

Algorithms for CTL

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Model Checking and Systems Verification

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Module 1:
Adequate CTL formulae

Recap of CTL

State formulae

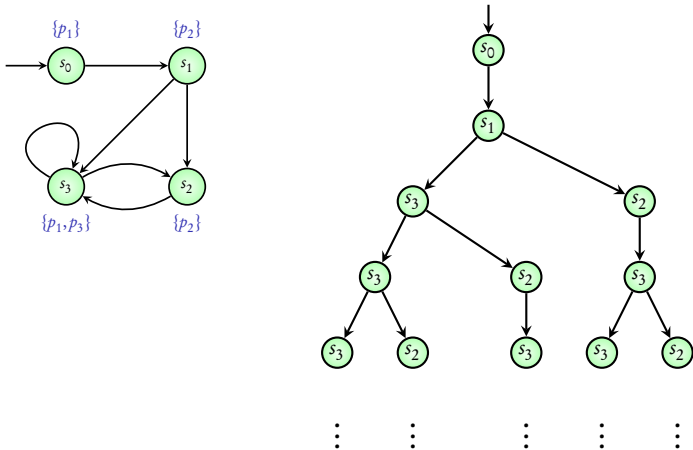
$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi_1 \mid E\alpha \mid A\alpha$

$p_i \in AP$ ϕ_1, ϕ_2 : State formulae α : Path formula

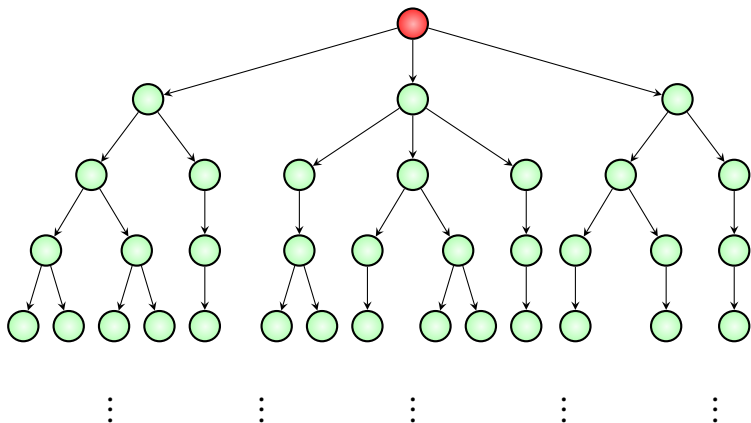
Path formulae

$\alpha := X\phi_1 \mid \phi_1 U \phi_2 \mid F\phi_1 \mid G\phi_1$

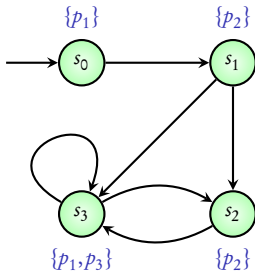
Transition system satisfies CTL state formula ϕ if its computation tree satisfies ϕ

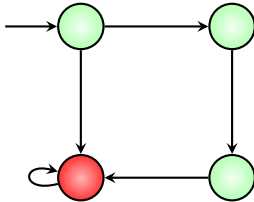


A **tree** satisfies CTL state formula ϕ if its **root** satisfies ϕ

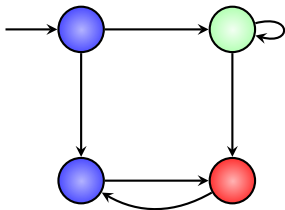


A **state** s in a transition system satisfies a CTL formula ϕ if the computation tree **starting at** s satisfies ϕ

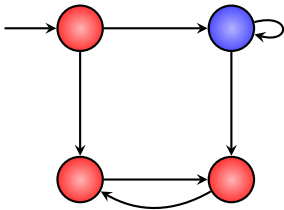




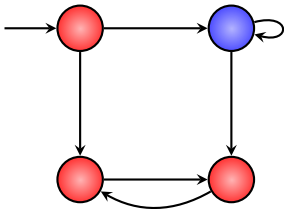
Above transition system satisfies **E X** *red*



Above transition system satisfies $E \text{ blue } U \text{ red}$



Above transition system satisfies **E G** *red*



Above transition system satisfies **E G** *red*

It does not satisfy **A F** *blue*

Mutual exclusion

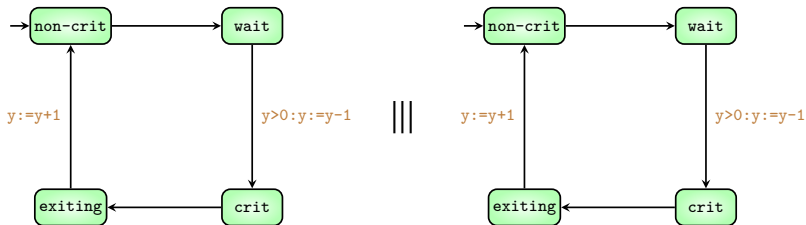
Atomic propositions $AP = \{p_1, p_2, p_3, p_4\}$

p_1 : `pr1.location=crit`

p_2 : `pr1.location=wait`

p_3 : `pr2.location=crit`

p_4 : `pr2.location=wait`



Above system satisfies $\mathbf{A G} \neg (p_1 \wedge p_3)$

Goal of this unit

Design an algorithm:

INPUT: A transition system M and a CTL formula ϕ

OUTPUT: Does M satisfy ϕ ?

Goal of this unit

Design an algorithm:

INPUT: A transition system M and a CTL formula ϕ

OUTPUT: Does M satisfy ϕ ?

We will answer a more general question:

Given M and ϕ , find all the states of M that satisfy ϕ

First step

State formulae

$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi_1 \mid E\alpha \mid A\alpha$

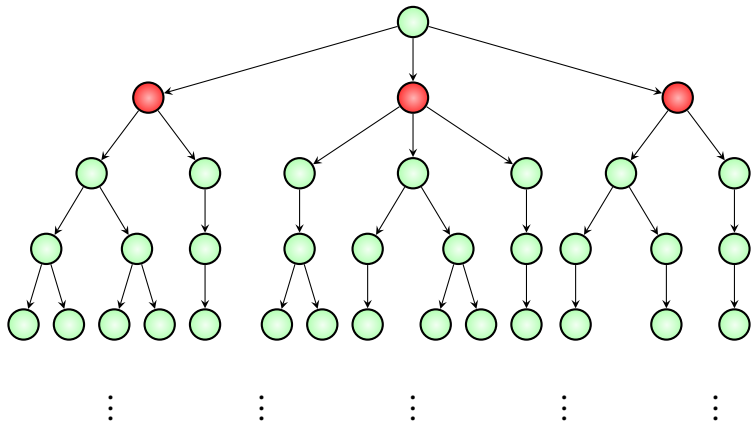
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Path formulae

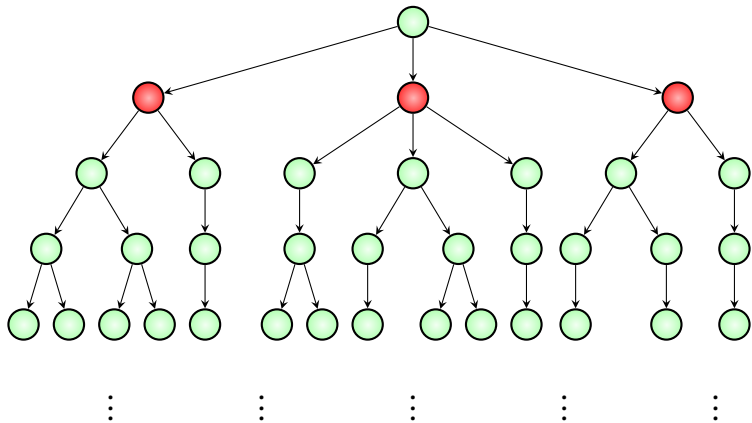
$\alpha := X\phi_1 \mid \phi_1 U \phi_2 \mid F\phi_1 \mid G\phi_1$

Rewrite **A** in terms of **E**

$\mathbf{A X}(\text{red})$ equivalent to $\neg \mathbf{E X}(\neg \text{red})$



$\mathbf{A X}(\text{red})$ equivalent to $\neg \mathbf{E X}(\neg \text{red})$



$$\mathbf{A X} \phi \equiv \neg \mathbf{E X} \neg \phi$$

Can we rewrite $\mathbf{A}(\phi \mathbf{U} \psi)$ as $\neg \mathbf{E} \neg(\phi \mathbf{U} \psi)$?

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No: $\neg \mathbf{E} \neg(\phi \mathbf{U} \psi)$ is not a CTL formula

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Path formulae

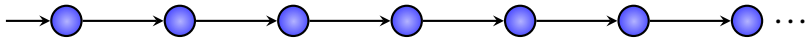
$\alpha := X \phi_1 \mid \phi_1 U \phi_2 \mid F \phi_1 \mid G \phi_1$

CTL does not allow negation of path formula!

Coming next: Rewrite $A U$ in terms of $E U$ and $E G$

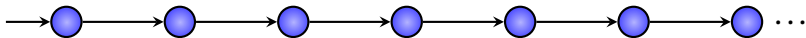
$\neg (\textit{blue} \cup \textit{red})$

$\neg (blue \cup red)$



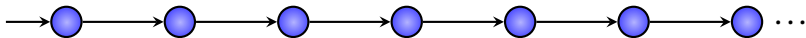
$\neg (\textit{blue} \textit{U} \textit{red})$

$G \neg \textit{red}$



$\neg (\textit{blue} \textit{U} \textit{red})$

$G \neg \textit{red}$



or

$\neg (\text{blue U red})$

$G \neg \text{red}$

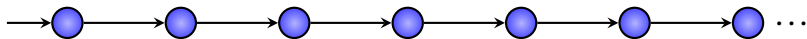


or

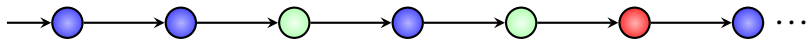


$$\neg (blue \text{ U } red)$$

$$G \neg red$$

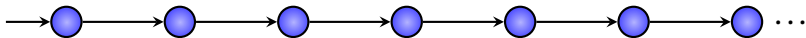


or $(\neg red) \text{ U } (\neg blue \wedge \neg red)$

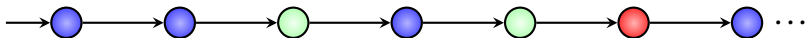


$\neg(\text{blue} \text{ U } \text{red})$

$\text{G} \neg \text{red}$



or $(\neg \text{red}) \text{ U } (\neg \text{blue} \wedge \neg \text{red})$



$$\neg(\phi \text{ U } \psi) \equiv \text{G} \neg \psi \vee (\neg \psi \text{ U } (\neg \phi \wedge \neg \psi))$$

$$\mathbf{A} (\phi \mathbf{U} \psi)$$

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$$\equiv$$
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(Not a CTL formula)

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\equiv

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(Not a CTL formula)

\equiv

$$\neg (\mathbf{E} \mathbf{G} \neg \psi \vee \mathbf{E} (\neg \psi \mathbf{U} (\neg \psi \wedge \neg \phi)))$$

$$\mathbf{A} (\phi \mathbf{U} \psi)$$

\equiv

$$\neg \mathbf{E} \neg (\phi \mathbf{U} \psi)$$

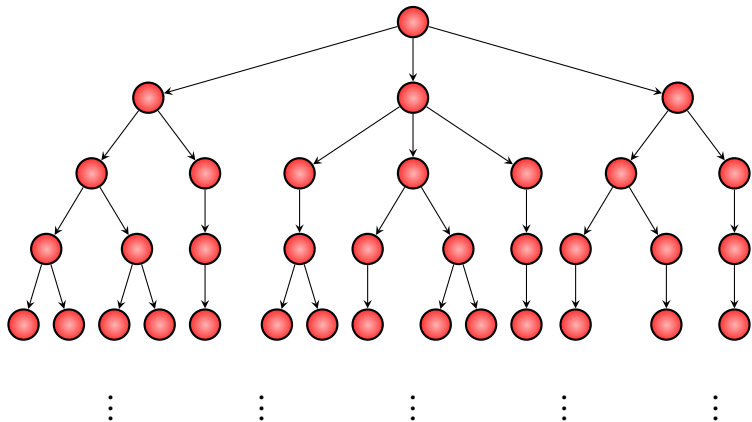
(Not a CTL formula)

\equiv

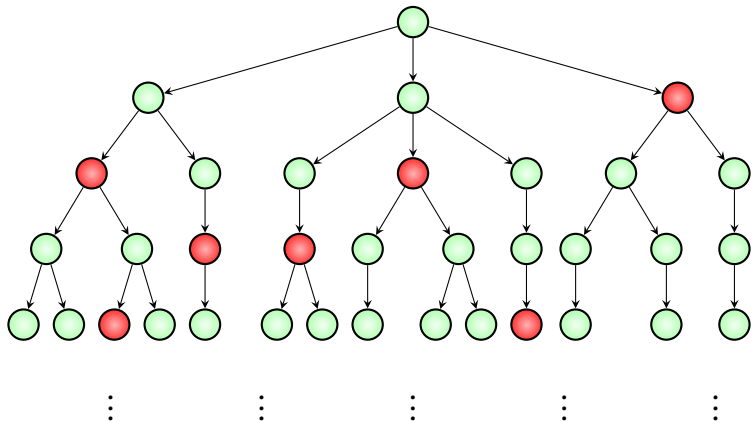
$$\neg (\mathbf{E} \mathbf{G} \neg \psi \vee \mathbf{E} (\neg \psi \mathbf{U} (\neg \psi \wedge \neg \phi)))$$

(A CTL formula!)

$\mathbf{A G}(\text{red})$ equivalent to $\neg \mathbf{E F}(\neg \text{red})$



$A F (red)$ equivalent to $\neg E G (\neg red)$



First step

State formulae

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Path formulae

$\alpha := X\phi_1 \mid \phi_1 U \phi_2 \mid F\phi_1 \mid G\phi_1$

Rewrite **A** in terms of **E** **Done!**

All CTL formulas can be written in terms of
E X , **E U** , **E G** and **E F**

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 $\mathbf{E X}$, $\mathbf{E U}$, $\mathbf{E G}$ and $\mathbf{E F}$

Moreover $\mathbf{E F } \phi \equiv \mathbf{E (true U } \phi)$

All CTL formulas can be written in terms of
E X , **E U** , **E G** and **E F**

Moreover $\mathbf{E F } \phi \equiv \mathbf{E (true U } \phi \mathbf{)}$

E X, **E U** and **E G** are adequate to describe all CTL formulas

Existential Normal Form (ENF) for CTL

State formulae

$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid EX\phi \mid E(\phi_1 U \phi_2) \mid EG\phi$

$p_i \in AP$

ϕ, ϕ_1, ϕ_2 : State formulae

Existential Normal Form (ENF) for CTL

State formulae

$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid EX\phi \mid E(\phi_1 U \phi_2) \mid EG\phi$

$p_i \in AP$

$\phi, \phi_1, \phi_2 : \text{State formulae}$

Theorem

For every CTL formula there exists an **equivalent** CTL formula in ENF

Module 2:
EX, EU and EG

CTL model-checking problem

Given transition system M and a CTL formula ϕ , find all states of M that satisfy ϕ

CTL model-checking problem

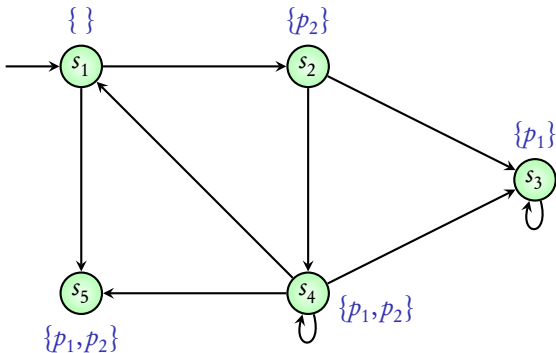
Given transition system M and a CTL formula ϕ , find all states of M that satisfy ϕ

In this unit: Special case when ϕ is either E X, E U or E G

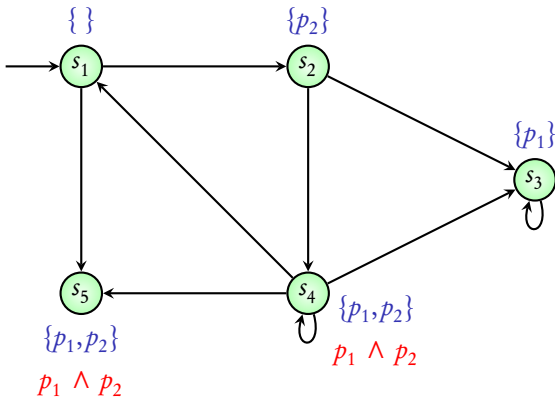
Part 1:

Algorithm for E X

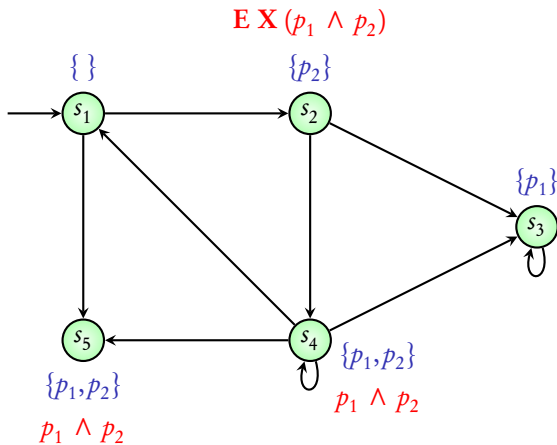
$\text{EX}(p_1 \wedge p_2)$



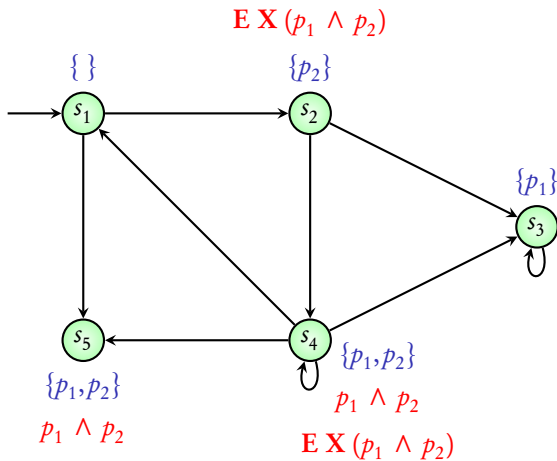
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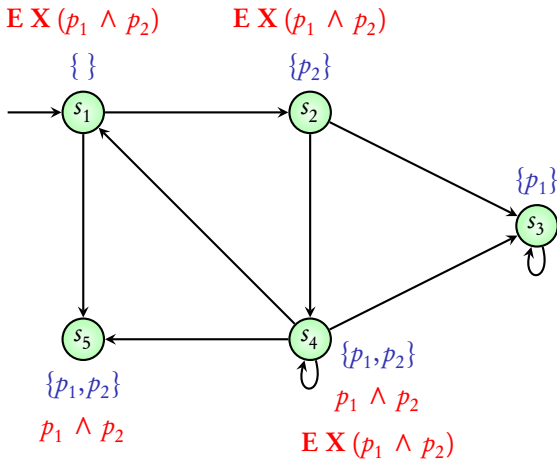
$EX(p_1 \wedge p_2)$



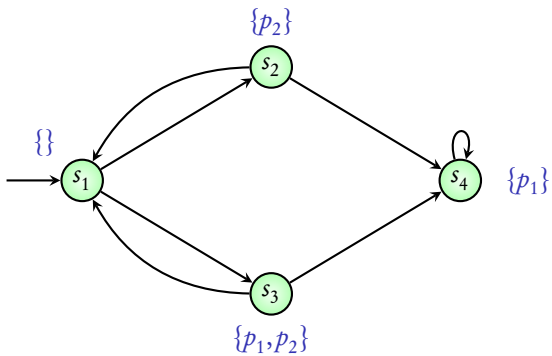
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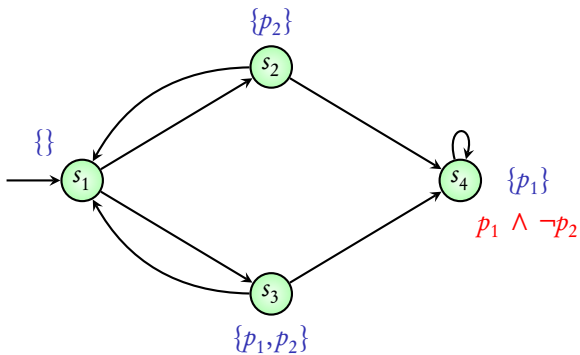
$EX(p_1 \wedge p_2)$



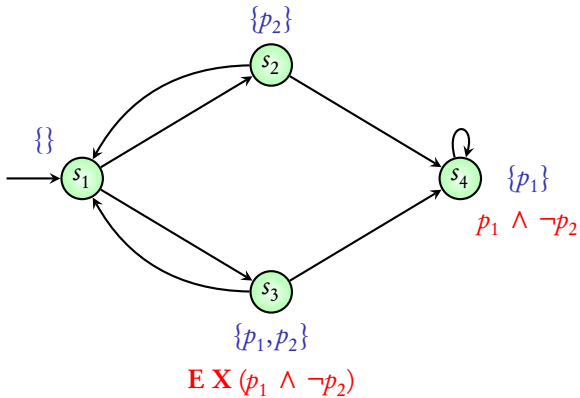
$\text{E X } (p_1 \wedge \neg p_2)$



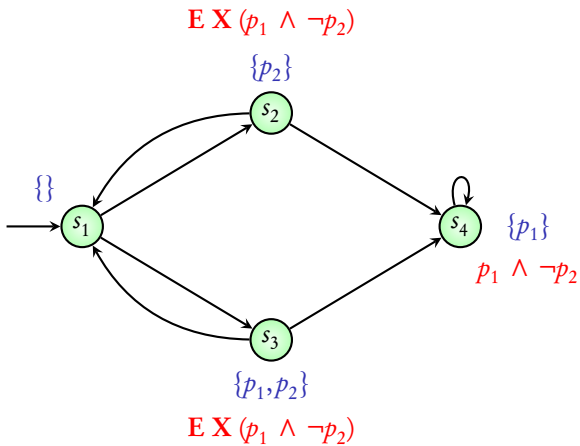
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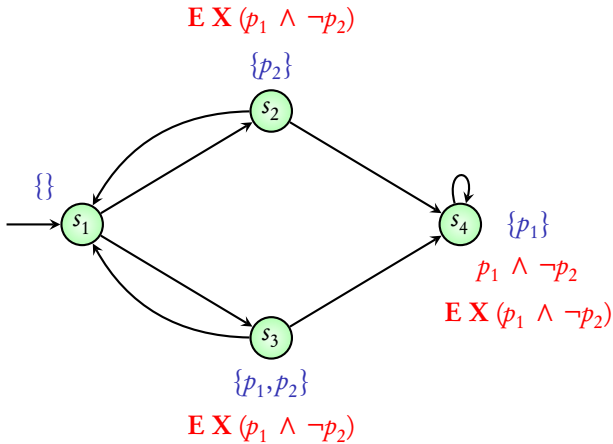
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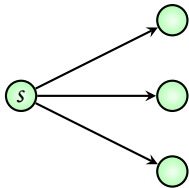
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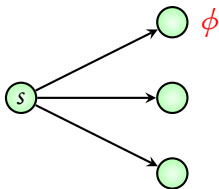


Algorithm for $E \times \phi$



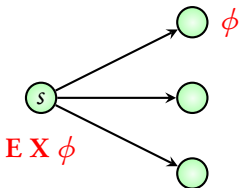
Algorithm for $E X \phi$

Suppose states satisfying ϕ have been labelled



Algorithm for $E X \phi$

Suppose states satisfying ϕ have been labelled

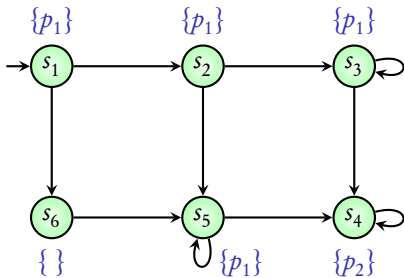


State s is labelled with $E X \phi$ if there **exists** a **successor** which is labelled ϕ

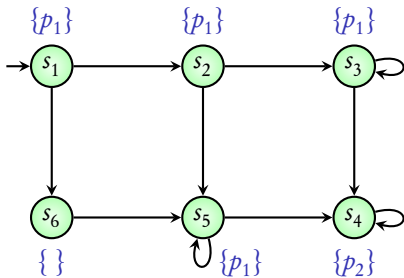
Part 2:

Algorithm for E U

$E(p_1 \text{ U } p_2)$

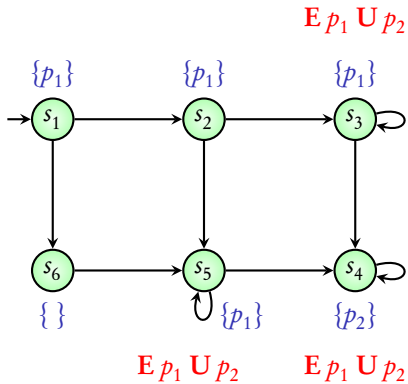


$E(p_1 \text{ U } p_2)$

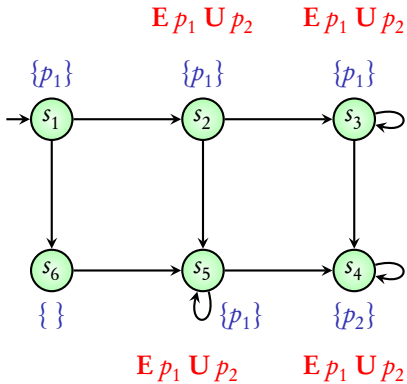


$E p_1 \text{ U } p_2$

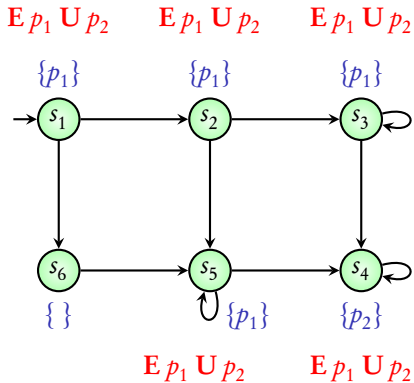
$E(p_1 \cup p_2)$



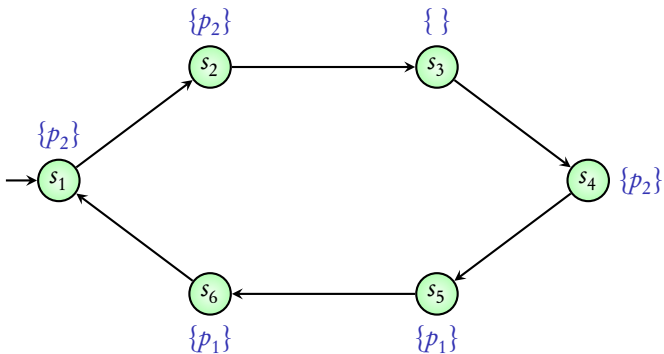
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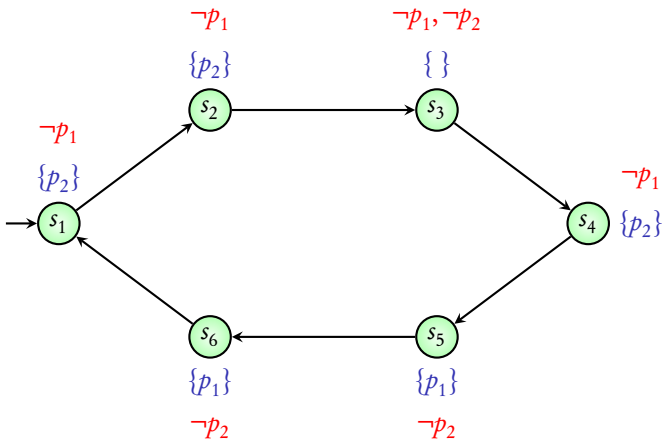
$E(p_1 \cup p_2)$



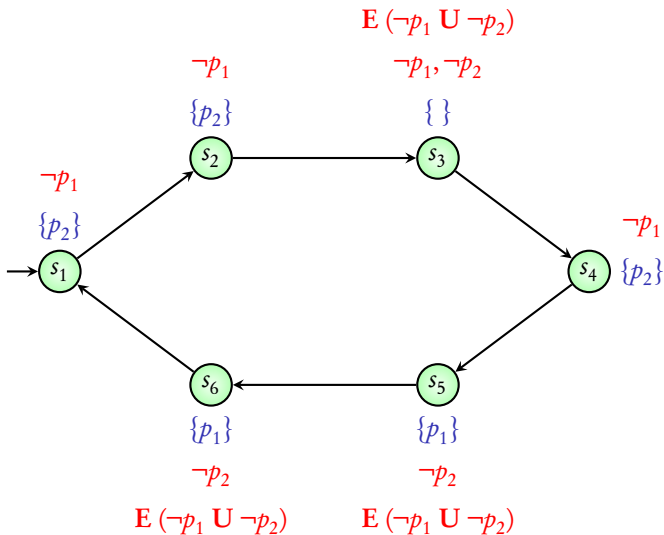
$E (\neg p_1 \text{ U } \neg p_2)$



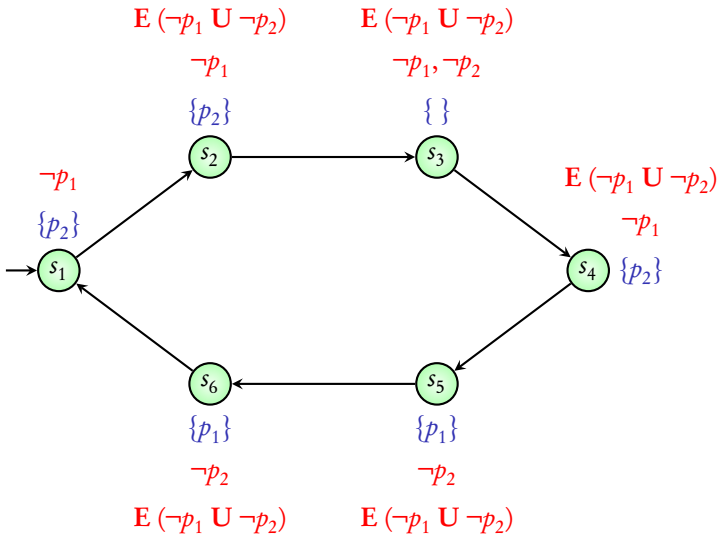
$$E (\neg p_1 \text{ U } \neg p_2)$$



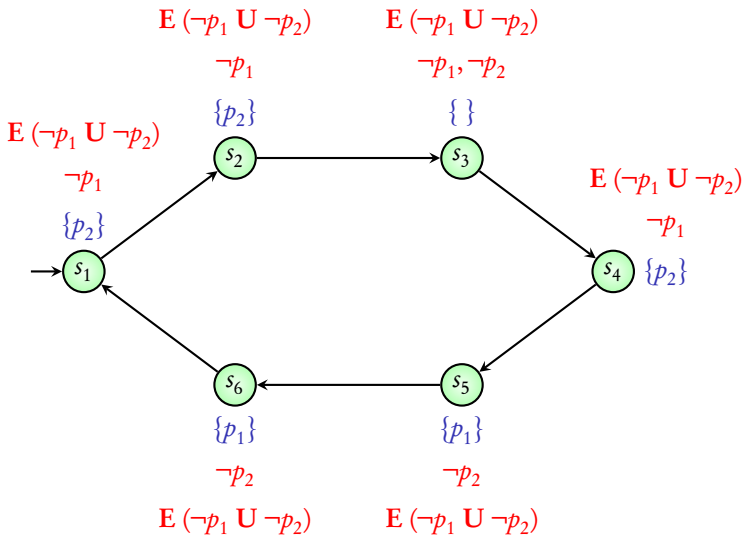
$$E (\neg p_1 \text{ U } \neg p_2)$$



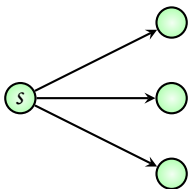
$$E (\neg p_1 \cup \neg p_2)$$



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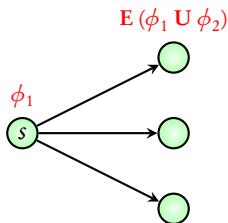


Algorithm for $E(\phi_1 \cup \phi_2)$



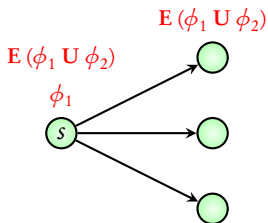
- ▶ If any state is labelled with ϕ_2 , label it with $E(\phi_1 \cup \phi_2)$
- ▶ *Repeat:*
Label any state with $E(\phi_1 \cup \phi_2)$ if it is labelled with ϕ_1 and at least one successor is labelled with $E(\phi_1 \cup \phi_2)$
until no change

Algorithm for $E(\phi_1 \cup \phi_2)$



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Algorithm for $E(\phi_1 \cup \phi_2)$

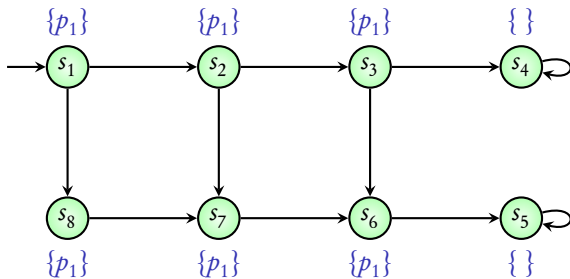


- ▶ If any state is labelled with ϕ_2 , label it with $E(\phi_1 \cup \phi_2)$
- ▶ *Repeat:*
Label any state with $E(\phi_1 \cup \phi_2)$ if it is labelled with ϕ_1 and at least one successor is labelled with $E(\phi_1 \cup \phi_2)$
until no change

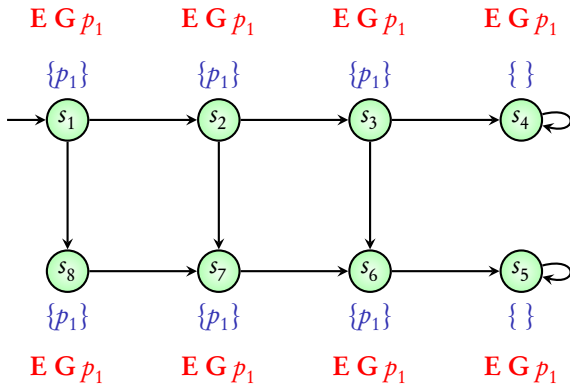
Part 3:

Algorithm for E G

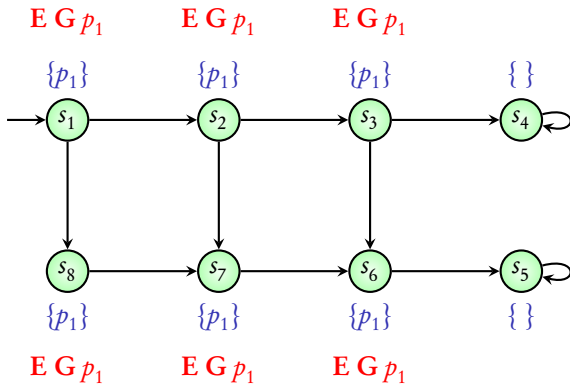
E G p_1



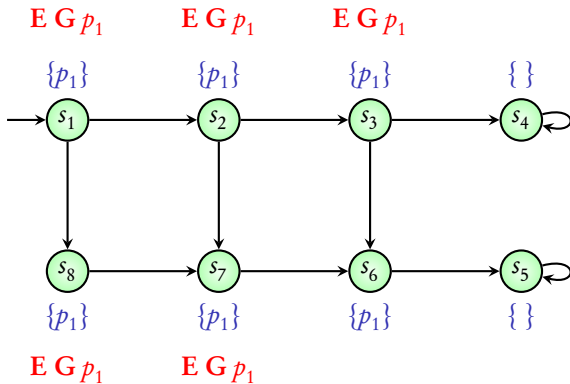
EG_{p_1}



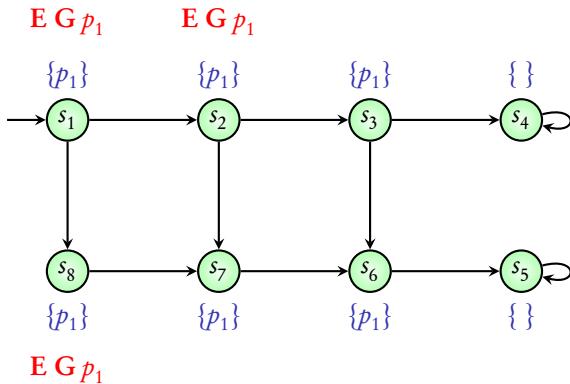
$EG p_1$



EG_{p_1}

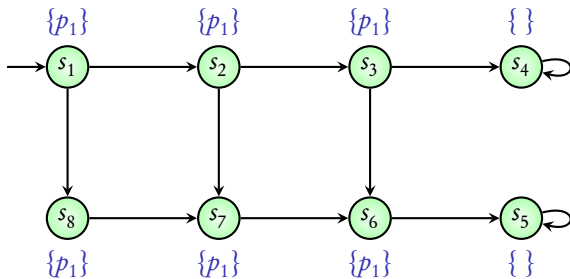


$EG p_1$

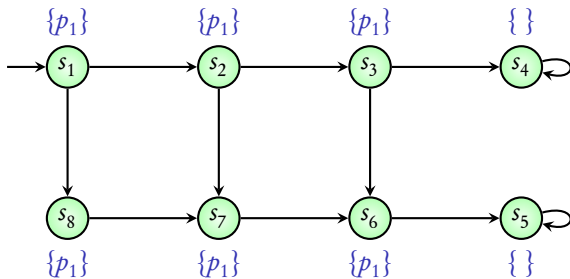


EG_{p_1}

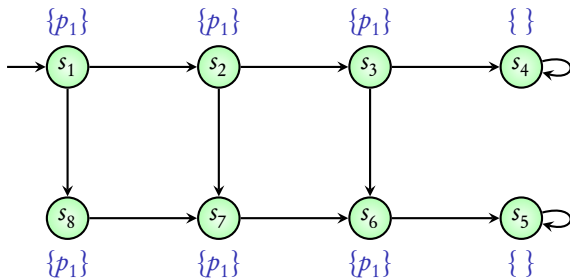
EG_{p_1}



$E G p_1$

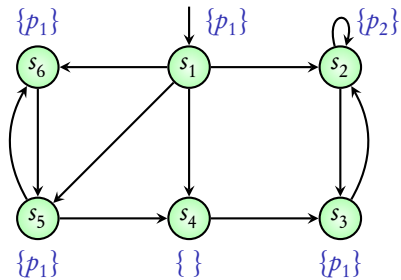


$E G p_1$

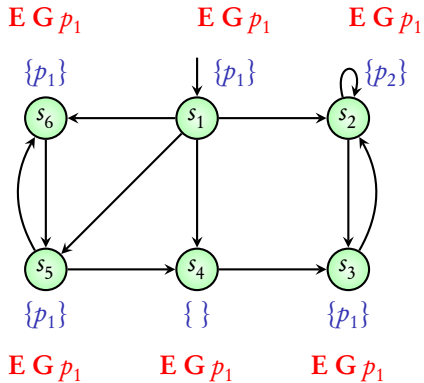


No state of the above transition system satisfies $E G p_1$

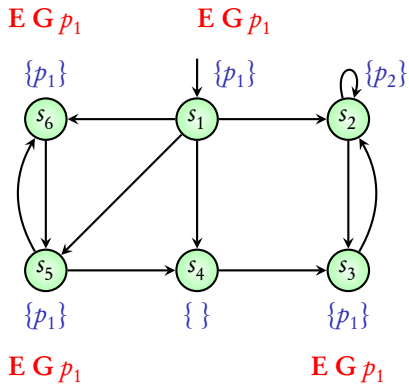
EG p_1



$EG p_1$



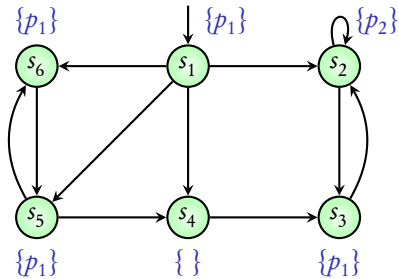
EG_{p_1}



EG_{p_1}

EG_{p_1}

EG_{p_1}



EG_{p_1}

Algorithm for $E \subseteq G \subseteq \phi$

Algorithm for $E G \phi$

- ▶ Label all states with $E G \phi$

Algorithm for $E G \phi$

- ▶ Label all states with $E G \phi$
- ▶ If any state is **not** labelled with ϕ , **delete** the label $E G \phi$

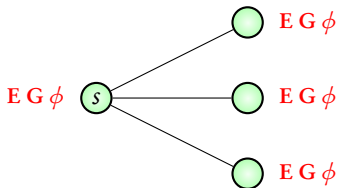
Algorithm for $E G \phi$

- ▶ Label all states with $E G \phi$
- ▶ If any state is **not** labelled with ϕ , **delete** the label $E G \phi$

- ▶ *Repeat:*
Delete the label $E G \phi$ from a state if **none** of its successors is labelled with $E G \phi$
until no change

Algorithm for $E G \phi$

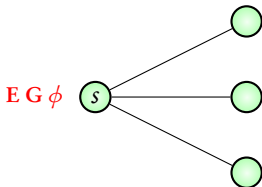
- ▶ Label all states with $E G \phi$
- ▶ If any state is **not** labelled with ϕ , **delete** the label $E G \phi$



- ▶ *Repeat:*
Delete the label $E G \phi$ from a state if **none** of its successors is labelled with $E G \phi$
until no change

Algorithm for $EG\phi$

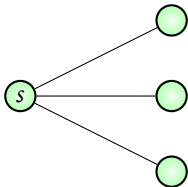
- ▶ Label all states with $EG\phi$
- ▶ If any state is **not** labelled with ϕ , **delete** the label $EG\phi$



- ▶ *Repeat:*
Delete the label $EG\phi$ from a state if **none** of its successors is labelled with $EG\phi$
until no change

Algorithm for $E G \phi$

- ▶ Label all states with $E G \phi$
- ▶ If any state is **not** labelled with ϕ , **delete** the label $E G \phi$



- ▶ *Repeat:*
Delete the label $E G \phi$ from a state if **none** of its successors is labelled with $E G \phi$
until no change

Summary

Algorithms

EX, EU, EG

Module 3:
Final algorithm

CTL model-checking problem

Given transition system M and a CTL formula ϕ , find all states of M that satisfy ϕ

CTL model-checking problem

Given transition system M and a CTL formula ϕ , find all states of M that satisfy ϕ

- ▶ **Module 1:** Every CTL formula can be written using EX, EU, EG
- ▶ **Module 2:** Labelling algorithms for EX, EU, EG

Coming next: Generic algorithm for a CTL formula

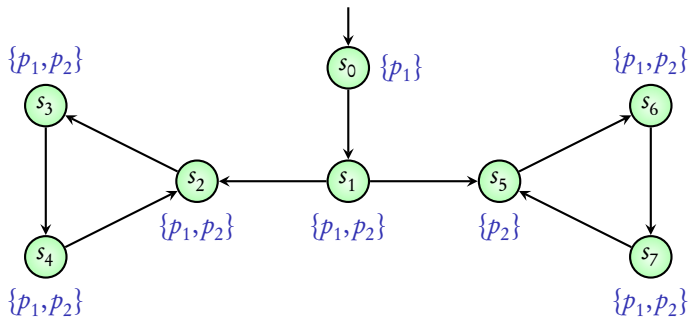
State formulae

$\phi := \text{true} \mid p_i \mid \phi_1 \wedge \phi_2 \mid \neg\phi \mid EX\phi \mid E(\phi_1 U \phi_2) \mid EG\phi$

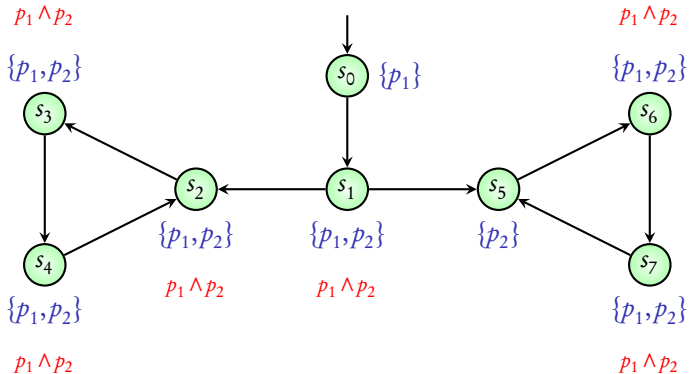
$p_i \in AP$

$\phi, \phi_1, \phi_2 : \text{State formulae}$

EXEG ($p_1 \wedge p_2$)



EXEG ($p_1 \wedge p_2$)



EXEG ($p_1 \wedge p_2$)

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)

$\{p_1, p_2\}$



EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



EG ($p_1 \wedge p_2$)

$\{p_1\}$



EG ($p_1 \wedge p_2$)

$\{p_2\}$



EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

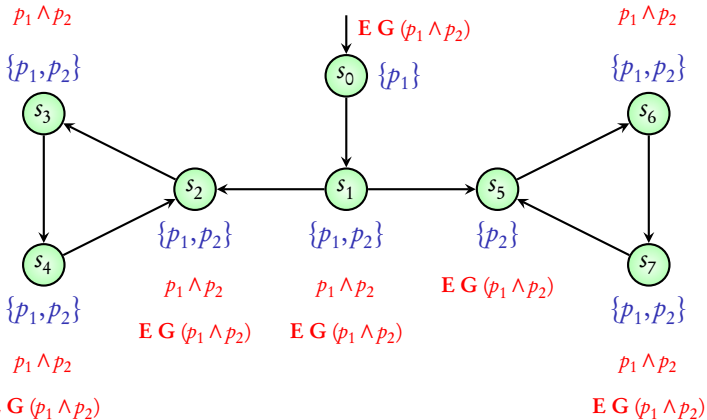
$\{p_1, p_2\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)



EXEG ($p_1 \wedge p_2$)

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)



$\{p_1\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)



$\{p_2\}$

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)

EXEG ($p_1 \wedge p_2$)

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)

$\{p_1, p_2\}$

$p_1 \wedge p_2$

EG ($p_1 \wedge p_2$)



$\{p_1, p_2\}$

$\{p_2\}$



EG ($p_1 \wedge p_2$)

$p_1 \wedge p_2$

$\{p_1, p_2\}$



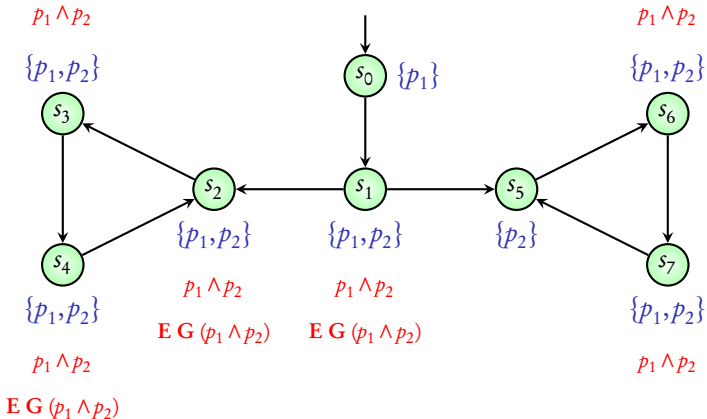
$\{p_1, p_2\}$

$p_1 \wedge p_2$



EXEG ($p_1 \wedge p_2$)

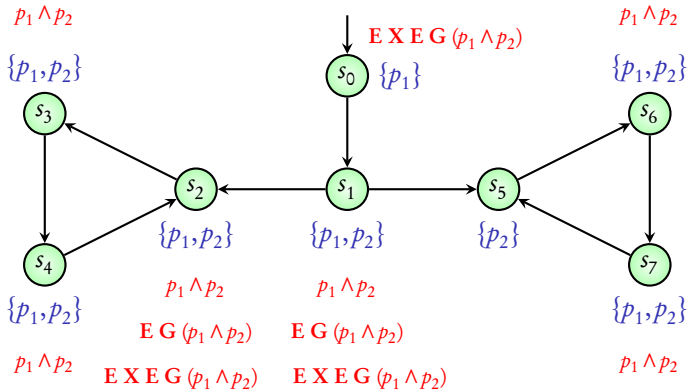
EG ($p_1 \wedge p_2$)



EXEG ($p_1 \wedge p_2$)

EXEG ($p_1 \wedge p_2$)

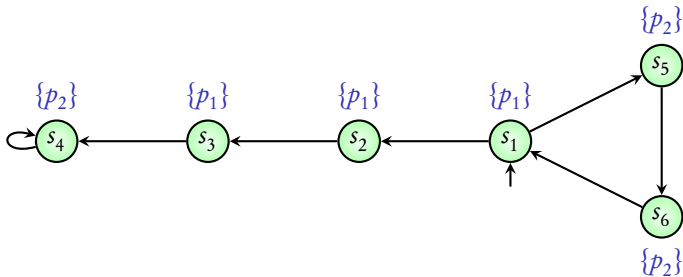
EG ($p_1 \wedge p_2$)



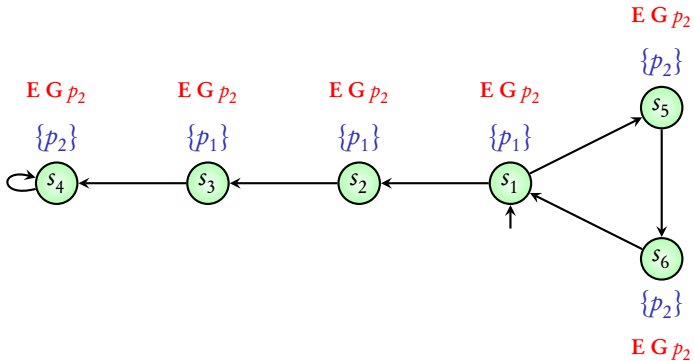
EG ($p_1 \wedge p_2$)

EXEG ($p_1 \wedge p_2$)

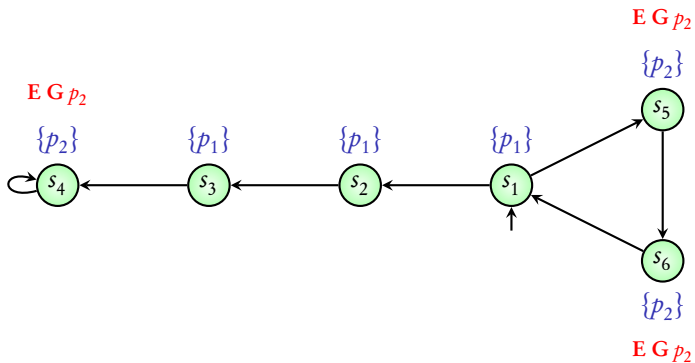
$E p_1 U (E G p_2)$



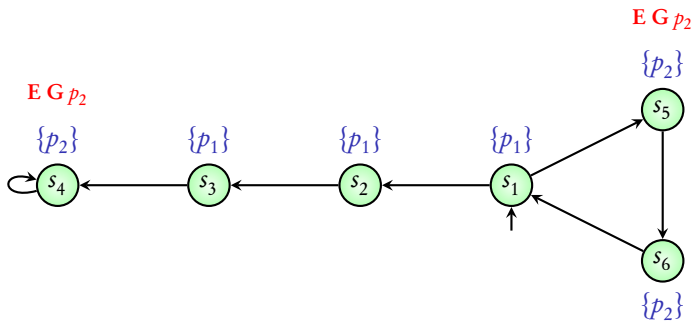
$$E p_1 U (E G p_2)$$



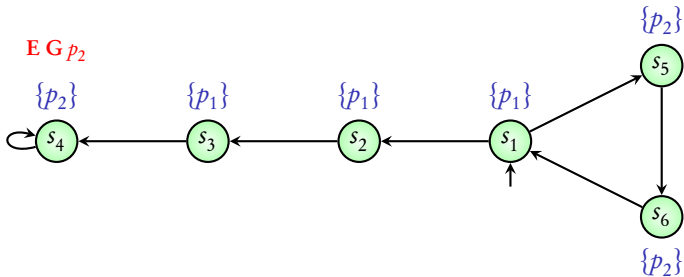
$$E p_1 U (E G p_2)$$



$$E p_1 U (E G p_2)$$



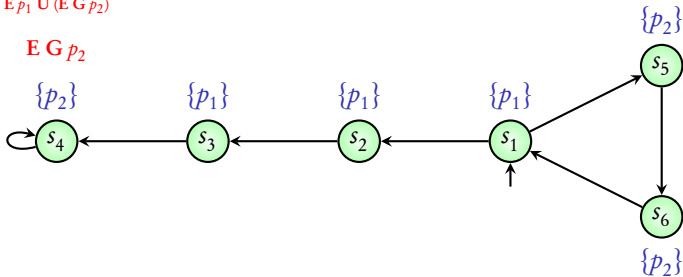
$$E p_1 U (E G p_2)$$



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$E p_1 U (E G p_2)$

$E G p_2$

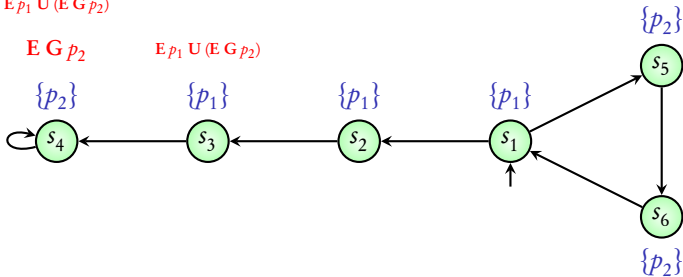


$$E p_1 U (E G p_2)$$

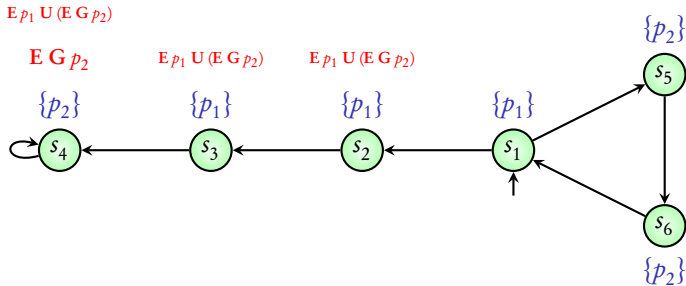
$E p_1 U (E G p_2)$

$E G p_2$

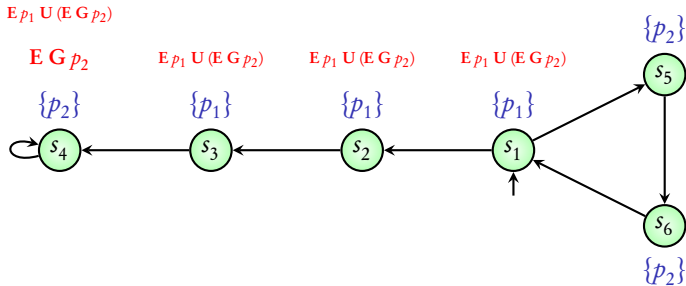
$E p_1 U (E G p_2)$



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function SAT(ϕ)

/ Input: Transition system M with state set S , CTL formula ϕ in ENF */*

/ Output: Set of states satisfying ϕ */*

end function

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ϕ is *true* : **return** S

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ϕ is *true* : **return** S

ϕ is p_i : **return** {states containing p_i }

end case

end function

function SAT(ϕ)

/ Input: Transition system M with state set S , CTL formula ϕ in ENF */*

/ Output: Set of states satisfying ϕ */*

case

ϕ is *true* : **return** S

ϕ is p_i : **return** {states containing p_i }

ϕ is $\phi_1 \wedge \phi_2$: **return** SAT(ϕ_1) \cap SAT(ϕ_2)

end case

end function

function SAT(ϕ)

*/** **Input:** Transition system M with state set S , CTL formula ϕ in ENF **/*

*/** **Output:** Set of states satisfying ϕ **/*

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ϕ is *true* : **return** S

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ϕ is $\phi_1 \wedge \phi_2$: **return** SAT(ϕ_1) \cap SAT(ϕ_2)

ϕ is $\neg\phi_1$: **return** $S - \text{SAT}(\phi_1)$

end case

end function

function SAT(ϕ)

/ Input: Transition system M with state set S , CTL formula ϕ in ENF */*

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ϕ is *true* : **return** S

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ϕ is **E X** ϕ_1 : **return** SAT_{EX}(ϕ_1) */* procedure seen in Module 2 */*

end case

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function SAT(ϕ)

/ Input: Transition system M with state set S , CTL formula ϕ in ENF */*

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case

ϕ is *true* : **return** S

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ϕ is **E X** ϕ_1 : **return** SAT_{EX}(ϕ_1) */* procedure seen in Module 2 */*

ϕ is **E** (ϕ_1 **U** ϕ_2) : **return** SAT_{EU}(ϕ_1, ϕ_2) */* procedure seen in Module 2 */*

end case

end function

function SAT(ϕ)

/ Input: Transition system M with state set S , CTL formula ϕ in ENF */*

/ Output: Set of states satisfying ϕ */*

case

ϕ is *true* : **return** S

ϕ is p_i : **return** {states containing p_i }

ϕ is $\phi_1 \wedge \phi_2$: **return** SAT(ϕ_1) \cap SAT(ϕ_2)

ϕ is $\neg\phi_1$: **return** $S - \text{SAT}(\phi_1)$

ϕ is **E X** ϕ_1 : **return** SAT_{EX}(ϕ_1) */* procedure seen in Module 2 */*

ϕ is **E** (ϕ_1 **U** ϕ_2) : **return** SAT_{EU}(ϕ_1, ϕ_2) */* procedure seen in Module 2 */*

ϕ is **E G** ϕ_1 : **return** SAT_{EG}(ϕ_1) */* procedure seen in Module 2 */*

end case

end function

CTL model-checking algorithm

Reference: Logic in Computer Science, *by Huth and Ryan* - Section 3.6.1