

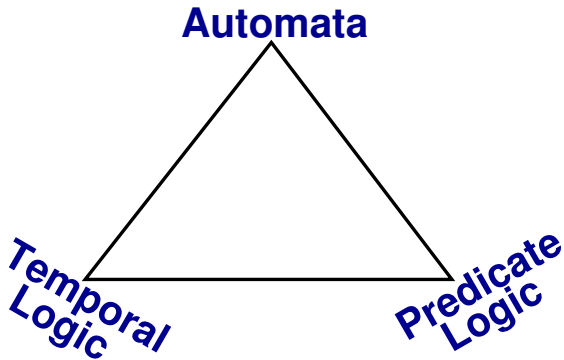
A Survey of Classical, Real-Time, and Time-Bounded Verification

Joël Ouaknine

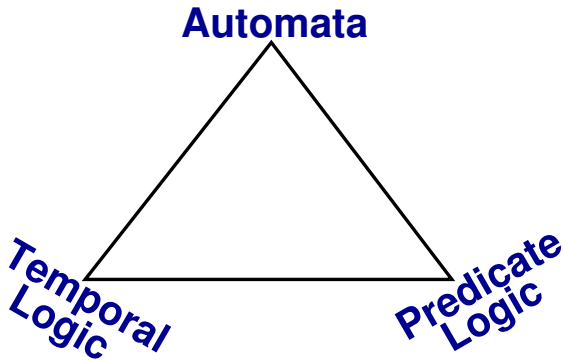
Department of Computer Science
Oxford University

Quantitative Model Checking Winter School, February 2012

The Classical Theory of Verification

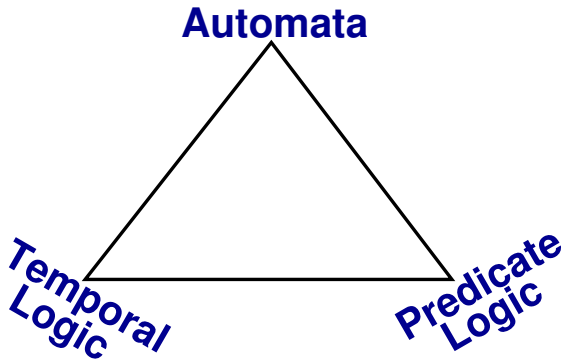


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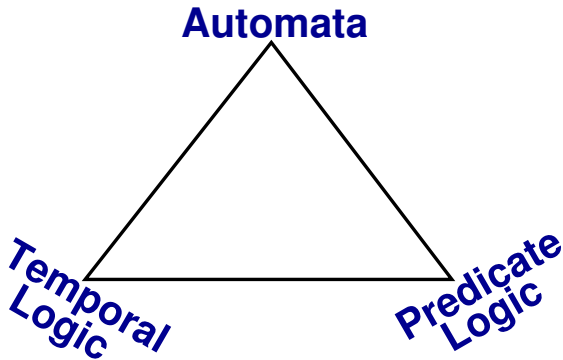
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- ▶ Time is modelled as the naturals $\mathbb{N} = \{0, 1, 2, 3, \dots\}$.
- ▶ Note: focus on linear time (as opposed to branching time).

A Simple Example

'P occurs infinitely often'

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$\square \diamond P$

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$\forall x \exists y (x < y \wedge P(y))$

Specification and Verification

- ▶ Linear Temporal Logic (LTL)

$$\theta ::= P \mid \theta_1 \wedge \theta_2 \mid \theta_1 \vee \theta_2 \mid \neg\theta \mid \bigcirc\theta \mid \diamond\theta \mid \square\theta \mid \theta_1 \mathcal{U} \theta_2$$

For example, $\square(REQ \rightarrow \diamond ACK)$.

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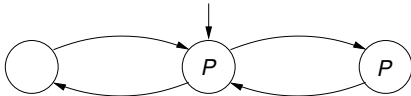
Verification is **model checking**: $IMP \models SPEC ?$

Another Example

*'P holds at every even position
(and may or may not hold at odd positions)'*

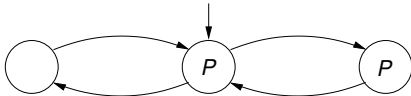
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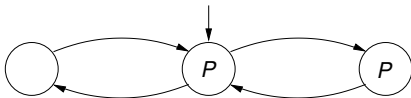
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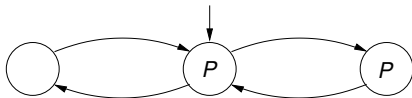
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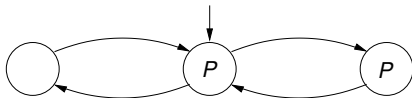


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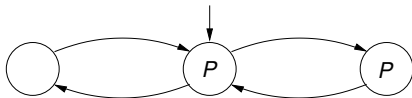
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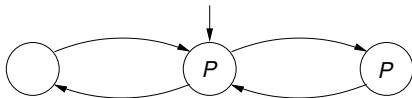
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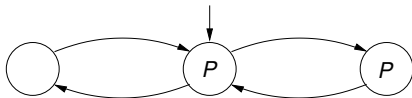
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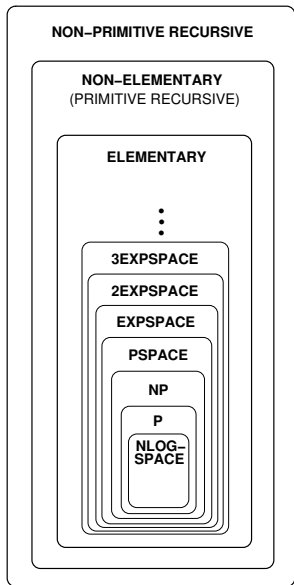
Corollary (Church 1960)

The model-checking problem for automata against MSO(<) specifications is decidable:

$$M \models \varphi \quad \text{iff} \quad L(M) \cap L(A_{\neg\varphi}) = \emptyset$$

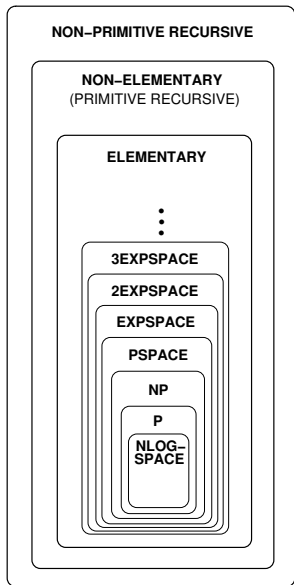
Complexity

UNDECIDABLE



Complexity

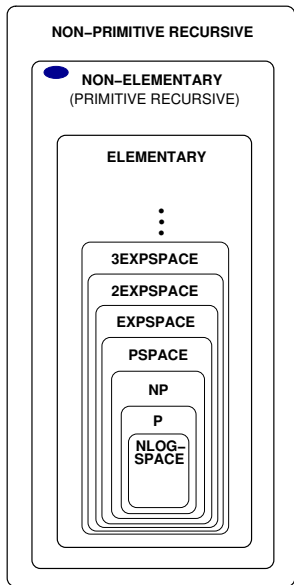
UNDECIDABLE



- ▶ NON-ELEMENTARY: $2^{2^{2^{\dots^n}}}$
- ▶ NON-PRIMITIVE RECURSIVE:
Ackerman: 3, 4, 8, 2048, $2^{2^{2^{\dots^2}}}$, ...
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But amazingly:

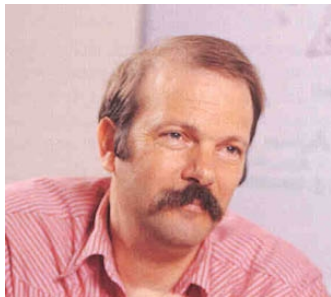
Theorem (Sistla & Clarke 1982)

LTL satisfiability and model checking are PSPACE-complete.

Logics and Automata

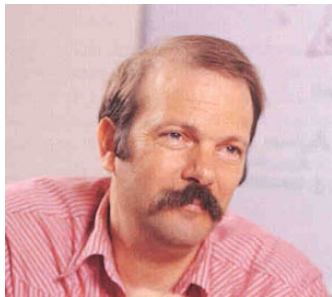
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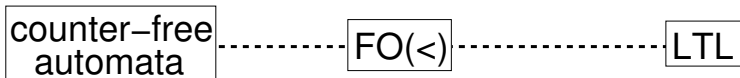
Theorem

Automata are closed under all Boolean operations. Moreover, the language inclusion problem ($L(A) \subseteq L(B) ?$) is PSPACE-complete.

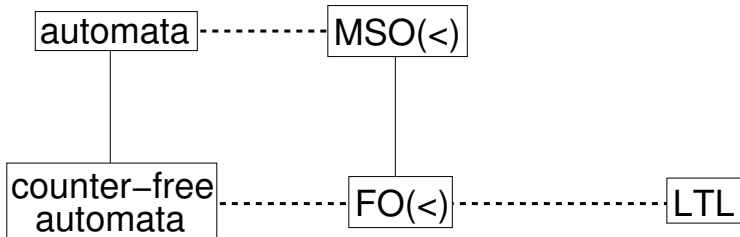
The Classical Theory: Expressiveness



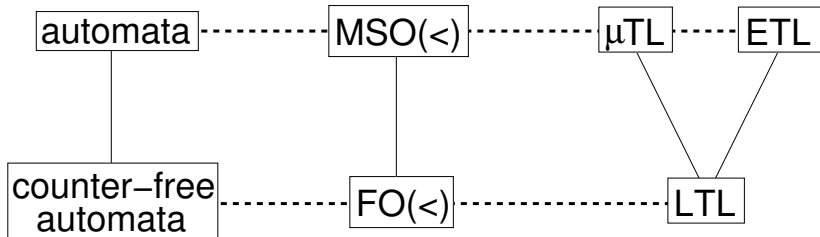
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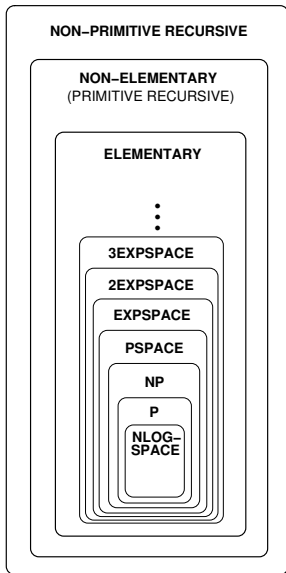


The Classical Theory: Expressiveness



The Classical Theory: Complexity

UNDECIDABLE



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UNDECIDABLE

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NON-ELEMENTARY
(PRIMITIVE RECURSIVE)

ELEMENTARY

⋮

3EXPSpace

2EXPSpace

EXPSpace

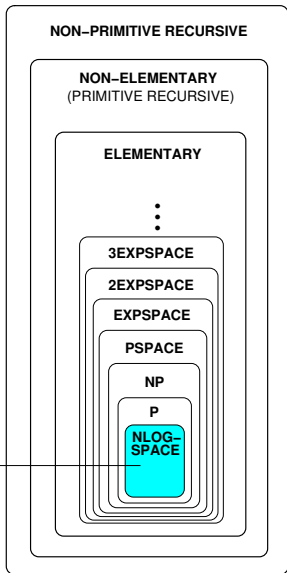
PSPACE

NP

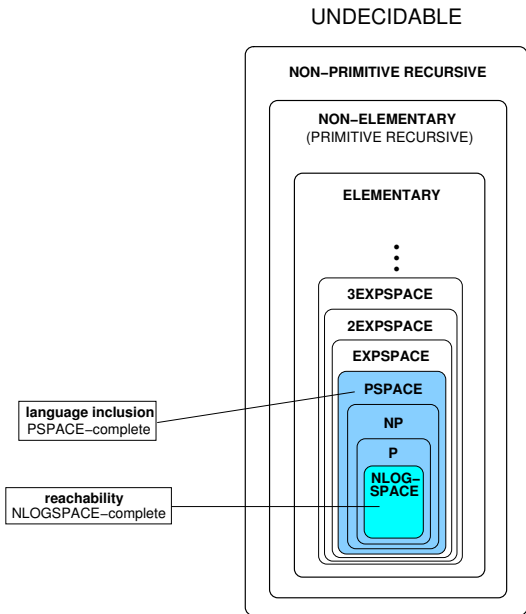
P

NLOG-
SPACE

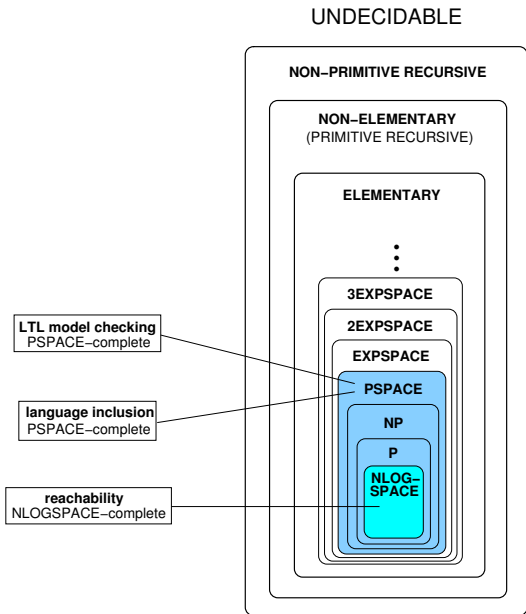
reachability
NLOGSPACE-complete



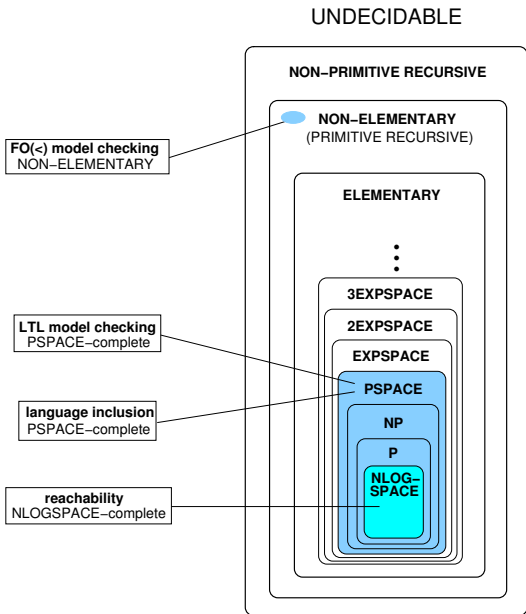
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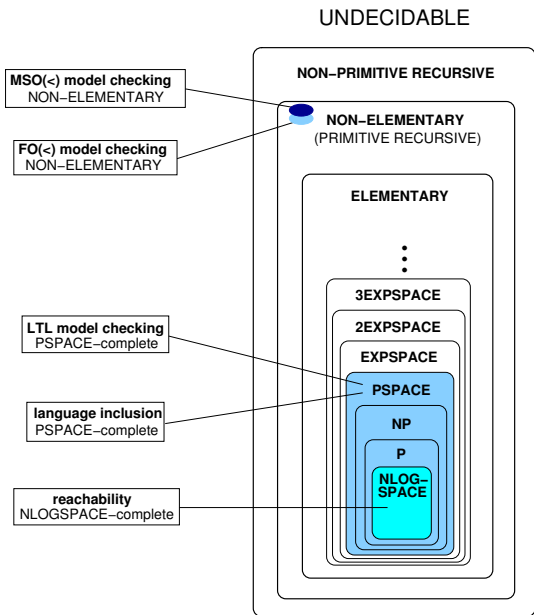
The Classical Theory: Complexity



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From Qualitative to Quantitative

*“Lift the classical theory
to the real-time world.”*

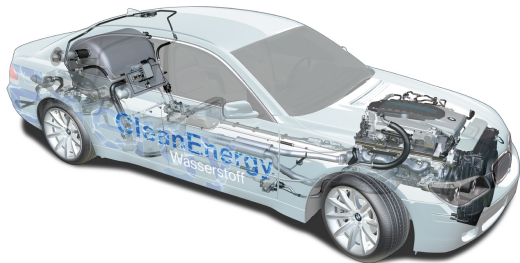
Boris Trakhtenbrot, LICS 1995



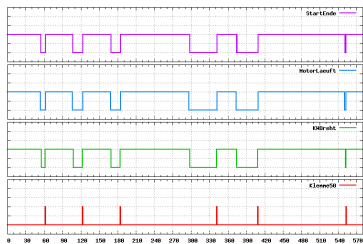
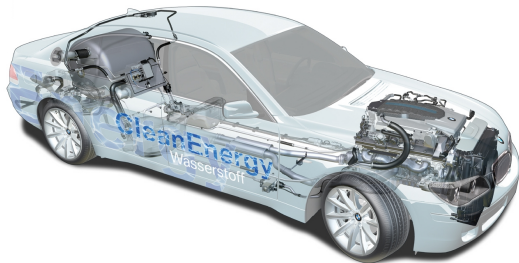
Airbus A350 XWB



BMW Hydrogen 7



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Timed Systems

Timed systems are everywhere. . .

- ▶ Hardware circuits
- ▶ Communication protocols
- ▶ Cell phones
- ▶ Plant controllers
- ▶ Aircraft navigation systems
- ▶ Sensor networks
- ▶ . . .

Timed Automata

Timed automata were introduced by Rajeev Alur at Stanford during his PhD thesis under David Dill:

- ▶ Rajeev Alur, David L. Dill: *Automata For Modeling Real-Time Systems*. ICALP 1990: 322-335
- ▶ Rajeev Alur, David L. Dill: *A Theory of Timed Automata*. TCS 126(2): 183-235, 1994



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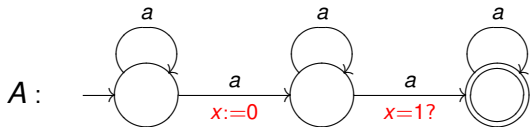
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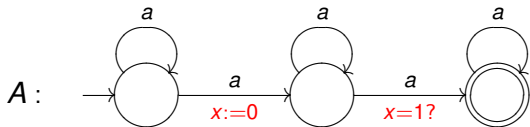
Theorem (Alur & Dill 1990)

Language inclusion is undecidable for timed automata.

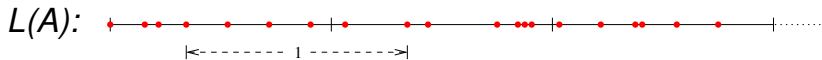
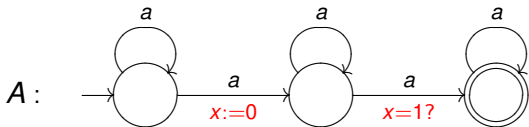
An Uncomplementable Timed Automaton



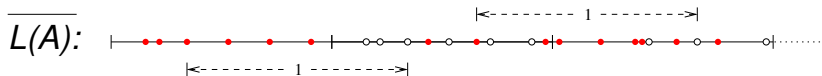
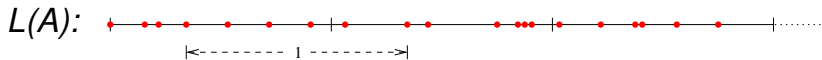
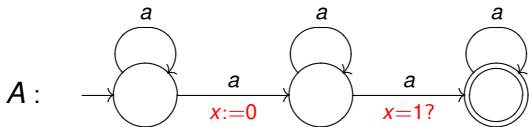
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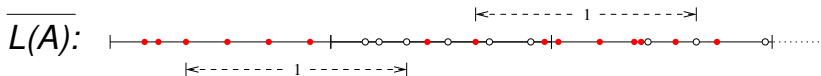
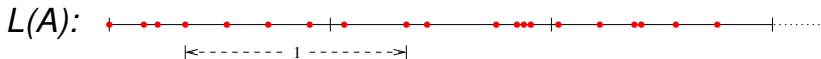
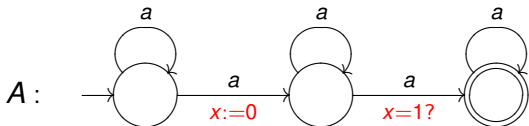
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A cannot be complemented:

There is no timed automaton B with $L(B) = \overline{L(A)}$.

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Metric Predicate Logic

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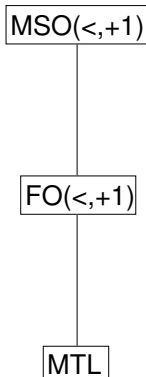
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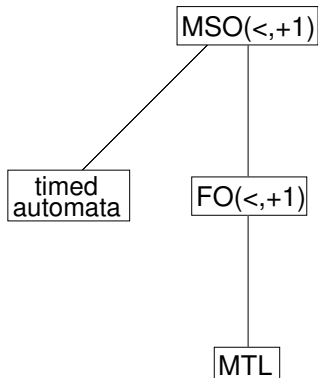


Corollary: $FO(<, +1)$ and $MSO(<, +1)$ satisfiability and model checking are undecidable over $\mathbb{R}_{\geq 0}$.

The Real-Time Theory: Expressiveness



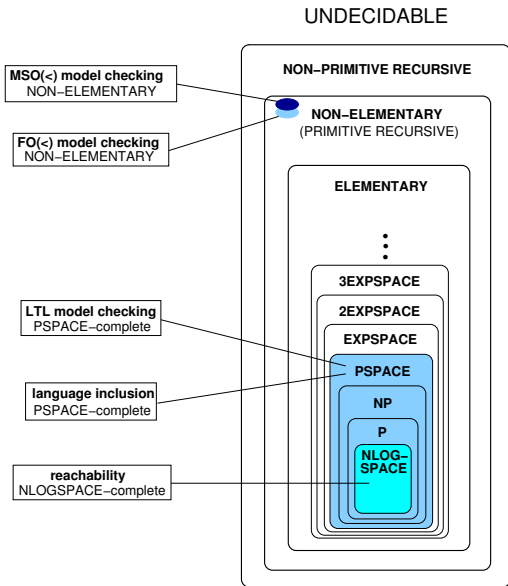
The Real-Time Theory: Expressiveness



The Real-Time Theory: Complexity

Classical Theory

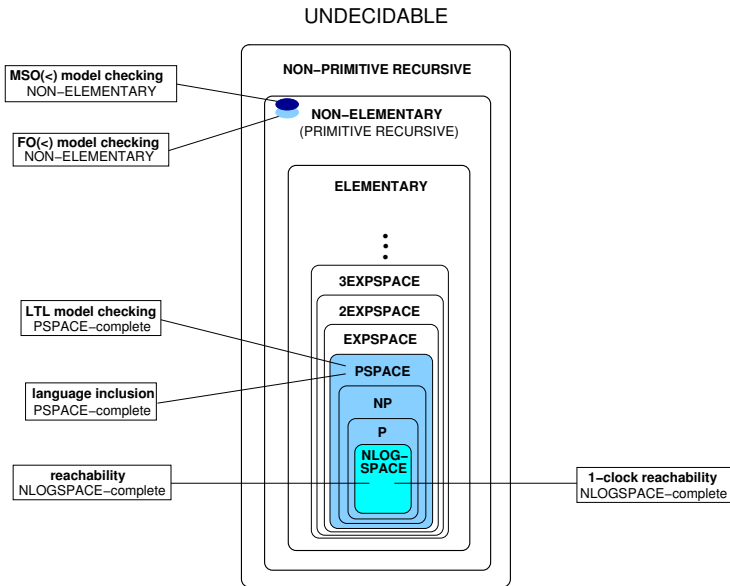
Real-Time Theory



The Real-Time Theory: Complexity

Classical Theory

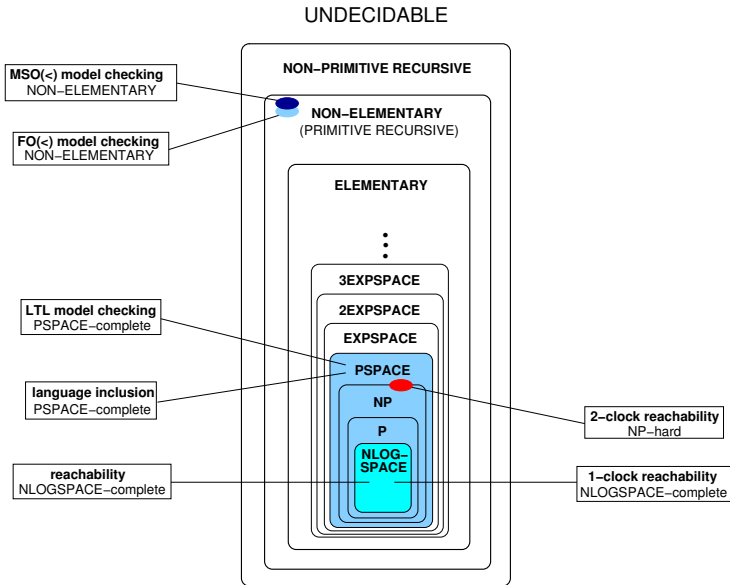
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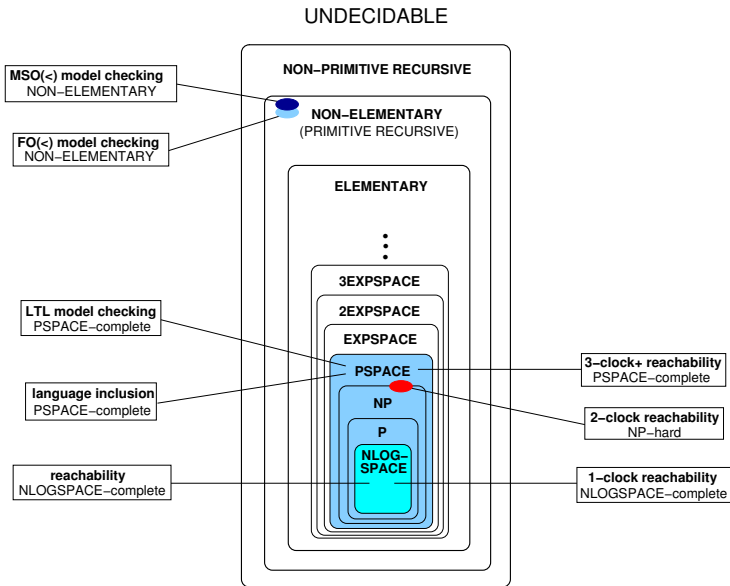
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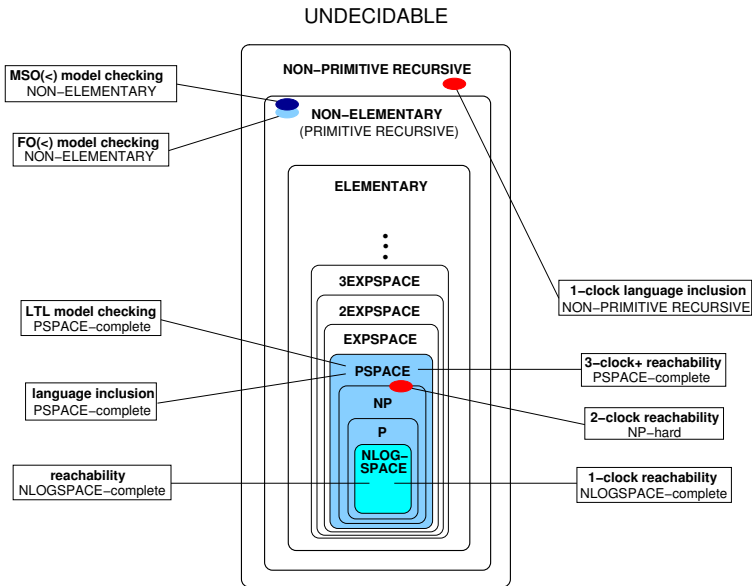
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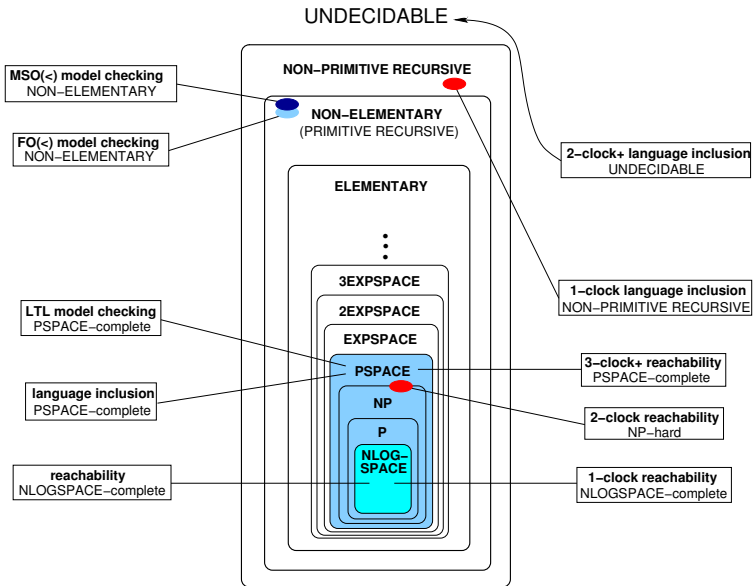
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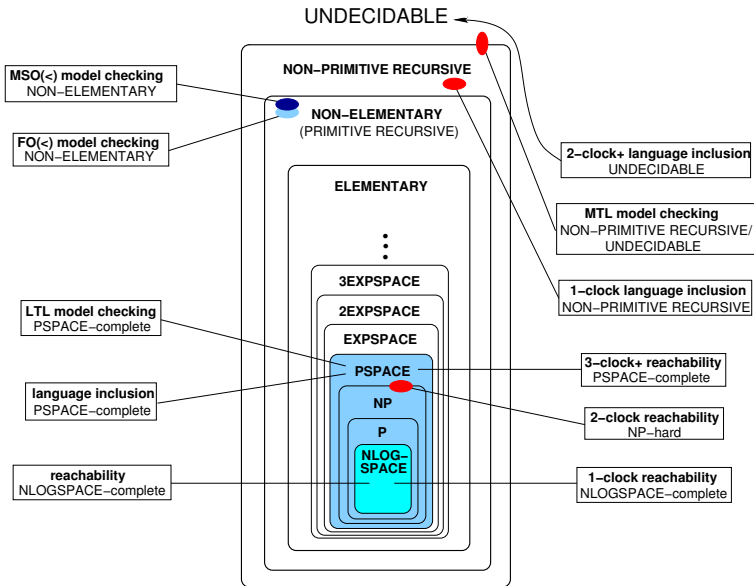
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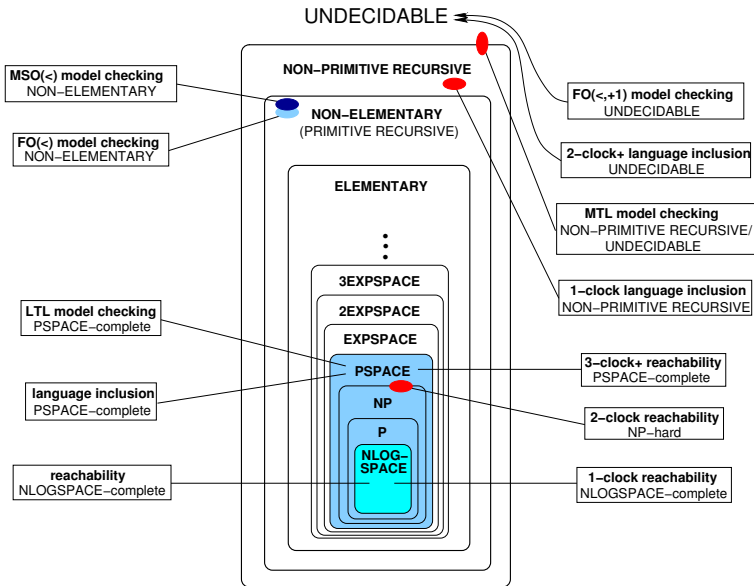
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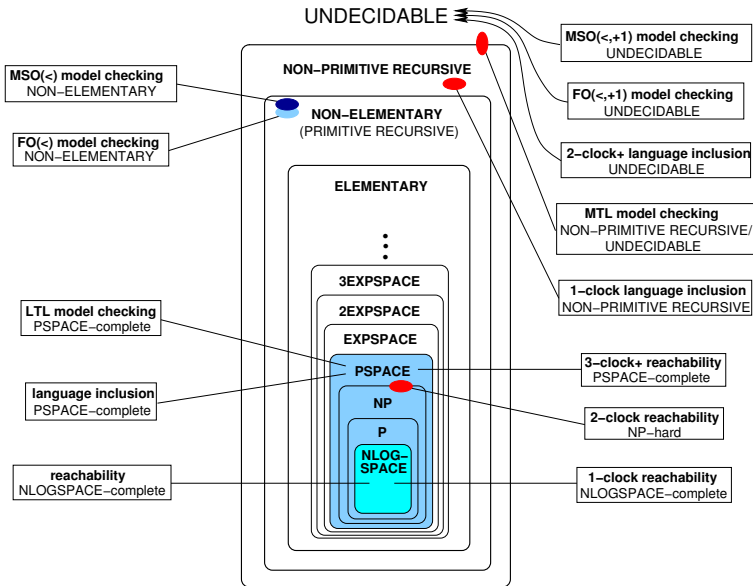
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Key Stumbling Block

Theorem (Alur & Dill 1990)

Language inclusion is undecidable for timed automata.

Timed Language Inclusion: Some Related Work

- ▶ **Topological restrictions and digitization techniques:**
[Henzinger, Manna, Pnueli 1992], [Bošnački 1999],
[Ouaknine & Worrell 2003]
- ▶ **Fuzzy semantics / noise-based techniques:**
[Maass & Orponen 1996],
[Gupta, Henzinger, Jagadeesan 1997],
[Fränzle 1999], [Henzinger & Raskin 2000], [Puri 2000],
[Asarin & Bouajjani 2001], [Ouaknine & Worrell 2003],
[Alur, La Torre, Madhusudan 2005]
- ▶ **Determinisable subclasses of timed automata:**
[Alur & Henzinger 1992], [Alur, Fix, Henzinger 1994],
[Wilke 1996], [Raskin 1999]
- ▶ **Timed simulation relations and homomorphisms:**
[Lynch *et al.* 1992], [Taşiran *et al.* 1996],
[Kaynar, Lynch, Segala, Vaandrager 2003]
- ▶ **Restrictions on the number of clocks:**
[Ouaknine & Worrell 2004], [Emmi & Majumdar 2006]

Time-Bounded Language Inclusion

TIME-BOUNDED LANGUAGE INCLUSION PROBLEM

Instance: Timed automata A , B , and time bound $T \in \mathbb{N}$

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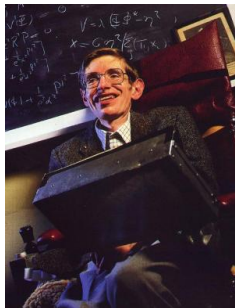
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- ▶ Inspired by Bounded Model Checking.
- ▶ Timed systems often have time bounds (e.g. timeouts), even if total number of actions is potentially unbounded.
- ▶ Universe's lifetime is believed to be bounded anyway...



Timed Automata and Metric Logics

- ▶ Unfortunately, timed automata cannot be complemented even over bounded time. . .

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Timed Automata and Metric Logics

- ▶ Unfortunately, timed automata cannot be complemented even over bounded time. . .
- ▶ Key to solution is to **translate problem into logic**: Behaviours of timed automata can be captured in $\text{MSO}(<, +1)$
- ▶ This reverses Vardi's 'automata-theoretic approach to verification' paradigm!



Monadic Second-Order Logic

Theorem (Shelah 1975)

$MSO(<)$ is undecidable over $[0, 1)$.



Monadic Second-Order Logic

Theorem (Shelah 1975)

MSO($<$) is undecidable over $[0, 1)$.



By contrast,

Theorem

- ▶ *MSO($<$) is decidable over \mathbb{N} [Büchi 1960]*
- ▶ *MSO($<$) is decidable over \mathbb{Q} , via [Rabin 1969]*

Finite Variability

Timed behaviours are modelled as **flows** (or **signals**):

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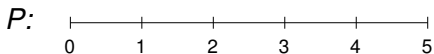
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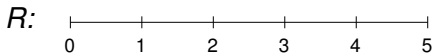
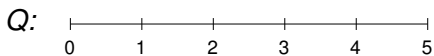
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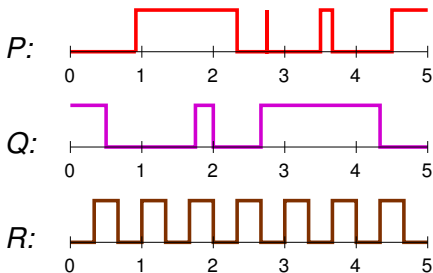
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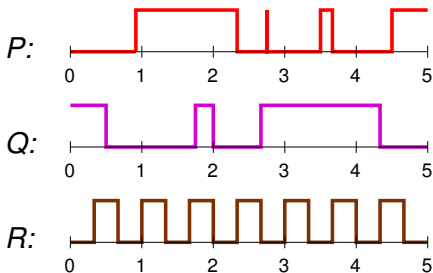
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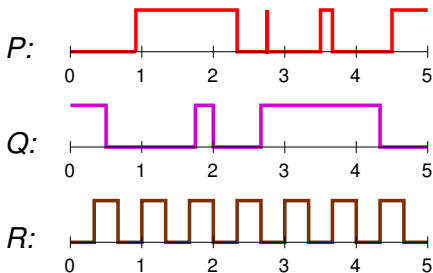


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Finite Variability

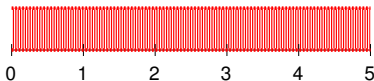
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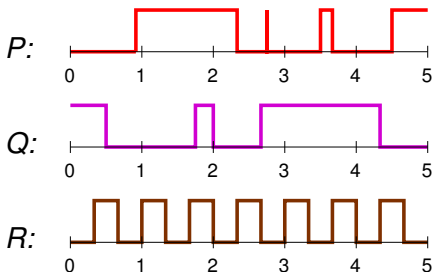
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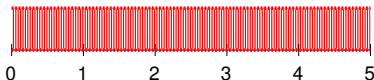
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Then:

Theorem (Rabinovich 2002)

MSO($<$) satisfiability over finitely-variable flows is decidable.

The Time-Bounded Theory of Verification

Theorem

For any bounded time domain $[0, T)$, *satisfiability* and *model checking* are decidable as follows:

$MSO(<, +1)$	<i>NON-ELEMENTARY</i>
$FO(<, +1)$	<i>NON-ELEMENTARY</i>
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MTL and $FO(<, +1)$ are *equally expressive* over any fixed bounded time domain $[0, T)$.

Theorem

Given timed automata A, B , and time bound $T \in \mathbb{N}$, the *time-bounded language inclusion problem* $L_T(A) \subseteq L_T(B)$ is decidable and 2EXPSPACE-complete.

MSO($<, +1$) Time-Bounded Satisfiability

Key idea: eliminate the metric by 'vertical stacking'.

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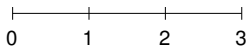
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- ▶ Conclude by invoking decidability of MSO($<$).

From $\text{MSO}(<, +1)$ to $\text{MSO}(<)$



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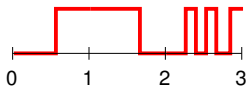
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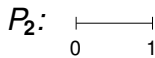
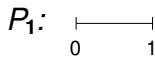
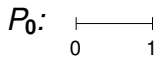
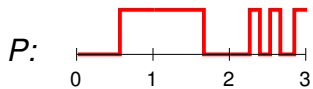


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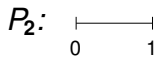
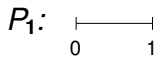
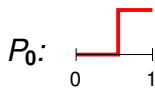
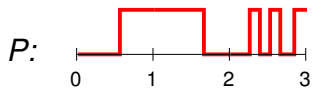
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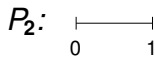
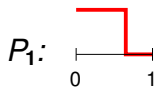
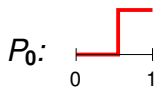
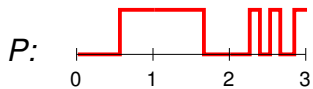
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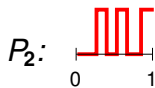
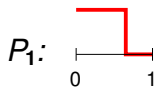
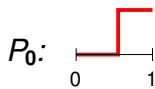
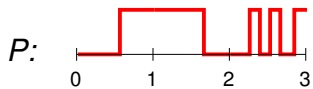
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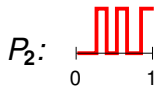
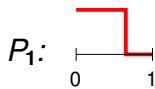
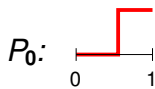
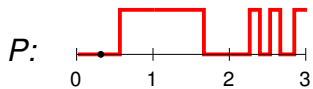
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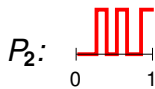
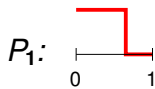
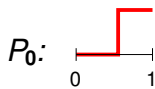
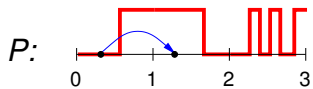
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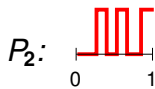
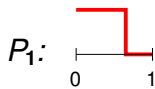
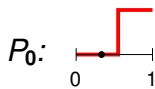
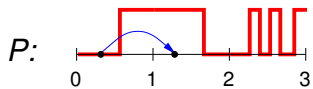
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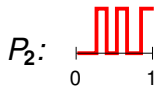
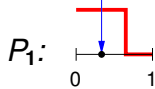
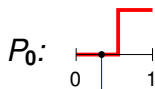
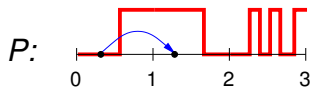
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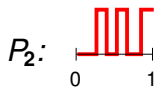
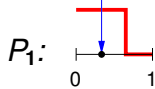
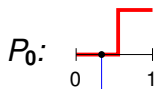
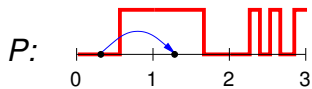
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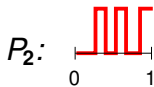
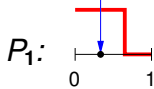
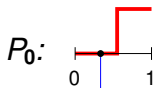
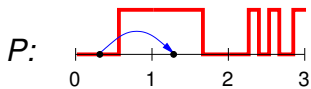
From MSO($<, +1$) to MSO($<$)



Replace every:

▶ $\forall x \psi(x)$

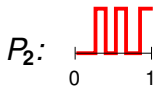
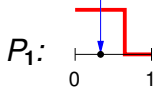
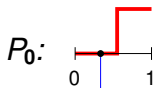
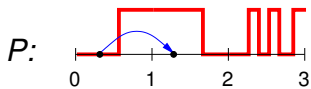
From MSO($<, +1$) to MSO($<$)



Replace every:

▶ $\forall x \psi(x)$ **by** $\forall x (\psi(x) \wedge \psi(x+1) \wedge \psi(x+2))$

From $\text{MSO}(<, +1)$ to $\text{MSO}(<)$

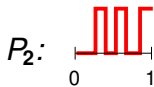
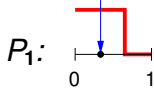
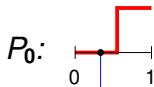
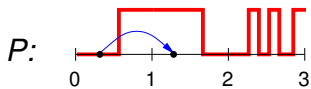


Replace every:

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From MSO($<, +1$) to MSO($<$)

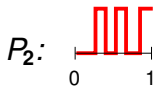
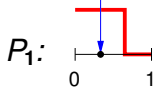
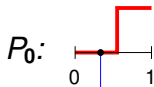
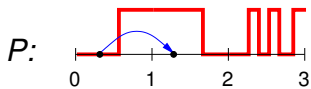


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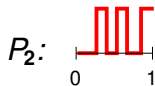
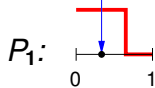
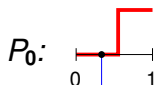
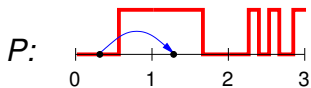
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▶ $P(x+k)$

From MSO($<, +1$) to MSO($<$)

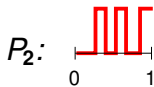
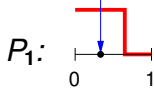
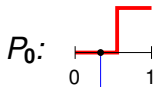
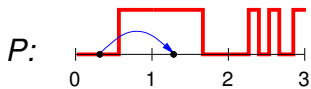


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$$\begin{cases} x < y & \text{if } k_1 = k_2 \\ \mathbf{true} & \text{if } k_1 < k_2 \\ \mathbf{false} & \text{if } k_1 > k_2 \end{cases}$$
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From MSO($<, +1$) to MSO($<$)

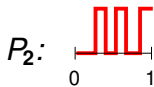
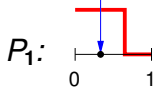
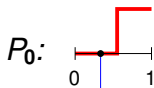
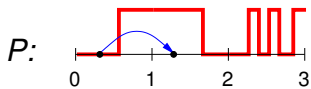


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From MSO($<, +1$) to MSO($<$)



Replace every:

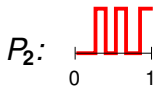
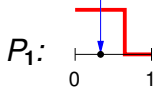
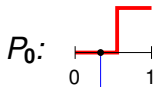
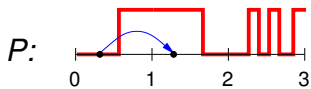
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▶ $\forall P \psi$ **by** $\forall P_0 \forall P_1 \forall P_2 \psi$

From MSO($<, +1$) to MSO($<$)



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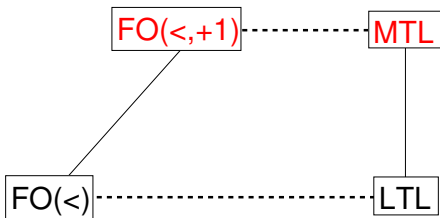
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Then φ is satisfiable over $[0, T)$ $\iff \bar{\varphi}$ is satisfiable over $[0, 1)$.

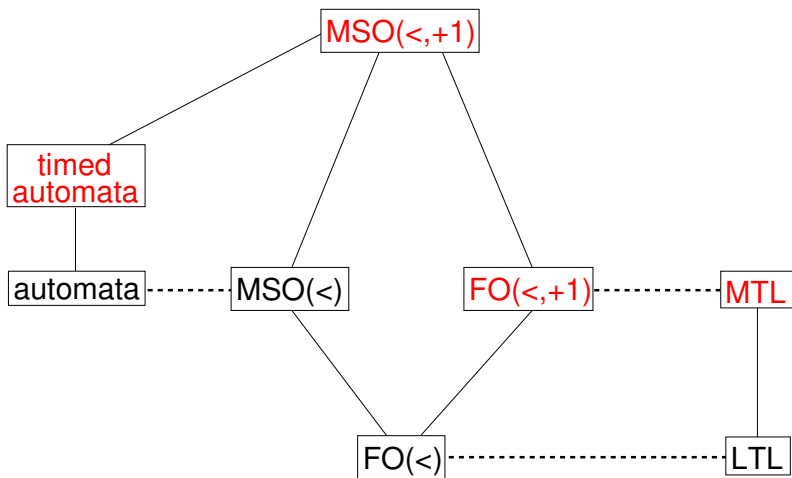
The Time-Bounded Theory: Expressiveness



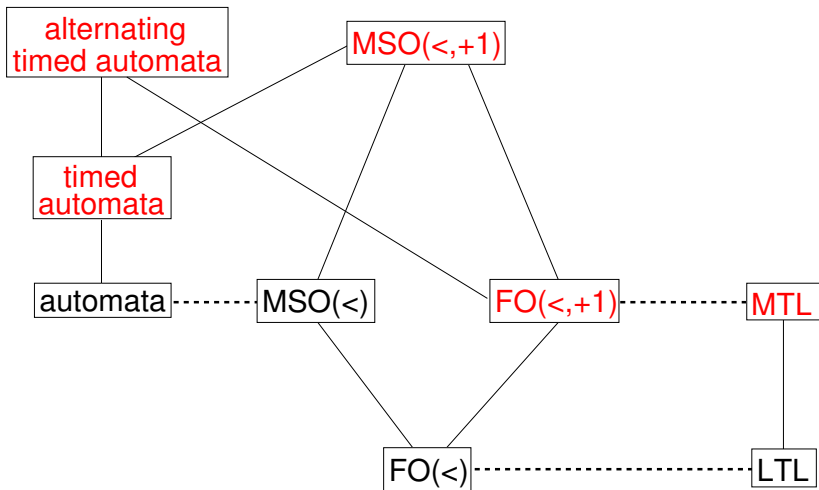
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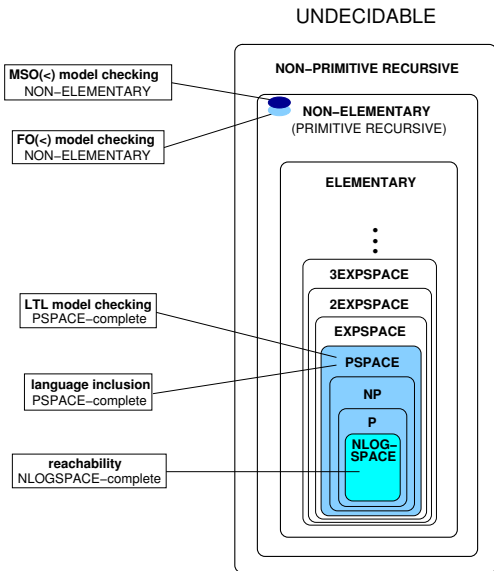
The Time-Bounded Theory: Expressiveness



The Time-Bounded Theory: Complexity

Classical Theory

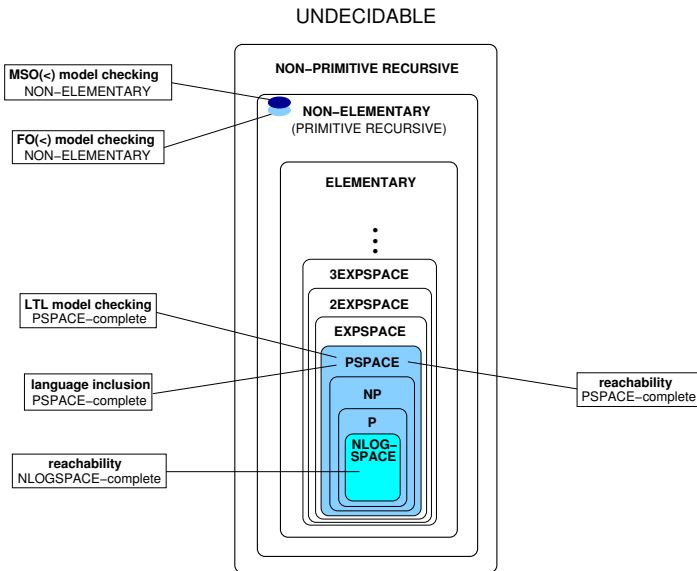
Time-Bounded Theory



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Classical Theory

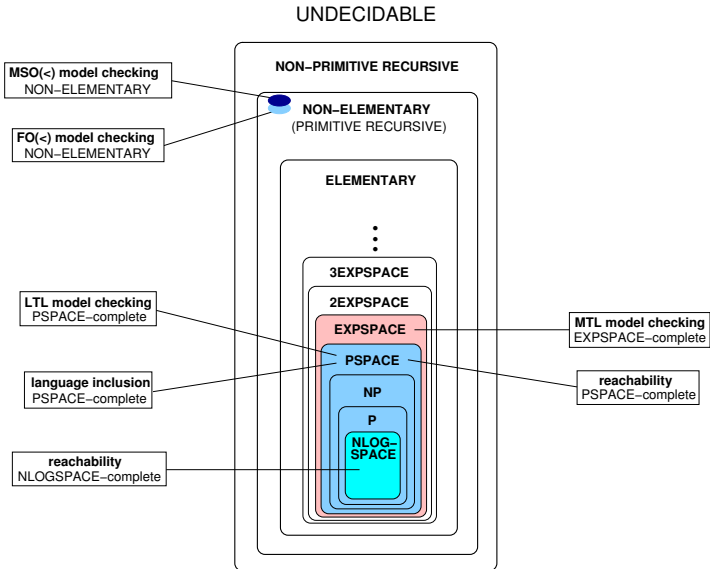
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Classical Theory

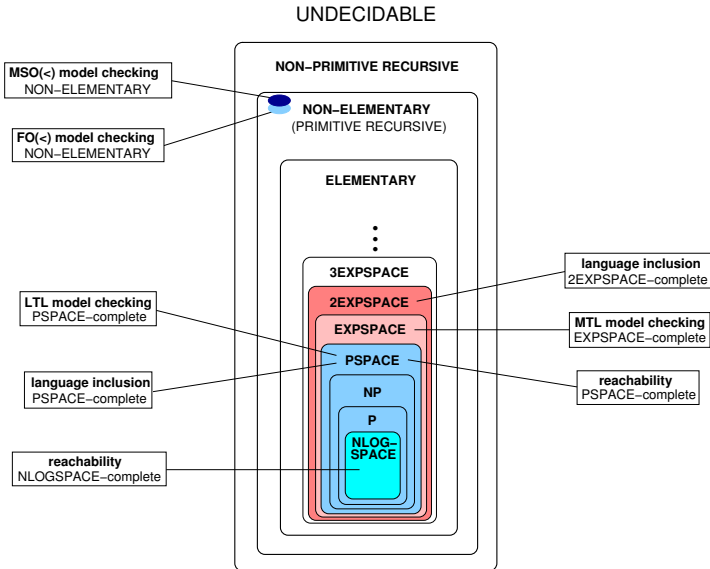
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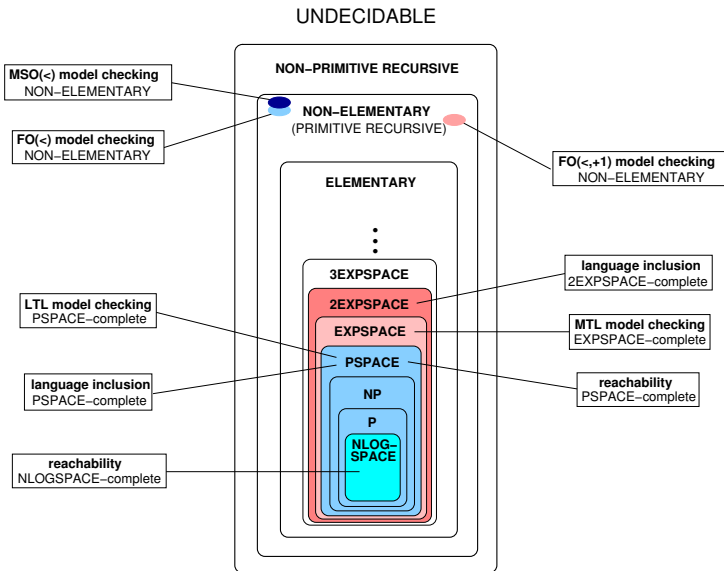
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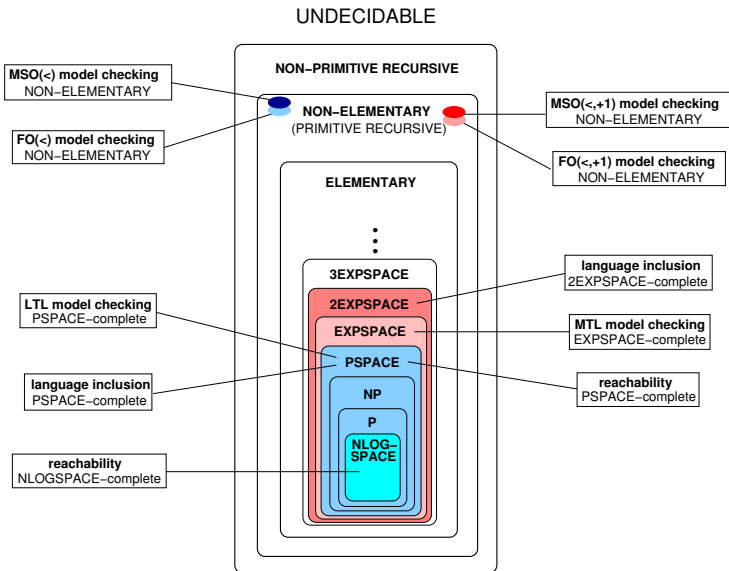
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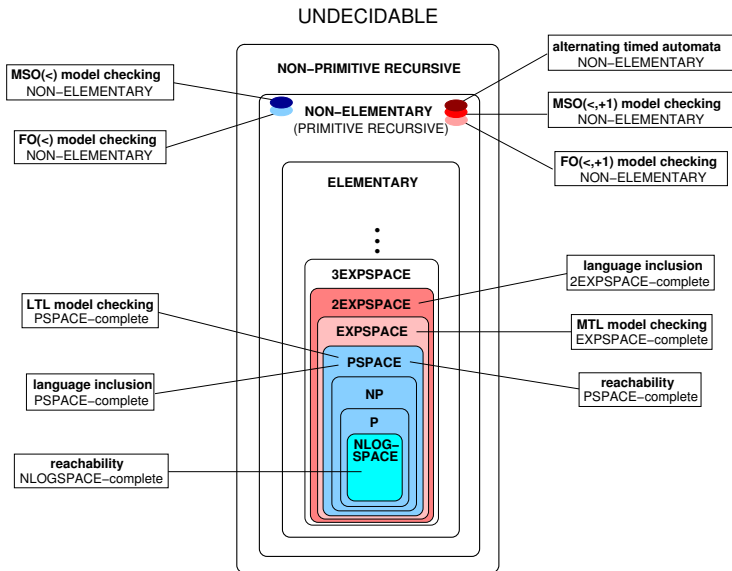
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Conclusion and Future Work

- ▶ For real-time systems, the **time-bounded theory** is much better behaved than the **real-time theory**.

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Future work:

- ▶ Extend the theory further!
 - ▶ Branching-time
 - ▶ Timed games and synthesis
 - ▶ Weighted and hybrid automata
 - ▶ ...
- ▶ Algorithmic and complexity issues
- ▶ Expressiveness issues
- ▶ Implementation and case studies