Topics in Timed Automata

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Reachability for timed automata

Key idea: Compute the zone graph, use abstraction for termination



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Coarser the abstraction, smaller the zone graph

Condition 1: a should have finite range

Condition 2: a should be sound $\Rightarrow \mathfrak{a}(W)$ can contain only valuations **simulated** by *W*



Bounds and abstractions

Theorem [LS00]

Coarsest simulation relation is EXPTIME-hard



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$$(y \le 3) (x < 4) (x > 6) (y < 1)$$

Bounds and abstractions

Theorem [LS00]

Coarsest simulation relation is EXPTIME-hard

$$(y \le 3)$$
 (x < 4)
(x < 1)
(x > 6)
(y < 1)

M-bounds [AD94] M(x) = 6, M(y) = 3 $v \preccurlyeq_M v'$ LU-bounds [BBLP04] $L(x) = 6, L(y) = -\infty$ U(x) = 4, U(y) = 3 $v \preccurlyeq_{LU} v'$

Abstractions in literature [BBLP04, Bou04]



Last lecture: Efficiently using the M-bounds based Closure_M abstraction

Lecture 7: Lower-upper bounds for abstraction

LU-guards: guards consistent with given L and U LU-guards for L(x) = 3, U(x) = 5, L(y) = 8, $U(y) = -\infty$ $x \ge 0, x \ge 1, x \ge 2, x \ge 3$ $x \le 0, x \le 1, \dots, x \le 5$ $y \ge 0, y \ge 1, \dots, y \ge 8$ (same with < and >) LU-automata: automata with only LU-guards $L(x) = 3, U(x) = 5, L(y) = 8, U(y) = -\infty$

$$\rightarrow \underbrace{q_0}_{\{x\}} \underbrace{x \ge 2,}_{\{x\}} \underbrace{q_1}_{\{x\}} \underbrace{y \ge 7}_{\{x\}}$$



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What do we need?

1. An abstraction abs_{LU} that is **sound** and **complete** for **all** LU-automata



2. Efficient inclusion testing $Z \subseteq abs_{LU}(Z')$

Step 1: LU-regions

- Invariance by guards: v' satisfies the same guards as v,
- ▶ Invariance by time-elapse: for every time elapse $\delta \in \mathbb{R}_{\geq 0}$, there is a $\delta' \in \mathbb{R}_{\geq 0}$ such that $v' + \delta' \in [v + \delta]^{M}$.



- Invariance by guards: v' satisfies the same guards as $v, \sqrt{}$
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- ▶ Invariance by guards: v' satisfies the same guards as v,
- ▶ Invariance by time-elapse: for every pair of clocks *x*, *y* with:

$$v(x) \leq M_x, \ v(y) \leq M_y \ ig v(x) ig = ig v'(x) ig \ ext{and} \ ig v(y) ig = ig v'(y) ig \ ext{and} \ ig v(y) ig = ig v'(y) ig \ ext{and} \ ig v(y) ig = ig v'(y) ig \ ext{and} \ ig v(y) ig \ ext{and} \ \ ext{and} \ ext{and} \ \ext{and} \ ext{and} \ \ext{and} \ \ext{a$$

we have:

• if $0 < \{v(x)\} < \{v(y)\}$, then $0 < \{v'(x)\} < \{v'(y)\}$ • if $0 < \{v(x)\} = \{v(y)\}$, then $0 < \{v'(x)\} = \{v'(y)\}$

> $\lfloor v(x) \rfloor$: integer part of v(x) $\{v(x)\}$: fractional part of v(x)

Coming next...

Regions for the LU-case

Invariance by (LU-) guards: v(x) is less than both L_x , U_x



Invariance by (LU-) guards: $v(x) > L_x$



Invariance by (LU-) guards: $v(x) > U_x$



Invariance by time-elapse: $v(x) \le U_x$, $v(y) \le L_y$



Invariance by time-elapse: $v(x) > U_x$, $v(y) \le L_y$



Invariance by time-elapse: $v(x) \le U_x$, $v(y) > L_y$



LU-regions

Definition: v' belongs to $\langle v \rangle^{LU}$ if:

- Invariance by guards: v' satisfies the same guards as v,
- ► **Invariance by time-elapse:** for every pair of clocks *x*, *y* with:

 $egin{aligned} & v(x) \leq U_x, \; v(y) \leq L_y \ & \lfloor \; v(x) \;
floor = \; \lfloor \; v'(x) \;
floor \; ext{ and } \; \lfloor \; v(y) \;
floor = \; \lfloor \; v'(y) \;
floor, \end{aligned}$

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- if $0 < \{v(x)\} < \{v(y)\}$, then $0 < \{v'(x)\} < \{v'(y)\}$
- if $0 < \{v(x)\} = \{v(y)\}$, then $0 < \{v'(x)\} = \{v'(y)\}$

Step 2: An abstraction abs_{LU}





Definition $abs_{LU}(W) = \{v \mid \exists v' \in W \text{ s.t. } v \sqsubseteq_{LU} v'\}$



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abs_{LU} is sound and complete

Example


















Time-elapsed zone Z: if $v \in Z$, then $v + \delta \in Z$ for all $\delta \in \mathbb{R}_{\geq 0}$

 $\mathfrak{a}_{\preccurlyeq LU}$ coincides with abs_{LU}

If Z is time-elapsed, then $\mathfrak{a}_{\preccurlyeq LU}(Z) = abs_{LU}(Z)$

Better abstractions for timed automata

Time-elapsed zone Z: if $v \in Z$, then $v + \delta \in Z$ for all $\delta \in \mathbb{R}_{\geq 0}$

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Optimality

$\mathfrak{a}_{\prec LU}(Z)$ is the **coarsest** abstraction that is **sound** and **complete** for all LU-automata

Better abstractions for timed automata

Step 3: Efficient inclusion

$$egin{aligned} & v \sqsubseteq_{LU} \ v' & & \ & ext{if} & \ & \exists \delta' \in \mathbb{R}_{\geq 0} & ext{s.t.} \ v' + \delta' \in \langle v
angle^{\scriptscriptstyle LU} \end{aligned}$$

Definition

$$\mathsf{abs}_{LU}(W) \;=\; \{ v \mid \exists v' \in W \text{ s.t. } v \sqsubseteq_{LU} v' \}$$

$$v \sqsubseteq_{LU} v'$$

if
 $\exists \delta' \in \mathbb{R}_{\geq 0} \text{ s.t. } v' + \delta' \in \langle v \rangle^{LU}$

Definition

$$abs_{LU}(W) = \{v \mid \exists v' \in W \text{ s.t. } v \sqsubseteq_{LU} v'\}$$

Z, Z': time-elapsed zones

 $Z \not\subseteq \operatorname{abs}_{LU}(Z')$ iff there exists $v \in Z$ s.t. $\langle v \rangle^{\scriptscriptstyle LU}$ does not intersect Z'

Reduction to two clocks

 $Z \not\subseteq \mathfrak{a}_{\preccurlyeq LU}(Z')$ if and only if there **exist 2 clocks** x, y s.t.

 $\operatorname{Proj}_{xy}(Z) \not\subseteq \mathfrak{a}_{\preccurlyeq LU}(\operatorname{Proj}_{xy}(Z'))$

Better abstractions for timed automata F. Herbreteau, B. Srivathsan, I. Walukiewicz. *LICS'12*

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Slightly modified comparison works!

Better abstractions for timed automata





Question: If $\mathfrak{a}_{\preccurlyeq LU}$ is best, can we do better?

Get better LU-bounds!

Global LU-bounds





Static analysis: bounds for every q [BBFL03]



Size of graph < 10

Static analysis: bounds for every q [BBFL03]



Size of graph $\sim 10^6$

Need to look at semantics...

LU bounds for every (q, Z) in zone graph



LU bounds for every (q, Z) in zone graph



$$M(x) = -\infty$$

(q, Z, M)






























Constant propagation



Theorem (Correctness)

An accepting state is reachable in A iff the constant propagation algorithm reaches a node with accepting state and a non-empty zone.

Key idea: Compute the zone graph, use abstraction for termination



Developments are recent, a lot of (not-so-low) hanging fruit available

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