a copy of S^1 .

An projection $\rho : S^2 \times U(1) \rightarrow S^2$ ($e^{\theta} + e^{i\theta}$)

help map $\rho : S^3 \rightarrow S^2$ ($e^{\theta} + e^{i\theta}$)

So we have the