

# Model-Checking Event Structures

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Formal Methods Update Meeting  
IIT Roorkee  
13 July 2009

# Logics and verification

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## Branching-time temporal logic

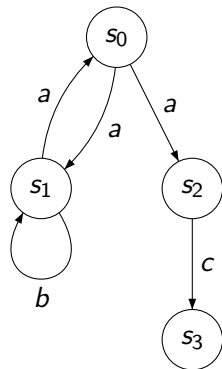
- ▶ Collect all runs of the system in a single structure, the **computation tree**
- ▶ Interpret formulas over computation tree
- ▶ Can quantify over runs, compare runs, ...

# The Computation Tree

- ▶ We will work finite-state systems
- ▶ Start at an initial state and explore all executions
- ▶ Unfold the system into a tree

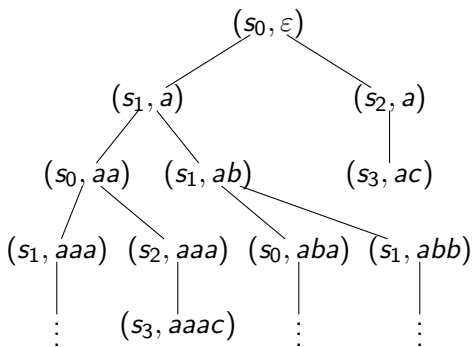
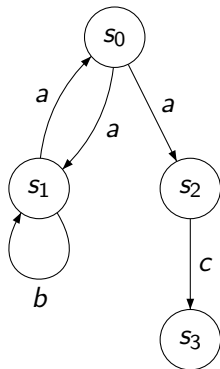
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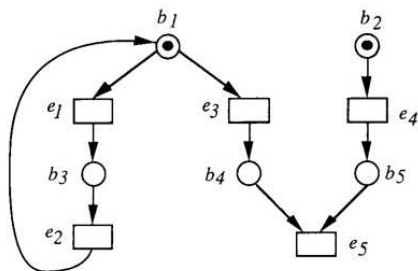
# Concurrent systems

- ▶ Suppose the system is a collection of interacting components
- ▶ During a run, some actions can be independent of each other
- ▶ Different sequences of actions may represent the same run



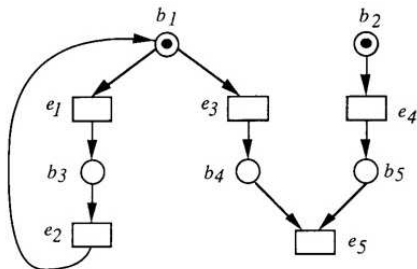
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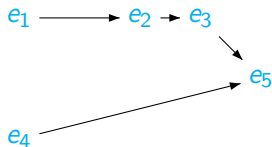
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# Runs as partial orders

- ▶ Convenient to view each execution as a labelled partial order
- ▶ Actions can be related in two ways
  - ▶ **Causality**  
An occurrence of  $b$  causally depends on an occurrence of  $a$  if  $a$  must happen before  $b$  happens
  - ▶ **Concurrency**  
An occurrence of  $b$  is independent of an occurrence of  $a$  if they can occur in any order



# Runs as partial orders

- ▶ In many interesting cases, the runs of concurrent systems can be described as traces [Mazurkiewicz]
- ▶ Actions are enriched with **independence relation** specifying which pairs are independent
  - ▶ Symmetric, irreflexive
  - ▶ Typically derived from structure of underlying system
    - ▶ Actions performed by disjoint sets of components
- ▶ In a linearization, adjacent independent actions can be swapped to yield an equivalent linearization

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# Temporal logics for concurrent systems

- ▶ Temporal logic interpreted on linearizations of runs makes too many distinctions
  - ▶ A property such as  $e_2$  is immediately followed by  $e_4$  is true in some linearizations and not in others
- ▶ Modify temporal logic to express causality and concurrency
- ▶ What about linear-time vs branching-time?
- ▶ How do we represent the computation tree of a concurrent system?

# Computation tree of a concurrent system

- ▶ In sequential systems, computation tree glues together all runs in a single branching structure
- ▶ In concurrent systems, each run is a labelled partial order (a trace)
- ▶ Need to glue together traces to form a tree

# Event structures

- ▶ Each action occurs in a context — what has happened earlier
- ▶ Each different occurrence of an action is an **event**
- ▶ In a single trace, events are related by **causality** or **concurrency**
- ▶ Across traces, events are related by **conflict**
  - ▶ Choosing between two mutually incompatible events generates different runs

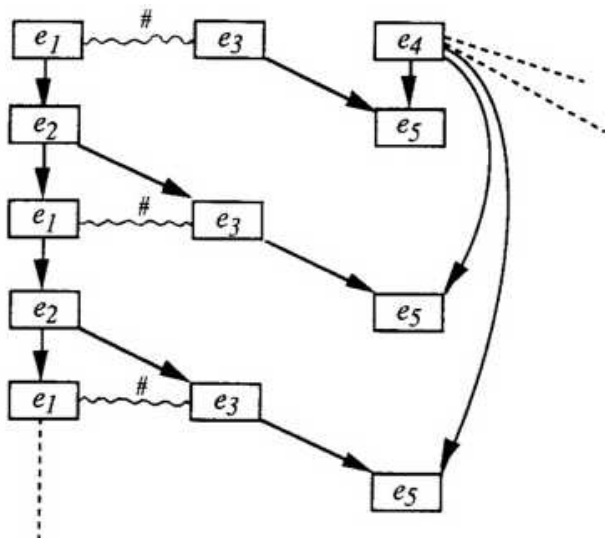
# Event Structures . . .

Formally, an event structure is of the form  $ES = (E, \leq, \#)$

- ▶  $E$  is the set of events
- ▶  $\leq$  is the causality relation (a partial order)
- ▶  $\#$  is a binary conflict relation
  - ▶ Irreflexive, symmetric
- ▶ Conflict is inherited via causality
  - ▶  $e\#f$  and  $f \leq f'$  implies  $e\#f'$
- ▶ Two events are concurrent if they are not related by  $\leq$  or  $\#$ 
  - $e \text{ co } f$



# Event Structures ...



# Event Structures . . .

- ▶ A **configuration** of an event structure is a set  $X \subseteq E$  such that
  - ▶  $X$  is  $\downarrow$ -closed
  - ▶  $X$  is conflict free
- ▶ A configuration represents a set of events that have happened so far — a global state of the system

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- ▶  $t \# t'$  if  $t$  and  $t'$  are **not** compatible
- ▶ Identify **events** with **prime traces**
  - ▶ **Prime trace**: Only one maximal element
  - ▶ “Earliest” occurrence of an action

# Temporal logics for event structures

- ▶ Interpret formulas at events of an event structure
  - ▶ Event  $e$  denotes the minimal configuration  $\downarrow e$  where it occurs
  - ▶  $\downarrow e$  can be thought of as the local state of the components involved in  $e$
- ▶ Modalities to express causality, conflict, concurrency
  - ▶  $ES, e \models A_{\leq} \varphi$  if at every  $f$  such that  $e \leq f$ ,  $ES, f \models \varphi$
  - ▶  $ES, e \models E_{\leq} \varphi$  if there exists  $f$  such that  $e \leq f$  and  $ES, f \models \varphi$
  - ▶  $ES, e \models A_{\#} \varphi$  if at every  $f$  such that  $e \# f$ ,  $ES, f \models \varphi$
  - ▶  $ES, e \models E_{\#} \varphi$  if there exists  $f$  such that  $e \# f$  and  $ES, f \models \varphi$
  - ▶  $ES, e \models A_{co} \varphi$  if at every  $f$  such that  $e co f$ ,  $ES, f \models \varphi$
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## $\triangleleft$ and $\#_\mu$

The immediate successor relation  $\triangleleft$  generates  $\leq$

$e \triangleleft f$  if  $e \leq f$  and for all  $g$ ,  $e \leq g \leq f \Rightarrow e = g$  or  $g = f$

Corresponding modality

- ▶  $ES, e \models A_{\triangleleft} \varphi$  if at every  $f$  such that  $e \triangleleft f$ ,  $ES, f \models \varphi$
- ▶  $ES, e \models E_{\triangleleft} \varphi$  if there exists  $f$  such that  $e \triangleleft f$  and  $ES, f \models \varphi$

Minimal conflict relation  $\#_\mu$  generates  $\#$  via  $\leq$

$e \#_\mu f$  if  $e \# f$  and for all  $e' \triangleleft e$ ,  $f' \triangleleft f$ , it is not the case that  $e \# f'$  or  $e' \# f$

Corresponding modality

- ▶  $ES, e \models A_{\#_\mu} \varphi$  if at every  $f$  such that  $e \#_\mu f$ ,  $ES, f \models \varphi$
- ▶  $ES, e \models E_{\#_\mu} \varphi$  if there exists  $f$  such that  $e \#_\mu f$  and  $ES, f \models \varphi$

# The model-checking problem

- ▶ Start with a finite-state representation of the system,  $M$ 
  - ▶ Petri net
  - ▶ Product of automata
  - ▶ ...
- ▶ Atomic propositions  $AP$  describing properties of (local) states
  - ▶ Valuation assigns a subset of  $AP$  to each (local) state
- ▶ In  $ES_M$ , event structure of  $M$ , each configuration  $\downarrow e$  corresponds to a unique (global) state of  $M$
- ▶ Formulas for system properties built from  $AP$ , boolean operations, event structure modalities
  - ▶  $A_{\leq}(b \Rightarrow E_{\#}a)$
  - ▶  $A_{<}((b \Rightarrow E_{\#\mu}a) \wedge (a \Rightarrow E_{\#\mu}b))$
- ▶ Does  $ES_M, e \models \varphi$ ?

# The model-checking problem

Apparently only two papers addressing this topic.

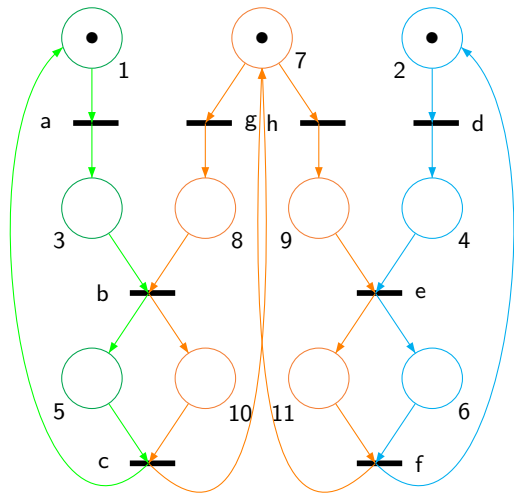
- ▶ [Model-Checking for a Subclass of Event Structures](#)  
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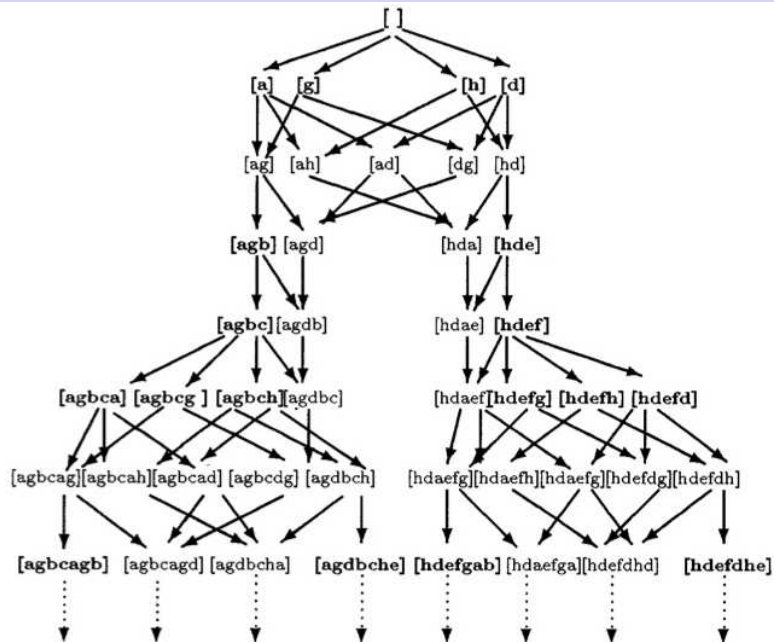
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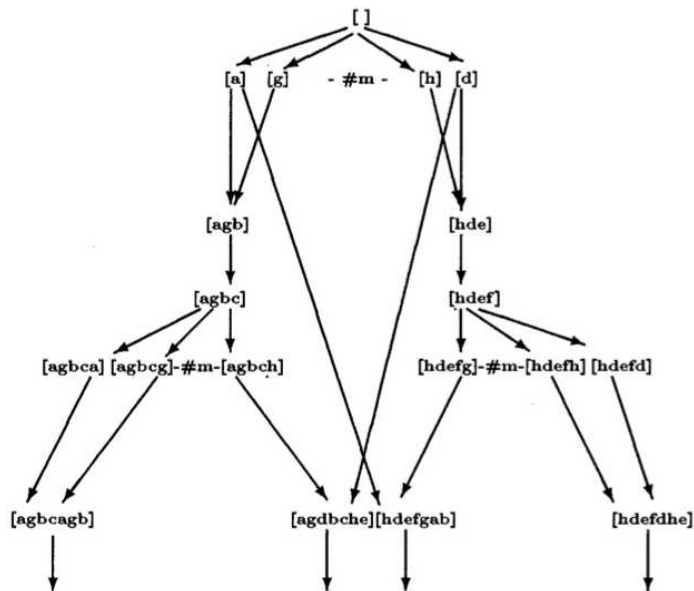
# Running example



# Trace semantics



# Event structure semantics



# Penczek's result

- ▶ Restrict the modalities
- ▶ Only  $A_{\leq}/E_{\leq}$ ,  $A_{<}/E_{<}$ ,  $A_{\#_m u}/E_{\#_m u}$
- ▶ No  $A_{co}/E_{co}$
- ▶ Though  $\#$  is generated by  $\#_{\mu}$  and  $\leq$ , cannot fully express  $A_{\#}/E_{\#}$ 
  - ▶  $\# = \leq^{-1} \circ \#_{\mu} \circ \leq$
  - ▶ No past modality to capture  $\leq^{-1}$



# Quotienting the trace system

## First attempt

- ▶ Two traces are equivalent if they reach the same global state
- ▶ This is not sufficient,
  - ▶ [], *[agbc]* and *[hdef]* all lead to (1, 2, 7)
  - ▶ Causal futures are different

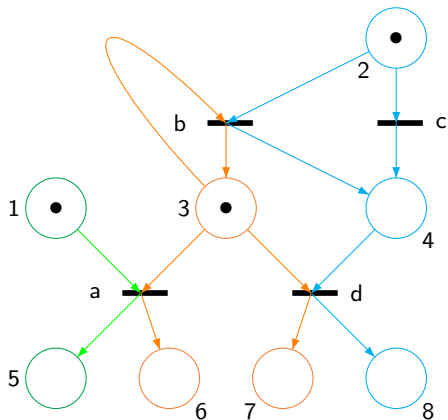
## Refine further

- ▶ Two traces are equivalent if they reach the same global state and the maximal actions in the traces are the same

# Quotienting the trace system . . .

- ▶ Recall that events are prime traces
- ▶ Let  $e, f$  be two events
- ▶ Would like the following property
  - ▶ If  $[e] = [f]$ , then  $ES_M, e \models \varphi$  iff  $ES_M, f \models \varphi$
- ▶ This does not hold in general

## Another example



# Quotienting the trace system ...

- ▶ Recall that events are prime traces
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- ▶ This does not hold in general
  - ▶ In this example,  $[bd]$  and  $[cd]$  are prime traces reaching same global state  $(1, 7, 8)$  with same maximal event  $d$
  - ▶  $[a]$  and  $[ba]$  are prime traces that reach different global states
  - ▶  $[bd] \#_{\mu} [ba]$  and  $[cd] \#_{\mu} [a]$ , so  $[bd]$  and  $[cd]$  don't satisfy the same  $E_{\#_{\mu}}$  formulas.

# Free-choice property

- ▶ Restrict systems to have the free-choice property
- ▶ Intuitively, choices available to one component cannot change due to actions of another component
  - ▶ Second example is not free-choice — if **third process** executes **c**, **second process** loses option of performing **b** (and vice versa)

## Formally

- ▶ If  $s \xrightarrow{a} s'$  involves components  $P_a$  and  $t \xrightarrow{b} t'$  involves components  $P_b$  then
  - ▶ Either  $P_a \cap P_b = \emptyset$ , or,
  - ▶ If  $s[j] = t[j]$  for some process  $j$ , then  $P_a = P_b$  and for all  $j \in P_a = P_b$ ,  $s[j] = t[j]$ .

# Free-choice property . . .

- ▶ Free-choice ensure that if  $e \#_{\mu} f'$  then
  - ▶ There is a common prefix  $t$  such that  $e = ta$ ,  $f = tb$
  - ▶ Actions  $a$  and  $b$  involve exactly the same set of components

Recall our definition of a quotiented trace system

$t \equiv t'$  if  $t$  and  $t'$  reach the same global state and have the same set of maximal actions

Our desired property

- ▶ If  $e \equiv f$ , then  $ES_M, e \models \varphi$  iff  $ES_M, f \models \varphi$

can be proved by structural induction on  $\varphi$  from the following

- ▶ If  $e \equiv f$  and  $e \prec e'$ , there exists  $f'$  such that  $f \prec f'$  and  $e' \equiv f'$
- ▶ If  $e \equiv f$  and  $e \#_{\mu} e'$ , there exists  $f'$  such that  $f \#_{\mu} f'$  and  $e' \equiv f'$

# The model-checking algorithm

## Naive

- ▶ Compute the quotiented trace system for the given model
  - ▶ This is a finite object
- ▶ Identify prime traces as events and constructed corresponding “quotiented” event structure
- ▶ Decompose formulas and use CTL-style bottom-up labelling to identify the formulas true at each event

## More efficient

- ▶ Use partial order techniques to construct a representative subset of the quotiented trace system
- ▶ Translate event structure logic to CTL and directly use CTL model checking on the quotiented trace system
  - ▶ Use a special proposition to mark prime traces

## Beyond Penczek's result

- ▶ Can we extend the algorithm to full logic involving  $A_{co}/E_{co}$  and  $A_{\#}/E_{\#}$ ?
- ▶ Can the free-choice restriction be relaxed?